# GRADIENT DESCENT

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## 1 Overview

**Definition 1.1.** It is an algorithm for minimizing a differentiable function.

### 1.1 Update rule

 $x_k = x_{k-1} - t_k \nabla f(x_{k-1})$ . where,  $t_k$  can be fixed or adaptive.

#### 1.2 Basic algorithm

- 1. choose initial point  $x_0 \in \mathbb{R}$
- 2. repeat  $x_k = x_{k-1} t_k \nabla f(x_{k-1})$
- 3. stop for instrice when objective decreases by less than  $\epsilon$  (user parameter).

### 1.3 Adaptive step size algorithm / Backtracking line search

- 1. Set  $x_0$ ,  $\alpha_0 > 0$ ,  $0 < \rho < 1$
- 2. On each iteration k:
- $f_k \leftarrow f(x_k)$
- 4. Set  $d_k \leftarrow -\nabla f(x_{k-1})$
- 5.  $\alpha \leftarrow \alpha_0$
- 6. while  $f(x_k + \alpha d_k) \ge f_k : \alpha \leftarrow \rho \alpha$
- 7.  $x_{k+1} \leftarrow x_k + \alpha d_k$

#### 1.3.1 Exact line search

Can we choose the ideal step direction?

This would also be a minimization problem as follows:

$$t = \operatorname*{argmin}_{s \ge 0} f(x - s\nabla f(x))$$

Answer: No

- approximation is not as efficient as backtracking
- not worth solving yet another minimization problem for an existing one

## 2 Convergence Analysis

#### 3 Considerations

#### 3.1 Pros and Cons

Pros

- $\bullet$  simple idea
- ullet low computational cost per iterations
- $\bullet$  fast for problems that are well-conditioned and strongly convex

#### Cons

- Slow for problems not strongly convex
- ullet slow if problem not well conditioned
- ullet only applicable to differentiable functions