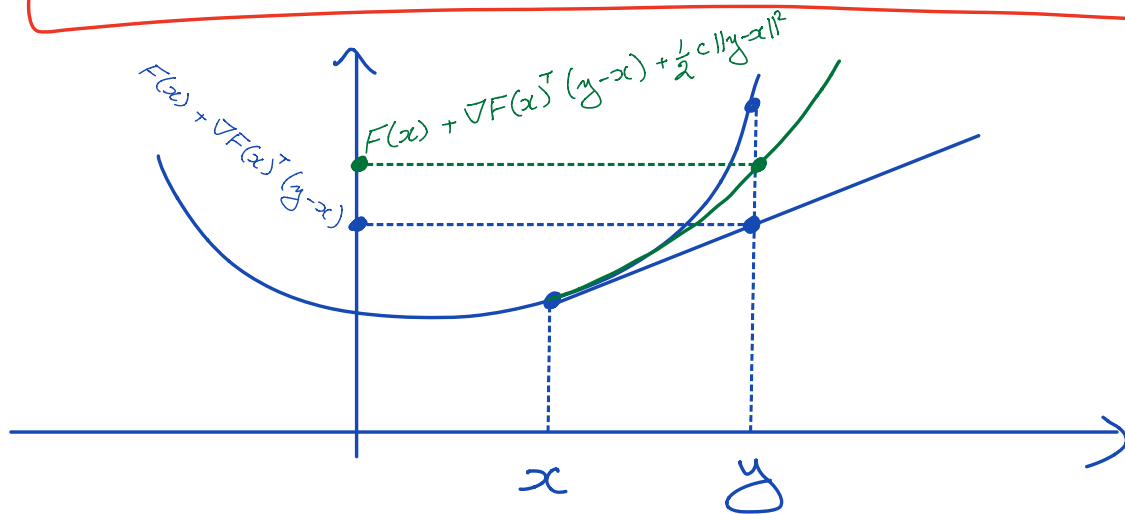


"Review" & Insights into GD and other 1st order methods

One more definition : Strong convexity

A function F is strongly convex if $\exists c > 0$ such that $\forall x, y \in \mathbb{R}^d$

$$F(y) \geq F(x) + \nabla F(x)^T (y-x) + \frac{1}{2} c \|y-x\|^2$$



and it also guarantees

$$(F(x) - F(x^*)) \leq \frac{\|\nabla F(x)\|^2}{2c}$$

\uparrow optimum

→ This is a fact. You'll prove it in HW

Want to minimize $F: \mathbb{R}^d \rightarrow \mathbb{R}$

Gradient Descent

$$x^{(t+1)} = x^{(t)} - \alpha_t \nabla F(x^{(t)})$$

A simple analysis of GD: Assume to start that
 $\|\nabla^2 F\| \leq L$

$$\begin{aligned} F(x^{(t+1)}) &= F(x^{(t)} - \alpha_t \nabla F(x^{(t)})) \\ &= F(x^{(t)}) - \underbrace{h^T \nabla F(x^{(t)})}_h + \frac{1}{2} \underbrace{h^T \nabla^2 F(\xi) h} \end{aligned}$$

Taylor's theorem

$$\begin{aligned} &= \langle h, \nabla^2 F(\xi) h \rangle \\ &\stackrel{\text{Cauchy}}{\leq} \|h\| \|\nabla^2 F(\xi) h\| \\ &\stackrel{\|Ax\| \leq \|A\| \|x\|}{\leq} \|h\|^2 \|\nabla^2 F(\xi)\| \\ &\leq L \|h\|^2 \end{aligned}$$

$$\begin{aligned} &\leq F(x^{(t)}) - \alpha_t \|\nabla F(x^{(t)})\|^2 + \frac{L \alpha_t^2}{2} \|\nabla F(x^{(t)})\|^2 \\ &\stackrel{\|\nabla^2 F\| \leq L}{\leq} \end{aligned}$$

$$\Rightarrow F(x^{(t+1)}) \leq F(x^{(t)}) - d_t \underbrace{\left(1 - \frac{L d_t}{2}\right)}_{\text{pick } d < \frac{1}{L}} \|\nabla F(x^{(t)})\|^2$$

$$\Rightarrow \boxed{F(x^{(t+1)}) \leq F(x^{(t)}) - \frac{\alpha}{2} \|\nabla F(x^{(t)})\|^2}$$

(1) (assumed only $\|\nabla^2 F\| \leq L$
 $\alpha < \frac{1}{L}$)

From here, two possibilities:

(A) Can't / Don't assume strong convexity.
 Then, rearranging (1) & taking a telescoping sum.

$$\frac{\alpha}{2} \sum_{t=0}^{T-1} \|\nabla F(x^{(t)})\|^2 \leq \sum_{t=0}^{T-1} [F(x^{(t)}) - F(x^{(t+1)})]$$

$$= F(x^{(0)}) - F(x^{(T)})$$

Telescoping \nearrow

$$\leq F(x^{(0)}) - \underbrace{F(x^*)}_{\text{constant}}$$

Thus as $T \rightarrow \infty \quad \|\nabla F(x^{(T)})\|^2 \rightarrow 0$

(Otherwise the LHS can't be smaller than the RHS as $T \rightarrow \infty$)

$$\text{Moreover } \frac{1}{T} \sum_{t=0}^{T-1} \|\nabla F(x^{(t)})\|^2 \leq \frac{2}{\alpha T} [F(x^{(0)}) - F(x^*)].$$

Averaging $\|\nabla F\|^2 \rightarrow 0$ so we "find" the minimizer.

(B) Can assume that F is strongly convex.

Recall: strong convexity with constant c
 $\Rightarrow F(x+h) \geq F(x) + h^T \nabla F(x) + \frac{c}{2} \|h\|^2$

& strong convexity also gives us:

$$\textcircled{2} \quad \|\nabla F(z)\|^2 \geq 2c [F(z) - F(x^*)]$$

(HW)

Recall ①

$$F(x^{(t+1)}) \leq F(x^{(t)}) - \frac{\alpha}{2} \|\nabla F(x^{(t)})\|^2$$

$$\begin{aligned} \Rightarrow F(x^{(t+1)}) - F(x^*) &\leq F(x^{(t)}) - F(x^*) \\ &\quad - \frac{\alpha}{2} \|\nabla F(x^{(t)})\|^2 \\ &\leq F(x^{(t)}) - F(x^*) - \frac{\alpha}{2} \cdot 2c \cdot [F(x^{(t)}) - F(x^*)] \end{aligned}$$

by (2) \rightarrow

$$\leq \left(1 - \frac{c}{L}\right) [F(x^{(t)}) - F(x^*)]$$

\uparrow pick $d = \frac{1}{L}$

$$\leq \left(1 - \frac{c}{L}\right)^{t+1} [F(x^{(0)}) - F(x^*)]$$

So : GD w/ strong convexity
w/ $\|\nabla^2 F\| \leq L$
w/ $\alpha = \frac{1}{L}$

guarantees

$$F(x^{(t)}) - F(x^*) \leq \left(1 - \frac{c}{L}\right)^t [F(x^{(0)}) - F(x^*)]$$

Fact : $1 - \frac{c}{L} \leq e^{-c/L}$ (why?)

\hookrightarrow cond'n number of the problem $\frac{L}{c} = \kappa$

What is this condition number?

Recall: $\|\nabla^2 F\| \leq L$

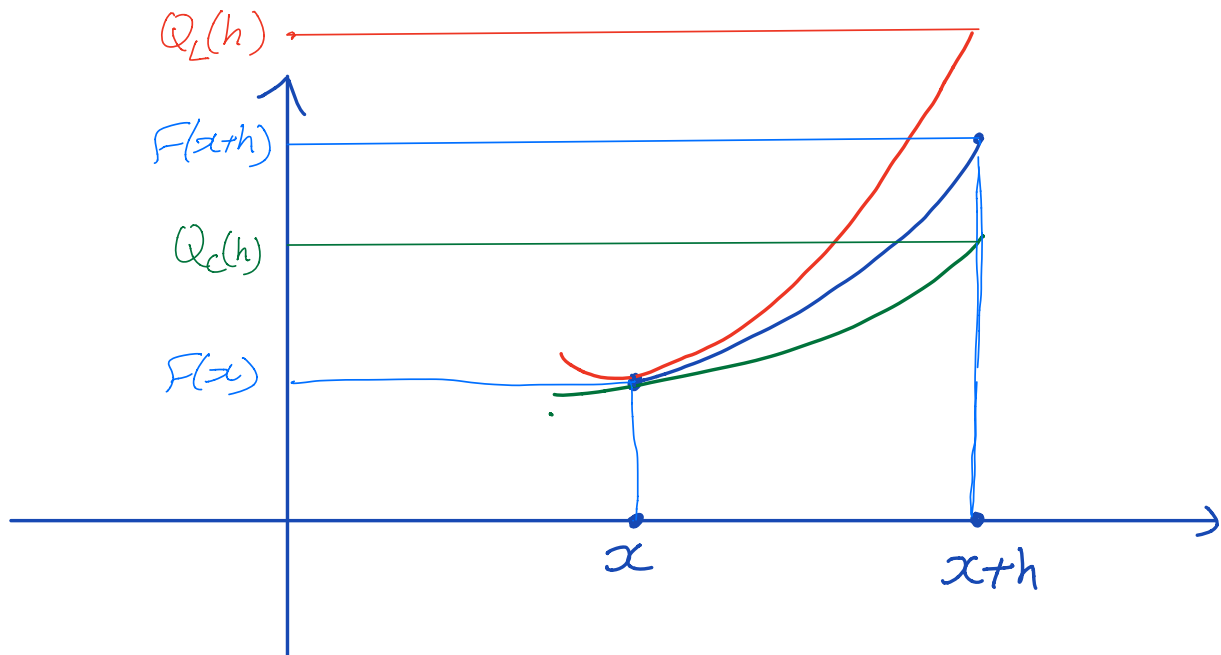
$$\Rightarrow F(x+h) \leq F(x) + h^T \nabla F(x) + \frac{L}{2} \|h\|^2$$

Quadratic in h
 $Q_L(h)$

Also: Strong convexity

$$\Rightarrow F(x+h) \geq F(x) + h^T \nabla F(x) + \frac{c}{2} \|h\|^2$$

Quadratic in h
 $Q_c(h)$



So bad condition number \Rightarrow slower convergence.

Some solutions:

GD with momentum

$$x^{(t+1)} = x^{(t)} - \alpha \nabla F(x^{(t)}) + \beta (x^{(t)} - x^{(t-1)})$$

remembers the history

the
In[^] strongly convex case:

Convergence is like $\beta^t \|x^{(0)} - x^*\|$

~best = $\beta = \frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1}$

better dependence on the cond'n number than GD \Rightarrow can be much faster than GD

In non-strongly convex case, momentum can fail.

⇒ Nesterov Acceleration

$$x^{(t+1)} = x^{(t)} + \beta(x^{(t)} - x^{(t-1)}) - \alpha \nabla F(x^{(t)} + \beta(x^{(t)} - x^{(t-1)}))$$

↑ Take a GD step not from $x^{(t)}$ but from $x^{(t)} + \beta(x^{(t)} - x^{(t-1)})$

Now, no longer only works for SC function, and also convergence is like

$$\left(\sqrt{\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa}}} \right)^t$$

Alternative, more "classical approach"

Conjugate Gradient :

Looks more complicated, simple to implement

Algorithm (FR) :

Initialize $x^{(0)}$, set $F_0 = F(x^{(0)})$
 $\nabla F_0 = \nabla F(x^{(0)})$

$$P_0 = -\nabla F_0$$

While $\nabla F_t \neq 0$, or ∇F_t too big

- Find d_t using line-search
- Set $x^{(t+1)} = x^{(t)} + \underline{d_t} P_t$
- Evaluate $\nabla F_{t+1} = \nabla F(x^{(t+1)})$
- $\beta_{t+1}^{FR} = \frac{\nabla F_{t+1}^T \nabla F_{t+1}}{\nabla F_t^T \nabla F_t}$
- $P_{t+1} = -\nabla F_{t+1} + \beta_{t+1}^{FR} P_t \quad (*)$

Converges in ϵ n-steps when F is
quadratic with positive def'n
 A .