```python
import configparser
import fcntl
from itertools import combinations
import json
import math
import os
import random
import selectors
from subprocess import Popen, PIPE, STDOUT
import time

from configmanager import validate_configs_by_filename


NUM_ROUTERS = 100


FOLDER = 'test_configs'
os.makedirs(FOLDER, exist_ok=True)


class Test:
    def __init__(self, neighbour_func, change_topology=None, topology_changes=1):
        self.make_neighbours_func = neighbour_func
        self.topology_change_func = change_topology
        self.topology_changes_remaining = topology_changes

    def make_neighbours(self, processes):
        self.make_neighbours_func(processes)

    def can_change_topology(self):
        return self.topology_change_func != None and self.
        topology_changes_remaining > 0

    def change_topology(self, processes):
        self.topology_changes_remaining -= 1
        self.topology_change_func(processes)


ports = iter(range(10000, 64000))
def make_neighbours(p1, p2):
    port1 = next(ports)
    port2 = next(ports)
    metric = random.randint(1, 15)
    p1.add_neighbour(port1, port2, metric, p2)
    p2.add_neighbour(port2, port1, metric, p1)

def fully_connected(processes):
    for p1, p2 in combinations(processes, 2):
        make_neighbours(p1, p2)

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```
51  def sparsely_connected(processes):
52      rand_processes = list(processes)
53      random.shuffle(rand_processes)
54      for p1 in processes:
55          num_neighbours = 0
56          for p2 in rand_processes:
57              if p1.routerid != p2.routerid and p2.routerid not in p1.get_neighbours ↵
                ():
58                  make_neighbours(p1, p2)
59                  num_neighbours += 1
60                  if num_neighbours >= 1:
61                      break
62
63  def change_topology(processes):
64      processes = list(processes)
65      if random.choice([False, True]):
66          to_stop = random.sample(processes, len(processes)//2)
67          print(f'stopping {len(to_stop)} processes randomly')
68          for p in to_stop:
69              p.stop()
70      else:
71          to_start = random.sample(processes, len(processes)//2)
72          print(f'starting {len(to_start)} processes randomly')
73          for p in to_start:
74              p.start()
75
76  test1 = Test(fully_connected)
77
78  test2 = Test(sparsely_connected)
79
80  test3 = Test(fully_connected, change_topology, 5)
81
82  test4 = Test(sparsely_connected, change_topology, 10)
83
84
85  class ProcessManager:
86      def __init__(self):
87          self.processes_dict = {}
88
89      def get_processes(self):
90          return self.processes_dict.values()
91
92      def get_alive_processes(self):
93          return [p for p in self.processes_dict.values() if p.alive]
94
95      def get_process(self, id):
96          return self.processes_dict[id]
97
98      def start_processes(self):
99          for p in self.get_processes():
100             p.start()
```

```
101
102     def stop_processes(self):
103         for p in self.get_processes():
104             p.stop()
105
106     def new_processes(self):
107         self.stop_processes()
108         for i in range(1, NUM_ROUTERS+1):
109             self.processes_dict[i] = Process(i)
110
111     def setup_test(self, test):
112         self.new_processes()
113         test.make_neighbours(self.get_processes())
114         self.write_configs()
115         validate_configs_by_filename([p.filename for p in self.get_processes()])
116         self.start_processes()
117
118     def change_test_topology(self, test):
119         test.change_topology(self.get_processes())
120         for p in self.get_processes():
121             p.clear_routing_table()
122
123     def write_configs(self):
124         for p in self.get_processes():
125             p.write_config()
126
127
128 class Process:
129     def __init__(self, routerid):
130         self.routerid = routerid
131         self.inputs = []
132         self.outputs = {}
133         self.filename = f'{FOLDER}/autoconfig{self.routerid}.ini'
134         self.process = None
135         self.alive = False
136
137         self.routing_table = None
138         self.routing_table_time = math.inf
139         self.have_checked_convergence = False
140         self.converged = False
141
142
143     def __str__(self):
144         return str(self.routerid)
145
146
147     def add_neighbour(self, in_port, out_port, metric, neighbour):
148         self.inputs.append(str(in_port))
149         self.outputs[neighbour.routerid] = [neighbour, out_port, metric]
150
151
```

```
152     def get_neighbours(self):
153         return self.outputs
154 
155 
156     def write_config(self):
157         config = configparser.ConfigParser()
158         config['SETTINGS'] = {
159             'router-id': str(self.routerid),
160             'input-ports': ','.join(self.inputs),
161             'outputs': ','.join(f'{port}-{metric}-{id}' for id, [_, port, metric]
                in self.outputs.items())
162         }
163         with open(self.filename, 'w') as file:
164             config.write(file)
165 
166 
167     def start(self):
168         """Start the process and make its stdout non-blocking."""
169         if not self.alive:
170             self.alive = True
171             self.process = Popen(["python", "daemon.py", self.filename,
                "--autotesting"], stdout=PIPE, stderr=STDOUT)
172             fcntl.fcntl(self.process.stdout.fileno(), fcntl.F_SETFL, os.O_NONBLOCK)
173 
174 
175     def stop(self):
176         self.alive = False
177         self.process.kill()
178 
179 
180     def get_stdout(self):
181         return self.process.stdout
182 
183 
184     def read_line(self):
185         line = self.process.stdout.readline()
186         if line:
187             line = line.decode().strip()
188             try:
189                 line = json.loads(line)
190             except json.decoder.JSONDecodeError as e:
191                 print(self, 'decode error', line)
192                 return
193             if type(line) != list:
194                 print(self, 'received non-list', line)
195                 return
196 
197             if line != self.routing_table:
198                 self.routing_table = line
199                 self.routing_table_time = time.time()
200                 self.have_checked_convergence = False
```

```
201                 self.converged = False
202
203
204     def clear_routing_table(self):
205         self.routing_table = None
206         self.routing_table_time = math.inf
207         self.have_checked_convergence = False
208         self.converged = False
209
210
211     def routing_table_entries(self):
212         return {routerid:metric for routerid, _, metric, _ in self.routing_table}
213
214
215     def check_convergence(self):
216         # an offline router is considered converged
217         if not self.alive:
218             self.converged = True
219             return
220
221         # don't check for convergence again if the routing table hasn't changed
222         if self.have_checked_convergence:
223             return
224
225         # only check if routing table hasn't changed for 10 seconds
226         if time.time() - self.routing_table_time < 10:
227             return
228
229         self.calculate_convergence()
230
231
232     def calculate_convergence(self):
233         min_costs, parents = dijkstras(self.routerid)
234         routing_table_entries = self.routing_table_entries()
235
236         self.converged = True
237         for routerid, metric in min_costs.items():
238             if metric >= 16 or routerid == self.routerid:
239                 continue
240
241             if routerid not in routing_table_entries:
242                 self.converged = False
243                 print(f'{self} not converged to router {routerid} (not in routing table, cost should be: {metric})')
244                 print('Dijkstras path:', dijsktras_path(min_costs, parents, self.routerid, routerid))
245                 print()
246                 continue
247
248             actual_metric = routing_table_entries[routerid]
249             if actual_metric != metric:
```

```
250                     self.converged = False
251                     print(f'{self} not converged to router {routerid} (current cost: {
                        actual_metric}, should be: {metric})')
252                     print('Dijkstras path:', dijsktras_path(min_costs, parents, self.
                        routerid, routerid))
253                     print('Current path:   ', end='')
254                     print_actual_path(self.routerid, routerid)
255                     print()
256
257             self.have_checked_convergence = True
258
259
260     def dijkstras(source_id):
261         dist = {}
262         prev = {}
263         queue = []
264         for p in processmanager.get_alive_processes():
265             id = p.routerid
266             dist[id] = math.inf
267             prev[id] = None
268             queue.append(id)
269         assert source_id in dist
270         dist[source_id] = 0
271
272         while queue:
273             u = None
274             min_dist = math.inf
275             for v in queue:
276                if dist[v] <= min_dist:
277                     u = v
278                     min_dist = dist[v]
279             queue.remove(u)
280
281             u_neighbours = processmanager.get_process(u).get_neighbours()
282             for v, [process, _, metric] in u_neighbours.items():
283                 if v not in queue:
284                     continue
285
286                 cost = dist[u] + metric
287                 if cost <= dist[v]:
288                     dist[v] = cost
289                     prev[v] = u
290
291         return dist, prev
292
293
294     def dijsktras_path(dist, prev, src, dest):
295         current = dest
296         path = f'{current} ({dist[current]})'
297         while current != src:
298             current = prev[current]
```

```
299             path = f'{current} ({dist[current]}) --> ' + path
300         return path
301 
302 
303     def print_actual_path(src, dest, depth=0):
304         if depth > 15:
305             print('ABORTING')
306             return
307         if src == dest:
308             print(f'{src} (0)')
309             return
310 
311         src_routing_table = processmanager.get_process(src).routing_table
312         if src_routing_table == None:
313             print(f'{src} (no route to {dest})')
314             return
315         for routerid, nexthop, metric, _ in src_routing_table:
316             if routerid == dest:
317                 break
318         print(f'{src} ({metric}) --> ', end='')
319         print_actual_path(nexthop, dest, depth+1)
320 
321 
322     processmanager = ProcessManager()
323 
324     def main():
325         tests = [test1, test2, test3, test4]
326         for i in range(len(tests)):
327             test = tests[i]
328             processmanager.setup_test(test)
329             print(f'test {i} starting')
330             run_to_convergence()
331             while test.can_change_topology():
332                 print(f'test {i} changing topology')
333                 processmanager.change_test_topology(test)
334                 run_to_convergence()
335             print(f'test {i} finished')
336 
337 
338     def run_to_convergence():
339         selector = selectors.DefaultSelector()
340         for p in processmanager.get_processes():
341             selector.register(p.get_stdout(), selectors.EVENT_READ, p)
342 
343         prev_not_converged = []
344         while True:
345             events = selector.select(timeout=1)
346             for key, _ in events:
347                 p = key.data
348                 p.read_line()
349 
```

```
350             all_converged = True
351             not_converged = []
352             for p in processmanager.get_processes():
353                 p.check_convergence()
354                 if not p.converged:
355                     all_converged = False
356                     not_converged.append(p.routerid)
357 
358             if all_converged:
359                 print('all routers converged correctly')
360                 return
361             elif not_converged != prev_not_converged:
362                 prev_not_converged = not_converged
363                 print(len(not_converged), 'routers not converged.', not_converged[:10])
364 
365 
366     try:
367         main()
368     except KeyboardInterrupt:
369         pass
370     finally:
371         processmanager.stop_processes()
372     print('exiting')
373 
```