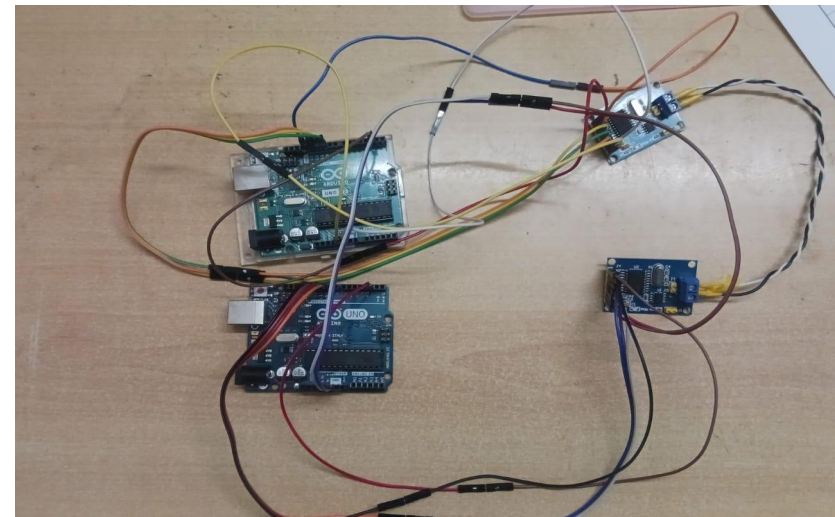
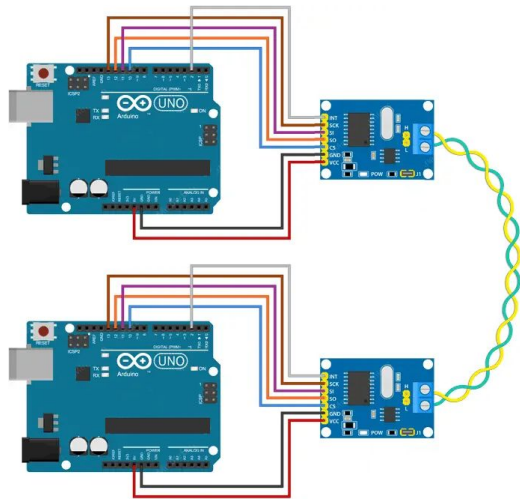


CAN Network Creation

Controller Area Network (CAN bus) is a communications standard designed to allow in-vehicle devices to communicate with each other without a host computer.

Project aims at creating CAN network using MCP2515 module. Two created nodes are made to communicate using CAN protocol. Implementation is done using Arduino using a open source MCP2515 library.



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