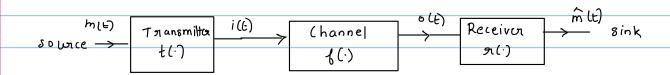
> time

Lecture 3

Review of lectures 1 & 2



Design
$$t(\cdot)$$
 and $s(\cdot)$
such that $e(m(t), \hat{m}(t)) \leq \varepsilon$.
given $f(\cdot)$

Objectives for lecture 3

- understand channel modelling on what is f()? how to find f()? etc...
- LTI system models for channels.
- Let us take an example to understand channel modelling.

Consider a channel with the following I and O (necall: LEEI, OCE) & O).

I = 0 = set of all DC signals.

so a i(E) would be a; o(E):

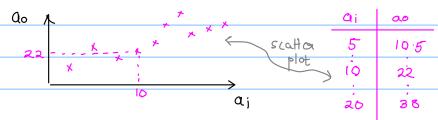
we have a channel that gives o(t) = f(i(t)).

* How do we get f() for this channel?

we need to fit a model f() to this channel - fit a model to data collected about the channel.

for this changel, we can look at at find

collect data about the channel - i.e., for an ai what is ao.

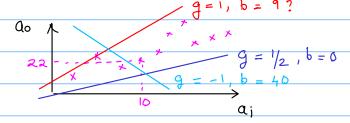


What is the nelationship f() that best fits this datu?

We do not really know what f() is / would be correct! Step 1 so we assume a form/structure for f().

For example, we could have i) f(ai) = g x ai (g: gain term, a linear model) 2) f(ai) = g x ai + b (b: bias, an affine model) 3) f(ai) = 9, ai2 + go ai + b.

We will choose a form for fire - e.g gai +b. (g and b are parameters) Step 2 Proceed to find for what g and b, we can best explain the data (ai, ao)



In onder to decide this g and b we will woully solve an optimization problem where we try to minimize the enror between what our model fi) predicts for the ai-s (which is f(ai)) and the actual data which is ao

ai ao

Let the
$$k^{k}$$
 data be denoted as $a_{i,k}$ and $a_{0,k}$

5 10.5

Then the craon is defined as

10 22

 \vdots \vdots $\bigg(a_{0,k} - f(a_{i,k})\bigg)^{2}$.

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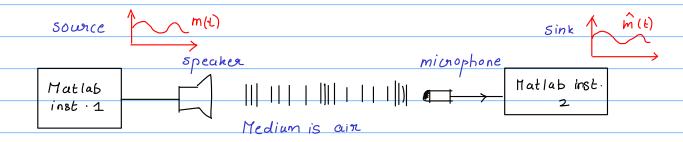
we find that g and b which minimizes \(\sum_{\nu} (ao, \nu - f(ai, \nu))^2\)

This is for the example of the channel considered here. But this is a common technique. An important point is that there is no night model for a channel (or anything for that malter, there are only better and better approximations)

We can think of the actual channel as a Gansformation factual. The model f() that we have is only an approximation to this.

Also note that nelated subjects like RF and prwave will use other models for the channel.

· Let us now consider a more complicated example



how to find f() for the above channel?

bounded

I and D are now not sets of scalars, but they are sets containing functions.

recall that we first need some form on structure for f() and then we need to fit
f() with the specified staucture to the data that we collect.

- What age structures / forms for f()?
- What data should we collect?
- How do we fit f() to the data?

Structures / Forms for f(): (signals and systems review)

- memony less with memony
- linear/non-linear
- causal / non-causal
- time invariant/ variant

Because we are comfortable with LTI systems, let us assume that the form for $f(\cdot)$ is that it is an LTI system. It $f(\cdot)$ is an LTI system, how do we find $f(\cdot)$?

Recall the following points regarding LTI syptems

- Superposition and homogenisty properties
- time invariance
- every LTI system is characterized by its impulse response. (denoted as h(t)).

- If we know h(t) then we can predict o(t) for any input i(t) as $o(t) = \int_{-\infty}^{\infty} i(\tau) \cdot h(t-\tau) d\tau$
- Assume that h(t) is finite energy, i.e., \int h(t)|2 dt < A
- Assume that h(t)'s (TFT (spectrum) exists, i.e., $H(t) = \int_{-\infty}^{\infty} h(t) e^{-j2\pi ft} dt$
- Then finding H(f) is equivalent to finding the Channel model.
- Note that H(f) is complex, and the magnitude and phase spectra need to be specified, in order that the LTI system is completely specified.
- so we need to find H(f) when we consider LTI system models for channels.