

Matrices

MATHEMATICS FOR COMPUTING (IT 1030)

Matrix Definition and Notations

- > A matrix is an array, which satisfies certain algebraic rules of operation.
- Capital letters are usually used to denote matrices

Eg:
$$\begin{bmatrix} -2 & 1 & 0 \\ -1 & 3 & 4 \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} = [a_{ij}], (1 \le i \le m, 1 \le j \le n)$$

Vectors

- Matrices, which have either one row or one column, are known as **vectors**
 - Row vectors

Eg: [1 0 2]

Column Vectors

$$\mathsf{Eg} \colon \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix}$$

Square Matrix

> A matrix in which the number of rows equals the number of columns is called a square matrix

$$\mathsf{Eg:} \begin{bmatrix} 1 & 8 \\ 0 & 5 \end{bmatrix}$$

Rectangular Matrix

A matrix in which the number of rows not equals the number of columns is called a rectangular matrix

$$\mathsf{Eg:} \begin{bmatrix} 8 & -4 & 1 \\ 2 & 0 & 3 \end{bmatrix}$$

1. Equality. Two matrices can only be equated if they are of the same *order*, that is, if they each have the same number of rows and the same number of columns. They are then said to be equal if the corresponding elements are equal. Thus if

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
 and $B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$

then $\mathbf{A} = \mathbf{B}$ if and only if a = e, b = f, c = g, and d = h

2. Multiplication by a constant. Let k be a constant or scalar. By the product kA we mean the matrix in which every element of A is multiplied by k. Thus, if

$$A = \begin{bmatrix} -2 & 1 & 0 \\ -1 & 3 & 4 \end{bmatrix} \text{ and } k = 10$$

$$k*A = \begin{bmatrix} -2*10 & 1*10 & 0*10 \\ -1*10 & 3*10 & 4*10 \end{bmatrix} = \begin{bmatrix} -20 & 10 & 0 \\ -10 & 30 & 40 \end{bmatrix}$$

3. Zero matrix. Any matrix in which every element is zero is called a **zero** or **null matrix**. If A is a zero matrix, we can simply write A = 0.

4. Matrix sums and differences. The sum of two matrices A and B is defined if A and B are of the same order, in which case A + B is defined as the matrix C whose elements are the sums of the corresponding elements in A and B. We write C = A + B.

Thus, if

 $A = [a_{ij}]$ and $B = [b_{ij}]$ are both $m \times n$ matrices, then

$$C = A + B = [a_{ij} + b_{ij}].$$

5. Commutative property of matrix addition, that is,

$$A + B = B + A$$

6. Associative law of addition

$$A + (B+C) = (A+B) + C$$

the order of addition of matrices is immaterial

7. Distributive law of addition

$$A(B + C) = AB + AC$$

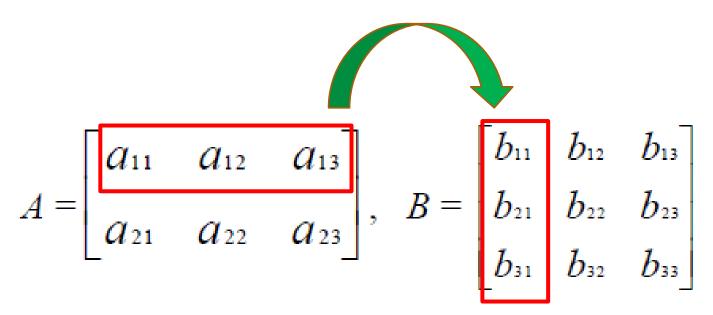
8. Associative law of multiplication

$$A(BC) = (AB)C$$

9.
$$k(A + B) = kA + kB$$

 $(k + l)A = kA + lA$. k, l are real numbers

10. Matrix multiplication. Matrices can be multiplied only if the number of columns in *A* equals the number of rows in *B*. Let us look at the case where *A* is a 2x3 matrix, and *B* is a 3x2 matrix, which are given by



Translation Matrix

Rotation Matrix

Rules of Matrix Algebra

$$\begin{bmatrix} 1.0 & 0.0 & 0.0 \\ 0.0 & 1.0 & 0.0 \\ -X & -Y & 1.0 \end{bmatrix} X \begin{bmatrix} \cos\theta & -\sin\theta & 0.0 \\ \sin\theta & \cos\theta & 0.0 \\ 0.0 & 0.0 & 1.0 \end{bmatrix}$$

Process elements: by Col in Row

by Row in Col

$$AB = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix}$$

$$= \begin{bmatrix} a_{11}b_{11} + a_{12}b_{21} + a_{13}b_{31} & a_{11}b_{12} + a_{12}b_{22} + a_{13}b_{32} & a_{11}b_{13} + a_{12}b_{23} + a_{13}b_{33} \\ a_{21}b_{11} + a_{22}b_{21} + a_{23}b_{31} & a_{21}b_{12} + a_{22}b_{22} + a_{23}b_{32} & a_{21}b_{13} + a_{22}b_{23} + a_{23}b_{33} \end{bmatrix}$$

$$= C.$$

> One conclusion which can be inferred from the previous example is that matrix multiplication does not commute; that is, in general,

$$AB \neq BA$$
.

AB can be a zero matrix without either A or B or BA being zero. Also, as a consequence, A(B - C) = 0 does not necessarily imply B = C.

1. The transpose of any matrix is one in which the rows and columns are interchanged. Then, the first row becomes the first column, the second row the second column, and so on. We denote the transpose of A by A^T . Hence if

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$$
 then $A^T = \begin{bmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \end{bmatrix}$

The 3 x 2 matrix A becomes the 2 x 3 matrix A^{T} .

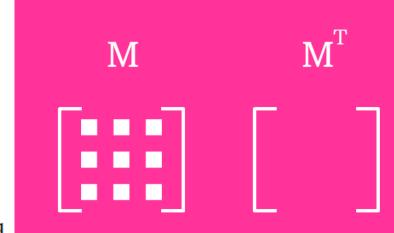
Properties of the transpose. Provided that the sum A + B and product AB are defined

for two matrices A and B, then

(a)
$$(A + B)^T = A^T + B^T$$
;

(b)
$$(AB)^{T} = B^{T} A^{T}$$
.

(c)
$$(A^T)^T = A$$
.



2. Symmetric matrices. A square matrix is said to be symmetric if $A = A^{T}$. Since rows and columns are interchanged in the transpose, this is equivalent to $a_{ij} = a_{ji}$ for all elements if $A = [a_{ij}]$. Symmetric matrices are easy to recognize since their elements are reflected in the **leading diagonal**.

$$A = \begin{bmatrix} 1 & 3 & -2 \\ 3 & 2 & 4 \\ -2 & 4 & -1 \end{bmatrix}$$
 is a 3 x 3 symmetric matrix.

A square matrix A for which $A = -A^T$ is said to be **skew-symmetric**. The elements along the leading diagonal of a skew-symmetric matrix must all be zero.

$$\begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & -3 \\ -2 & 3 & 0 \end{bmatrix}$$
 is skew-symmetric.

Note: If A is any square matrix, then $A + A^T$ is symmetric and $A - A^T$ is skew-symmetric.

3. Row and column vectors. As we defined them in Section 4.1, a row vector is a matrix with one row, and a column vector is one with one column. For vectors, we usually use bold-faced small letters and write, for example,

$$\boldsymbol{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}, \qquad \boldsymbol{b}^{\mathrm{T}} = [b_1 \ b_2 \ \dots \ b_n]$$

The transpose of a row vector is a column vector and vice versa. If A is an $m \times n$ matrix, then Aa is a column vector with m rows.

4. Diagonal matrices. A square matrix all of whose elements off the leading diagonal are zero is called a diagonal matrix. Thus, if $A = [a_{ij}]$ is an $n \times n$ matrix, then A is diagonal if $a_{ij} = 0$ for all $i \neq j$.

Hence

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$
 is an example of a 3 x 3 diagonal matrix.

A diagonal matrix is obviously symmetric. If A and B are diagonal matrices of the same order then A + B and AB are also both diagonal

5. Identity matrix. The diagonal matrix with all diagonal elements 1 is called the Identity or unit matrix I_n. Hence, the 3 x 3 identity is

$$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- 6. Powers of matrices. If A is a square matrix of order $n \times n$, then we write AA as A^2 , AA^2 as A^3 and so on.
- 7. Inverse matrix, for a square matrix A, the inverse is written A^{-1} . When A is multiplied by A^{-1} the result is the identity matrix.

$$A A^{-1} = A^{-1} A = I$$