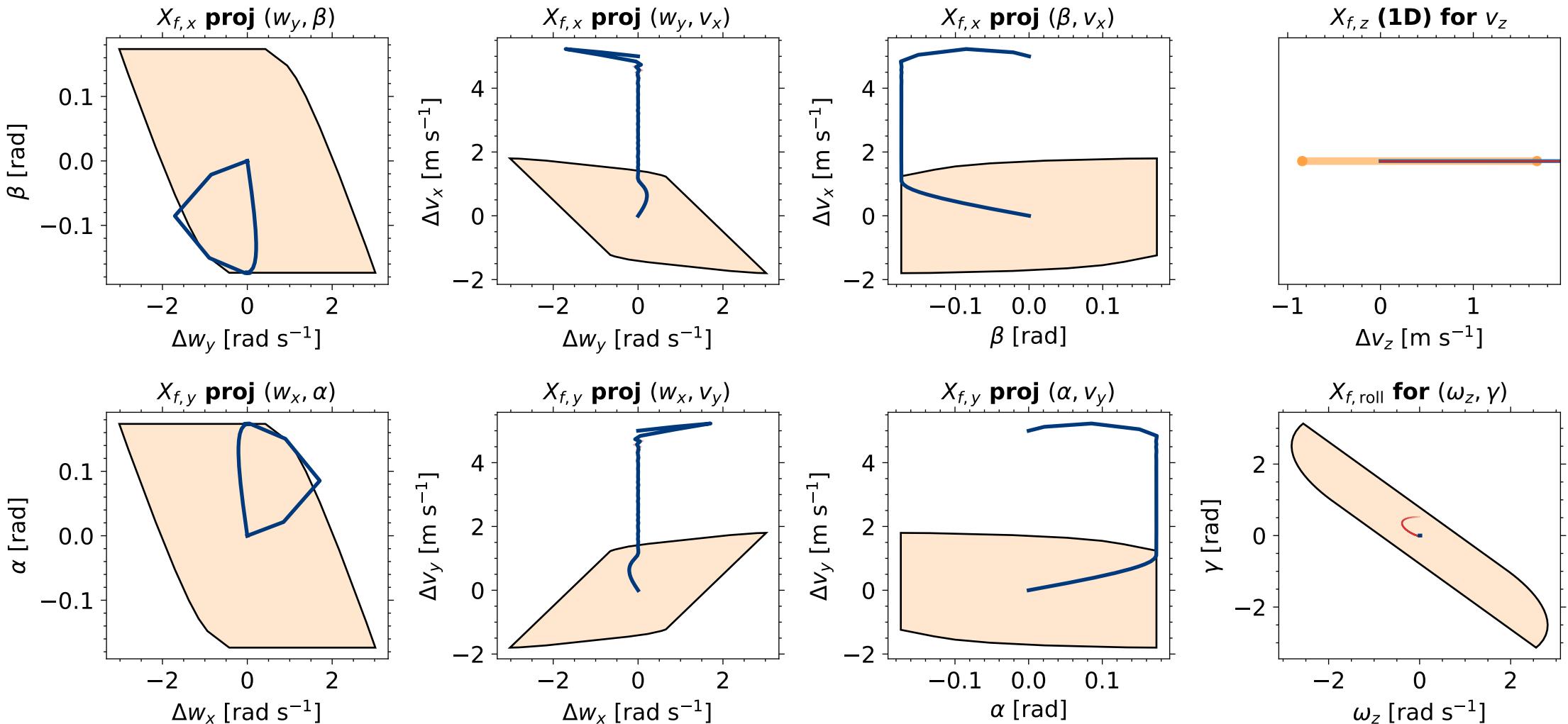


Terminal invariant sets X_f with closed-loop trajectory and MPC predictions



— open-loop predictions — closed-loop