

EDK II source code analysis --- USB protocol EHCI (example) 1

原创

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This article details the different interface standards of USB controllers, including OHCI, UHCI, EHCI, and XHCI, as well as their roles in USB device management. The focus is on the USB host controller driver of EHCI (Enhanced Host Controller Interface), especially the logic of the `EhcDriverBindingStart` function, and the role of URB (USB Request Block) in data transmission. In addition, the management and transmission process of USB device drivers are mentioned, including the processing ...

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Base

- 1. OHCI (Open Host Controller Interface) is a standard that supports USB1.1, but it is not only for USB**, but also supports some other interfaces, such as Apple's Firewire (IEEE 1394) interface. Compared with UHCI, OHCI's hardware is complex and the hardware does more things, so it is relatively simple to implement the corresponding software driver task. It is mainly used for non-x86 USB, such as expansion cards and USB host controllers of **embedded development** boards.
- 2. UHCI (Universal Host Controller Interface) is an interface standard for USB1.0 and 1.1 led by Intel and is incompatible with OHCI.** UHCI's software driver task is heavy and needs to be more complicated, but it can use USB controllers with cheaper and simpler hardware. Intel and VIA use UHCI, while other hardware providers use OHCI.
- 3. EHCI (Enhanced Host Controller Interface) is an interface standard for USB2.0 led by Intel.** EHCI only provides high-speed functions of USB2.0, and relies on UHCI or OHCI to provide support for full-speed or low-speed devices.
- 4. XHCI (eXtensible Host Controller Interface) is the latest USB3.0 interface standard. It has greatly improved the speed, energy saving, virtualization and other aspects compared with the previous three.** xHCI supports USB devices of all speeds (USB 3.0 SuperSpeed, USB 2.0 Low-, Full-, and High-speed, USB 1.1 Low- and Full-speed). The purpose of xHCI is to replace the previous three (UHCI/OHCI/EHCI).

The USB protocol stack in EDKII consists of three driver programs:

USB host controller driver, USB bus driver and USB device driver

in:

The USB host controller driver source code is located in the MdeModulePkg\Bus\Pci directory

The USB bus driver and USB device driver source code are located in the MdeModulePkg\Bus\Usb directory.

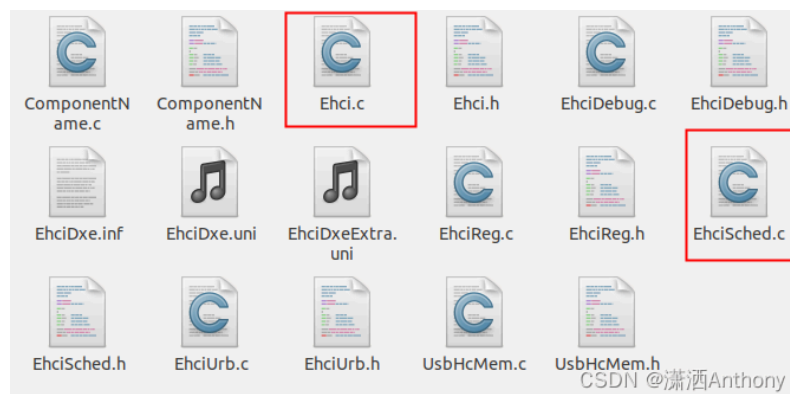
USB host controller driver (HCDI: **EFI_USB2_HC_PROTOCOL**)

USB bus driver (USBDI: **EFI_USB_IO_PROTOCOL**)

USB device drivers

Take EHCI as an example:

Let's start with the USB host controller driver. The code mainly focuses on the EhciDxe driver. What kind of driver is this? A driver that conforms to the UEFI driver model.



In Ehci.c:

```

EFI_STATUS
EFI_API
EhciDriverEntryPoint (
    IN EFI_HANDLE      ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
)
{
    return EfiLibInstallDriverBindingComponentName2 (
        ImageHandle,
        SystemTable,
        &gEhciDriverBinding,
        ImageHandle,
        &gEhciComponentName,
        &gEhciComponentName2
    );
}

```

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```

EFI_DRIVER_BINDING_PROTOCOL
gEhciDriverBinding = {
    EhciDriverBindingSupported,
    EhciDriverBindingStart,
    EhciDriverBindingStop,
    0x30,
    NULL,
    NULL
};

```

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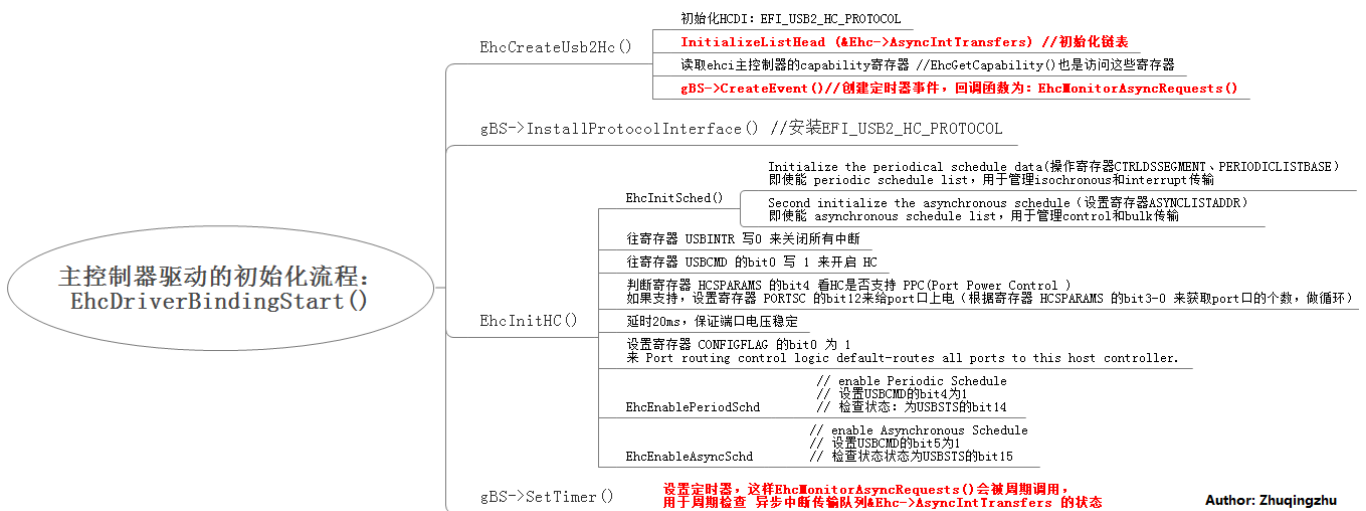
Mainly look at the following function:

```

1 | EFI_STATUS
2 | EFI_API
3 | EhciDriverBindingStart (
4 |     IN EFI_DRIVER_BINDING_PROTOCOL *This,
5 |     IN EFI_HANDLE                  Controller,
6 |     IN EFI_DEVICE_PATH_PROTOCOL    RemainingDevicePath
7 | )
8 | {

```

The function logic is as follows:



EhciDriverBindingStart starts-----Open PciIo protocol, enable USB host controller-----Open device path protocol on USB host controller----Save original PCI properties----Get Pci device class code-----Determine whether the device is UHCI or OHCI host controller. If so, find out the matching USB ehci host controller and force the ehci driver to connect to it before the UHCI or OHCI driver connects to the UHCI or OHCI host controller-----Whether the matching USB host controller is judged, if it is passed, start instantiating USB2_HC_DEV and install EFI_USB2_HC_PROTOCOL, and then the sequence in the above figure is as follows

```

1 | //
2 | // Init EFI_USB2_HC_PROTOCOL interface and private data structure
3 | //
4 | Ehc->Signature = USB2_HC_DEV_SIGNATURE;
5 |
6 | Ehc->Usb2Hc.GetCapability = EhcGetCapability;
7 | Ehc->Usb2Hc.Reset = EhcReset;
8 | Ehc->Usb2Hc.GetState = EhcGetState;

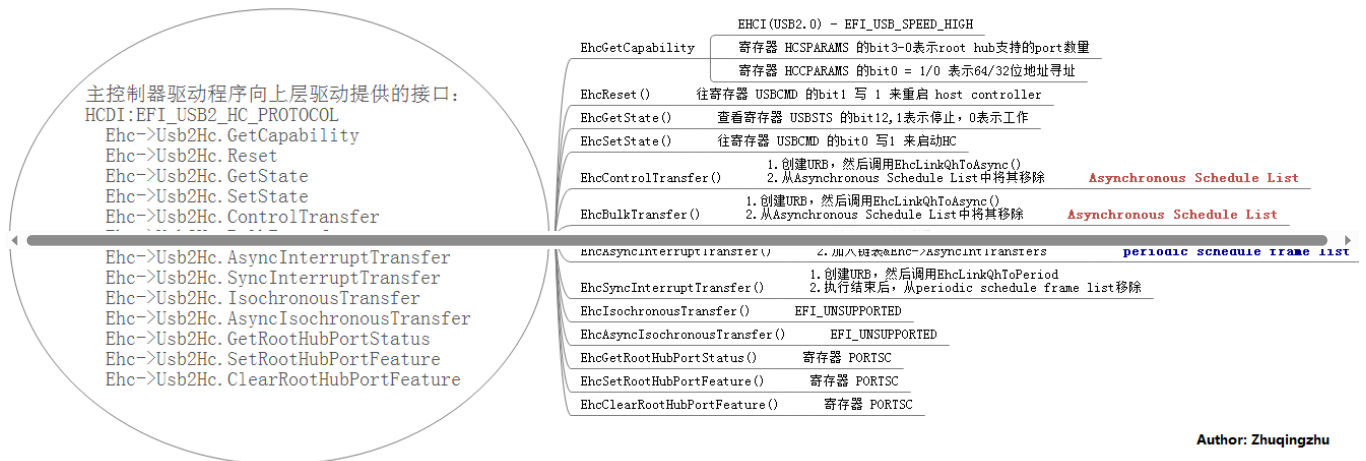
```

```

9 | Ehc->Usb2Hc.SetState = EhcSetState;10 | Ehc->Usb2Hc.ControlTransfer = EhcControlTransfer;
11 | Ehc->Usb2Hc.BulkTransfer = EhcBulkTransfer;
12 | Ehc->Usb2Hc.AsyncInterruptTransfer = EhcAsyncInterruptTransfer;
13 | Ehc->Usb2Hc.SyncInterruptTransfer = EhcSyncInterruptTransfer;
14 | Ehc->Usb2Hc.IsochronousTransfer = EhcIsochronousTransfer;
15 | Ehc->Usb2Hc.AsyncIsochronousTransfer = EhcAsyncIsochronousTransfer;
16 | Ehc->Usb2Hc.GetRootHubPortStatus = EhcGetRootHubPortStatus;
17 | Ehc->Usb2Hc.SetRootHubPortFeature = EhcSetRootHubPortFeature;
18 | Ehc->Usb2Hc.ClearRootHubPortFeature = EhcClearRootHubPortFeature;
19 | Ehc->Usb2Hc.MajorRevision = 0x2;
20 | Ehc->Usb2Hc.MinorRevision = 0x0;
21 |
22 | Ehc->PciIo = PciIo;
23 | Ehc->DevicePath = DevicePath;
24 | Ehc->OriginalPciAttributes = OriginalPciAttributes;

```

收起 ^



Author: Zhuqingzhu

The above figure only talks about the functions in Ehc.c. In fact, some of the interfaces here eventually need to call the functions in Ehcsched.c. Here we need to understand a concept: what is URB

URB: USB request block, containing information about various data

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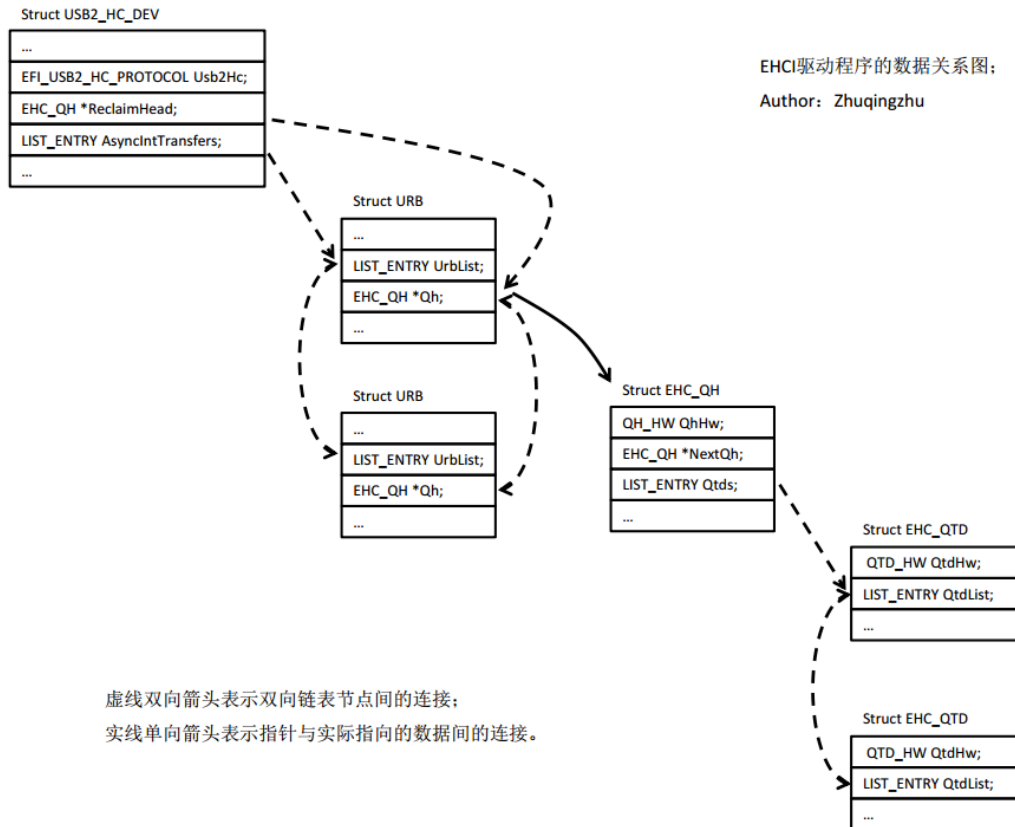
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```

1 | struct _URB {
2 |     UINT32 Signature;
3 |     LIST_ENTRY UrbList;
4 |
5 |     //
6 |     // Transaction information
7 |     //
8 |     USB_ENDPOINT Ep;
9 |     EFI_USB_DEVICE_REQUEST *Request; // Control transfer only
10 |     VOID *RequestPhy; // Address of the mapped request
11 |     VOID *RequestMap;
12 |     VOID *Data;
13 |     UINTN DataLen;
14 |     VOID *DataPhy; // Address of the mapped user data
15 |     VOID *DataMap;
16 |     EFI_ASYNC_USB_TRANSFER_CALLBACK Callback;
17 |     VOID *Context;
18 |
19 |     //
20 |     // Schedule data
21 |     //
22 |     EHC_QH *Qh;
23 |
24 |     //
25 |     // Transaction result
26 |     //
27 |     UINT32 Result;
28 |     UINTN Completed; // completed data length
29 |     UINT8 DataToggle;
30 | };

```

收起 ^



1. Struct USB2_HC_DEV is the core data structure of the Host controller, which is created during the initialization process; the data structure definitions of QTD and QH are located in EHCI spec 3.5/3.6;

2. Manage controller and bulk transfers: insert into the Asynchronous Schedule list

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```

1 //把组装好的Qh插入EHCI主控制器的Asynchronous Schedule List,以便硬件执行传输命令
2 EhcLinkQhToAsync (Ehc, Urb->Qh);
3 //阻塞式的执行此次controller传输
4 Status = EhcExecTransfer (Ehc, Urb, TimeOut);
5 //从Asynchronous Schedule List中将其移除
6 EhcUnlinkQhFromAsync (Ehc, Urb->Qh);

```

3. Manage isochronous and interrupt transmissions: insert the Periodic schedule frame list

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```

1 //把组装好的Qh插入EHCI主控制器的Periodic schedule frame list,以便硬件执行传输命令
2 EhcLinkQhToPeriod (Ehc, Urb->Qh);
3 //并把URB插入异步中断传输链表 &Ehc->AsyncIntTransfers
4 InsertHeadList (&Ehc->AsyncIntTransfers, &Urb->UrbList);

```

4. Insert the URB in the hardware linked list, and the hardware will automatically execute the send;

5. The linked list &Ehc->AsyncIntTransfers is created and managed by the driver and managed by **EhcMonitorAsyncRequests()** ;

(1) He will loop each urb on &Ehc->AsyncIntTransfers;

(2) Determine the execution result by judging QTD.status (a urb contains a QH and a string of QTDs);

(3) Update QH to prepare for the next round of asynchronous transmission;

(4) If there is a callback function, execute the callback function.

Let me emphasize: Execute the controller transfer in a blocking manner: **Status = EhcExecTransfer (Ehc, Urb, TimeOut);**

```

1 EFI_STATUS
2 EhcExecTransfer (
3     IN  USB2_HC_DEV    *Ehc,
4     IN  URB             *Urb,
5     IN  UINTN           TimeOut
6 )
7 {

```

```

8 | EFI_STATUS          Status; 9 | UINTN          Index;
10 | UINTN              Loop;
11 | BOOLEAN            Finished;
12 | BOOLEAN            InfiniteLoop;
13 |
14 | Status = EFI_SUCCESS;
15 | Loop = Timeout * EHC_1_MILLISECOND;
16 | Finished = FALSE;
17 | InfiniteLoop = FALSE;
18 |
19 | //
20 | // According to UEFI spec section 16.2.4, If Timeout is 0, then the caller
21 | // must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR
22 | // is returned.
23 | //
24 | if (Timeout == 0) {
25 |     InfiniteLoop = TRUE;
26 | }
27 |
28 | for (Index = 0; InfiniteLoop || (Index < Loop); Index++) {
29 |     Finished = EhcCheckUrbResult (Ehc, Urb);
30 |
31 |     if (Finished) {
32 |         break;
33 |     }
34 |
35 |     gBS->Stall (EHC_1_MICROSECOND);
36 | }
37 |
38 | if (!Finished) {
39 |     DEBUG ((EFI_D_ERROR, "EhcExecTransfer: transfer not finished in %dms\n", (UINT32)Timeout));
40 |     EhcDumpQh (Urb->Qh, NULL, FALSE);
41 |
42 |     Status = EFI_TIMEOUT;
43 |
44 | } else if (Urb->Result != EFI_USB_NOERROR) {
45 |     DEBUG ((EFI_D_ERROR, "EhcExecTransfer: transfer failed with %x\n", Urb->Result));
46 |     EhcDumpQh (Urb->Qh, NULL, FALSE);
47 |
48 |     Status = EFI_DEVICE_ERROR;
49 | }
50 |
51 | return Status;
52 | }

```

收起 ^

What if the device fails in this function? The phenomenon is that it will keep retrying until the maximum number of retries is reached. If the device still fails, it will be skipped directly. However, there is a problem. It usually takes several minutes to reach the maximum number of retries. This can easily create the illusion that you cannot enter the system and have to wait until the retry is completed. This situation usually occurs in industrial computers. Due to the large number of external USB devices, USB device abnormalities cannot be ruled out.

OK, let's analyze USB device in the next section.