

## 2A - L1 images as functions

1. [2017/11/02 15:21](#)

2. Sum

- a. one image is a function
- b. manipulation of the image through the matrix
  - i. add, multiply, subtract, blend, crop
- c. display the image
  - i. imshow, plot
- d. Octave/matlab functions
  - i. imread, imshow, hist,
- e. noise
  - i. Gaussian noise
  - ii. sigma

3. Images as Functions - mathematical view

- a. One image can be regarded as a function.  $I(x, y)$ , the value of the light intensity
  - i. can be shown in matlab
  - ii. function - grey scaled
    - 1. mapping:  $R \times R \rightarrow R$
    - 2.  $f: [a, b] \times [c, d] \rightarrow [\min, \max]$
    - 3. each  $(x, y)$  corresponding to a value  $i$

### Images as functions

We think of an image as a *function*,  $f$  or  $I$ , from  $R^2$  to  $R$ :

$f(x, y)$  gives the intensity or value at position  $(x, y)$

Practically define the image over a rectangle, with a finite range:

$$f: [a, b] \times [c, d] \rightarrow [\min, \max]$$

b. function - colored

- i. mapping:  $R \times R \rightarrow R \times R \times R$
- ii.  $f: [a, b] \times [c, d] \rightarrow [\min, \max] \times [\min, \max] \times [\min, \max]$
- iii. each  $(x, y)$  corresponding to a vector  $(r, g, b)$
- iv. each channel can be taken out alone as a r/g/b plane

to be processed

A color image is just three functions “stacked” together. We can write this as a “vector-valued” function:

$$f(x, y) = \begin{bmatrix} r(x, y) \\ g(x, y) \\ b(x, y) \end{bmatrix}$$

c. #we do in grey scale images, it’s easier cuz it only has one channel

i.

#### 1. Digital Images

a. It’s the discrete-valued image. so we require two discretions:  
Sample and Quantize

i. **ATT: when computing, regard the value as floating point**

ii. **# pixel : an image element**

In computer vision we typically operate on digital (discrete) images:

*Sample* the 2D space on a regular grid

*Quantize* each sample (round to “nearest integer”)

b. Image thus represented as a **matrix** of integer values.

i. matlab typically with interger values

ii. index

1. x, y used in math, x is along the column,  
y is along the row

2. i, j used in computation, i is along the  
row, j is along the column

iii. 1 D signals are just represented as vectors

#### 1. Quiz: Compute Image Size Quiz

a. image size = #row x #column x #channel #value size

#### 2. Matlab Images are Matrices

a. Matlab Images are Matrices, (r, c, rgb), so that you can  
manipulate them as matrices.

#### 3. Load and Display an Image

a. `imread('xx.xxx')`

#### 4. Quiz: Image Size and Data Type Quiz

- a. size
  - i. size()
- b. class type
  - i. e.g. uint8
    1. u: unsigned means only non-negative value
    2. int: integer
    3. 8: 8 bits, 1 byte
    - 4.
5. Inspect Image Values
  - a. as to access matrix
    - i. but to show a row/column, better to use `plot(img(1,:))`
6. Crop an Image
  - a. to take a big part of the image
  - b. for index, both the start and end row/column are included
7. Color Planes
  - a. in images, bright area represents higher values, while dark area represents lower values.
8. Add 2 Images Demo
  - a. `img [0, 255]`, when the value exceeds, round to 255;
  - b. Octave rounds the value to the nearest integer for uint8,  $1.5 \Rightarrow 2$
  - c. add
  - d. average:  $/2 \Rightarrow +$ ; not  $+ \Rightarrow /2$
9. Multiply by a Scalar Demo
10. Quiz: Blend 2 Images
  - a. Rule: keep the sum of the weights equal to 1; the bigger the weight, the more the effect of this image.
11. [Common Types of Noise](#)
  - a.  $\eta(x, y)$
  - b. salt and pepper noise: random occurrences of black and white pixels
  - c. Impulse noise: random occurrences of white pixels
  - d. Gaussian noise -- most common
    - i. variations in intensity drawn from a Gaussian normal distribution
    - ii. `rand(size(img)) .* sigma`

## 1. zero mean, sigma standard deviation

iii. `imgnew = img + noise`

### 12. Image Difference Demo

- a. directly subtract may lose some values, since `uint8` is `[0,255]`;
- b. so use `imabsdiff(a,b)` – order doesn't matter

### 13. Generate Gaussian Noise

#### a. e.g.

i. `noise = randn(1,10000);`

ii. `noise2 = noise .* 2;`

iii. `std(noise)`

iv. % `noise2` has doubled standard deviation of `noise`

v. because the GD represents the distribution the number of values in certain bin rather than the values themselves.

- b. when add the noise to certain signal, what should be the concern is the noise magnitude compared to image magnitude. that's the effect of the sigma

### 14. Displaying Images in Matlab

#### a. determine how to show the image

i. `imshow(im)`

#### 1. original range

ii. `imshow(im, [low, high])`

1. rescaled, low represents the darkest black, high represents the whitest white

iii. `imshow(im, [])`

1. rescaled, low is the min, high is the max in the original image

#### b. ATT

- i. only the display may require rescale, never the computation

### 15.