Final exam Probabilistic graphical models Master MVA 2015-2016

December 16th 2015

A - Short problems

- 1. What is the family of distribution $(p_{\alpha})_{\alpha \in \mathbb{R}_{+}}$ with p_{α} the distribution of maximal entropy on \mathbb{N} , the set of natural integers $\{0, 1, 2, \ldots\}$, such that $\mathbb{E}_{p}[X] = \alpha$?
- 2. Propose a sampling scheme to sample exactly from the distribution $\mathbb{P}(X \in \cdot \mid ||X y||_2 \leq 1)$ where $y \in \mathbb{R}^d$ and X is a multivariate Gaussian random variable $\mathcal{N}(0, I_d)$. Prove that the proposed sampling scheme indeed yields a variable that has exactly the desired distribution.

B - Factorization and Markov properties

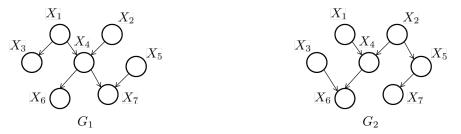
- 1. Find an undirected graphical model on four random variables X_1, X_2, X_3, X_4 that satisfies simultaneous the following conditions (a) and (b)
 - (a) All distributions that factorize according to the model satisfy the following conditional independence statements:

$$X_1 \perp \!\!\! \perp X_2 \mid (X_3, X_4), \quad X_3 \perp \!\!\! \perp X_4 \mid (X_1, X_2),$$

(b) There exist distributions that factorize according to the model and such that

$$X_1 \not\perp X_3 \mid X_2$$
, $X_1 \not\perp X_3$, $X_2 \not\perp X_3$, $X_1 \not\perp X_4$, $X_2 \not\perp X_4$.

2. Consider the two directed graphical models below. Is it possible to have a distribution p on X_1, \ldots, X_7 such that $p \in \mathcal{L}(G_1)$ and $p \in \mathcal{L}(G_2)$? Justify your answer.



C - EM algorithm

Consider (X, Y) a pair of correlated Bernoulli random variables which we parameterize by $(\pi_{00}, \pi_{01}, \pi_{10}, \pi_{11})$ with $\pi_{kj} = \mathbb{P}(X = k, Y = j)$. Assume that we observe the three following independent samples

- an i.i.d. sample (X_1, \ldots, X_{n_x}) from the marginal distribution of X, together with
- an i.i.d. sample (Y_1, \ldots, Y_{n_y}) from the marginal distribution of Y, and
- an i.i.d. sample $((X'_1, Y'_1), \dots, (X'_m, Y'_m))$ from the joint distribution of (X, Y)

Consider the notations:

- $N_x = \sum_{i=1}^{n_x} X_i, N_y = \sum_{i=1}^{n_y} Y_i,$
- $M_{jk} = \sum_{i=1}^{m} \delta(X_i', k) \, \delta(Y_i', j)$

Propose an EM algorithm to estimate $(\pi_{00}, \pi_{01}, \pi_{10}, \pi_{11})$. In particular, specify which quantities are computed for the E-step and which quantities are computed for the M-step.

D - Parallel chains

Consider the directed graphical model G below:

$$X_1 \quad X_2 \qquad X_{T-1} \quad X_T$$

$$X_T \quad X_T \quad Z$$

$$Y_1 \quad Y_2 \qquad Y_{T-1} \quad Y_T$$

$$X_T \quad X_T \quad Z$$

Suppose that the variables X_t and Y_t are discrete K-valued for t = 1, ..., T, and that Z is a binary random variable. Consider the following form for the factors for a specific distribution p in $\mathcal{L}(G)$:

- $p(X_1 = l) = p(Y_1 = l) = \pi_l$ for l = 1, ..., K.
- $p(X_t = i | X_{t-1} = j) = p(Y_t = i | Y_{t-1} = j) = A_{ij}$ for i, j = 1, ..., K and t = 2, ..., T.
- $p(Z=1|X_T=k,Y_T=l)$ takes the value p whenever k=l, and q otherwise (i.e. when $k\neq l$).

By using the graph eliminate algorithm (or just clever use of distributivity), give a simple formula for the marginal p(Z=1) in terms of the matrix A, vector π and scalars q, p and T. Provide brief explanations of how to obtain the result.

E - Metropolized Gibbs sampler

We consider the Gibbs distribution p of the random variable $X = (X_1, ..., X_n)$ (which we can think of as a distribution from a graphical model of interest). For simplicity we assume that the X_i are K-valued random variables. We will use the notation X_{-i} to refer to $X_{\{1,...,n\}\setminus\{i\}}$. We will denote by p_i the conditional distribution of the ith variable given all the others, as induced from the Gibbs distribution so that

$$p_i(z_i \mid x_{-i}^t) := \mathbb{P}(X_i = z_i \mid X_{-i} = x_{-i}^t).$$

The Metropolized Gibbs sampler is a variant of Gibbs sampling, which takes the form of a Metropolis-Hasting algorithm that updates a single variable X_i at a time: to update the variable X_i , instead of just sampling this variable conditionally on the other variables, it makes a proposal drawn from the transition T_i with

$$T_i((x_i^t, x_{-i}^t), (z_i, x_{-i}^t)) := \begin{cases} \frac{p_i(z_i \mid x_{-i}^t)}{1 - p_i(x_i^t \mid x_{-i}^t)} & \text{for } z_i \neq x_i^t \\ 0 & \text{for } z_i = x_i^t \end{cases}$$
(1)

and accepts the move with probability

$$\alpha_i((x_i^t, x_{-i}^t), (z_i, x_{-i}^t)) := \min \left\{ 1, \frac{1 - p_i(x_i^t \mid x_{-i}^t)}{1 - p_i(z_i \mid x_{-i}^t)} \right\}.$$

You may use the notations $\alpha_i(x_i^t, z_i) := \alpha_i((x_i^t, x_{-i}^t), (z_i, x_{-i}^t))$ and $T_i(x_i^t, z_i) := T_i((x_i^t, x_{-i}^t), (z_i, x_{-i}^t))$ in you answers to simplify the notations.

- 1. Show that the transition corresponding to an update of variable X_i of the Metropolized Gibbs sampler satisfies detailed balance with the Gibbs distribution.
- 2. Does the Markov Chain produced by the Metropolized Gibbs sampler converge to the Gibbs distribution? Explain why. To answer this question you can either consider a random scan Gibbs sampler that picks the variable i uniformly at random at each iteration or a cyclic scan Gibbs sampler that samples each variable X_i in a cycle.

F - Bayesian estimation: posterior mean vs MAP

Assume we observe an i.i.d. sample (x_1, \ldots, x_n) of realizations of a Bernoulli random variable whose unknown moment parameter we denote by $\mu = \mathbb{E}_{\mu}[X] = \mathbb{P}_{\mu}(X=1)$.

We consider first the Bayesian estimation of μ and the corresponding MAP estimator, based on a uniform prior distribution of μ .

- 1. Express the posterior mean estimate $\hat{\mu}_{PM}$ for μ as a function of $\bar{x} := \frac{1}{n} \sum_{i=1}^{n} x_i$.
- 2. What is the maximum a posteriori (MAP) estimate $\hat{\mu}_{MAP}$ for μ ?

We now consider again the same estimators, but we instead work with η , the canonical parameter of the exponential family.

- (c) If a uniform prior distribution $p_{\mu}(\mu)$ is placed on μ what is the induced prior distribution on η ? Provide the density of that prior $p_{\eta}(\eta)$ when p_{μ} is the uniform prior on the interval [0,1].
- (d) What is the value of the posterior mean estimate $\int \mu(\eta) p(\eta|x_1,\ldots,x_n) d\eta$ under this prior p_{η} on η , for $\mu(\eta) = (1 + e^{-\eta})^{-1}$ the usual moment mapping?
- (e) For this prior p_{η} , what is the MAP estimator $\hat{\eta}_{\text{MAP}}$? What is the corresponding moment parameter $\mu(\hat{\eta}_{\text{MAP}})$?
- (f) Comment on the different estimators obtained.