

Task 4: Operational Amplifier

Discrete Amplifier

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Abstract

The design, simulation, and construction of experiments to measure the performance of an operation amplifier is explored. The operational amplifier consists of 4 discrete stages: a resistively loaded differential pair, an actively loaded differential pair, a common source amplifier, and finally a Bipolar Junction Transistor amplifier. The operational amplifier was designed to operate with a bias current of $400\mu\text{A}$. The common mode rejection ratio, input common mode voltage range and differential gain will be measured. FINAL VALUES HERE.

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Contents

1	Introduction	1
2	Circuit Development	2
2.1	Resistively Loaded Differential Amplifier	3
2.2	Active Load Differential Pair	5
2.3	Common Source Amplifier	6
2.4	Output Stage	8
3	Experimental Implementation	11
4	Discussion	11
5	Conclusion	12

List of Figures

1	General operational amplifier symbol [1]	1
2	Generic schematic for chosen topology [2]	2
3	Simulated op amp circuit	3
4	Typical ALD bias conditions [3]	3
5	Simulated resistive load differential amplifier	4
6	Simulated resistive load differential gain	4
7	Simulated resistive load differential phase	5
8	Simulated active load differential amplifier	5
9	Simulated active load differential gain	6
10	Simulated active load differential phase	6
11	Simulated common source amplifier	7
12	Simulated common source amplifier gain	7
13	Simulated common source amplifier phase	8
14	Simulated output stage gain	9
15	Simulated output stage phase	9
16	Simulated overall gain	10
17	Simulated overall phase	10

1 Introduction

This report describes the design, construction, and analysis of an discrete component operational amplifier. The topology chosen includes a simple current mirror that sinks current to a resistively loaded amplifier which in turn is cascaded with an actively loaded differential pair which outputs single-endedly to a common source amplifier stage. This common source stage is then passed to an output Bipolar Junction Transistor (BJT) amplifier stage. The general schematic for a generic op amp is shown in Figure 1.

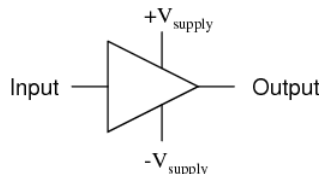


Figure 1: General operational amplifier symbol [1]
[1]

Operation amplifiers serve an integral building block for modern electronics. Op amps provide large gain with various configuration schema. This allows the circuit designer to use the op amp in different topologies and achieve different results, all without modifying the op amp circuit itself. In addition, an op amp provides significant gain while maintaining stability. The objective of this lab is to create an op amp out of discrete components that achieves the specifications as seen in Table 1.

Table 1: Specifications

Specifications	
Power	$\pm 5V$
Bias Current	$500 \mu A$
Overall Voltage Gain	$200V/V$ (46 dB)
CMRR	$\geq 60dB$
Output Voltage Swing	$\geq \pm 2V$

The input stage of an operational amplifier consists of a differential amplifier. For the purposes of this experiment, the NMOS MOSFET that will be used is the ALD1106, and the ALD1107 for the PMOS MOSFET. Differential amplifiers are desirable for their increased immunity to noise and that DC coupling of stages is possible without disturbing bias conditions. Each one of these designs will have some advantage as well as some disadvantage over the other circuits. The primary function of the input differential pair will be to provide a high common mode rejection ratio (CMRR). The differential gain, A_d , need not be high, as long as the common mode gain, A_{cm} , is very small. Some op-amp designs use multiple differential input-differential output stages until they convert to a single ended input.

These differential amplifiers are biased by a current mirror, cascoded or simple, (assumed to be ideal for simulations) and constructed using PMOS and NMOS integrated circuits. The circuit on the left is a resistively loaded differential amplifier. The circuit depicted on the right is an actively loaded differential amplifier.

Section 2 of this report describes the design, and when relevant, the simulations of the experiments. Experimental results and implementation are addressed in Section 3. A discussion of the results, sources of

error, and areas of possible improvement are outlined in Section 4. Section 5 concludes this report.

2 Circuit Development

Three different op amp topologies were provided as part of the lab. The chosen circuit can be seen in can be seen in Figure 2.

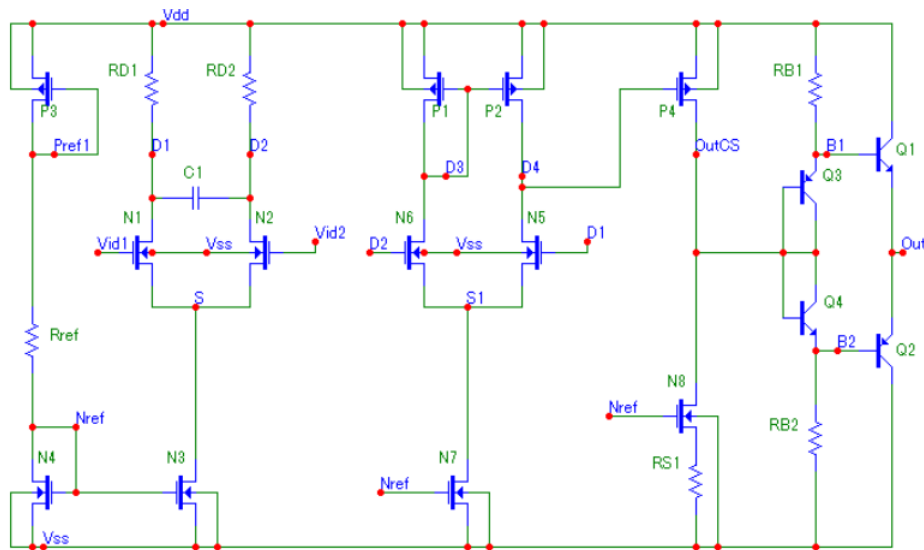


Figure 2: Generic schematic for chosen topology [2]

This design was chosen due to the fact that every stage, with the exclusion of the output stage, was designed as part of a previous task. The stages can be broken down as such: a simple current mirror, a resistively loaded differential pair, an active loaded differential pair, an active load common source amplifier and finally a BJT amplifier output stage. The final simulated circuit can be seen in Figure 3.

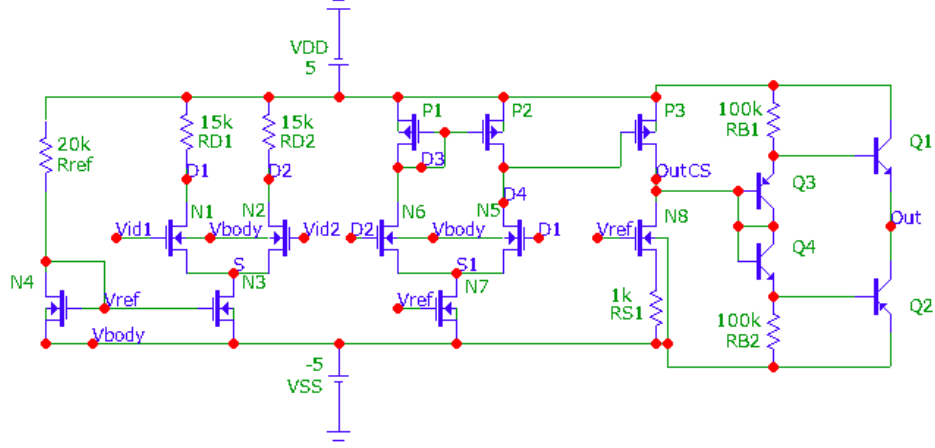


Figure 3: Simulated op amp circuit

The circuits will be simulated in MicroCap 11. The values for the components will initially be the values calculated in circuit development. The generic bias conditions for the ALD1106 and 1107 are summarized in Table 4.

I_{DS}	ALD1106				ALD1107			
	V_{OV}	V_{GS}	g_m	r_o	$ V_{OV} $	V_{GS}	g_m	r_o
100 μA	0.63	1.43	3.16E-04	333 k Ω	1.00	-1.80	2.00E-04	333 k Ω
200 μA	0.89	1.69	4.47E-04	167 k Ω	1.41	-2.21	2.83E-04	167 k Ω
400 μA	1.26	2.06	6.32E-04	83.3 k Ω	2.00	-2.80	4.00E-04	83.3 k Ω
500 μA	1.41	2.21	7.07E-04	66.7 k Ω	2.24	-3.04	4.47E-04	66.7 k Ω
1 mA	2.00	2.80	1.00E-03	33.3 k Ω	3.16	-3.96	6.32E-04	33.3 k Ω
2 mA	2.83	3.63	1.41E-03	16.7 k Ω	4.47	-5.27	8.94E-04	16.7 k Ω

Figure 4: Typical ALD bias conditions [3]

Here the typical bias conditions for the constraining MOSFETs can be seen. For the purposes of this lab, the bias current of 400 μA was chosen.

2.1 Resistively Loaded Differential Amplifier

The resistively loaded amplifier stage requires a current mirror in order to generate the chosen bias current of 400 μA . This was achieved by applying Ohm's Law. The V_{GS} of the simple current mirror needs to be -3V. In order to have the correct current R_{ref} was set to 20k Ω . The simulated resistive load differential pair can be seen in Figure 5.

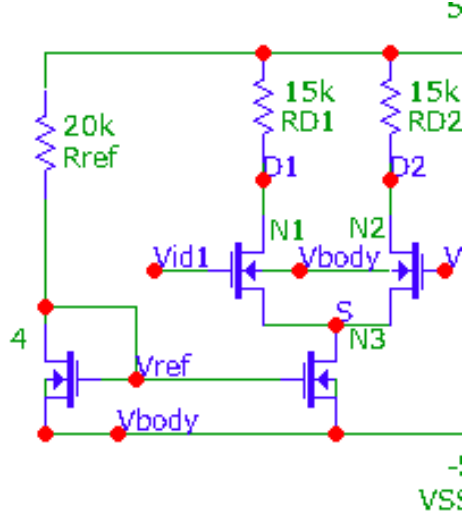


Figure 5: Simulated resistive load differential amplifier

In addition, the current through the load resistors needs to be half of the bias current. As a result, the resistance values can be found by applying KVL which can be seen in Equation ??

$$V_{o1} = V_{DD} - \frac{1}{2}I_{bias}R_d, \quad (1)$$

where V_{DD} is the supply voltage. This leads to R_{drain} of 15k Ω . The differential gain of the circuit can be found by Equation 2

$$A_d = g_m R_d, \quad (2)$$

where g_m is the transconductance of the amplifying NMOS and R_d is the drain resistance and was calculated to be 16 dB. The output is double ended due to it feeding another amplifier stage. The simulated gain can be seen in Figure 6.

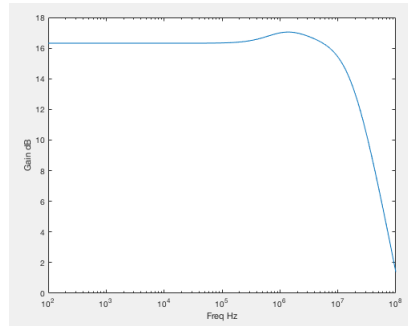


Figure 6: Simulated resistive load differential gain

This was measured by performing an AC analysis in Microcap from 100Hz to 1MHz. This was performed

by grounding one of the inputs whilst measuring the voltage differentially from the output nodes. The simulated value was marginally higher at 16.2 dB. The simulated phase can be seen in Figure 7.

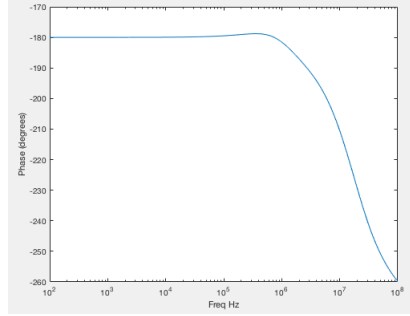


Figure 7: Simulated resistive load differential phase

The phase can be seen to be 180 degrees stable until 1 MHz. This is desirable for an input stage, which is why the differential pair was chosen as the first stage. This stage was then cascaded with an active load differential pair.

2.2 Active Load Differential Pair

The next stage of op amp is the active load differential pair. This circuit is identical to that designed in Task 3. This circuit can be seen in Figure 8. This modification allows for the single ended output to achieve gain that is comparable to that of the active load with a double ended output.

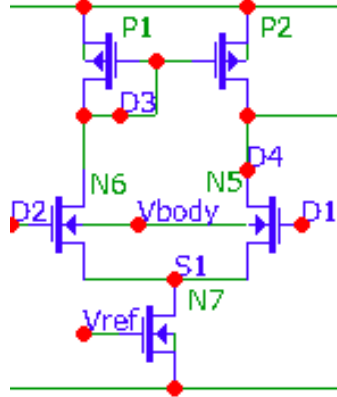


Figure 8: Simulated active load differential amplifier

The differential gain for an actively loaded differential pair can be seen with Equation ??

$$A_d = g_{m_N}(r_{o_P} || r_{o_N}), \quad (3)$$

where r_o is the small signal output resistance of a MOSFET which is found by the Equation ??

$$r_o = \frac{1}{\lambda I_{DS}}, \quad (4)$$

where λ is the channel length modulation parameter. The output resistance for NMOS is found to be $172\text{k}\Omega$ and PMOS is found to be $162\text{k}\Omega$. The differential gain was calculated to be 35 dB. The simulated differential gain for the active load can be seen in Figure 9.

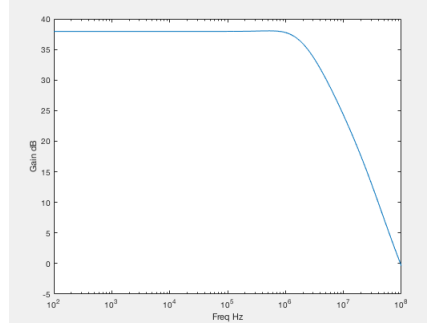


Figure 9: Simulated active load differential gain

This simulation was performed in the same manner as the resistive load. The differential gain is found to be much higher than resistive load at 38 dB and consistent with the calculated value of 35 dB. The phase of the active load can be seen in Figure 10.

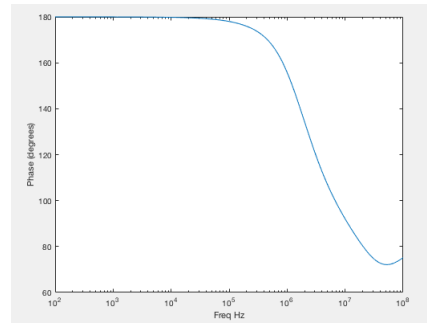


Figure 10: Simulated active load differential phase

This stage can be seen to only be 180 degree stable until 100 kHz. This is the minimum required by the lab specifications. This stage is then passed to an active loaded common source stage.

2.3 Common Source Amplifier

The common source amplifier features an active load which serves as a biasing network. The common source allows for the output loading effects of the active load to be ignored due to the near infinite input

impedence seen at the gate of the common source. The simulated circuit can be seen in Figure 11.

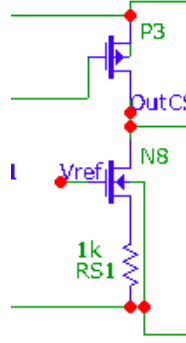


Figure 11: Simulated common source amplifier

The voltage gain of a common source amplifier can be expressed in Equation 5

$$A_{vo} = -\frac{g_m R_d}{1 + g_m R_s}, \quad (5)$$

where R_s is the resistance seen at the source of the amplifying transistor which in this case is the r_o of the active load. The gain can be calculated to be 23 dB. The active load features source degeneration, this resistor value should be large enough to ensure that with grounded inputs the common source output node is 0V. The resistor that achieved this is 1 k Ω . The simulated gain can be seen in Figure 12.

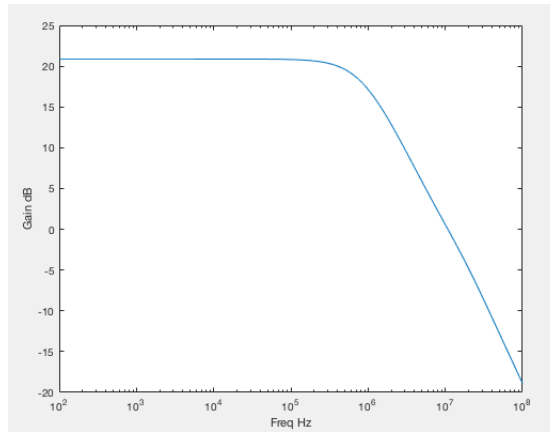


Figure 12: Simulated common source amplifier gain

The gain is slightly less than the calculated 23 dB at 20.5 dB. The phase the common source stage can be seen in Figure 13.

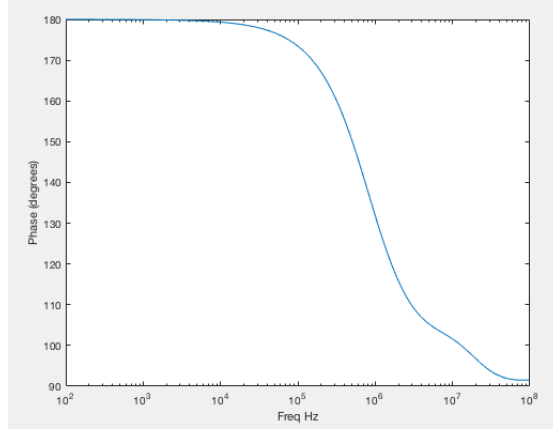


Figure 13: Simulated common source amplifier phase

The common source, similar to that of the active load, is 180 degree stable until 100 kHz. The common source is then fed to an output stage. The output stage will be covered in more detail in a later task. For the purposes of this lab the output stage can be treated as an emitter follower.

2.4 Output Stage

Due to the design of this stage is mostly beyond the scope of this task, the largest design consideration was choosing resistors values great enough to ensure that the base emitter voltages of remain less than 0.7V. These values were changed in Microcap until the correct bias conditions were found. The resistor values were found to be 100 k Ω . The output gain can be expressed through Equation 6

$$A_{vo} = \frac{g_m R_E}{g_m R_E + 1}, \quad (6)$$

where R_E is the resistance seen at the emitter of the BJT and g_m is the transconductance on the BJT. The gain can be calculated to be 0.96 V/V. The simulated gain can be seen in Figure 14.

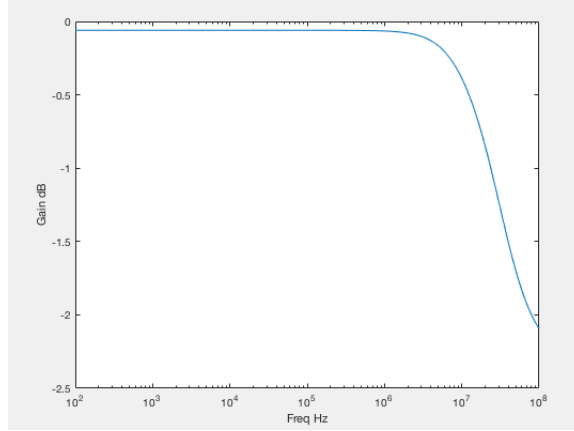


Figure 14: Simulated output stage gain

The gain can be seen to be a little less than one, this is expected by the emitter follower nature of the stage. The Ideal emitter follower has a voltage gain of 1 V/V. The simulated phase can be seen in Figure 15.

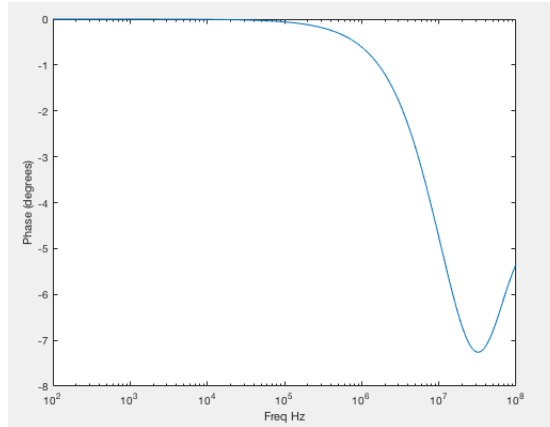


Figure 15: Simulated output stage phase

The output stage remains 180 degree stable until 1 MHz, which is a decade higher than the previous two stages. The overall gain of the circuit can be seen in Figure 16.

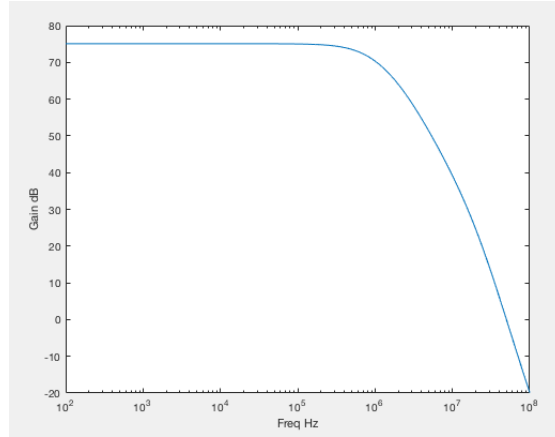


Figure 16: Simulated overall gain

The gain can be seen to be much greater than the required 46 dB at 75 dB. Care is necessary when building this circuit as very little input could result in a railed output. The final phase can be seen in Figure 17.

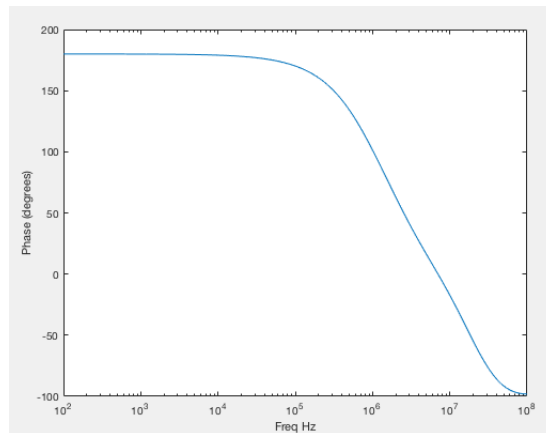


Figure 17: Simulated overall phase

The final output can be seen to be 180 degree stable until 100 kHz, which is required by the specifications. The DC bias conditions measured in Microcap can be seen in Table 2.

Table 2: DC bias values

Simulated Values	
Vref	-3.003V
D1	1.284V
D2	1.284V
D3	2.78V
D4	2.78V
S	.972V
S1	-1.34V
OutCS	-82mV
Out	-11.4mV
A_d First Stage	16.2 dB
A_d Second Stage	38 dB
A_{vo} Common source	20.5 dB
A_{vo} Output Stage	-.1 dB
A_d Final	75dB

The DC bias conditions match that of this found in previous tasks. Notably the output of both the CS and final stage is not 0V. This is due to body effect and channel length modulation effects, this voltage is known as the offset voltage.

3 Experimental Implementation

This section details the experimental implementation of the two differential amplifiers, the resistively loaded and active loaded. The power supplies and analysis were implemented using the Digilent Analog Discovery kit.

NOTE TO TA: The circuit stopped working during the final stages of testing over the weekend. As a result we currently have no graphs to put here as all attempts to rebuild have continued to lead to inoperable circuits. Apologies – Lab group #9.

4 Discussion

This lab served as the culmination of all prior tasks. The operation amplifier includes a current mirror, both types of differential pairs active and resistive as well as a common source amplifier. The final values can be seen in Table 3 below.

Table 3: Final values for operational amplifier

Operational Amplifier Results		
Components/Nodes	Simulated	Experimental
V_{ref}	-3.03 V	??
I_{bias}	400 μ A	?? μ A
R_{ref}	20k Ω	??
R_{D1}	15k Ω	??
R_{D2}	15k Ω	??
Ad	75 dB	??

The final circuit is still in a state of needing modifications. FINAL STUFF GOES HERE ONCE CIRCUIT IS WORKING.

5 Conclusion

The design, simulation, and construction of experiments to measure the performance of an operational amplifier was explored. The amplifier consisted of four discrete stages, a resistively loaded differential pair, and active load differential pair, a common source amplifier, and a BJT output stage. This circuit will serve as the foundation for the final design of the operational amplifier in task 6. The operational amplifier still requires frequency compensation in order to maintain stability. FINAL VALUES HERE. An important lesson learned during this lab was that simply achieving a high gain is not enough for a circuit to be considered operational. Whether or not the op amp is stable is as important as the final gain value.

References

- [1] All About Circuits. (2018) Single-ended differential amplifiers [Online]:
<https://www.allaboutcircuits.com/textbook/semiconductors/chpt-8/single-ended-differential-amplifiers/>
- [2] N. W. Emanatoglu. (2018) Task 4 [Online]
- [3] N. W. Emanatoglu. (2018) Task 4 briefing [Online]