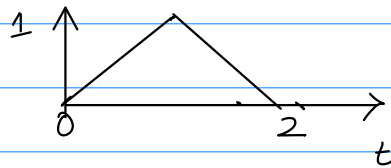


Representation / simulation of signals and systems in Matlab

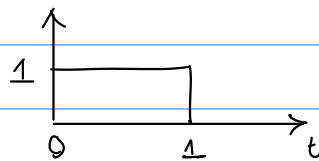
- ① Draw the function $\sin(11t)$ for $t \in [0.01, 0.1]$ by hand (make a rough plot). This is just so that you have a baseline to compare your results with. Make a plot of $\sin(11t)$ vs t in Matlab - your function should match the expected plot that you have drawn by hand before. How did you choose to represent $\sin(11t)$? What was the sampling period.

- ② Suppose you are given an LTI system with impulse response $h(t)$ as shown.



You have to write a Matlab function that will take an appropriately sampled version x_n of a c.t. signal $x(t)$ as an input argument and compute an approximation y_n of the output signal $y(t) = x(t) * h(t)$.

Test your function with $x(t) =$



Does the function give an output y_n that matches with the $y(t)$ that you obtain by doing the convolution by hand?

- ③ Find out whether convolution satisfies the property

$$\begin{aligned} \text{i.e. if } y(t) &= (x_1(t) + x_2(t)) * h(t) \\ &= x_1(t) * h(t) + x_2(t) * h(t). \end{aligned}$$

Suppose I have an extremely long duration signal $x(t)$ which needs to be filtered by a LTI sys. with a short duration impulse response $h(t)$. Can the above property be put to any use in this situation. If so, how?