view_frames Result

Recorded at time: 1762727812.2634883

map

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

odom

Broadcaster: default_authority
Average rate: 16.069
Buffer length: 3.921
Most recent transform: 1762727812.184259
Oldest transform: 1762727808.263563

base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

chassis

Robot/lidar_link/gpu_lidar

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 998.9
Buffer length: 1.819
Most recent transform: 56.234
Oldest transform: 54.415

Broadcaster: default_authority
Average rate: 998.9
Buffer length: 1.819
Most recent transform: 56.234
Oldest transform: 54.415

lidar_link

left_wheel

right_wheel