

Homework1

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1. Geometry of linear equations:

- (1) Describe the intersection of the three "planes" $u+v+w+z=8$, $u+w+z=6$ and $u+w=1$, all in 4-dimensional space. Is it a 0-D point, a 1-D line or a 2-D plane? What is the intersection if the fourth "plane" $u=2$ is included?
- (2) For the plane $ax+by+cz=1$ in a 3-D space, what vector is perpendicular to this plane and why?
- (3) For the equations $x+y=4$, $2x-2y=4$, draw the row picture (two intersection lines) and the column picture (combination of two columns equal to the column vector $[4,4]^T$).

2. Gaussian elimination

- (1) Find the pivots and solve the system:

$$2u - v = 0$$

$$-u + 2v - w = 0$$

$$-v + 2w - z = 0$$

$$-w + 2z = 5$$

- (2) Consider the system

$$x + ay = 4$$

$$ax + 9y = b$$

- (a) For which values of a does the system have a unique solution?
- (b) Find those pairs of values (a,b) for which the system has more than one solution.

3. Matrix multiplication

(1) $\underline{A} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$ (2) $\underline{B} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ (3) $\underline{C} = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$

Find the powers $\underline{A}^2, \underline{A}^3, \dots, \underline{B}^2, \underline{B}^3, \dots, \underline{C}^2, \underline{C}^3, \dots$

(2) $\underline{A}(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ Verify that $\underline{A}(\theta_1) \underline{A}(\theta_2) = \underline{A}(\theta_1 + \theta_2)$

- (3) More general than multiplication by columns is block multiplication. If matrices are separated into blocks (submatrices) and their shapes make block multiplication possible, then it is allowed.

$$\underline{A} \underline{B} = \begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} \begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix}$$

- (a) Replace those X's by numbers (1~9 different values in each matrix) and confirm that block multiplication works.
- (b) Give two more examples (with X's) if \underline{A} is 3 by 4 and \underline{B} is 4 by 2.

4. Matrices in triangular and echelon form

- (1) Factor $\underline{A} = \underline{LU}$

(a) $\underline{A} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 4 & 4 \\ 1 & 4 & 8 \end{bmatrix}$ (b) $\underline{A} = \begin{bmatrix} 2 & 3 & 3 \\ 0 & 5 & 7 \\ 6 & 9 & 8 \end{bmatrix}$

- (2) Solve $\underline{LUx} = \underline{b}$ without multiplying \underline{LU}

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix}$$

- (3) Find $\underline{PA} = \underline{LDU}$ for

(a) $\underline{A} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$ (b) $\underline{A} = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \end{bmatrix}$

(a) $\underline{A} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 2 & 3 & 4 \end{bmatrix}$ (b) $\underline{A} = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 1 & 1 \end{bmatrix}$

5. Inverses and transposes

(1) Use the Gauss-Jordan method to invert

(a) $\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$ (c) $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

(2) Show that for any square matrix \mathbf{B} , $\mathbf{A} = \mathbf{B} + \mathbf{B}^T$ is always symmetric, and $\mathbf{K} = \mathbf{B} - \mathbf{B}^T$ is always skew-symmetric ($\mathbf{K}^T = -\mathbf{K}$).

Find these matrices when $\underline{B} = \begin{bmatrix} 1 & 3 \\ 1 & 1 \end{bmatrix}$ and write \mathbf{B} as the sum of a symmetric matrix and a skew symmetric matrix.

(3) Compute \mathbf{LDL}^T of $\begin{bmatrix} 1 & 3 & 5 \\ 3 & 12 & 18 \\ 5 & 18 & 30 \end{bmatrix}$

6. Find the general solution of the following $\mathbf{Ax} = \mathbf{b}$ by finding \mathbf{x}_n and \mathbf{x}_p .

(1) $\begin{bmatrix} 1 & 2 & 2 \\ 2 & 4 & 5 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$ (2) $\begin{bmatrix} 1 & -2 & 3 & 1 \\ 1 & 1 & 4 & -1 \\ 2 & 5 & 9 & -2 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 8 \end{bmatrix}$

7. Find the dimensions and the bases for the four subspaces associated with \mathbf{A}

(1) $\underline{A} = \begin{bmatrix} 1 & 3 & -2 & 5 & 4 \\ 1 & 4 & 1 & 3 & 5 \\ 1 & 4 & 2 & 4 & 3 \\ 2 & 7 & -3 & 6 & 13 \end{bmatrix}$ (2) $\underline{A} = \begin{bmatrix} 1 & 1 & 2 \\ 4 & 5 & 5 \\ 5 & 8 & 1 \\ -1 & -2 & 2 \end{bmatrix}$ (3) $\underline{A} = \begin{bmatrix} 1 & 2 & -3 & -2 \\ 1 & 3 & -2 & 0 \\ 3 & 8 & -7 & -2 \\ 2 & 1 & -9 & -10 \end{bmatrix}$