# Joshua Francis

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#### Technical Skills

Palantir: Advanced Python: Intermediate CI/CD: Intermediate Dataiku: Advanced React: Intermediate Linux: Novice Docker: JavaScript: Novice Advanced Intermediate K3s: GitOps: Advanced C# / Java: Intermediate Assembly: Novice

#### Education

#### Louisiana State University of Shreveport | BS in Computer Science | Concentration: Software Development

→ GPA: 4.0 (Chancellor's List 2021 - 2025)

→ Graduation Date: May 2025

# Work Experience

# Data Engineering Support Specialist | Small Business Consulting Corporation (Active Security Clearance) May 2024 - Present | Bossier City, LA

## Software Developer | Louisiana State University in Shreveport

February 2024 - April 2024 | Shreveport, LA

□ Developed a Python visualization tool to analyse temperature variance in robot traversal paths. Led a team to assemble and deploy an autonomous Blue Boat robot at LSU Shreveport Watershed Institute

## Software Engineer Intern | PRAESES

June 2023 - August 2023 | Shreveport, LA

- → Managed Kubernetes instances, configured and maintained Backstage instances with custom JavaScript plugins, and implemented containerization using Docker and Flux in a K3s environment
- □ Created CI/CD pipelines with DevOps principles in Gitlab (GitOps) in the deployment of applications and tests

#### Cyber Challenge Writer | CYBER.ORG

August 2021 - August 2022 | Bossier City, LA

- Created over 500 cyber challenges for CYBER.ORG's CTF events for elementary through high school
- ▶ Implemented challenges involving programming, cyber security, and problem-solving, with a focus on increasing student engagement and pursuit of creativity in a collaborative environment

# Projects

#### Senior Project | Team Lead & Full Stack Developer

#### Full Stack Database Application | Full Stack Developer

▶ Engineered a full stack database advancing my proficiency in schema design and SQL implementation with Java, laying a solid foundation for real-world database implementations

## Kinect Posture Software | Front End Developer

→ Created detection software using Xbox's Kinect SDK with a development team for the purpose of negative reinforcement to correct posture using C# and XAML alongside hardware solutions with Arduino