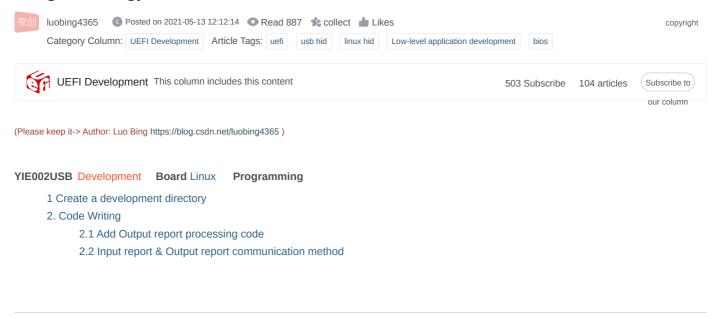
# **UEFI Development Exploration 90- YIE002USB Development Board (13 Linux Programming)**



In the previous article, we used the hidraw method of hidapi to implement a test program for the communication between the Linux host computer and the USB HID device. However, we only implemented two of the three communication methods. This article will use the libusb method of hidapi to implement all three communication methods.

## 1 Create a development directory

As in the previous article, first create a directory for development. Create a new folder hidlibusb and copy the following files into it:

```
1 libusb/hid.c
2 hidapi/hidapi.h
3 hidtest/test.c
```

Write a Makefile for the current code with the following content:

```
all: hidtest-libusb libs
  2
  3
     libs: libhidapi-libusb.so
  4
              ?= gcc
  5
     CFLAGS ?= -Wall -g -fpic
  6
     LDFLAGS ?= -Wall -g
  7
  8
    COBJS_LIBUSB = hid.o
  9
     COBJS = $(COBJS_LIBUSB) test.o
 10
     0BJS
              = $(COBJS)
 11
    LIBS_USB = `pkg-config libusb-1.0 --libs` -lrt -lpthread
 12
             = $(LIBS_USB)
 13 | INCLUDES ?= `pkg-config libusb-1.0 --cflags`
 14
 15 | # Console Test Program
 16 | hidtest-libusb: $(COBJS)
 17
         $(CC) $(LDFLAGS) $^ $(LIBS_USB) -0 $@
 18
     # Shared Libs
 19
     libhidapi-libusb.so: $(COBJS_LIBUSB)
 20
         (CC) (LDFLAGS) (LIBS_USB) - shared - fpic - Wl, - soname, $@.0 $^ - o $@
twen # Objects
twen $(COBJS): %.o: %.c
twen
         $(CC) $(CFLAGS) -c $(INCLUDES) $< -o $@
twen
 25
     clean:
 26
         rm -f $(OBJS) hidtest-libusb libhidapi-libusb.so hidtest.o
```

```
28 .PHONY: clean libs
```

### 2. Code Writing

After creating the development directory, you can modify the code.

The three communication methods of USB HID, hid\_read() & hid\_write() communication method and feature report communication method, have been implemented in the previous article. Since hid.c under libusb now provides a consistent function interface, the codes of these two methods do not need to be modified at all. We only need to add code to support input report and output report.

#### 2.1 Add Output report processing code

What is strange is that in the source file hid.c of libusb, the function hid\_get\_input\_report() for processing Input report is provided, but there is no function for processing Output report.

The code for processing the Output report is also very simple. Just modify a number in the hid\_send\_feature\_report() function. The code is as follows:

```
1
    int HID_API_EXPORT HID_API_CALL hid_set_output_report(hid_device *dev, const unsigned char *data, size_t length)
  2
  3
         int res = -1;
  4
         int skipped_report_id = 0;
  5
         int report_number = data[0];
  6
  7
         if (report_number == 0x0) {
  8
             data++;
  9
             length--;
 10
             skipped_report_id = 1;
 11
         }
 12
 13
         res = libusb_control_transfer(dev->device_handle,
             LIBUSB REQUEST TYPE CLASS|LIBUSB RECIPIENT INTERFACE|LIBUSB ENDPOINT OUT,
 14
 15
             0x09/*HID set_report*/,
             (2/*HID Output*/ << 8) | report_number,
 16
 17
             dev->interface.
 18
             (unsigned char *)data, length,
 19
             1000/*timeout millis*/);
 20
twen
         if (res < 0)
twen
             return -1;
twen
twen
         /* Account for the report ID */
 25
         if (skipped report id)
 26
             length++;
 27
 28
         return length;
 29
    }
```

## 2.2 Input report & Output report communication method

The other two communication methods have been implemented in the previous article, so there is no need to modify any code. Now we need to add the sending of Output report and receiving of Input report. The implementation code is as follows:

```
1
        memset(yie_buf,0,sizeof(yie_buf));
        yie_buf[0] = 0x00;
 2
 3
        yie_buf[1] = 0xA0;
 4
        yie_buf[2] = 0x0a;
 5
        yie buf[3] = 0x0b;
 6
        yie_buf[4] = 0x0c;
 7
 8
        res = hid_set_output_report(handle, yie_buf, 17);
 9
        if (res < 0) {
10
            printf("Unable to send a output report.\n");
11
12
        memset(yie buf,0,sizeof(yie buf));
13
        res = hid_get_input_report(handle, yie_buf, sizeof(yie_buf));
14
        if (res < 0) {
15
            printf("Unable to get a input report.\n");
```

```
printf("%ls", hid error(handle));
 17
 18
         else {
 19
             // Print out the returned buffer.
 20
             printf("Input Report\n
twen
             printf("report number:%d\n
                                          ",yie_buf[0]);
twen
             for (i = 1; i < res; i++)
twen
                 printf("%02x ", yie_buf[i]);
twen
             printf("\n");
 25
```

Start the command line and use the make command to compile and obtain the executable file hidtest-libusb.

Insert the homemade USB HID device and run hidtest-libusb. The output information is as follows:

```
1
    robin@NUC6CAYHC:~/luotest/hidapi$ sudo ./ hidtest-libusb
 2
 3
    Manufacturer String: Robin
 4
    Product String: Robin's UEFI Explorer
 5
    Serial Number String: (77) My123
 6
    Indexed String 1: Robin
 7
    Feature Report
 8
       report number:0
 9
       a0 03 0b 0c 00 00 00 00 00 00 00 00 00 00 00 00
10
    Input Report
11
       report number:0
12
       a0 02 0b 0c 00 00 00 00 00 00 00 00 00 00 00 00
    Read data, Length=16
13
14
       a0 01 0b 0c 00 00 00 00 00 00 00 00 00 00 00
```

Comparing with the previous blog on making USB HID devices, it can be seen that the three communication modes have been implemented.

So far, all the codes we planned in the introduction of the YIE002 development board have been completed, from the production of the USB HID device of the development board to the Windows software and Linux software of the host computer.

The study of UEFI related to the YIE002 development board ends here. For other embedded programming of this development board, please move to my " Embedded Development " column, which I will update from time to time.

Gitee address: https://gitee.com/luobing4365/uefi-explorer Project code is located under: /90 hidlibusb