

Elements of LGM Model

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Abstract

In this note, we document the elements of Linear Markov Model (LGM) and its calibration to swaptions.

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1 Elements of one-factor LGM model

In this section, we review the elements of one-factor LGM model and its calibration to swaptions, as presented in Hagan [1] and Piza [4].

1.1 HJM framework

We assume that we have a family of zero-coupon bonds traded in the market. The price at time t of a zero-coupon bond with maturity T ($0 \leq t \leq T$) will be denoted by $P(t, T)$. We assume the bond price satisfies the following SDE:

$$dP(t, T) = P(t, T)[A(t, T)dt + B(t, T)dW_t], \quad P(T, T) = 1, \quad A(T, T) = B(T, T) = 0,$$

where W is a 1-dimensional standard Brownian motion. We assume there is also a strictly positive process N , which will be chosen as the numéraire, that satisfies the following SDE:

$$dN_t = N_t(\mu_t^N dt + \sigma_t^N dW_t), \quad N_0 = 1.$$

By the Fundamental Theorem of Asset Pricing, a necessary and sufficient condition for the no arbitrage property (more precisely, no-free-lunch-with-vanishing-risk, NFLVR, for allowable strategies) is that we can find a probability measure Q such that the discounted bond price process

$$\bar{P}(t, T) := \frac{P(t, T)}{N_t}$$

is a Q -local martingale. Itô calculus yields

$$\frac{d\bar{P}(t, T)}{\bar{P}(t, T)} = [B(t, T) - \sigma_t^N] \left[\frac{A(t, T) - \mu_t^N + (\sigma_t^N)^2 - \sigma_t^N B(t, T)}{B(t, T) - \sigma_t^N} dt + dW_t \right]$$

provided $B(t, T) - \sigma_t^N \neq 0$, $0 \leq t \leq T$.

If the probability measure Q is defined by (P denotes the original probability measure)

$$\left. \frac{dQ}{dP} \right|_{\mathcal{F}_t} = D_t = \exp \left\{ \int_0^t \theta_s dW_s - \frac{1}{2} \int_0^t \theta_s^2 ds \right\},$$

we necessarily have

$$\frac{A(t, T) - \mu_t^N + (\sigma_t^N)^2 - \sigma_t^N B(t, T)}{B(t, T) - \sigma_t^N} = -\theta_t,$$

which must be independent of T . We are already in the risk-neutral measure (i.e. $P = Q$) if and only if

$$A(t, T) - \mu_t^N + (\sigma_t^N)^2 - \sigma_t^N B(t, T) = 0.$$

1.2 Forward rate model

The results in HJM model can be translated into those in forward rate model. Denote by $f(t, T)$ the forward rate such that $P(t, T) = \exp \left\{ - \int_t^T f(t, s) ds \right\}$. Assume $f(t, T)$ follows the SDE

$$df(t, T) = a(t, T)dt + b(t, T)dW_t.$$

We then have the following relations

$$A(t, T) = f(t, t) - \int_t^T a(t, s) ds + \frac{1}{2} \left(\int_t^T b(t, s) ds \right)^2, \quad B(t, T) = - \int_t^T b(t, s) ds$$

and

$$a(t, T) = \frac{\partial B(t, T)}{\partial T} B(t, T) - \frac{\partial A(t, T)}{\partial T}, \quad b(t, T) = -\frac{\partial B(t, T)}{\partial T}$$

Then the condition $A(t, T) - \mu_t^N + (\sigma_t^N)^2 - \sigma_t^N B(t, T) = 0$ translates into

$$a(t, T) = \int_t^T b(t, s) ds \cdot b(t, T) + \sigma_t^N b(t, T).$$

1.3 The LGM model

To get the LGM model, we assume that we are already under the risk-neutral measure associated with the numeraire N , where N is specified by the following parameter specification

$$\begin{cases} b(t, T) = H'(T)\alpha_t \\ \sigma_t^N = H(t)\alpha_t \end{cases}$$

Here H and α are two deterministic functions with $H(0) = 0$. This specification gives

$$a(t, T) = H(T)H'(T)\alpha_t^2, \quad B(t, T) = -[H(T) - H(t)]\alpha_t.$$

Define $\zeta_t = \int_0^t \alpha_s^2 ds$ and $X_t = \int_0^t \alpha_s dW_s$, we have $f(t, T) = f(0, T) + H'(T)H(T)\zeta_t + H'(T)X_t$. This gives

$$A(t, T) = f(0, t) + H'(t)H(t)\zeta_t + H'(t)X_t - [H(T) - H(t)]H(t)\alpha_t^2$$

and

$$\mu_t^N = f(0, t) + H'(t)H(t)\zeta_t + H'(t)X_t + H^2(t)\alpha_t^2.$$

In summary, the HJM parameter specifications of LGM model are

$$\boxed{\begin{cases} A(t, T) = f(0, t) + H'(t)H(t)\zeta_t + H'(t)X_t - [H(T) - H(t)]H(t)\alpha_t^2 \\ B(t, T) = -[H(T) - H(t)]\alpha_t \\ a(t, T) = H(T)H'(T)\alpha_t^2 \\ b(t, T) = H'(T)\alpha_t \\ \mu_t^N = f(0, t) + H'(t)H(t)\zeta_t + H'(t)X_t + H^2(t)\alpha_t^2 \\ \sigma_t^N = H(t)\alpha_t \end{cases}} \quad (1)$$

where H and α are two deterministic functions with $H(0) = 0$, $\zeta_t = \int_0^t \alpha_s^2 ds$, $X_t = \int_0^t \alpha_s dW_s$, and $f(0, t)$ is given by market quoted yield curve.

Consequently, we have $r_t := f(t, t) = f(0, t) + H'(t)H(t)\zeta_t + H'(t)X_t$,

$$P(t, T) = \exp \left\{ - \int_t^T f(t, s) ds \right\} = \frac{P(0, T)}{P(0, t)} \exp \left\{ -[H(T) - H(t)]X_t - \frac{1}{2}[H^2(T) - H^2(t)]\zeta_t \right\}.$$

and

$$\frac{d\bar{P}(t, T)}{\bar{P}(t, T)} = [B(t, T) - \sigma_t^N]dW_t.$$

The last SDE gives

$$\bar{P}(t, T) = P(0, T) \exp \left\{ -H(T)X_t - \frac{1}{2}H^2(T)\zeta_t \right\}.$$

Therefore

$$N_t = \frac{P(t, T)}{\bar{P}(t, T)} = \frac{1}{P(0, t)} \exp \left\{ H(t)X_t + \frac{1}{2}H^2(t)\zeta_t \right\}.$$

In summary, we have

$$\begin{cases} f(t, T) = f(0, T) + H'(T)H(t)\zeta_t + H'(T)X_t \\ r_t = f(0, t) + H'(t)H(t)\zeta_t + H'(t)X_t \\ P(t, T) = \frac{P(0, T)}{P(0, t)} \exp \left\{ -[H(T) - H(t)]X_t - \frac{1}{2}[H^2(T) - H^2(t)]\zeta_t \right\} \\ \bar{P}(t, T) = P(0, T) \exp \left\{ -H(T)X_t - \frac{1}{2}H^2(T)\zeta_t \right\} \\ N_t = \frac{1}{P(0, t)} \exp \left\{ H(t)X_t + \frac{1}{2}H^2(t)\zeta_t \right\} \end{cases} \quad (2)$$

1.4 Connection with one-factor Hull-White model

Denote by Q the martingale measure associated with money market account numeraire. The one-factor Hull-White model assumes the short rate process r_t follows the following dynamics under Q

$$dr_t = (b_t - \kappa r_t)dt + \sigma_t dW_t^Q,$$

where κ is a constant, b_t and σ_t are deterministic functions of t , and W^Q is a standard Brownian motion under Q .

Define $\theta_t = e^{-\kappa t}r_0 + e^{-\kappa t} \int_0^t e^{\kappa s} b_s ds$ and $X_t^Q = e^{-\kappa t} \int_0^t e^{\kappa s} \sigma_s dW_s^Q$. Then θ_t is a deterministic function of t and X_t^Q is Gaussian process with mean 0 and variance $e^{-2\kappa t} \int_0^t e^{2\kappa s} \sigma_s^2 ds$. In summary, we have

$$r_t = \theta_t + X_t^Q, \quad dX_t^Q = -\kappa X_t^Q dt + \sigma_t dW_t^Q, \quad X_0^Q = 0, \quad E[X_t^Q] = 0, \quad E[(X_t^Q)^2] = e^{-2\kappa t} \int_0^t e^{2\kappa s} \sigma_s^2 ds.$$

It's easy to verify that (see Zeng [5])

$$\begin{cases} P(t, T) = P(t, T; X_t^Q) = \frac{P(0, T)}{P(0, t)} \exp \left\{ -H^Q(T - t) \left[X_t^Q + \nu^h(t) + \frac{1}{2}\nu(t)H^Q(T - t) \right] \right\} \\ P(0, t) = \exp \left\{ -\int_0^t \theta_s ds + \nu_t^{H^Q} \right\} \end{cases} \quad (3)$$

where

$$\begin{cases} h(t) = e^{-\kappa t} \\ H^Q(t) = \int_0^t h(s) ds \\ \nu(t) = e^{-2\kappa t} \int_0^t e^{2\kappa s} \sigma_s^2 ds \\ \nu^h(t) = h * \nu(t) = \int_0^t e^{-\kappa(t-s)} \nu(s) ds \\ \nu^{H^Q}(t) = H^Q * \nu(t) = \int_0^t H^Q(t-s) \nu(s) ds. \end{cases}$$

We also note that $\frac{d}{dt} \nu^{H^Q}(t) = \nu^h(t)$. The one-to-one correspondence between one-factor LGM model and one-factor Hull-White model is therefore

$$\begin{cases} \alpha_t = e^{\kappa t} \sigma_t \\ \zeta_t = e^{2\kappa t} \nu(t) = \int_0^t \alpha_s^2 ds = \int_0^t e^{2\kappa s} \sigma_s^2 ds \\ H(t) = H^Q(t) = \int_0^t e^{-\kappa s} ds. \end{cases}$$

To verify this relationship, we note

$$\begin{aligned} & -H^Q(T - t)[X_t^Q + \nu^h(t) + \frac{1}{2}\nu(t)H^Q(T - t)] \\ &= -H(T - t) \left[e^{-\kappa t} \int_0^t e^{\kappa s} \sigma_s dW_s^Q + e^{-\kappa t} \int_0^t e^{\kappa s} e^{-2\kappa s} \zeta_s ds + \frac{1}{2} e^{-2\kappa t} \zeta_t H(T - t) \right] \\ &= -[H(T) - H(t)] \left[\int_0^t e^{\kappa s} \sigma_s dW_s^Q + \int_0^t e^{-\kappa s} \zeta_s ds \right] - \frac{1}{2} [H(T) - H(t)]^2 \zeta_t \\ &= -[H(T) - H(t)] \left[\int_0^t e^{\kappa s} \sigma_s dW_s^Q - \int_0^t H(s) e^{2\kappa s} \sigma_s^2 ds \right] - \frac{1}{2} [H^2(T) - H^2(t)] \zeta_t. \end{aligned}$$

We shall show $\int_0^t e^{\kappa s} \sigma_s dW_s^Q - \int_0^t H(s) e^{2\kappa s} \sigma_s^2 ds = \int_0^t e^{\kappa s} \sigma_s (dW_s^Q - H(s) e^{\kappa s} \sigma_s ds) = \int_0^t e^{\kappa s} \sigma_s dW_s = X_t$, and thus prove that formula (3) agrees with the zero coupon bond price formula in (2). Indeed, the Radon-Nikodym derivative of Q^N w.r.t. Q is

$$D_t = \frac{N_t}{e^{\int_0^t r_u du}}.$$

So $d \ln D_t = \frac{dN_t}{N_t} + (\dots)dt$. Since D_t is a martingale under Q , we conclude

$$dD_t = D_t \sigma_t^N dW_t^Q = D_t H(t) \alpha_t dW_t^Q.$$

Girsanov's Theorem (see Appendix A) implies $W_t^Q - \int_0^t H(s) \alpha_s$ is a martingale under Q^N . This proves our claim.

1.5 Pricing formula of swap

Consider a swap with start date t_0 , fixed leg pay dates t_1, t_2, \dots, t_n , and fixed rate K . Then the fixed leg makes the payments (assuming notional is one unit of currency)

$$\begin{cases} \tau_i K & \text{paid at } t_i, \text{ for } i = 1, 2, \dots, n-1 \\ 1 + \tau_n K & \text{paid at } t_n, \end{cases}$$

where τ_i is the day count of $[t_{i-1}, t_i]$ in year fraction. For any $t \leq t_0$, these payments have the value

$$V_{fix}(t) = K \sum_{i=1}^n \tau_i P(t, t_i) + P(t, t_n).$$

The swap's floating leg usually has a different frequency than the fixed leg, so let this leg's start and pay dates be

$$t_0 = u_0 < u_1 < \dots < u_m = t_n.$$

The floating leg pays

$$\begin{cases} \tilde{\tau}_j L_j & \text{paid at } u_j, \text{ for } j = 1, 2, \dots, m-1 \\ 1 + \tilde{\tau}_m L_m & \text{paid at } u_m = t_n \end{cases}$$

where $\tilde{\tau}_j$ is the day count of $[u_{j-1}, u_j]$ in year fraction and L_j is the Libor or Euribor floating rate for the interval $[u_{j-1}, u_j]$. The rate L_j is set on the fixing date, which is generally two London business days before the interval starts on u_{j-1} . In formula,

$$L_j = \frac{1}{\tilde{\tau}_j} \left[\frac{P(u_{j-1}^{fix}, u_{j-1})}{P(u_{j-1}^{fix}, u_j)} - 1 \right] + s_j,$$

where the first part of the formula stands for risk-free floating rate, and the second part s_j stands for a spread for credit risk. The payment of $\tilde{\tau}_j L_j$ at time u_j is equal to a payment of

$$[P(u_{j-1}^{fix}, u_{j-1}) - P(u_{j-1}^{fix}, u_j)] + \tilde{\tau}_j s_j P(u_{j-1}^{fix}, u_j)$$

at time u_j^{fix} , which is further equal to a payment of

$$[P(t, u_{j-1}) - P(t, u_j)] + \tilde{\tau}_j s_j P(t, u_j)$$

at time t . The value of the floating leg is therefore

$$V_{flt}(t) = P(t, t_0) + \sum_{j=1}^m \tilde{\tau}_j s_j P(t, u_j).$$

The value of the receiver swap (receiving the fixed leg, paying the floating leg) is

$$V_{rec}(t) = K \sum_{i=1}^n \tau_i P(t, t_i) + P(t, t_n) - P(t, t_0) - \sum_{j=1}^m \tilde{\tau}_j s_j P(t, u_j) \quad (4)$$

For $t = 0$, we can write the formula in a nicer form

$$V_{rec}(0) = K^{adj} \sum_{i=1}^n \tau_i P(0, t_i) + P(0, t_n) - P(0, t_0)$$

where $K^{adj} = K - \frac{\sum_{j=1}^m \tilde{\tau}_j s_j P(0, u_j)}{\sum_{i=1}^n \tau_i P(0, t_i)}$. This leads to the following pragmatic approximation

$$V_{rec}(t) \approx K^{adj} \sum_{i=1}^n \tau_i P(t, t_i) + P(t, t_n) - P(t, t_0) \quad (5)$$

1.6 Pricing formula of swaption

The value of a receiver swaption at time zero is ($t_{ex} \leq t_0$ is the option exercise time)

$$V_{rec}^{opt}(0) = N_0 E^{Q_N} \left[\frac{\max\{V_{rec}(t_{ex}), 0\}}{N_{t_{ex}}} \right] \approx E^{Q_N} \left[\left(K^{adj} \sum_{i=1}^n \tau_i \bar{P}(t_{ex}, t_i; X_{t_{ex}}) + \bar{P}(t_{ex}, t_n; X_{t_{ex}}) - \bar{P}(t_{ex}, t_0; X_{t_{ex}}) \right)^+ \right]$$

where $X_{t_{ex}} \sim N(0, \zeta_{t_{ex}})$ under the martingale measure Q_N associated with numeraire N . By change of variable $y = x + H(t_0)\zeta_{t_{ex}}$, we have

$$\begin{aligned} V_{rec}^{opt}(0) &\approx \frac{1}{\sqrt{2\pi\zeta_{t_{ex}}}} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2\zeta_{t_{ex}}}} \left(K^{adj} \sum_{i=1}^n \tau_i P(0, t_i) \exp \left\{ -H(t_i)x - \frac{1}{2}H^2(t_i)\zeta_{t_{ex}} \right\} \right. \\ &\quad \left. + P(0, t_n) \exp \left\{ -H(t_n)x - \frac{1}{2}H^2(t_n)\zeta_{t_{ex}} \right\} - P(0, t_0) \exp \left\{ -H(t_0)x - \frac{1}{2}H^2(t_0)\zeta_{t_{ex}} \right\} \right)^+ dx \\ &= \frac{1}{\sqrt{2\pi\zeta_{t_{ex}}}} \int_{-\infty}^{\infty} e^{-\frac{y^2}{2\zeta_{t_{ex}}}} \left(K^{adj} \sum_{i=1}^n \tau_i D_i \exp \left\{ -(H_i - H_0)y - \frac{1}{2}(H_i - H_0)^2\zeta_{t_{ex}} \right\} \right. \\ &\quad \left. + D_n \exp \left\{ -(H_n - H_0)y - \frac{1}{2}(H_n - H_0)^2\zeta_{t_{ex}} \right\} - D_0 \right)^+ dy \end{aligned}$$

where $H_i = H(t_i)$, $D_i = P(0, t_i)$ for $i = 0, 1, \dots, n$.

We now assume without loss of generality that H is a strictly increasing function so that $H' > 0$. Then

$$\exp \left\{ -[H(T) - H(t)]y - \frac{1}{2}[H(T) - H(t)]^2\zeta_{t_{ex}} \right\}, \quad t_{ex} \leq t \leq T$$

is a monotone decreasing function of y , with limit 0 as $y \rightarrow \infty$ and limit ∞ as $y \rightarrow -\infty$. So there exists a unique break-even point y^* such that the term inside $(\dots)^+$ is

$$\begin{cases} < 0 & \text{if } y > y^* \\ = 0 & \text{if } y = y^* \\ > 0 & \text{if } y < y^* \end{cases}$$

Then

$$\begin{aligned}
& V_{rec}^{opt}(0) \\
& \approx \frac{1}{\sqrt{2\pi\zeta_{tex}}} \int_{-\infty}^{y^*} e^{-\frac{y^2}{2\zeta_{tex}}} \left(K^{adj} \sum_{i=1}^n \tau_i D_i e^{-(H_i-H_0)y - \frac{1}{2}(H_i-H_0)^2\zeta_{tex}} + D_n e^{-(H_n-H_0)y - \frac{1}{2}(H_n-H_0)^2\zeta_{tex}} - D_0 \right) dx \\
& = \left[K^{adj} \sum_{i=1}^n \tau_i D_i \Phi\left(\frac{y^* + (H_i-H_0)\zeta_{tex}}{\sqrt{\zeta_{tex}}}\right) + D_n \Phi\left(\frac{y^* + (H_n-H_0)\zeta_{tex}}{\sqrt{\zeta_{tex}}}\right) - D_0 \Phi\left(\frac{y^*}{\sqrt{\zeta_{tex}}}\right) \right] \quad (6)
\end{aligned}$$

where $\Phi(\cdot)$ is the c.d.f. of a standard normal distribution and y^* is the unique solution of

$$K^{adj} \sum_{i=1}^n \tau_i D_i e^{-[H(t_i)-H(t_0)]y^* - \frac{1}{2}[H(t_i)-H(t_0)]^2\zeta_{tex}} + D_n e^{-[H(t_n)-H(t_0)]y^* - \frac{1}{2}[H(t_n)-H(t_0)]^2\zeta_{tex}} = D_0.$$

1.7 Calibration to swaption market

We define the forward swap rate S as

$$S(t) = \frac{P(t, t_0) - P(t, t_n)}{\sum_{i=1}^n \tau_i P(t, t_i)}, \quad t \leq t_0$$

and the annuity numeraire as

$$L(t) = \sum_{i=1}^n \tau_i P(t, t_i), \quad t \leq t_0.$$

Then

$$V_{rec}(t) \approx K^{adj} \sum_{i=1}^n \tau_i P(t, t_i) + P(t, t_n) - P(t, t_0) = (K^{adj} - S(t))L(t)$$

and the rule of change-of-numeraire gives us

$$V_{rec}^{opt}(0) = N_0 E^{Q_N} \left[\frac{\max\{V_{rec}(t_{ex}), 0\}}{N_{t_{ex}}} \right] = L_0 E^{Q_L} \left[\frac{\max\{V_{rec}(t_{ex}), 0\}}{L_{t_{ex}}} \right] \approx L_0 E^{Q_L} [(K^{adj} - S(t_{ex}))^+].$$

By the pricing formula of zero coupon bond, $S(t)$ is a function of t and X_t . So Ito's formula yields

$$dS(t) = dS(t, X_t) = \frac{\partial S(t, x)}{\partial x} \Big|_{x=X_t} \alpha_t dW_t + (\dots)dt.$$

Since $S(t)$ has the form of tradable numeraire, it is a martingale under the martingale measure Q_L associated with the annuity numeraire L . Therefore

$$dS(t) = \frac{\partial S(t, x)}{\partial x} \Big|_{x=X_t} \alpha_t dW_t^L,$$

where W^L is a standard Brownian motion under Q_L .

This is a setup for the equivalent vol techniques of Hagan [3], and we have the following approximation (formula (3.44b), formula (3.44c) of Hagan [1])

$$\sigma_N \sqrt{t_{ex}} \approx \sqrt{\zeta_{tex}} \frac{S(0) \sum_{i=1}^n \tau_i D_i (H_i - H_0) + D_n (H_n - H_0)}{\sum_{i=1}^n \tau_i D_i} \quad (7)$$

$$\sigma_B \sqrt{t_{ex}} \approx \sqrt{\zeta_{tex}} \frac{\log \frac{K^{adj}}{S(0)}}{K^{adj} - S(0)} \frac{S(0) \sum_{i=1}^n \tau_i D_i (H_i - H_0) + D_n (H_n - H_0)}{\sum_{i=1}^n \tau_i D_i} \quad (8)$$

where σ_N is the implied normal vol and σ_B is the implied Black vol. Here $\frac{\log \frac{K^{adj}}{S(0)}}{K^{adj} - S(0)}$ is interpreted as $\frac{1}{K^{adj}}$ when $S(0) = K^{adj}$.

1.7.1 Calibration to ATM swaption

The ATM calibration function takes as input an ATM vol surface; then for a given expiry, it computes ζ for each tenor by the formula (8)

$$\sigma_B \sqrt{t_{ex}} \approx \sqrt{\zeta_{t_{ex}}} \frac{1}{S(0)} \frac{S(0) \sum_{i=1}^n \tau_i D_i (H_i - H_0) + D_n (H_n - H_0)}{\sum_{i=1}^n \tau_i D_i};$$

finally, it takes a weighted average as the value of ζ at the given expiry. Doing the same thing to each expiry, the function produces the values of ζ at all expiries. That is,

- Step1. Input an ATM vol surface with n expiries and m tenors;
- Step2. For i -th expiry, compute the value of ζ at i -th expiry m times, once for each tenor;
- Step3. Take a weighted average of these m values of ζ , and use this average as the value of ζ at i -th expiry;
- Step4. Go to step2 for $(i + 1)$ -th expiry, until we go through all the n expiries.

1.7.2 Calibration to OTM swaption

The OTM calibration function takes as input a volatility band (an array of swaptions); secondly, for a given expiry, it computes the market quoted price of swaption by Black's formula; it then computes ζ by formula (6)

$$V_{rec}^{opt}(0) = K^{adj} \sum_{i=1}^n \tau_i D_i \Phi \left(\frac{y^* + (H_i - H_0) \zeta_{t_{ex}}}{\sqrt{\zeta_{t_{ex}}}} \right) + D_n \Phi \left(\frac{y^* + (H_n - H_0) \zeta_{t_{ex}}}{\sqrt{\zeta_{t_{ex}}}} \right) - D_0 \Phi \left(\frac{y^*}{\sqrt{\zeta_{t_{ex}}}} \right),$$

with the initial guess based on

$$\sigma_B \sqrt{t_{ex}} = \sqrt{\zeta_{t_{ex}}} \frac{\log \frac{K^{adj}}{S(0)} \left[1 + \frac{1}{24} (1 - (\log \frac{K^{adj}}{S(0)})^2 / 120) \sigma_B^2 t_{ex} \right]}{K^{adj} - S(0)} \frac{S(0) \sum_{i=1}^n \alpha_i D_i (H_i - H_0) + D_n (H_n - H_0)}{\sum_{i=1}^n \alpha_i D_i}.$$

That is,

- Step1. Input a volatility band with n swaptions (n different expiries);
- Step2. For i -th swaption, compute the initial guess of ζ at the swaption's expiry;
- Step3. Use Black's formula to compute market quoted price of the i -th swaption;
- Step4. Solve equation (6) for ζ ;
- Step5. Go to Step2 for $(i + 1)$ -th swaption, until we go through all the n swaptions.

1.8 Pricing formula of caplet and calibration to caps market

Consider the Libor rate for time period $[T_s, T_e]$, which is fixed at time $t_f \leq T_s$. The market quotes give Black volatilities of caplets for various strikes. Suppose a caplet has strike K and the year fraction of $[T_s, T_e]$ is τ . The market price for this caplet is

$$V_0^{mkt} = P(0, T_e) \tau \text{Bl}(K, F, \sigma_B \sqrt{t_f}, 1)$$

where $F = F(0; T_s, T_e)$ is the forward rate for $[T_s, T_e]$ at time 0, σ_B is the market quoted Black vol, and $\text{Bl}(K, F, v, w)$ is given by

$$\text{Bl}(K, F, v, w) = Fw\Phi(wd_1) - Kw\Phi(wd_2), \quad d_1 = \frac{\ln(F/K) + v^2/2}{v}, \quad d_2 = \frac{\ln(F/K) - v^2/2}{v}$$

The theoretical price of the above caplet based on one-factor LGM model is

$$V_0^{model} = P(0, T_e) \tau \text{Bl} \left(K + \frac{1}{\tau}, F + \frac{1}{\tau}, [H(T_e) - H(T_s)] \sqrt{\zeta_{t_f}}, 1 \right)$$

where $H(t) = \int_0^t e^{-\kappa s} ds$ and $\zeta_t = \int_0^t e^{2\kappa s} \sigma_s^2 ds$ (σ is the volatility parameter in the corresponding one-factor Hull-White model).

Therefore, calibration to caplets in order to obtain ζ_{t_f} requires solving the following equation

$$\text{Bl}(K, F, \sigma_B \sqrt{t_f}, 1) = \text{Bl}\left(K + \frac{1}{\tau}, F + \frac{1}{\tau}, [H(T_e) - H(T_s)] \sqrt{\zeta_{t_f}}, 1\right)$$

We note $\text{Bl}(K, F, v, 1)$ is a monotone increasing function of v with a range of $((F - K)^+, F)$. So the above calibration equation always has a solution.

1.9 Interpolation of LGM model parameter ζ

We assume there is a coupon period $[t_s, t_e]$ and we are given the values of ζ at t_s and t_e : ζ_s and ζ_e , respectively. If the volatility of one-factor Hull-White model (equivalent to one-factor LGM model) is a constant σ over $[t_s, t_e]$, we have for $t \in [t_s, t_e]$

$$\zeta_t = \begin{cases} \zeta_s + \sigma^2(t - t_s) & \text{if } \kappa = 0 \\ \zeta_s + \sigma^2 \frac{e^{2\kappa t} - e^{2\kappa t_s}}{2\kappa} & \text{if } \kappa \neq 0 \end{cases}$$

By setting t to t_e , we can solve for σ :

$$\sigma = \begin{cases} \frac{\zeta_s(t_e - t_s) + \zeta_e(t - t_s)}{t_e - t_s} & \text{if } \kappa = 0 \\ \frac{e^{2\kappa(t_e - t_s)} - e^{2\kappa(t - t_s)}}{e^{2\kappa(t_e - t_s)} - 1} \zeta_s + \frac{e^{2\kappa(t - t_s)} - 1}{e^{2\kappa(t_e - t_s)} - 1} \zeta_e & \text{if } \kappa \neq 0 \end{cases}$$

2 Elements of two-factor LGM model

The two-factor LGM model has two state variables, $\mathbf{X}_t = (X_1(t), X_2(t))^T$, where for $k = 1, 2$, $X_k(t) = \int_0^t \alpha_k(s) dW_k(s)$, with W_k a standard Brownian motion, α_k a deterministic function, and $dW_1(t)dW_2(t) = \rho(t)dt$. This is the evolution under the risk neutral measure induced by a numeraire. We choose the numeraire to be

$$\begin{aligned} N_t &= \frac{1}{P(0, t)} \exp \left\{ \mathbf{H}(t) \mathbf{X}(t) + \frac{1}{2} \mathbf{H}(t) \zeta(t) \mathbf{H}(t) \right\} \\ &= \frac{1}{P(0, t)} \exp \left\{ H_1(t) X_1(t) + H_2(t) X_2(t) + \frac{1}{2} H_1^2(t) \zeta_{11}(t) + H_1(t) H_2(t) \zeta_{12}(t) + \frac{1}{2} H_2^2(t) \zeta_{22}(t) \right\}. \end{aligned}$$

Here $\mathbf{H}(t) = (H_1(t), H_2(t))$ is a deterministic, strictly increasing function of t , and

$$\zeta(t) = \begin{bmatrix} \int_0^t \alpha_1^2(s) ds & \int_0^t \rho(s) \alpha_1(s) \alpha_2(s) ds \\ \int_0^t \rho(s) \alpha_1(s) \alpha_2(s) ds & \int_0^t \alpha_2^2(s) ds \end{bmatrix}.$$

Similar to one-factor LGM model (formual (2)), we have

$$\begin{cases} f(t, T) = f(0, T) + \mathbf{H}'(T) \mathbf{X}_t + \mathbf{H}'(T) \zeta(t) \mathbf{H}(T) \\ r_t = f(0, t) + \mathbf{H}'(t) \mathbf{X}_t + \mathbf{H}'(t) \zeta(t) \mathbf{H}(t) \\ P(t, T) = \frac{P(0, T)}{P(0, t)} \exp \left\{ -[\mathbf{H}(T) - \mathbf{H}(t)] \mathbf{X}_t - \frac{1}{2} \mathbf{H}(T) \zeta(t) \mathbf{H}(T) + \frac{1}{2} \mathbf{H}(t) \zeta(t) \mathbf{H}(t) \right\} \\ \bar{P}(t, T) = P(0, T) \exp \left\{ -\mathbf{H}(T) \mathbf{X}_t - \frac{1}{2} \mathbf{H}(T) \zeta(t) \mathbf{H}(T) \right\} \\ N_t = \frac{1}{P(0, t)} \exp \left\{ \mathbf{H}(t) \mathbf{X}(t) + \frac{1}{2} \mathbf{H}(t) \zeta(t) \mathbf{H}(t) \right\} \end{cases} \quad (9)$$

The value of the receiver swap (receiving the fixed leg, paying the floating leg) is

$$V_{rec}(t) = K \sum_{i=1}^n \tau_i P(t, t_i) + P(t, t_n) - P(t, t_0) - \sum_{j=1}^m \tilde{\tau}_j s_j P(t, u_j) \quad (10)$$

and a pragmatic approximation is

$$\boxed{V_{rec}(t) \approx K^{adj} \sum_{i=1}^n \tau_i P(t, t_i) + P(t, t_n) - P(t, t_0)} \quad (11)$$

where $K^{adj} = K - \frac{\sum_{j=1}^m \bar{\tau}_j s_j P(0, u_j)}{\sum_{i=1}^n \tau_i P(0, t_i)}$.

2.1 Pricing formula of swaption

2.1.1 Exact formula

By direct integration

$$\begin{aligned} & V_{rec}^{opt}(0) \\ &= E^{Q_N} \left[\left(K^{adj} \sum_{i=1}^n \tau_i \bar{P}(t_{ex}, t_i) + \bar{P}(t_{ex}, t_n) - \bar{P}(t_{ex}, t_0) \right)^+ \right] \\ &= \frac{1}{2\pi |\det \zeta|^{1/2}} \int \int e^{-\frac{1}{2} \mathbf{Y} \zeta^{-1} \mathbf{Y}} \left[K^{adj} \sum_{i=1}^n \tau_i D_i e^{-\Delta \mathbf{H}_i \mathbf{Y} - \frac{1}{2} \Delta \mathbf{H}_i \cdot \zeta \Delta \mathbf{H}_i} + D_n e^{-\Delta \mathbf{H}_n \mathbf{Y} - \frac{1}{2} \Delta \mathbf{H}_n \cdot \zeta \Delta \mathbf{H}_n} - D_0 \right]^+ dY_1 dY_2 \end{aligned}$$

where $\zeta = \zeta_{t_{ex}}$, $D_i = P(0, t_i)$, and $\Delta \mathbf{H}_i = \mathbf{H}(t_i) - \mathbf{H}(t_0)$, $i = 1, 2, \dots, n$.

By fixing one variable and integrating with respect to the other, we have

$$\begin{aligned} V_{rec}^{opt}(0) &= \frac{1}{\sqrt{2\pi \zeta_{22}}} \int \left[K^{adj} \sum_{i=1}^n \tau_i D_i e^{-(z + \zeta_{12} \Delta H_i^{(1)} + \zeta_{22} \Delta H_i^{(2)})^2 / 2\zeta_{22}} \Phi \left(\frac{-\zeta_{12} z + \zeta_{22} y^* + \Delta H_i^{(1)} [\zeta_{11} \zeta_{22} - \zeta_{12}^2]}{\sqrt{\zeta_{22}} \sqrt{\zeta_{11} \zeta_{22} - \zeta_{12}^2}} \right) \right. \\ &\quad + D_n e^{-(z + \zeta_{12} \Delta H_n^{(1)} + \zeta_{22} \Delta H_n^{(2)})^2 / 2\zeta_{22}} \Phi \left(\frac{-\zeta_{12} z + \zeta_{22} y^* + \Delta H_n^{(1)} [\zeta_{11} \zeta_{22} - \zeta_{12}^2]}{\sqrt{\zeta_{22}} \sqrt{\zeta_{11} \zeta_{22} - \zeta_{12}^2}} \right) \\ &\quad \left. D_0 e^{-z^2 / 2\zeta_{22}} \Phi \left(\frac{-\zeta_{12} z + \zeta_{22} y^*}{\sqrt{\zeta_{22}} \sqrt{\zeta_{11} \zeta_{22} - \zeta_{12}^2}} \right) \right] dz \quad (12) \end{aligned}$$

Here $y^* = y^*(z)$ is the numerically determined break-even point, where the vector $\mathbf{Y} = \begin{pmatrix} y^*(z) \\ z \end{pmatrix}$ satisfies

$$K^{adj} \sum_{i=1}^n \tau_i D_i e^{-\Delta \mathbf{H}_i \cdot \mathbf{Y} - \frac{1}{2} \Delta \mathbf{H}_i \cdot \zeta \Delta \mathbf{H}_i} + D_n e^{-\Delta \mathbf{H}_n \cdot \mathbf{Y} - \frac{1}{2} \Delta \mathbf{H}_n \cdot \zeta \Delta \mathbf{H}_n} = D_0.$$

In addition,

$$\Delta \mathbf{H}_i = \mathbf{H}(t_i) - \mathbf{H}(t_0) = \begin{pmatrix} \Delta H_i^{(1)} \\ \Delta H_i^{(2)} \end{pmatrix}, \quad \zeta_{t_{ex}} = \begin{pmatrix} \zeta_{11} & \zeta_{12} \\ \zeta_{21} & \zeta_{22} \end{pmatrix}.$$

2.1.2 Approximate formula

Same as the one-factor case, the pricing formula of swaption can be written as

$$V_{rec}^{opt}(0) = L_0 E^{Q_L} [(K^{adj} - S(t_{ex}))^+],$$

where

$$L(t) = \sum_{i=1}^n \tau_i P(t, t_i)$$

($t \leq t_0$, $i = 1, \dots, n$) is the annuity numeraire, $S(t) = \frac{P(t, t_0) - P(t, t_n)}{\sum_{i=1}^n \tau_i P(t, t_i)}$ is the forward swap rate, and Q_L is the martingale measure associated with annuity numeraire. By the equivalent vol technique, we have (see Hagan [2], formula(3.66a))

$$\boxed{\sigma_N^2 t_{ex} = \mathbf{H}_{tot} \cdot \zeta \mathbf{H}_{tot}} \quad (13)$$

where

$$\mathbf{H}_{tot} = \frac{S(0) \sum_{i=1}^n \tau_i D_i \Delta \mathbf{H}_i + D_n \Delta \mathbf{H}_n}{\sum_{i=1}^n \tau_i D_i}$$

and $\Delta \mathbf{H}_i = \mathbf{H}_i - \mathbf{H}_0$. This allows us to obtain the swaption price by Black's formula with normal vol $\sigma_N = \sqrt{\frac{\mathbf{H}_{tot} \cdot \zeta t_{ex} \mathbf{H}_{tot}}{t_{ex}}}$:

$$\boxed{V_{rec}^{opt}(0) = L_0 \left[(K^{adj} - S(0)) \Phi(-d_1) + \frac{\sigma_N \sqrt{t_{ex}}}{\sqrt{2\pi}} e^{-d_1^2/2} \right]} \quad (14)$$

where $\Phi(\cdot)$ is the c.d.f. of standard normal distribution and $d_1 = \frac{S(0) - K^{adj}}{\sigma_N \sqrt{t_{ex}}}$.

2.2 Calibration to ATM swaption market

For a given sequence of expiries $t_{ex}^0 < t_{ex}^1 < \dots < t_{ex}^N$, we shall use the approximate formula (13) to obtain $\zeta(t_{ex}^i)$, $i = 1, \dots, N$. In the case of one-factor model, formula (13) alone is able to produce $\zeta_{t_{ex}}$; in the case of two-factor model, formula (13) is one equation for two unknowns (assuming α or σ is piecewise constant). So we typically need a sequence of swaptions to deduce $(\zeta_{t_{ex}^i})_{i=1}^N$ by bootstrapping.

More precisely, suppose the tenors are T_1, T_2, \dots, T_M . Formula (13) gives us

$$(\sigma_N^{ij})^2 t_{ex}^i - \mathbf{H}_{tot}^{ij} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{H}_{tot}^{ij} = \mathbf{H}_{tot}^{ij} \cdot (\zeta_{t_{ex}^i} - \zeta_{t_{ex}^{i-1}}) \mathbf{H}_{tot}^{ij},$$

where \mathbf{H}_{tot}^{ij} is the quantity similar to the one in formula (13) and corresponds to the $t_{ex}^i \times T^j$ swaption, and σ_N^{ij} is the normal vol for the $t_{ex}^i \times T^j$ swaption. Then $\zeta_{t_{ex}^i}$ is defined via α or σ (recall $\zeta_t = \int_0^t \alpha_s^2 ds = \int_0^t e^{2\kappa s} \sigma_s^2 ds$) such that

$$\sum_{j=1}^M \left\{ \mathbf{H}_{tot}^{ij} \cdot (\zeta_{t_{ex}^i} - \zeta_{t_{ex}^{i-1}}) \mathbf{H}_{tot}^{ij} - \left[(\sigma_N^{ij})^2 t_{ex}^i - \mathbf{H}_{tot}^{ij} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{H}_{tot}^{ij} \right] \right\}^2 \omega_{ij}^2$$

is minimized (assuming $\zeta_{t_{ex}^{i-1}}$ is already determined). Here $(\omega_{ij})_{0 \leq i \leq N, 1 \leq j \leq M}$ is a weight matrix. To represent ζ_t in terms of α or σ , we note for $s < t$,

$$\zeta_t - \zeta_s = \begin{cases} \begin{pmatrix} \alpha_1^2(t-s) & \rho \alpha_1 \alpha_2(t-s) \\ \rho \alpha_1 \alpha_2(t-s) & \alpha_2^2(t-s) \end{pmatrix} & \text{if } \alpha \text{ is constant in } [s, t] \\ \begin{pmatrix} \sigma_1^2 \frac{e^{-2\kappa_1 s} - e^{-2\kappa_1 t}}{2\kappa_1} & \rho \sigma_1 \sigma_2 \frac{e^{-(\kappa_1 + \kappa_2)s} - e^{-(\kappa_1 + \kappa_2)t}}{\kappa_1 + \kappa_2} \\ \rho \sigma_1 \sigma_2 \frac{e^{-(\kappa_1 + \kappa_2)s} - e^{-(\kappa_1 + \kappa_2)t}}{\kappa_1 + \kappa_2} & \sigma_2^2 \frac{e^{-2\kappa_2 s} - e^{-2\kappa_2 t}}{2\kappa_2} \end{pmatrix} & \text{if } \sigma \text{ is constant in } [s, t] \end{cases}$$

Then (recall $\mathbf{H}_{tot} = (H_{tot}^1, H_{tot}^2)$)

$$\begin{aligned} & \mathbf{H}_{tot} \cdot (\zeta_t - \zeta_s) \mathbf{H}_{tot} \\ &= (H_{tot}^1)^2 (\zeta_t - \zeta_s)_{11} + 2H_{tot}^1 H_{tot}^2 (\zeta_t - \zeta_s)_{12} + (H_{tot}^2)^2 (\zeta_t - \zeta_s)_{22} \\ &= \begin{cases} \left[(H_{tot}^1)^2 \alpha_1^2 + 2H_{tot}^1 H_{tot}^2 \rho \alpha_1 \alpha_2 + (H_{tot}^2)^2 \alpha_2^2 \right] (t-s) & \text{if } \alpha \text{ is constant in } [s, t] \\ (H_{tot}^1)^2 \frac{e^{-2\kappa_1 s} - e^{-2\kappa_1 t}}{2\kappa_1} \sigma_1^2 + 2\rho \Delta H_{tot}^1 H_{tot}^2 \frac{e^{-(\kappa_1 + \kappa_2)s} - e^{-(\kappa_1 + \kappa_2)t}}{\kappa_1 + \kappa_2} \sigma_1 \sigma_2 \\ + (H_{tot}^2)^2 \frac{e^{-2\kappa_2 s} - e^{-2\kappa_2 t}}{2\kappa_2} \sigma_2^2 & \text{if } \sigma \text{ is constant in } [s, t] \end{cases} \\ &= \begin{cases} \alpha \cdot \mathbf{A} \alpha & \text{if } \alpha \text{ is constant in } [s, t] \\ \sigma \cdot \mathbf{A} \sigma & \text{if } \sigma \text{ is constant in } [s, t] \end{cases} \end{aligned}$$

where $\alpha = (\alpha^1, \alpha^2)$, $\sigma = (\sigma_1, \sigma_2)$, and

$$\mathbf{A} = \begin{cases} \begin{pmatrix} (H_{tot}^1)^2 & \rho H_{tot}^1 H_{tot}^2 \\ \rho H_{tot}^1 H_{tot}^2 & (H_{tot}^2)^2 \end{pmatrix} (t-s) & \text{if } \alpha \text{ is constant in } [s, t] \\ \begin{pmatrix} (H_{tot}^1)^2 \frac{e^{-2\kappa_1 s} - e^{-2\kappa_1 t}}{2\kappa_1} & \rho H_{tot}^1 H_{tot}^2 \frac{e^{-(\kappa_1 + \kappa_2)s} - e^{-(\kappa_1 + \kappa_2)t}}{\kappa_1 + \kappa_2} \\ \rho H_{tot}^1 H_{tot}^2 \frac{e^{-(\kappa_1 + \kappa_2)s} - e^{-(\kappa_1 + \kappa_2)t}}{\kappa_1 + \kappa_2} & (H_{tot}^2)^2 \frac{e^{-2\kappa_2 s} - e^{-2\kappa_2 t}}{2\kappa_2} \end{pmatrix} & \text{if } \sigma \text{ is constant in } [s, t] \end{cases}$$

Therefore, the calibration problem is reformulated to the following optimization problem:

$$\begin{cases} \arg_{\alpha_i} \min \sum_{j=1}^M \left\{ \alpha_i \cdot \mathbf{A}^{ij} \alpha_i - \left[(\sigma_N^{ij})^2 t_{ex}^i - \mathbf{H}_{tot}^{ij} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{H}_{tot}^{ij} \right]^2 \omega_{ij}^2, (i = 1, \dots, N) \right\} & \text{if } \alpha \text{ is piecewise constant} \\ \arg_{\sigma_i} \min \sum_{j=1}^M \left\{ \sigma_i \cdot \mathbf{A}^{ij} \sigma_i - \left[(\sigma_N^{ij})^2 t_{ex}^i - \mathbf{H}_{tot}^{ij} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{H}_{tot}^{ij} \right]^2 \omega_{ij}^2, (i = 1, \dots, N) \right\} & \text{if } \sigma \text{ is piecewise constant} \end{cases} \quad (15)$$

where for the i -th optimization problem to be solved, the first $(i-1)$ optimization problems must be already solved.

2.3 Calibration to CMS spread option

The calibration of two-factor LGM model to CMS spread option is based on a sequence of swaptions and a sequence of CMS spread options.

More precisely, for a given sequence of expiries $t_{ex}^0 < t_{ex}^1 < \dots < t_{ex}^N$ and corresponding sequence of swap maturities T_1, T_2, \dots, T_N , formula (13) gives

$$(\sigma_N^i)^2 t_{ex}^i - \mathbf{H}_{tot}^i \cdot \zeta_{t_{ex}^{i-1}} \mathbf{H}_{tot}^i = \mathbf{H}_{tot}^i \cdot (\zeta_{t_{ex}^i} - \zeta_{t_{ex}^{i-1}}) \mathbf{H}_{tot}^i, \quad i = 1, \dots, N,$$

where σ_N^i is the normal vol for the $t_{ex}^i \times T_i$ swaption and \mathbf{H}_{tot}^i is the quantity similar to the one in formula (13) corresponding to the $t_{ex}^i \times T^i$ swaption.

Assuming $\zeta_{t_{ex}^1}, \dots, \zeta_{t_{ex}^{i-1}}$ have been given, to find out $\zeta_{t_{ex}^i}$, we repeat what's done in ATM calibration and write $\mathbf{H}_{tot}^i \cdot (\zeta_{t_{ex}^{i-1}} - \zeta_{t_{ex}^i}) \mathbf{H}_{tot}^i$ as

$$\mathbf{H}_{tot}^i \cdot (\zeta_{t_{ex}^i} - \zeta_{t_{ex}^{i-1}}) \mathbf{H}_{tot}^i = \begin{cases} \alpha \cdot \mathbf{A}_i \alpha & \text{if } \alpha \text{ is constant in } [t_{ex}^{i-1}, t_{ex}^i] \\ \sigma \cdot \mathbf{A}_i \sigma & \text{if } \sigma \text{ is constant in } [t_{ex}^{i-1}, t_{ex}^i] \end{cases}$$

We further parameterize \mathbf{A}_i by finding r_1, r_2, ϕ_0 such that

$$\frac{\mathbf{A}_i}{(\sigma_N^i)^2 t_{ex}^i - \mathbf{H}_{tot}^i \cdot \zeta_{t_{ex}^{i-1}} \mathbf{H}_{tot}^i} = \begin{pmatrix} \cos \phi_0 & -\sin \phi_0 \\ \sin \phi_0 & \cos \phi_0 \end{pmatrix} \begin{pmatrix} \frac{1}{r_1^2} & 0 \\ 0 & \frac{1}{r_2^2} \end{pmatrix} \begin{pmatrix} \cos \phi_0 & \sin \phi_0 \\ -\sin \phi_0 & \cos \phi_0 \end{pmatrix}$$

Then the first equation for $\zeta_{t_{ex}^i}$ is

$$1 = \begin{cases} \alpha \cdot \begin{pmatrix} \cos \phi_0 & -\sin \phi_0 \\ \sin \phi_0 & \cos \phi_0 \end{pmatrix} \begin{pmatrix} \frac{1}{r_1^2} & 0 \\ 0 & \frac{1}{r_2^2} \end{pmatrix} \begin{pmatrix} \cos \phi_0 & \sin \phi_0 \\ -\sin \phi_0 & \cos \phi_0 \end{pmatrix} \alpha & \text{if } \alpha \text{ is constant in } [t_{ex}^{i-1}, t_{ex}^i] \\ \sigma \cdot \begin{pmatrix} \cos \phi_0 & -\sin \phi_0 \\ \sin \phi_0 & \cos \phi_0 \end{pmatrix} \begin{pmatrix} \frac{1}{r_1^2} & 0 \\ 0 & \frac{1}{r_2^2} \end{pmatrix} \begin{pmatrix} \cos \phi_0 & \sin \phi_0 \\ -\sin \phi_0 & \cos \phi_0 \end{pmatrix} \sigma & \text{if } \sigma \text{ is constant in } [t_{ex}^{i-1}, t_{ex}^i] \end{cases}$$

For the second equation, consider an ATM CMS spread option with payoff

$$[S_1(t_{ex}^i) - S_2(t_{ex}^i) - K]^+$$

at time t_{ex}^i , where S_1 and S_2 are two swap rates, and $K = E^{Q_{t_{ex}^i}}[S_1(t_{ex}^i)] - E^{Q_{t_{ex}^i}}[S_2(t_{ex}^i)]$. The normal vol of $S_1(t_{ex}^i) - S_2(t_{ex}^i)$ can be quoted directly from market, while Hagan's formula gives the normal spread vol as

$$(\sigma_N^{sprd})^2 t_{ex}^i = (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2) \cdot \zeta_{t_{ex}^i} (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2),$$

where \mathbf{H}_{tot}^1 corresponds to S_1 and \mathbf{H}_{tot}^2 corresponds to S_2 . Matching σ_N^{sprd} with market quote will give us the second equation for $\zeta_{ex}^{t^i}$.

These two equations combined allow us to solve for $\zeta_{ex}^{t^i}$. More precisely, we use $x = (x_1, x_2)^T$ to stand for either α or σ . On the interval $[t_{ex}^{i-1}, t_{ex}^i]$ we have two equations for two unknowns:

$$\begin{cases} 1 = (x_1, x_2) \cdot \begin{pmatrix} \cos \phi_0 & -\sin \phi_0 \\ \sin \phi_0 & \cos \phi_0 \end{pmatrix} \begin{pmatrix} \frac{1}{r_1^2} & 0 \\ 0 & \frac{1}{r_2^2} \end{pmatrix} \begin{pmatrix} \cos \phi_0 & \sin \phi_0 \\ -\sin \phi_0 & \cos \phi_0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \\ (\sigma_N^{mkt})^2 t_{ex}^i = (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2) \cdot \zeta_{ex}^{t^i} (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2) \end{cases} \quad (16)$$

where σ_N^{mkt} is market quote of the normal spread vol and

$$\zeta_{ex}^{t^i} = \zeta_{ex}^{t_{ex}^{i-1}} + \begin{pmatrix} x_1 & 0 \\ 0 & x_2 \end{pmatrix} \mathbf{B} \begin{pmatrix} x_1 & 0 \\ 0 & x_2 \end{pmatrix}. \quad (17)$$

where

$$\mathbf{B} = \begin{cases} \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} (t_{ex}^i - t_{ex}^{i-1}) & \text{if } \alpha \text{ is constant in } [t_{ex}^{i-1}, t_{ex}^i] \\ \begin{pmatrix} \frac{e^{-2\kappa_1 t_{ex}^{i-1}} - e^{-2\kappa_1 t_{ex}^i}}{2\kappa_1} & \rho \frac{e^{-(\kappa_1 + \kappa_2) t_{ex}^{i-1}} - e^{-(\kappa_1 + \kappa_2) t_{ex}^i}}{2\kappa_2} \\ \rho \frac{e^{-(\kappa_1 + \kappa_2) t_{ex}^{i-1}} - e^{-(\kappa_1 + \kappa_2) t_{ex}^i}}{\kappa_1 + \kappa_2} & \frac{e^{-2\kappa_2 t_{ex}^{i-1}} - e^{-2\kappa_2 t_{ex}^i}}{2\kappa_2} \end{pmatrix} & \text{if } \sigma \text{ is constant in } [t_{ex}^{i-1}, t_{ex}^i] \end{cases}$$

We set the re-parametrization

$$\begin{cases} x_1 = r \cos \phi \\ x_2 = r \sin \phi \end{cases}$$

such that the first equation of system (16) becomes $1 = \frac{r^2 \cos^2(\phi - \phi_0)}{r_1^2} + \frac{r^2 \sin^2(\phi - \phi_0)}{r_2^2}$, or equivalently,

$$r = \frac{r_1 r_2}{\sqrt{r_2^2 \cos^2(\phi - \phi_0) + r_1^2 \sin^2(\phi - \phi_0)}}. \quad (18)$$

This allows us to use the following trial-and-error procedure to solve system (16):

Step 1. try a testing value of ϕ ;

Step 2. use formula (18) to obtain the value of r ;

Step 3. obtain the values of x_1 and x_2 by those of r and ϕ ;

Step 4. obtain $\zeta_{ex}^{t^i}$ by formula (17);

Step 5. use the RHS of the second equation of system (16) to obtain theoretical normal spread vol σ_N^{sprd} ;

Step 6. check the error $|\sigma_N^{sprd} - \sigma_N^{mkt}|$: if sufficiently small, stop; otherwise, return to Step 1 with a different value for ϕ .

The above procedure has the advantage of reducing problem's dimensionality. The cost is a complicated nonlinear equation of the unknown ϕ , such that it becomes hard to analyze the effectiveness of global Newton's method:

$$\frac{(\sigma_N^{mkt})^2 t_{ex}^i - (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2) \cdot \zeta_{ex}^{t_{ex}^{i-1}} (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2)}{r_1^2 r_2^2} = \frac{(\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2) \cdot \begin{pmatrix} \cos \phi & 0 \\ 0 & \sin \phi \end{pmatrix} \mathbf{B} \begin{pmatrix} \cos \phi & 0 \\ 0 & \sin \phi \end{pmatrix} (\mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2)}{r_2^2 \cos^2(\phi - \phi_0) + r_1^2 \sin^2(\phi - \phi_0)}$$

This equation can actually be simplified to give closed-form solution as follows. We define $\mathbf{h} = \mathbf{H}_{tot}^1 - \mathbf{H}_{tot}^2 = (h_1, h_2)^T$ and $\mathbf{Q} = \begin{pmatrix} h_1 & 0 \\ 0 & h_2 \end{pmatrix} \mathbf{B} \begin{pmatrix} h_1 & 0 \\ 0 & h_2 \end{pmatrix}$. Then the equation becomes

$$\frac{(\sigma_N^{mkt})^2 t_{ex}^i - \mathbf{h} \cdot \zeta_{ex}^{t_{ex}^{i-1}} \mathbf{h}}{r_1^2 r_2^2} = \frac{(\cos \phi \quad \sin \phi) \mathbf{Q} \begin{pmatrix} \cos \phi \\ \sin \phi \end{pmatrix}}{r_2^2 \cos^2(\phi - \phi_0) + r_1^2 \sin^2(\phi - \phi_0)} \quad (19)$$

To solve for ϕ , we set $C = (\sigma_N^{mkt})^2 t_{ex}^i - \mathbf{h} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{h}$, $\theta = \phi - \phi_0$, and

$$\begin{aligned}\hat{\mathbf{Q}} &= \begin{pmatrix} \cos \phi_0 & \sin \phi_0 \\ -\sin \phi_0 & \cos \phi_0 \end{pmatrix} \mathbf{Q} \begin{pmatrix} \cos \phi_0 & -\sin \phi_0 \\ \sin \phi_0 & \cos \phi_0 \end{pmatrix} \\ &= \begin{pmatrix} Q_{11} \cos^2 \phi_0 + Q_{22} \sin^2 \phi_0 + 2Q_{12} \sin \phi_0 \cos \phi_0 & (Q_{22} - Q_{11}) \sin \phi_0 \cos \phi_0 + Q_{12}(\cos^2 \phi_0 - \sin^2 \phi_0) \\ (Q_{22} - Q_{11}) \sin \phi_0 \cos \phi_0 + Q_{12}(\cos^2 \phi_0 - \sin^2 \phi_0) & Q_{11} \sin^2 \phi_0 + Q_{22} \cos^2 \phi_0 - 2Q_{12} \sin \phi_0 \cos \phi_0 \end{pmatrix}\end{aligned}$$

Then the equation (19) becomes

$$\sin(2\theta + \gamma) = \frac{C(r_1^2 + r_2^2) - r_1^2 r_2^2 (\hat{Q}_{11} + \hat{Q}_{22})}{\sqrt{[r_1^2 r_2^2 (\hat{Q}_{11} - \hat{Q}_{22}) - C(r_2^2 - r_1^2)]^2 + 4r_1^4 r_2^4 \hat{Q}_{12}^2}} \quad (20)$$

where γ is determined by

$$\begin{cases} \sin \gamma = \frac{r_1^2 r_2^2 (\hat{Q}_{11} - \hat{Q}_{22}) - C(r_2^2 - r_1^2)}{\sqrt{[r_1^2 r_2^2 (\hat{Q}_{11} - \hat{Q}_{22}) - C(r_2^2 - r_1^2)]^2 + 4r_1^4 r_2^4 \hat{Q}_{12}^2}} \\ \cos \gamma = \frac{2r_1^2 r_2^2 \hat{Q}_{12}}{\sqrt{[r_1^2 r_2^2 (\hat{Q}_{11} - \hat{Q}_{22}) - C(r_2^2 - r_1^2)]^2 + 4r_1^4 r_2^4 \hat{Q}_{12}^2}} \end{cases} \quad (21)$$

A necessary and sufficient for equation (20) to have a solution is

$$\left| C(r_1^2 + r_2^2) - r_1^2 r_2^2 (\hat{Q}_{11} + \hat{Q}_{22}) \right| \leq \sqrt{[r_1^2 r_2^2 (\hat{Q}_{11} - \hat{Q}_{22}) - C(r_2^2 - r_1^2)]^2 + 4r_1^4 r_2^4 \hat{Q}_{12}^2},$$

which is equivalent to an inequality for a quadratic polynomial of C . Tedious calculation shows the inequality can be reduced to $C_- \leq C \leq C_+$, where

$$C_{\pm} = \frac{r_1^2 \hat{Q}_{11} + r_2^2 \hat{Q}_{22}}{2} \pm \frac{\sqrt{r_1^4 \hat{Q}_{11}^2 + r_2^4 \hat{Q}_{22}^2 + 4r_1^2 r_2^2 \hat{Q}_{12}^2}}{2}.$$

Therefore, the necessary and sufficient condition for a successful calibration is

$$-\frac{\sqrt{r_1^4 \hat{Q}_{11}^2 + r_2^4 \hat{Q}_{22}^2 + 4r_1^2 r_2^2 \hat{Q}_{12}^2}}{2} \leq (\sigma_N^{mkt})^2 t_{ex}^i - \left[\mathbf{h} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{h} + \frac{r_1^2 \hat{Q}_{11} + r_2^2 \hat{Q}_{22}}{2} \right] \leq \frac{\sqrt{r_1^4 \hat{Q}_{11}^2 + r_2^4 \hat{Q}_{22}^2 + 4r_1^2 r_2^2 \hat{Q}_{12}^2}}{2}.$$

Simultaneously, we have discovered the follow procedure to solve system (16) explicitly:

Step 1: obtain the value of $C = (\sigma_N^{mkt})^2 t_{ex}^i - \mathbf{h} \cdot \zeta_{t_{ex}^{i-1}} \mathbf{h}$ by inserting the value of σ_N^{mkt} , and use it to compute the value of γ by equation (21);

Step 2: invert equation (20) to obtain the value of θ ;

Step 3: use the value of θ to obtain the value of $\phi = \theta + \phi_0$ and compute the value of r by formula (18);

Step 4: obtain the values of x_1 and x_2 : $x_1 = r \cos \phi$, $x_2 = r \sin \phi$;

Step 5: obtain $\zeta_{t_{ex}^i}$ by formula (17).

Remark 1. From Step 2, we shall have two representative solutions of θ , with the relation

$$\theta^{(1)} + \theta^{(2)} \mod \pi = \frac{\pi}{2}.$$

This leads to two representative solution pairs of (r, ϕ) with the relation

$$\begin{cases} \phi^{(1)} + \phi^{(2)} \mod \pi = \frac{\pi}{2} \\ r^{(1)} = \frac{r_1 r_2}{\sqrt{r_2^2 \cos^2 \theta^{(1)} + r_1^2 \sin^2 \theta^{(1)}}} = \frac{r_1 r_2}{\sqrt{r_2^2 \sin^2 \theta^{(2)} + r_1^2 \cos^2 \theta^{(2)}}} \\ r^{(2)} = \frac{r_1 r_2}{\sqrt{r_2^2 \cos^2 \theta^{(2)} + r_1^2 \sin^2 \theta^{(2)}}} = \frac{r_1 r_2}{\sqrt{r_2^2 \sin^2 \theta^{(1)} + r_1^2 \cos^2 \theta^{(1)}}} \end{cases}$$

A Summary of Girsanov's Theorem for continuous semimartingale

For sake of convenience, we record here a version of Girsanov's Theorem as presented in Revuz and Yor [?]. We will freely use jargons in the theory of continuous semimartingales.

Suppose $(\Omega, (\mathcal{F}_t)_{t \geq 0}, P)$ is a filtered probability space that satisfies the usual hypotheses. Q is another probability measure such that $Q|_{\mathcal{F}_t}$ is absolutely continuous with respect to $P|_{\mathcal{F}_t}$. We call D_t the Radon-Nikodym derivative of Q with respect to P on \mathcal{F}_t . These random variables $(D_t)_{t \geq 0}$ form a (\mathcal{F}_t, P) -martingale and can be chosen in such a way that it has cadlag path a.s..

Theorem A.1 (Girsanov's Theorem). *If D is continuous, every continuous (\mathcal{F}_t, P) -semimartingale is a continuous (\mathcal{F}_t, Q) -semimartingale. More precisely, if M is a continuous (\mathcal{F}_t, P) -local martingale, then*

$$\widetilde{M} = M - D^{-1} \cdot \langle M, D \rangle$$

is a continuous (\mathcal{F}_t, Q) -local martingale. Moreover, if N is another continuous P -local martingale,

$$\langle \widetilde{M}, \widetilde{N} \rangle = \langle \widetilde{M}, N \rangle = \langle M, N \rangle.$$

To apply Girsanov's Theorem more conveniently, we often use the following results.

Proposition A.1. *If D is a strictly positive continuous local martingale, there exists a unique continuous local martingale L such that*

$$D_t = \exp \left\{ L_t - \frac{1}{2} \langle L, L \rangle_t \right\} = \mathcal{E}(L)_t;$$

L is given by the formula

$$L_t = \log D_0 + \int_0^t D_s^{-1} dD_s.$$

Theorem A.2. *If $Q = \mathcal{E}(L) \cdot P$ and M is a continuous P -local martingale, then*

$$\widetilde{M} = M - D^{-1} \cdot \langle M, D \rangle = M - \langle M, L \rangle$$

is a continuous Q -local martingale. Moreover, $P = \mathcal{E}(-L)^{-1} \cdot Q = \mathcal{E}(-\widetilde{L}) \cdot Q$.

B Convexity adjustment of Libor rate

We denote by $F(t; t_s, t_e)$ the forward Libor rate over the period $[t_s, t_e]$

$$F(t; t_s, t_e) = \frac{1}{\tau} \left(\frac{P(t, t_s)}{P(t, t_e)} - 1 \right)$$

where τ is the year fraction of the period. Denote by t_f the rate's fixing time, which is typically two business days before t_s . For given payment time t_p ($\geq t_s$), we are concerned with computing

$$E_t^{t_p}[F(t_f; t_s, t_e)] = E_t^{t_p}[F(t_f; t_s, t_e)|\mathcal{F}_t],$$

where $E_t^{t_p}[\cdot|\mathcal{F}_t]$ is the conditional expectation under the t_p -forward measure.

We focus on computing $E_t^{t_p} \left[\frac{P(t_f, t_s)}{P(t_f, t_e)} \right]$. An \mathcal{F}_{t_f} -measurable payment of ξ at time t_p is equivalent to a payment of $P(t_f, t_p) \cdot \xi$ at time t_f ; we also would like to price under the martingale measure Q_N associated with the LGM numeraire N . By uniqueness of the arbitrage-free price, we have for any $t \leq t_f$

$$P(t, t_p) E_t^{t_p} \left[\frac{P(t_f, t_s)}{P(t_f, T_e)} \right] = P(t, t_f) E_t^{t_f} \left[P(t_f, t_p) \cdot \frac{P(t_f, t_s)}{P(t_f, T_e)} \right] = N_t E_t^{Q_N} \left[\frac{P(t_f, t_p)}{N_{t_f}} \cdot \frac{P(t_f, t_s)}{P(t_f, T_e)} \right]$$

which gives

$$E_t^{t_p} \left[\frac{P(t_f, t_s)}{P(t_f, t_e)} \right] = E_t^{Q_N} \left[\frac{\bar{P}(t_f, t_p)}{\bar{P}(t, t_p)} \cdot \frac{P(t_f, t_s)}{P(t_f, t_e)} \right]$$

Under Q_N , the state variable X_t is Gaussian with zero mean and variance ζ_t .

By formula (2), we have (note $X_{t_f} - X_t \perp \mathcal{F}_t$ and $X_{t_f} - X_t \sim \mathcal{N}(0, \zeta_{t_f} - \zeta_t)$)

$$\begin{aligned} & E_t^{Q_N} \left[\frac{\bar{P}(t_f, t_p)}{\bar{P}(t, t_p)} \cdot \frac{P(t_f, t_s)}{P(t_f, t_e)} \right] \\ = & E_t^{Q_N} \left[\frac{\bar{P}(t_f, t_p)}{\bar{P}(t, t_p)} \cdot \frac{\bar{P}(t_f, t_s)/\bar{P}(t, t_s)}{\bar{P}(t_f, t_e)/\bar{P}(t, t_e)} \cdot \frac{P(t, t_s)}{P(t, t_e)} \right] \\ = & \frac{P(t, t_s)}{P(t, t_e)} \cdot E_t^{Q_N} \left[\exp \left\{ -H(t_p)(X_{t_f} - X_t) - \frac{1}{2}H^2(t_p)(\zeta_{t_f} - \zeta_t) \right\} \cdot \right. \\ & \left. \exp \left\{ -[H(t_s) - H(t_e)](X_{t_f} - X_t) - \frac{1}{2}[H^2(t_s) - H^2(t_e)](\zeta_{t_f} - \zeta_t) \right\} \right] \\ = & \frac{P(t, t_s)}{P(t, t_e)} \cdot \exp \left\{ \frac{1}{2}[H(t_p) + H(t_s) - H(t_e)]^2(\zeta_{t_f} - \zeta_t) - \frac{1}{2}[H^2(t_p) + H^2(t_s) - H^2(t_e)](\zeta_{t_f} - \zeta_t) \right\} \\ = & \frac{P(t, t_s)}{P(t, t_e)} \exp \{ [H(t_e) - H(t_p)][H(t_e) - H(t_s)](\zeta_{t_f} - \zeta_t) \} \end{aligned}$$

Consequently, we have

$$\begin{aligned} E_t^{t_p} [F(t_f; t_s, t_e)] &= \frac{1}{\tau} \left(\frac{P(t, t_s)}{P(t, t_e)} \exp \{ [H(t_e) - H(t_p)][H(t_e) - H(t_s)](\zeta_{t_f} - \zeta_t) \} - 1 \right) \\ &= F(t; t_s, t_e) + \frac{1}{\tau} \frac{P(t, t_s)}{P(t, t_e)} [\exp \{ [H(t_e) - H(t_p)][H(t_e) - H(t_s)](\zeta_{t_f} - \zeta_t) \} - 1] \end{aligned}$$

and

$$\text{conv. adj.} = \frac{1}{\tau} \frac{P(t, t_s)}{P(t, t_e)} [\exp \{ [H(t_e) - H(t_p)][H(t_e) - H(t_s)](\zeta_{t_f} - \zeta_t) \} - 1]$$

C Convexity adjustment of CMS rate

Recall the forward swap rate S is defined as

$$S(t) = \frac{P(t, t_0) - P(t, t_n)}{\sum_{i=1}^n \tau_i P(t, t_i)}, \quad t \leq t_0$$

and the annuity numeraire (also called *level numeraire*) L is defined as

$$L(t) = \sum_{i=1}^n \tau_i P(t, t_i), \quad t \leq t_0.$$

Under the *level measure* Q_L associated with the level numeraire, we have

$$E_t^{t_e} [S(t_f)]$$

D Convexity adjustment of caplet

We denote by $V_{pay}(t)$ and $\bar{V}_{pay}(t)$ the values of a payer's swaption and a numeraire-discounted payer's swaption at time t , respectively. To begin with, we note

$$\begin{aligned} E_t^{t_p}[(F(t_f; t_s, t_e) - K)^+] &= \frac{1}{\tau} E_t^{t_p} \left[\frac{(P(t_f, t_s) - P(t_f, t_e) - K\tau P(t_f, t_e))^+}{P(t_f, t_e)} \right] \\ &= \frac{1}{\tau} E_t^{Q_N} \left[\frac{P(t_f, t_p)/P(t, t_p)}{N_{t_f}/N_t} \cdot \frac{\max\{V_{pay}(t_f; X_{t_f}), 0\}}{P(t_f, t_e)} \right] \\ &= \frac{1}{\tau} \frac{1}{\bar{P}(t, t_p)} E_t^{Q_N} \left[\frac{\bar{P}(t_f, t_p)}{\bar{P}(t_f, t_e)} \max\{\bar{V}_{pay}(t_f; X_{t_f}), 0\} \right] \end{aligned}$$

Since

$$\begin{aligned} \bar{V}_{pay}(t_f; X_{t_f}) &= \bar{P}(t_f, t_s; X_{t_f}) - \bar{P}(t_f, t_e; X_{t_f}) - K\tau \bar{P}(t_f, t_e; X_{t_f}) \\ &= P(0, t_s) \exp\{-H(t_s)X_{t_f} - \frac{1}{2}H^2(t_s)\zeta_{t_f}\} - (1 + K\tau)P(0, t_e) \exp\{-H(t_e)X_{t_f} - \frac{1}{2}H^2(t_e)\zeta_{t_f}\} \end{aligned}$$

we can find by an argument similar to that of formula (6) a unique $\hat{y}^* = \ln \left[\frac{(1+K\tau)P(0, t_e)}{P(0, t_s)} \right] - \frac{H(t_e)+H(t_s)}{2}\zeta_{t_f}$ such that

$$V_{pay}(t_f; y) \begin{cases} > 0 & \text{if } y > \hat{y}^* \\ = 0 & \text{if } y = \hat{y}^* \\ < 0 & \text{if } y < \hat{y}^* \end{cases}$$

Note $\hat{y}^* = y^* - H(t_s)\zeta_{t_f}$ where y^* is from formula (6). The discrepancy is because that formula (6) applied change-of-variable while we didn't (in order to preserve the neat term $V_{pay}(t_f; X_{t_f})$).

Consequently, we have

$$\begin{aligned} &E_t^{t_p}[(F(t_f; t_s, t_e) - K)^+] \\ &= \frac{1}{\tau} \frac{1}{\bar{P}(t, t_p)} E_t^{Q_N} \left[\frac{P(0, t_p)}{P(0, t_e)} \exp \left\{ -[H(t_p) - H(t_e)]X_{t_f} - \frac{1}{2}[H^2(t_p) - H^2(t_e)]\zeta_{t_f} \right\} \bar{V}_{pay}(t_f; X_{t_f}) 1_{\{X_{t_f} > \hat{y}^*\}} \right] \end{aligned}$$

To prepare for the next step computation, we compute $E[e^{-uX} 1_{\{X > x_0\}}]$ for $X \sim \mathcal{N}(0, \sigma^2)$:

$$E[e^{-uX} 1_{\{X > x_0\}}] = \int_{x_0}^{\infty} \frac{e^{-\frac{x^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} e^{-ux} dx = e^{\frac{1}{2}u^2\sigma^2} \cdot \int_{x_0}^{\infty} \frac{e^{-\frac{(x+u\sigma^2)^2}{2\sigma^2}}}{\sqrt{2\pi}\sigma} dx = e^{\frac{1}{2}u^2\sigma^2} \Phi \left(-\frac{x_0 + u\sigma^2}{\sigma} \right).$$

Then

$$E_t^{Q_N} \left[\exp \left\{ -[H(t_p) - H(t_e)]X_{t_f} \right\} \bar{V}_{pay}(t_f; X_{t_f}) 1_{\{X_{t_f} > \hat{y}^*\}} \right] = \text{I} - \text{II}$$

where

$$\begin{cases} \text{I} = E_t^{Q_N} \left[\exp \left\{ -[H(t_p) - H(t_e)]X_{t_f} \right\} P(0, t_s) \exp\{-H(t_s)X_{t_f} - \frac{1}{2}H^2(t_s)\zeta_{t_f}\} 1_{\{X_{t_f} > \hat{y}^*\}} \right] \\ \text{II} = E_t^{Q_N} \left[\exp \left\{ -[H(t_p) - H(t_e)]X_{t_f} \right\} (1 + K\tau)P(0, t_e) \exp\{-H(t_e)X_{t_f} - \frac{1}{2}H^2(t_e)\zeta_{t_f}\} 1_{\{X_{t_f} > \hat{y}^*\}} \right] \end{cases}$$

and we have

$$\begin{aligned} \text{I} &= P(0, t_s) \exp \left\{ -[H(t_p) - H(t_e) + H(t_s)]X_t - \frac{1}{2}H^2(t_s)\zeta_{t_f} \right\} \\ &\quad \cdot E_t^{Q_N} \left[\exp \left\{ -[H(t_p) - H(t_e) + H(t_s)](X_{t_f} - X_t) \right\} 1_{\{X_{t_f} - X_t > \hat{y}^* - X_t\}} \right] \\ &= P(0, t_s) \exp \left\{ -[H(t_p) - H(t_e) + H(t_s)]X_t - \frac{1}{2}H^2(t_s)\zeta_{t_f} \right\} \\ &\quad \cdot \exp \left\{ \frac{1}{2}[H(t_p) - H(t_e) + H(t_s)]^2(\zeta_{t_f} - \zeta_t) \right\} \Phi \left(-\frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} - [H(t_p) - H(t_e) + H(t_s)]\sqrt{\zeta_{t_f} - \zeta_t} \right) \end{aligned}$$

and

$$\begin{aligned}
\mathbb{I} &= (1 + K\tau)P(0, t_e) \exp \left\{ -H(t_p)X_t - \frac{1}{2}H^2(t_e)\zeta_{t_f} \right\} E_t^{Q_N} \left[\exp \left\{ -H(t_p)(X_{t_f} - X_t) 1_{\{X_{t_f} - X_t > \hat{y}^* - X_t\}} \right\} \right] \\
&= (1 + K\tau)P(0, t_e) \exp \left\{ -H(t_p)X_t - \frac{1}{2}H^2(t_e)\zeta_{t_f} \right\} \\
&\quad \cdot \exp \left\{ \frac{1}{2}H^2(t_p)(\zeta_{t_f} - \zeta_t) \right\} \Phi \left(-\frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} - H(t_p)\sqrt{\zeta_{t_f} - \zeta_t} \right)
\end{aligned}$$

Therefore

$$\begin{aligned}
&E_t^{t_p}[(F(t_f; t_s, t_e) - K)^+] \\
&= \frac{1}{\tau} \frac{P(t, t_s)}{P(t, t_e)} e^{[H(t_e) - H(t_p)][H(t_e) - H(t_s)](\zeta_{t_f} - \zeta_t)} \Phi \left(-\frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} - [H(t_p) - H(t_e) + H(t_s)]\sqrt{\zeta_{t_f} - \zeta_t} \right) \\
&\quad - \frac{1 + K\tau}{\tau} \Phi \left(-\frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} - H(t_p)\sqrt{\zeta_{t_f} - \zeta_t} \right)
\end{aligned}$$

In particular, we have

$$\begin{aligned}
&E_t^{t_e}[(F(t_f; t_s, t_e) - K)^+] \\
&= \frac{1}{\tau} \frac{P(t, t_s)}{P(t, t_e)} \Phi \left(-\frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} - H(t_s)\sqrt{\zeta_{t_f} - \zeta_t} \right) - \frac{1 + K\tau}{\tau} \Phi \left(-\frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} - H(t_e)\sqrt{\zeta_{t_f} - \zeta_t} \right)
\end{aligned}$$

This gives us the convexity adjustment

$$\begin{aligned}
&\text{conv. adj.} \\
&= E_t^{t_p}[(F(t_f; t_s, t_e) - K)^+] - E_t^{t_e}[(F(t_f; t_s, t_e) - K)^+] \\
&= \frac{P(t, t_s)}{\tau P(t, t_e)} \left\{ e^{[H(t_e) - H(t_p)][H(t_e) - H(t_s)]\Delta\zeta} \Phi \left(-\lambda - [H(t_p) - H(t_e) + H(t_s)]\sqrt{\Delta\zeta} \right) - \Phi \left(-\lambda - H(t_s)\sqrt{\Delta\zeta} \right) \right\} \\
&\quad - \frac{1 + K\tau}{\tau} \left[\Phi \left(-\lambda - H(t_p)\sqrt{\Delta\zeta} \right) - \Phi \left(-\lambda - H(t_e)\sqrt{\Delta\zeta} \right) \right]
\end{aligned}$$

where

$$\begin{cases} \Delta\zeta = \zeta_{t_f} - \zeta_t \\ \lambda = \frac{\hat{y}^* - X_t}{\sqrt{\zeta_{t_f} - \zeta_t}} \end{cases}$$

E Convexity adjustment of CMS caplet

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