
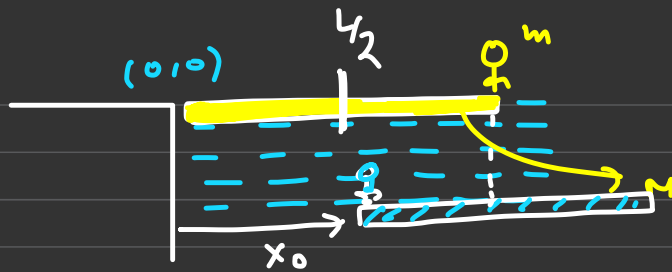


Problem solving E&M





Q)



initially both are at rest

Now man starts walking towards bank

find displacement of plank when man is on other side of plank.

$F_{ext} = 0 \Rightarrow a_{cm} = 0$

if $a_{cm} = 0$

$v_{cm} = 0$

$v_{cm} = \text{const}$

$x_{cm} = \text{fixed}$

$x \neq \text{const}$

as $\{ \underline{F_{ext} = 0} \text{ and } \underline{v_{cm} = 0} \}$ hence $\underline{x_{cm} = \text{const}}$

$$(x_{cm})_i = \frac{M \times \frac{L}{2} + m \times L}{m + M} \quad \text{--- (1)}$$

$$(x_{cm})_f = \frac{m x_0 + M (x_0 + L/2)}{m + M} \quad \text{--- (11)}$$

$$(x_{cm})_i = (x_{cm})_f$$

$$\cancel{m x L/2} + m L = m x_0 + \cancel{M (x_0 + L/2)}$$

$$m L = (m + M) x_0$$

$$x_0 = \left(\frac{m L}{m + M} \right)$$

$$\underline{F_{ext} = 0 \quad \text{and} \quad v_{cm} = 0}$$

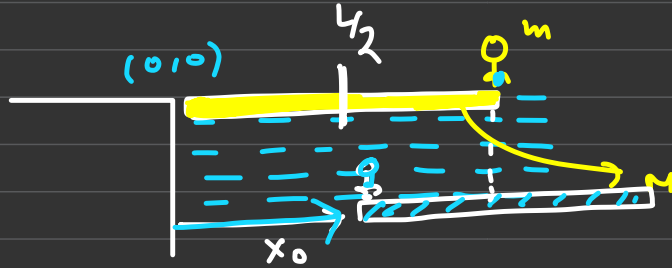
method 2:

$$\Rightarrow \boxed{x_{cm}} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$

$$\Delta (x_{cm}) = \frac{m_1 (\Delta x_1) + m_2 (\Delta x_2)}{m_1 + m_2}$$

$$0 = m_1 \Delta x_1 + m_2 \Delta x_2$$

$$\# \quad m_1 \Delta x_1 + m_2 \Delta x_2 = 0 \quad \Delta = \underline{\underline{f - i}}$$

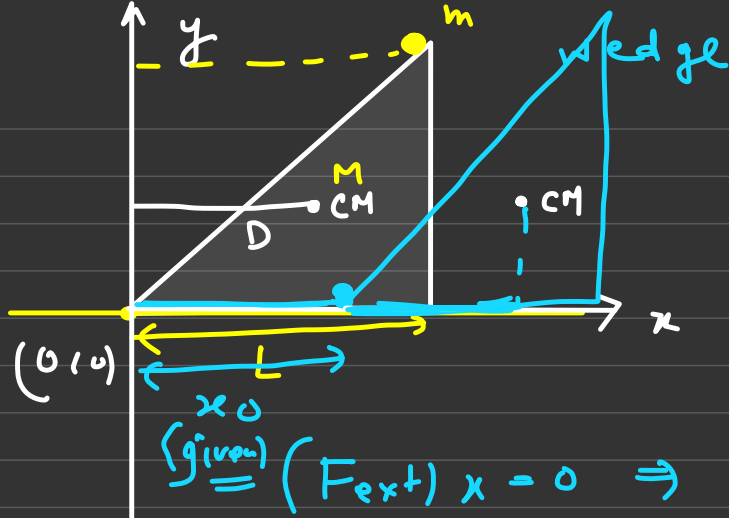


$$m(x_0 - L) + M(x_0 + \cancel{\frac{L}{2}} - \cancel{\frac{L}{2}}) = 0$$

$$m x_0 - m L + M x_0 = 0$$

$$\boxed{x_0 = \frac{m L}{m + M}} \quad \underline{\underline{Ans}}$$

0)



initially
System is at
rest
find displac
of wedge
when point
mass is
at bottom
of wedge?
On System

$$\begin{aligned} (F_{ext})_x &= 0 \Rightarrow (q_{cm})_x = 0 \\ (V_{cm})_x &= 0 \\ \text{then } x_{cm} &= \text{const} \end{aligned}$$

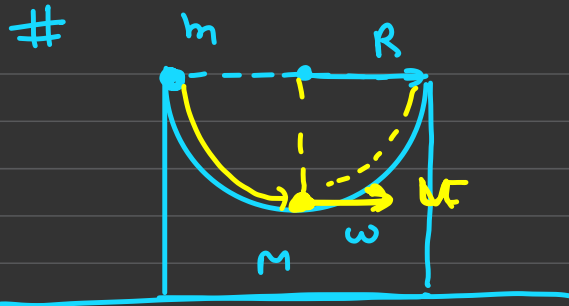
$$m_1 \Delta x_1 + m_2 \Delta x_2 = 0$$

$$m \{ x_0 - L \} + M \{ x_0 + D - \underline{D} \} = 0$$

$$m x_0 - m L + M x_0 = 0$$

$$x_0 = \left(\frac{m L}{m + M} \right) \underline{\underline{=}}$$

Q)



- # initially rest
- # smooth
- # find displacement of wedge when point mass is at other of wedge?

find max Speed of wedge

L. of Conservation of energy

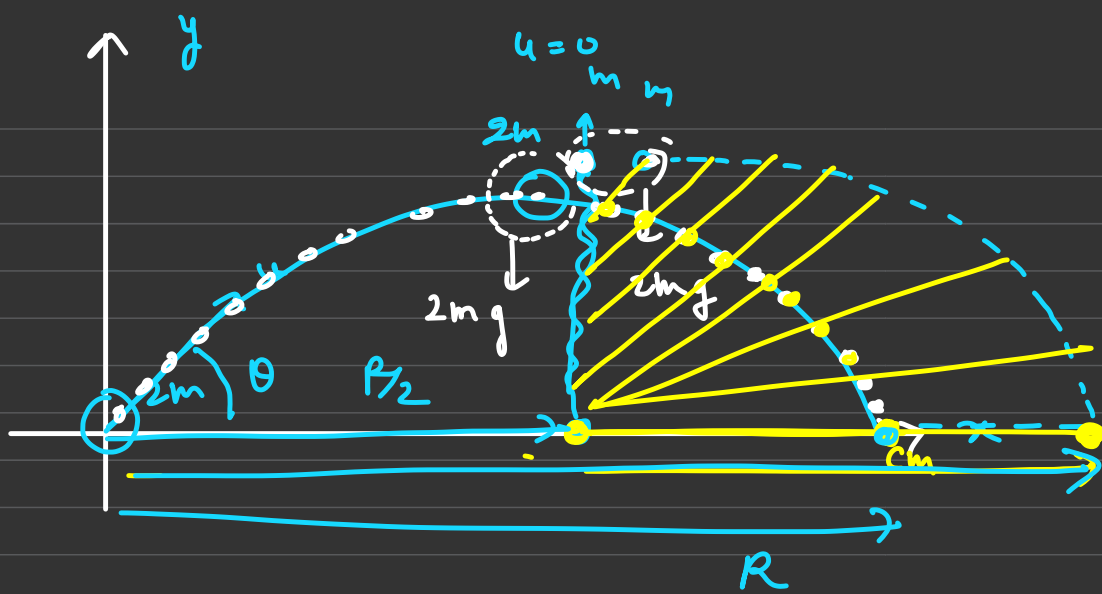
$$mgR = \frac{1}{2} m v_{\max}^2 + \frac{1}{2} M u$$

L. of Con of momentum

$$m u - M v_{\max} = 0 + 0$$

#

0)

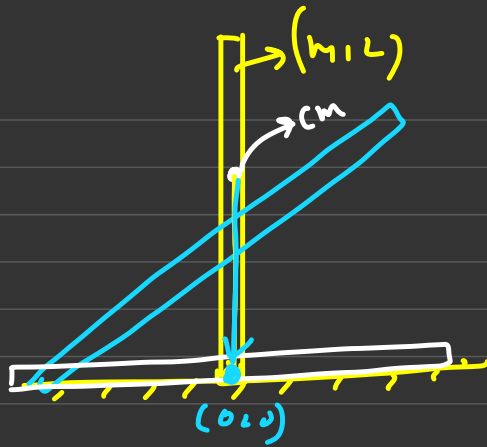


find location
of second
particle?

$$R = \frac{u^2 \sin 2\theta}{g}$$

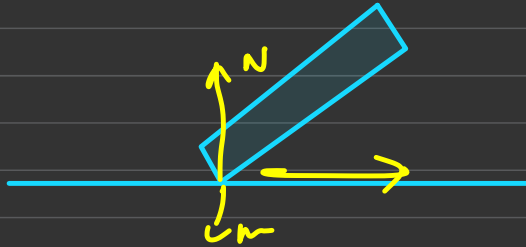
$$\left\{ \begin{aligned} + R &= \frac{m \times \frac{R}{2}}{2m} + m (u_0) \\ 2 + (R) &= \frac{R}{2} + u_0 \Rightarrow u_0 = \frac{3R}{2} \\ u_0 &= 1.5R \end{aligned} \right.$$

Q)



- find final location of COM
- # rod is released from rest
- # smooth surface

as no ext force along horizontal hence C.M is going move downwards



Conservative force & Non-Conservative:

Conservation: work done by conservative in a loop is always $= 0$

$$(W_{CF})_{\text{Loop}} = 0$$




Spring, gravity

Electrostatic

magnetic

Non-Conservative force: work done by ^{Non-}conservative force in a loop is never $= 0$

$$(W_{NCF})_{\text{loop}} \neq 0$$

$\left\{ \begin{array}{l} \# \text{ frictional} \\ \# \text{ viscous} \\ \# \text{ Tension} \end{array} \right.$


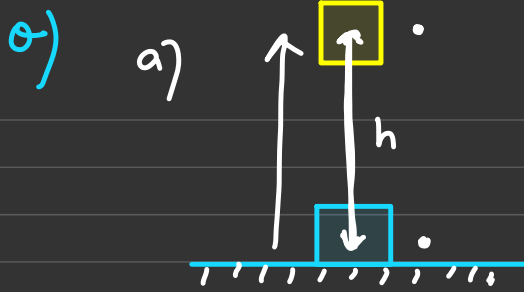
$$w_f = \underline{f_k \times (\text{distance})}$$

$\#$ Conservative force:

$$\left\{ \begin{array}{l} \underline{\underline{\{ \underline{du} = - \underline{\vec{F}_c \cdot d\vec{r}} \}}} \\ \# \underline{\underline{(\vec{F}_c)_x = - \frac{du}{dx}}} \Rightarrow \end{array} \right.$$

Basic definition

$$\underline{\underline{F_c = - \frac{du}{dr}}}$$



$$\Delta u = +mgh$$

#

$$\Delta u = - \vec{F}_c \cdot \vec{dr}$$

$$\Delta u = - [-mgh]$$

$$\Delta u = +mgh$$

$$\Delta u = -mgh$$



$$\Delta u = - \vec{F}_c \cdot \vec{dr}$$

$$\Delta u = - [mgh] = \underline{\underline{-mgh}}$$

#

$$U(r)$$



$$F_c = - \frac{dU}{dr}$$



$$F_c = 0 \quad \underline{\text{Equilibrium}}$$

#

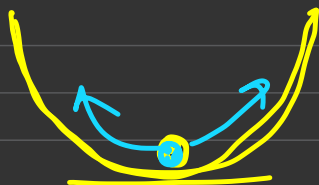
Stable
Equilibrium

#

Unstable
Equilibrium

#

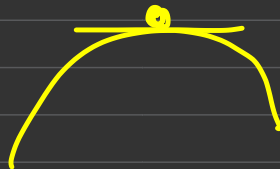
Neutral
Equilibrium



$$U(r)$$



$$F_c = - \frac{dU}{dr}$$



$$F_c = - \frac{dU}{dr}$$

$$F_c = 0$$

$$\left\{ \frac{d^2 U}{dr^2} = 0 \right. \Rightarrow$$

it can restore it # it can run

Equilibrium position

$$\# \frac{d^2 u}{dr^2} > 0$$

if P.E \Rightarrow min then only
we can stable equilibrium

restoring eqb. pos. \neq It attains new eqb position

$$\frac{d^2 u}{dr^2} < 0$$

if P.E = max the
only unstable equilibrium

e)

$$U(r) = \frac{a}{r^2} - \frac{b}{r^3}$$

$$\left\{ \begin{array}{l} a, b \text{ +ve} \\ \text{constant} \end{array} \right\}$$

{ # find position of equilibrium

{ # find particle is at stable or unstable equilibrium

$$\# \quad F = - \frac{dU}{dr} = - \left(- \frac{2a}{r^3} + \frac{3b}{r^4} \right) = 0$$

$$\frac{2a}{r^3} = \frac{3b}{r^4}$$

$$r = \frac{3b}{2a} \quad \underline{\underline{=}}$$

#

$$\left(\frac{d^2 u}{dr^2} \right)_{at_{eq}} = \left\{ \frac{6a}{r^4} - \frac{12b}{r^5} \right\}$$

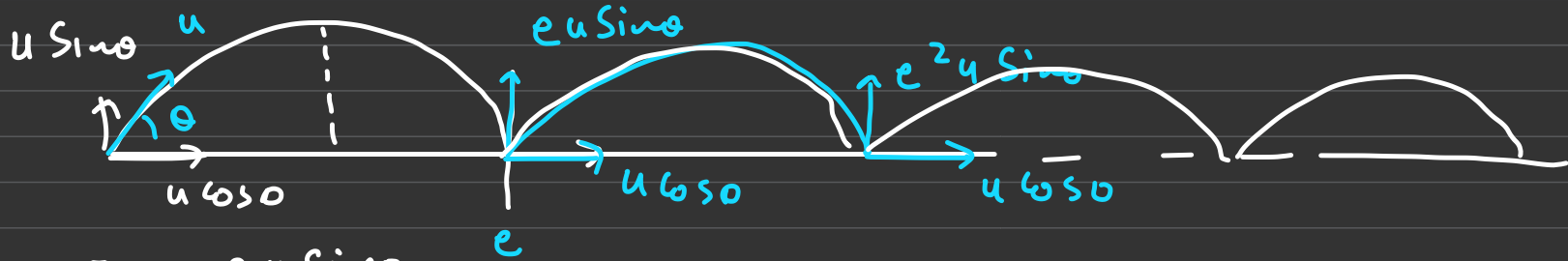
$$= \frac{1}{r^4} \left[6a - \frac{12b \times 2a}{3} \right]$$

$$= \left(\frac{1}{r_0} \right)^{+ve} \left\{ \frac{6a - \frac{24a}{3}}{-ve} \right\}$$

$$\frac{d^2 u}{dr^2} < 0$$

Unstable eqn.

9)



$$\# \quad T_0 = \frac{2u \sin \theta_0}{g} \quad T_1 = \frac{2eu \sin \theta_0}{g} = eT_0$$

$$\# \quad H_{\max} = \frac{u^2 \sin^2 \theta_0}{2g} = H_m \quad H_{\max} = \frac{e^2 u^2 \sin^2 \theta_0}{2g} = e^2 H_{\max}$$

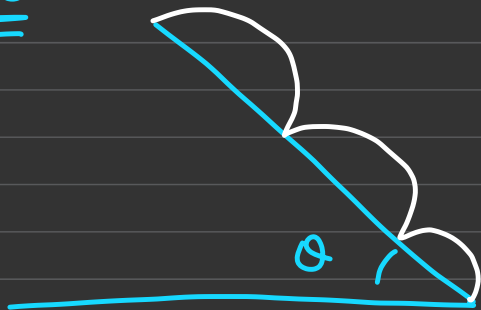
$$\# \quad R_{\text{rang}} = \frac{u^2 \sin 2\theta_0}{g} = R_0 \quad R_{\text{range}} = \left\{ \frac{u \cos \theta_0 \times eT_0}{g} \right\} = eR_0$$

	\rightarrow	1 st collision	2 nd collision		
Time \rightarrow	T_0	eT_0	$e^2 T_0$	$e^3 T_0$	\dots
$H_{\max} \rightarrow$	H_m	$e^2 H_m$	$e^4 H_m$	$e^6 H_{\max}$	$e^{2n} H_{\max}$

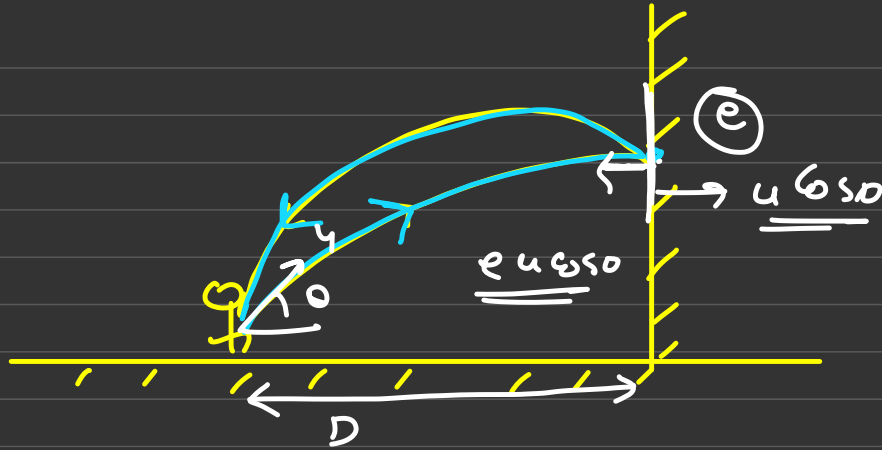
$$\text{Ker} \eta = R_0 \{ \quad e R_0 \quad e^2 R_0 \quad e^3 R_0 \quad e^n R_0$$

H.W #

find general condition for
(T, R, Hmax)



e)

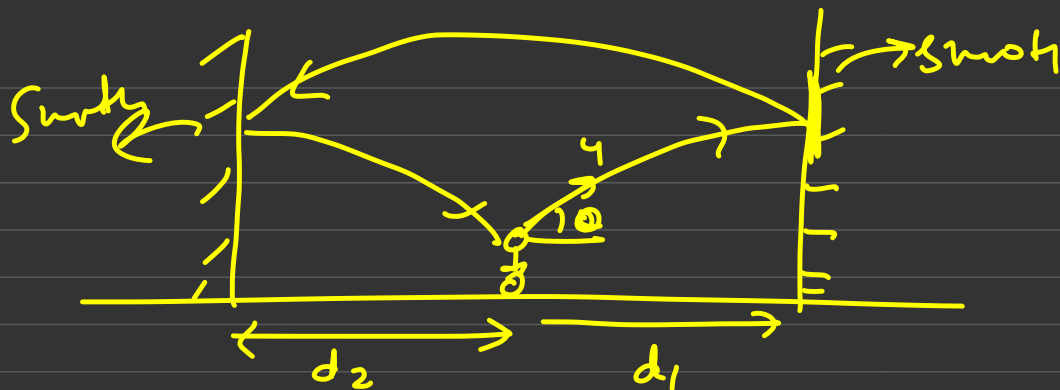


find condition for which ball comes back in hand of observer?

Change vertical velocity with wall or without wall is going to same as net external force = mg } No - impulse during collision in upward direction }

$$\frac{2 u \sin \theta}{g} = \frac{D}{u \cos \theta} + \frac{D}{e u \cos \theta}$$
 $\underline{A_1}$

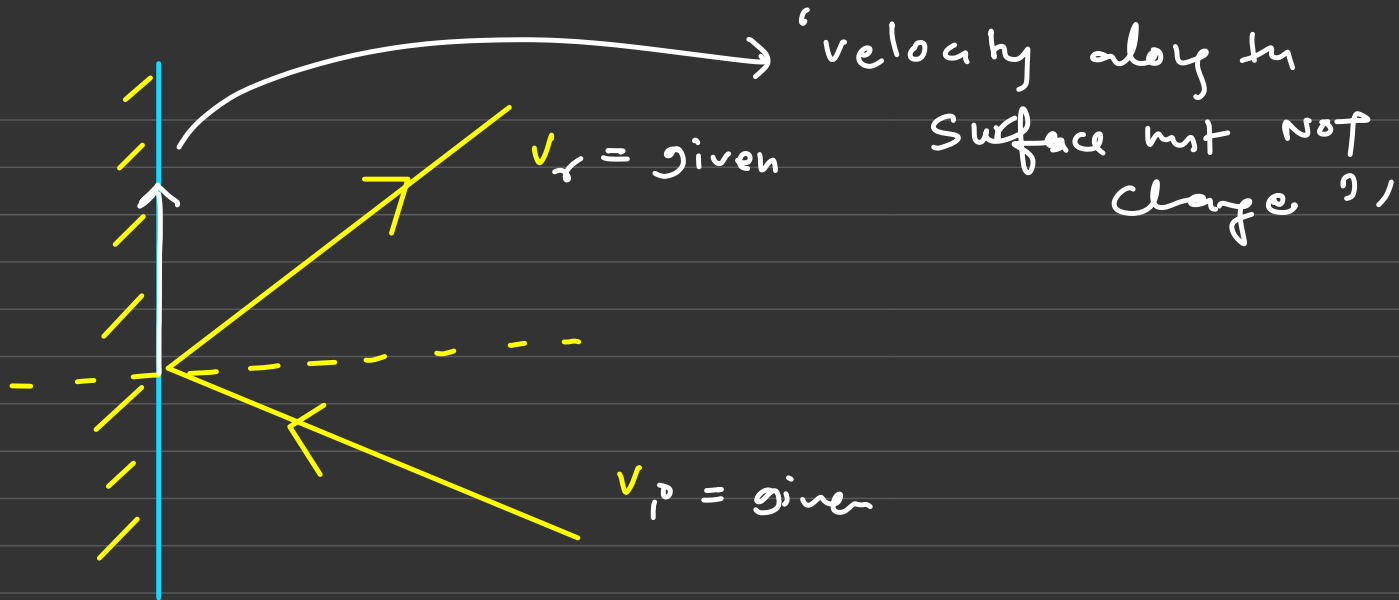
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find condition such ball comes back in hand of

$$\# \quad \frac{2u \sin \theta}{g} = \frac{d_1}{u \cos \theta} + \frac{d_1 + d_2}{e u \cos \theta} + \frac{d_2}{e^2 u \cos \theta} \quad \text{obs.}$$

#



#

$$\hat{r}_+ = x\hat{i} + y\hat{j}$$

$$\sqrt{x^2 + y^2} = 1 \Rightarrow \boxed{x^2 + y^2 = 1} \quad (1)$$

unit vector along wall

$$\vec{r}_{11} = x'i + y'j$$

$$\# \left\{ \begin{array}{l} -xy + x'y = 0 \\ x'x + y'y = 0 \\ \underline{x' = -y \quad y' = x} \end{array} \right\} \quad \vec{r}_{11} = -yi + xj$$

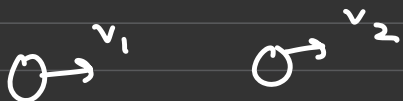


$$\# \frac{\vec{U}_j \cdot \vec{r}_{11}}{|\vec{r}_{11}|} = \frac{\vec{v}_r \cdot \vec{r}_{11}}{|\vec{r}_{11}|} \quad \text{--- (II)}$$

Solve (I) and (II)
get x and y
and get (r_{11}) & \vec{r}_{11}

Q)

all collision are
elastic



$$v_2 - v_1 = 1 \times u \quad \text{--- (1)}$$

$$v_2 = v_1 + u$$

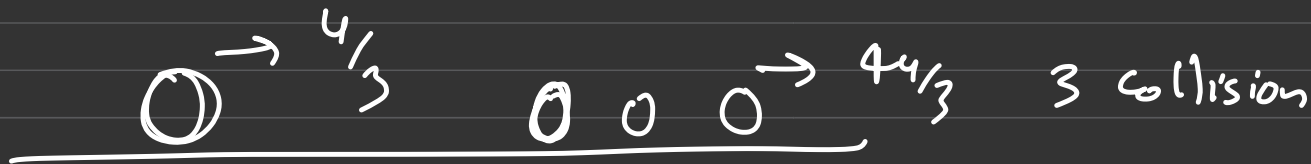
$$v_2 = \frac{4u}{3}$$

$$2m \times u = 2m v_1 + m v_2$$

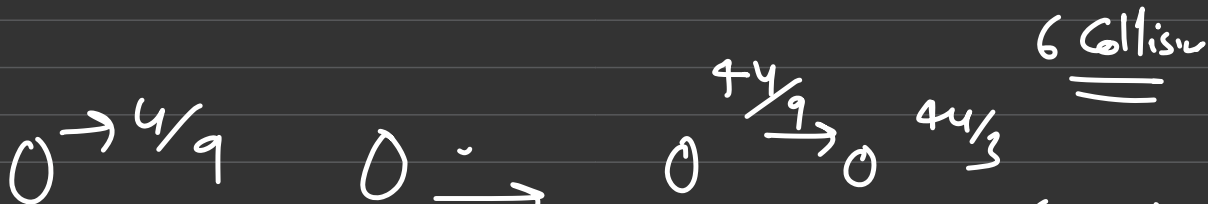
$$2u = 2v_1 + v_2 \quad \text{--- (1)}$$

$$2u = 3v_1 \quad v_1 = \frac{4u}{3}$$

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