

# Bandits

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Seminar Online Learning

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# Outline

1 Introduction

2 Online Mirror Descent with Estimated Gradient

3 Regret Bound for Bandit Algorithm

4 Code Simulation

5 Summary

6 References

# Multi-armed Bandit Problem

<b>Round</b>	<b>Arm 1</b>	<b>Arm 2</b>	<b>Arm 3</b>
<b>1</b>	0.5	0.3	0.2
<b>2</b>	0.9	0.3	0.5
<b>3</b>	0.8	0.1	0.6
<b>4</b>	0.4	0.7	0.3
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**How can we choose an arm to minimize our cumulative cost?**

# Multi-armed Bandit Problem

$d$ : number of arms

$T$ : number of rounds played

$t$ : current round

$p_t$ : arm chosen

$\mathbf{w}_t \in S$ : weights

$$S = \{\mathbf{w} : \|\mathbf{w}\|_1 = 1 \wedge \mathbf{w} \geq 0\}$$

$$\mathbb{P}[p_t = i] = w_t[i]$$

$\mathbf{y}_t \in [0, 1]^d$ : cost vector

$f_t(\mathbf{w}) = \langle \mathbf{w}, \mathbf{y}_t \rangle$ : loss function

$$\nabla f_t(\mathbf{w}) = \mathbf{y}_t$$

## Regret

$$\underbrace{\mathbb{E} \left[ \sum_{t=1}^T y_t[p_t] \right]}_{\text{cumulative cost of the algorithm}} - \underbrace{\min_i \sum_{t=1}^T y_t[i]}_{\text{cumulative cost of the best arm in hindsight}}$$

The expected value is taken with respect to the randomness in choosing an arm.

# Estimating the Gradient

Since only one arm is picked, just  $y_t[p_t]$  is known.

## Unbiased gradient estimate

$\mathbf{z}_t$  is an unbiased estimate of  $\mathbf{y}_t$  and defined as

$$z_t[j] = \begin{cases} \frac{y_t[j]}{w_t[j]} & \text{if } j = p_t, \\ 0 & \text{else.} \end{cases}$$

$$\mathbb{E}[z_t[j] | \mathbf{z}_{t-1}, \dots, \mathbf{z}_1] = \sum_{i=1}^d \mathbb{P}[p_t = i] z_t^{(i)}[j] = w_t[j] \frac{y_t[j]}{w_t[j]} = y_t[j]$$

# Sub-gradient definition

- Since  $\mathbf{y}_t$  is the gradient of  $f_t$  at  $\mathbf{w}_t$ , it is also the sub-gradient at that point.
- This can be written as  $\mathbb{E}[\mathbf{z}_t] = \mathbf{y}_t \in \partial f_t(\mathbf{w}_t)$ .

## Sub-gradient

Let  $f$  be a convex function.

$\mathbf{y}$  is a sub-gradient of  $f$  at  $\mathbf{w}$  if it satisfies the inequality

$$f(\mathbf{u}) \geq f(\mathbf{w}) + \langle \mathbf{u} - \mathbf{w}, \mathbf{y} \rangle$$

# Stochastic Bandits

- We assume a fixed iid distribution of costs for every arm.
- This assumption can be difficult to verify.
- Goal: Learning the arm with the lowest cost.
- Applications:
  - A/B testing
  - Choosing ads for consumers

# Adversarial Bandits

- Costs are chosen by an adversary, which may be oblivious or adaptive.
- Oblivious adversary: The adversary chooses all the costs before the first round.
- Adaptive adversary: The adversary chooses the cost before each round. The adversary can adapt to our prior decisions.
- Randomization in choosing an arm is essential when dealing with an adaptive adversary.
- Goal: Perform well even in worst-case scenarios.
- Applications:
  - Auction bidding
  - Spam detection / Cybersecurity

# Learning with Expert Advice

- We randomly choose one out of  $d$  experts every round. Every expert receives a cost, but we get to see every experts cost.
- Since we have full information in every round, learning is faster.
- Costs could be generated by a fixed iid distribution or chosen by an adversary, just like with bandits.
- Applications:
  - Portfolio selection
  - weather forecasting

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- 1 Introduction
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# Online Mirror Descent with Estimated Gradient

## Algorithm for OMD with estimated Gradient

**parameter:** a link function  $g : \mathbb{R}^d \rightarrow S$

**initialize:**  $\theta_1 = 0$

**for**  $t = 1, 2, \dots$

    predict  $\mathbf{w}_t = g(\theta_t)$

    pick  $\mathbf{z}_t$  at random such that  $\mathbb{E}[\mathbf{z}_t | \mathbf{z}_{t-1}, \dots, \mathbf{z}_1] \in \partial f_t(\mathbf{w}_t)$

    update  $\theta_{t+1} = \theta_t - \mathbf{z}_t$

$g$  links / mirrors the primal space  $S$ , where  $\mathbf{w}$  lives and the dual space  $\mathbb{R}^d$ , where  $\theta$  lives.

# OMD Bound

## Theorem 1

If the subgradient is chosen such that with Probability 1 we have

$$\sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \mathbf{z}_t \rangle \leq B(\mathbf{u}) + \sum_{t=1}^T \|\mathbf{z}_t\|_t^2$$

$B$  is some function and  $\|\cdot\|_t$  depends on  $\mathbf{w}_t$ . From this follows

$$\mathbb{E} \left[ \sum_{t=1}^T (f_t(\mathbf{w}_t) - f_t(\mathbf{u})) \right] \leq \mathbb{E} \left[ \sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \mathbf{z}_t \rangle \right] \leq B(\mathbf{u}) + \sum_{t=1}^T \mathbb{E}[\|\mathbf{z}_t\|_t^2]$$

The expected value is being taken with respect to the randomness of the learner in choosing the gradient  $\mathbf{z}_1, \dots, \mathbf{z}_T$ .

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# Normalized Exponentiated Gradient Result

Consider the OMD with estimated Gradient Algorithm. If we choose  $S = \{\mathbf{w} : \|\mathbf{w}\|_1 = 1 \wedge \mathbf{w} \geq 0\}$  and  $g$ , such that the  $i$ -th element of  $g$  is

$$g_i(\boldsymbol{\theta}) = \frac{\exp(\eta\theta[i])}{\sum_j \exp(\eta\theta[j])},$$

we get the Normalized Exponentiated Gradient Algorithm.

For this Algorithm we have the following Result:

## Theorem 2

For a sequence of linear loss functions such that for all  $t, i$  we have  $\eta z_t[i] \geq -1$ , then

$$\sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \mathbf{z}_t \rangle \leq \frac{\log(d)}{\eta} + \eta \sum_{t=1}^T \sum_i w_t[i] z_t[i]^2$$

# Bandit Algorithm

## Bandit Exponentiated Gradient Algorithm

**parameters:**  $\eta \in (0, 1)$

**initialize:**  $\mathbf{w}_1 = (\frac{1}{d}, \dots, \frac{1}{d})$

**for**  $t = 1, 2, \dots$

choose  $p_t \sim \mathbf{w}_t$

receive  $y_t[p_t] \in [0, 1]$

**update**

$$\tilde{w}[p_t] = w_t[p_t] \exp\left(\frac{-\eta y_t[p_t]}{w_t[p_t]}\right)$$

$$\text{for } i \neq p_t, \tilde{w}[i] = w_t[i]$$

$$\forall i, w_{t+1} = \frac{\tilde{w}[i]}{\sum_j \tilde{w}[j]}$$

# Bandit Regret Bound Proof

*Proof of a Regret Bound for the Bandit Algorithm:*

Combining Theorem 1 and Theorem 2 and taking the expected value, we have

$$\begin{aligned}\mathbb{E} \left[ \sum_{t=1}^T (f_t(\mathbf{w}_t) - f_t(\mathbf{u})) \right] &\leq \mathbb{E} \left[ \sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \mathbf{z}_t \rangle \right] \\ &\leq \frac{\log(d)}{\eta} + \eta \sum_{t=1}^T \mathbb{E} \left[ \sum_i w_t[i] z_t[i]^2 \right].\end{aligned}$$

# Bandit Regret Bound Proof

$$\mathbb{E} \left[ \sum_{t=1}^T (f_t(\mathbf{w}_t) - f_t(\mathbf{u})) \right] \leq \frac{\log(d)}{\eta} + \eta \sum_{t=1}^T \mathbb{E} \left[ \sum_i w_t[i] z_t[i]^2 \right]$$

We can bound the expected value in the last term.

$$\begin{aligned} \mathbb{E} \left[ \sum_i w_t[i] z_t^{(p_t)}[i]^2 | \mathbf{z}_{t-1}, \dots, \mathbf{z}_1 \right] &= \sum_j \mathbb{P}[p_t = j] \sum_i w_t[i] z_t^{(j)}[i]^2 \\ &= \sum_j w_t[j] w_t[j] \frac{y_t[j]^2}{w_t[j]^2} \\ &= \sum_j \underbrace{y_t[j]^2}_{\leq 1, \text{ since } \mathbf{y} \in [0,1]^d} \\ &\leq d \end{aligned}$$

# Bandit Regret Bound Proof

$$\mathbb{E} \left[ \sum_{t=1}^T (f_t(\mathbf{w}_t) - f_t(\mathbf{u})) \right] \leq \frac{\log(d)}{\eta} + \eta T d$$

Let  $\mathbf{u}$  be the decision to always pull the best arm in hindsight.

$$\begin{aligned} \sum_{t=1}^T \underbrace{\mathbb{E}[f_t(\mathbf{w}_t)]}_{=\mathbb{E}[y_t[p_t]]} - \sum_{t=1}^T \underbrace{f_t(\mathbf{u})}_{=\min_i y_t[i]} &= \sum_{t=1}^T \mathbb{E}[y_t[p_t]] - \min_i \sum_{t=1}^T y_t[i] \\ &= \underbrace{\mathbb{E} \left[ \sum_{t=1}^T y_t[p_t] \right] - \min_i \sum_{t=1}^T y_t[i]}_{= \text{Regret}} \end{aligned}$$

# Bandit Regret Bound

## Regret Bound

$$\mathbb{E} \left[ \sum_{t=1}^T y_t[p_t] \right] - \min_i \sum_{t=1}^T y_t[i] \leq \frac{\log(d)}{\eta} + \eta T d$$

- Can be used to find optimal  $\eta^* = \sqrt{\frac{\log(d)}{dT}}$ .
- Plugging in  $\eta^*$  gives us sublinear regret, with  $\text{Regret}_T = O(\sqrt{d \log(d) T})$ .

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# Code Simulation

- We generate data, with  $T = 500$ ,  $d = 3$  and a fixed distribution for the costs of every arm. The costs are bounded, so  $\mathbf{y}_t \in [0, 1]^d$ .

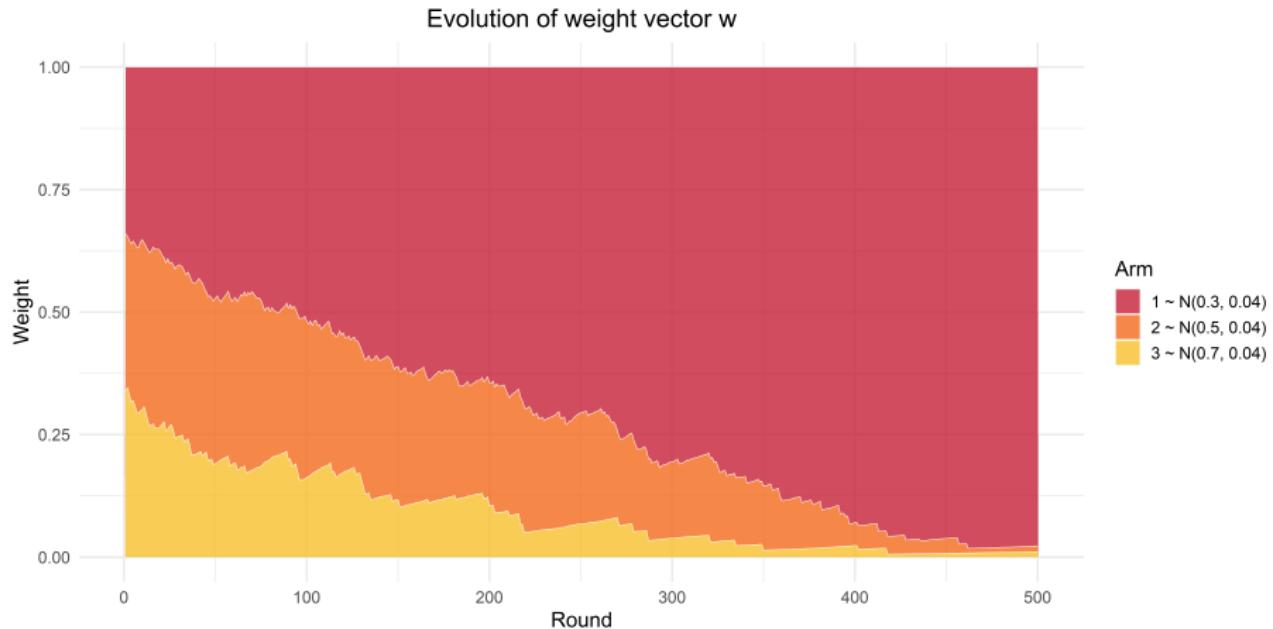
Arm 1  $\sim N(0.3, 0.04)$ , Arm 2  $\sim N(0.5, 0.04)$ , Arm 3  $\sim N(0.7, 0.04)$

- But we make no assumptions about how the costs were generated.
- To minimize regret we use the bound and choose an optimal  $\eta$ .

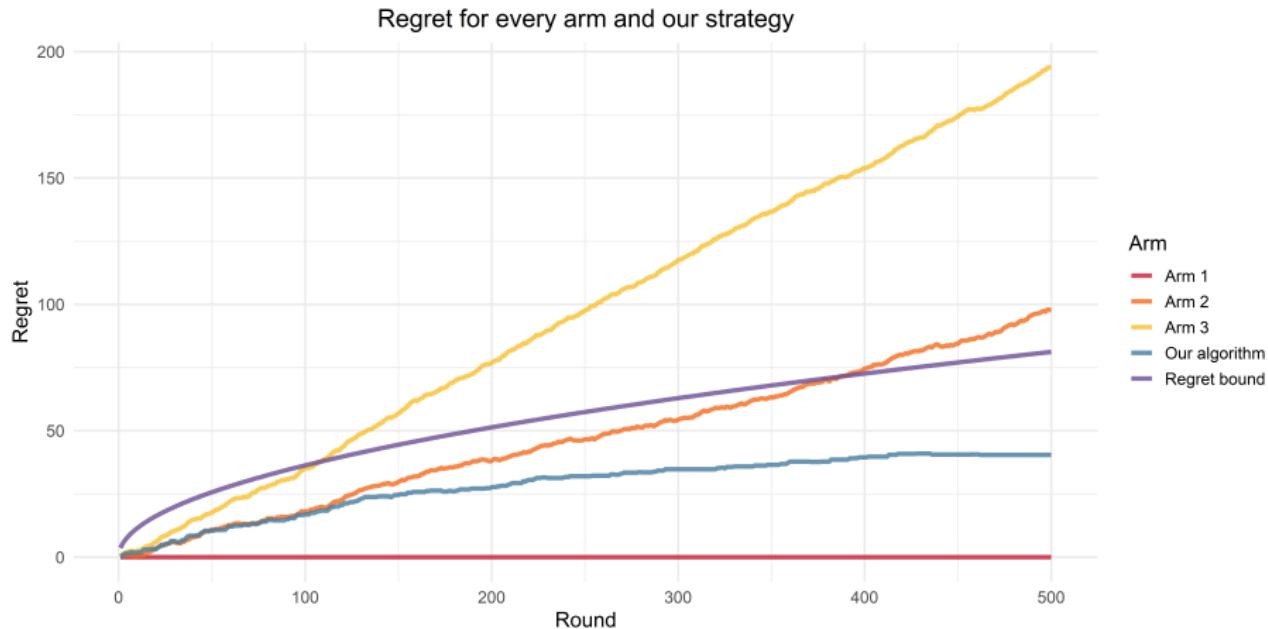
$$\arg \min_{\eta} \frac{\log(d)}{\eta} + \eta T d \approx 0.0271$$

- We will look at how  $w_t$  changes and how our observed regret compares to the regret if we only pulled one arm.

# Evolution of $w_t$



# Regret Comparison



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# Summary

- Goal: Optimizing sequential decision making under uncertainty.
- We can make assumptions about how the costs are generated (Stochastic, Adversarial Bandits).
- Regret is the central performance measure, where we compare the cumulative cost of our algorithm to the best possible fixed decision in hindsight.
- Through randomization in picking an arm we can achieve sublinear regret even if the costs are chosen by an adversary.

$$\lim_{T \rightarrow \infty} \frac{\text{Regret}_T}{T} = 0$$

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- [2] Tor Lattimore and Csaba Szepesvári, *Bandit Algorithms*, July 2020
- [3] Francesco Orabona, *A Modern Introduction to Online Learning*, May, 2025