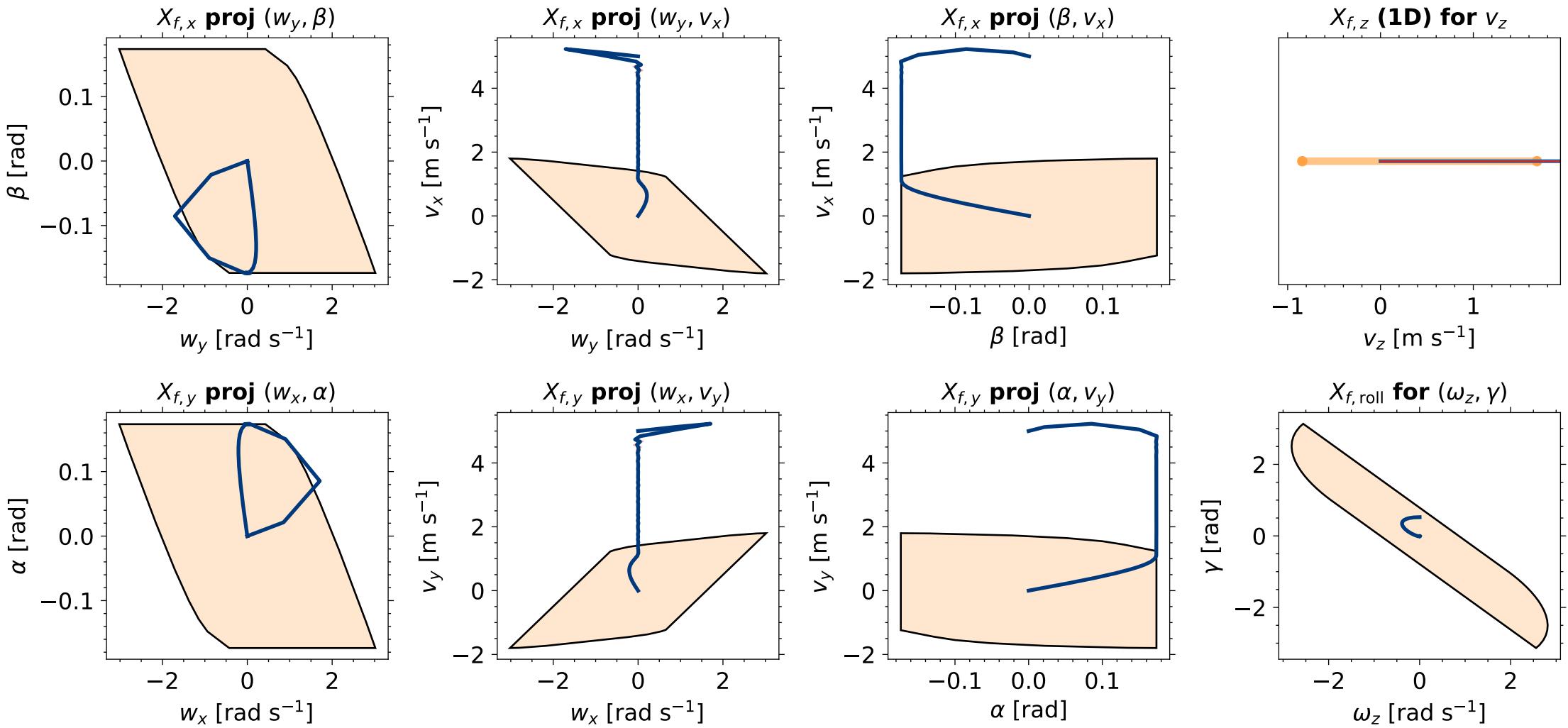


# Terminal invariant sets $X_f$ with closed-loop trajectory and MPC predictions



— closed-loop