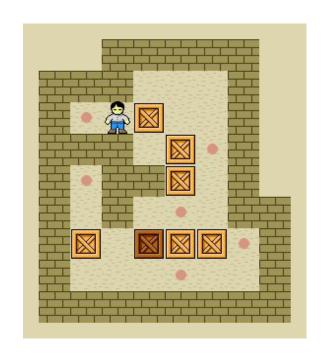
A Tabled Prolog Program for Solving Sokoban

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Problema: Sokoban

- Levar cada caixa para a devida posição
- Menor quantidade de movimentos
- Evitar repetições e loops
- Deadlocks



Algoritmo

- B-Prolog
- Utiliza tabelamento para armazenar caminhos
- Simplificação do problema a problema de menor caminho
- Objetivos se dividem em dois
- Alto uso de memória
- Velocidade

```
:-table plan sokoban(+,+,-,min).
                                                                                :-table neib/3.
plan sokoban( SokobanLoc, BoxLocs, Plan, Len): -
                                                                                neib(Loc1,Loc2,up):-
    goal reached (BoxLocs), !,
                                                                                    top(Loc1,Loc2).
    Plan=[],Len=0.
                                                                                neib(Loc1,Loc2,down): -
plan sokoban(SokobanLoc, BoxLocs, [push(BoxLoc, Dir, DestLoc) | Plan], Len):-
                                                                                    top(Loc2,Loc1).
    select (BoxLoc, BoxLocs, BoxLocsl),
                                                                                neib(Loc1,Loc2, right) :-
    neib (PrevNeibLoc, BoxLoc, Dir),
                                                                                    right (Loc1, Loc2).
    \+ member(PrevNeibLoc, BoxLocsl).
                                                                                neib(Loc1,Loc2,left):-
    neib (BoxLoc, NextNeibLoc, Dir) .
                                                                                    right (Loc2, Loc1).
    good dest(NextNeibLoc, BoxLocsl),
    reachable by sokoban(SokobanLoc, PrevNeibLoc, BoxLocs),
                                                                                goal reached([]).
    choose dest (BoxLoc, NextNeibLoc, Dir, DestLoc, NewSokobanLoc, BoxLocsl),
                                                                                goal reached ([Loc Locs]):-
    insert ordered(DestLoc, BoxLocsl, NewBoxLocs),
                                                                                    storage(Loc),
    plan sokoban (NewSokobanLoc, NewBoxLocs, Plan, Len1),
                                                                                    goal reached (Locs) .
    Len is Len1+1.
                                                                                :-table corner/1.
:-table reachable by sokoban/3.
                                                                                corner(X):-
reachable by sokoban (Loc, Loc, BoxLocs) .
                                                                                    \+ top(X, ),
reachable by sokoban (Loc1, Loc2, BoxLocs) :-
                                                                                    (\+ right( ,X); \+ right(X, )),!.
    neib(Loc1, Loc3, ),
    \+ member(Loc3, BoxLocs),
                                                                                    \+ top( ,X),
    reachable by sokoban(Loc3, Loc2, BoxLocs).
                                                                                    (\+ right( ,X); \+ right(X, )),!.
good dest(Loc.BoxLocs):-
                                                                                :-table stuck/2.
    \+ member(Loc, BoxLocs),
                                                                                stuck(X,Y):-
    (corner (Loc) ->storage(Loc);true),
                                                                                     (right(X,Y); right(Y,X)),
    foreach (BoxLoc in BoxLocs, \+ stuck (BoxLoc, Loc)).
                                                                                     (\+ storage(X); \+ storage(Y)),
                                                                                    (\+ top(X, ), \+ top(Y, );
                                                                                     \+ top(_,X), \+ top(_,Y)),!.
choose dest(Loc, NextLoc, Dir, Dest, NewSokobanLoc, BoxLocs): -
    Dest=NextLoc, NewSokobanLoc=BoxLoc.
                                                                                stuck(X,Y):-
choose dest (Loc, NextLoc, Dir, Dest, NewSokobanLoc, BoxLocs) :-
                                                                                     (top(X,Y);top(Y,X)),
    neib (NextLoc, NextNextLoc, Dir),
                                                                                     (\+ storage(X); \+ storage(Y)),
    good dest (NextNextLoc, BoxLocs),
                                                                                    (\+ right(X,_), \+ right(Y,_);
    choose dest(NextLoc,NextNextLoc,Dir,Dest,NewSokobanLoc,BoxLocs).
                                                                                     \+ right( ,X) , \+ right( ,Y)),!.
```

Resultados

- Passou em 11 de 15 testes
- Falta de memória
- Pode ser melhorado aplicando conceitos mais avançados de programação
- Analisa todas as possíveis soluções, inclusive as não ótimas

COMPETITION RESULTS (CPU TIME, SECONDS).

Instance	BPSolver	Clasp
1-sokoban-optimization-0-0.asp	0.58	0.06
13-sokoban-optimization-0-0.asp	0.06	0.74
18-sokoban-optimization-0-0.asp	0.00	9.80
20-sokoban-optimization-0-0.asp	33.57	13.24
24-sokoban-optimization-0-0.asp	2.66	3.52
27-sokoban-optimization-0-0.asp	0.78	1.16
29-sokoban-optimization-0-0.asp	0.78	2.92
33-sokoban-optimization-0-0.asp	1.96	26.74
37-sokoban-optimization-0-0.asp	0.38	8.52
4-sokoban-optimization-0-0.asp	Mem Out	0.62
43-sokoban-optimization-0-0.asp	Mem Out	35.67
45-sokoban-optimization-0-0.asp	Mem Out	9.30
47-sokoban-optimization-0-0.asp	Mem Out	18.66
5-sokoban-optimization-0-0.asp	0.00	0.16
9-sokoban-optimization-0-0.asp	0.00	2.12

Referência

N. -F. Zhou and A. Dovier, "A Tabled Prolog Program for Solving Sokoban," 2011 IEEE 23rd International Conference on Tools with Artificial Intelligence, 2011, pp. 896-897, doi: 10.1109/ICTAI.2011.145.