

## Rotation7

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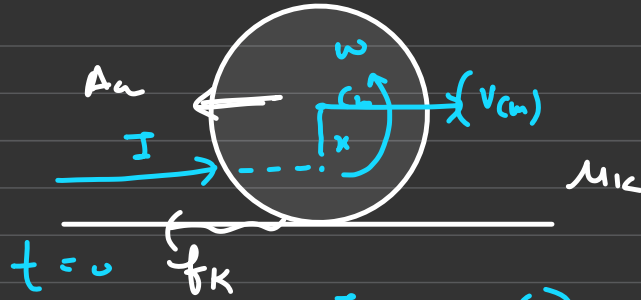
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Solution #

Solid sphere



find  $x$  for which  
solid sphere  
comes back?

$$v_{cm} = 0 \text{ and } \omega \neq 0$$

$$t = 0 \quad \begin{cases} f_k \\ v_{cm} = \frac{I}{m} \quad \text{--- (I)} \end{cases}$$

$$\left\{ \begin{aligned} I x &= \frac{2}{5} m R^2 \alpha \Rightarrow \omega = \frac{5 I x}{2 m R^2} \quad \text{--- (II)} \end{aligned} \right.$$

After time 't'

$$\left\{ \begin{aligned} v_{cm}(t) &= \frac{I}{m} - f_k \times t \end{aligned} \right.$$

$$f_k \times R = \frac{2}{5} m R^2 \alpha$$

$$\left\{ \begin{aligned} \omega(t) &= \frac{5 I x}{2 m R^2} - \frac{5 f_k}{2 m R} \times t \end{aligned} \right.$$

$$f_k = \mu_k m g$$

if this ball is going to come back then

$$v_{cm}(t) = 0 \Rightarrow \frac{I}{m} = \frac{b_K}{m} \times t$$

$$t = \frac{I}{b_K}$$

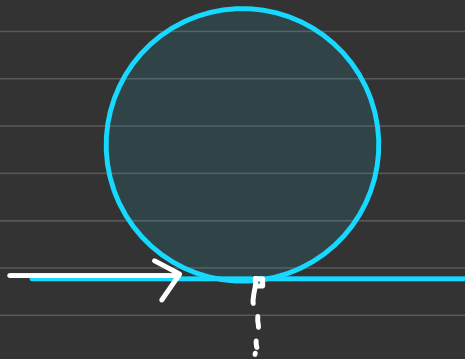
$$w(t) = \frac{\cancel{b} \cancel{t} u}{\cancel{t} m R^2} + \frac{\cancel{b} \cancel{t} K}{\cancel{t} m R} \times \left[ \frac{\cancel{t}}{\cancel{b} K} \right] > 0$$

$$\frac{x}{R} - 1 > 0$$

$$\frac{x}{R} > 1$$

$$\boxed{x > R}$$

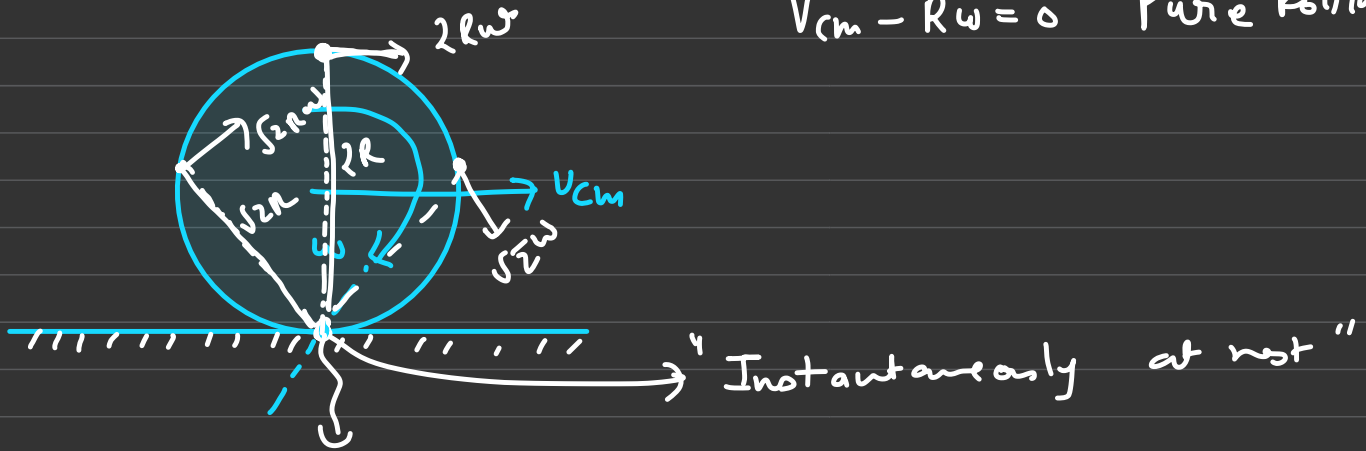
$$\underline{A}$$



# Instantaneous axis of rotation:

#

$$V_{cm} - R\omega = 0 \quad \text{Pure Rolling}$$

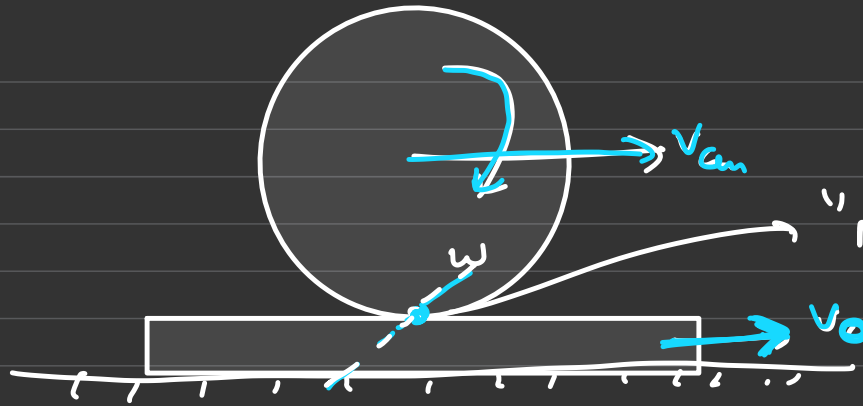


"Instantaneous axis of rotation"

we can analyse this sphere  
like fixed axis of  
rotation

# valid only for pure  
rolling

#

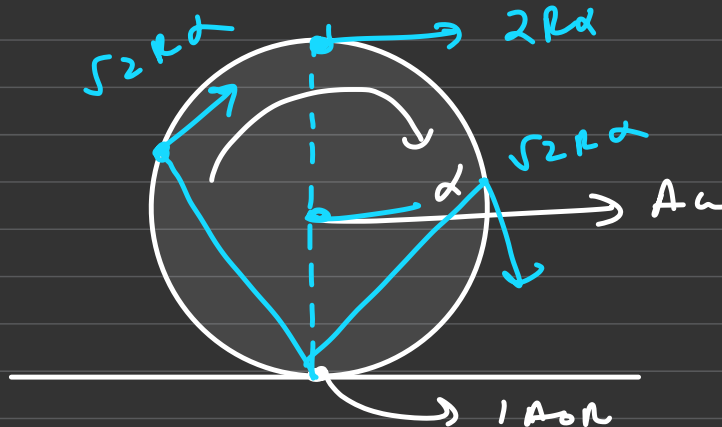


# Pure rolling  
 # I AOR should be at rest

"NOT I AOR"

# we can not assume F AOR at this instant "

#

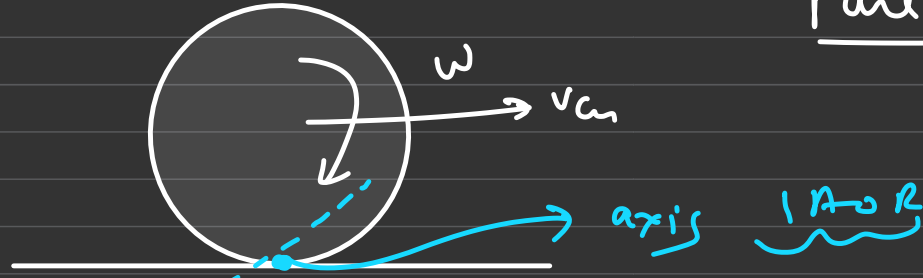


Pure rolling

# Energy in IAR:

Pure rolling

#

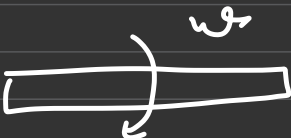


$$(KE)_{\text{GRBM}} = \frac{1}{2} M v_{\text{cm}}^2 + \frac{1}{2} I_{\text{cm}} \omega^2$$

$$= \frac{1}{2} M (R\omega)^2 + \frac{1}{2} M k^2 \omega^2$$

$$(KE)_{\text{GRBM}} = \frac{1}{2} M \omega^2 [R^2 + k^2]$$

==

① (x) 

$$KE = \frac{1}{2} I_{\text{CM OR } R} \omega^2$$

Using I AOR Concept!

②



$$\Rightarrow (KE)_{\text{body}} = \frac{1}{2} I_{\text{AOR}} \times \omega^2$$

CM

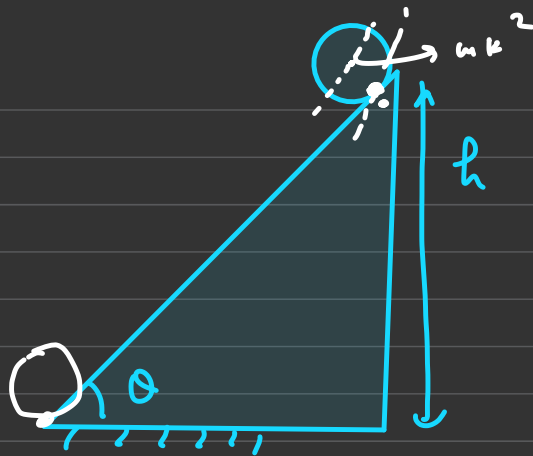
$$\frac{1}{2} m v_{\text{CM}}^2 + \frac{1}{2} I_{\text{CM}} \omega^2$$

$$= \frac{1}{2} (m k^2 + m R^2) \times \omega^2 \quad (3)$$



$$(KE) = \frac{1}{2} I_{\text{AOR}} \times \omega^2$$

0)



# Pure rolling

IAOR method

# Released from rest

$$\left\{ \begin{aligned} mgh &= \frac{1}{2} I_{AOR} \omega^2 - 0 \\ 2mgh &= (mk^2 + mR^2) \omega^2 \end{aligned} \right\} \quad \left\{ \begin{aligned} I_{AOR} &= \\ mk^2 + mR^2 \end{aligned} \right.$$

$$\sqrt{\frac{2gh}{k^2 + R^2}} = \omega$$

$$v_C - R\omega = 0$$

$$v_C = ?$$

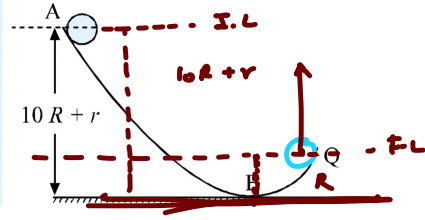




**Example - 4**

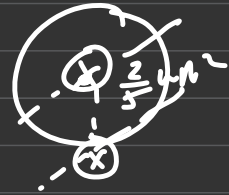
A solid sphere of radius  $r$  and mass  $m$  rolls without slipping down the track shown in the figure. At the end of its run at point  $Q$  its center-of-mass velocity is directed upward. The lower portion of track is circular of radius  $R$ .

- (a) Determine the force with which the sphere presses against the track at  $B$ .  
 (b) Upto what height does the CM rise after it leaves the track?

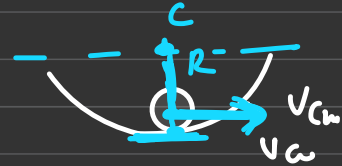


$$\Rightarrow m g (10R) = \left\{ \frac{1}{2} I_{\text{CM}} \omega^2 - 0 \right\}$$

$$m g 10R = \frac{1}{2} \left\{ \left( \frac{7}{5} m r^2 \right) \omega^2 \right\}$$



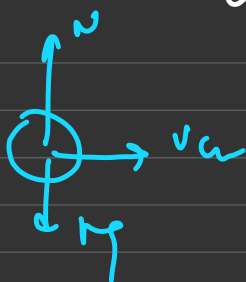
$$10 m g R = \frac{7}{10} (m r^2) \omega^2$$



$$\omega = \sqrt{\frac{100 g R}{7 r^2}}$$

$$v_{\text{CM}} = r \omega = r \sqrt{\frac{100 g R}{7 r^2}}$$

$$v_a = \sqrt{\frac{100gR}{7}}$$



$$N - mg = \frac{m v_{cw}^2}{(R-r)}$$

$$N - mg = m \left( \frac{100gR}{7} \right) \frac{1}{R-r}$$

$$\underline{\underline{N = mg + \frac{100mgR}{7(R-r)}}} \quad \underline{\underline{A_1}}$$

$$b) \quad W_g(9R+r) = \left\{ \frac{1}{2} I_{\text{com}} \omega^2 - 0 \right\}$$

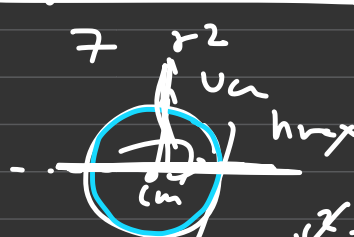
$$W_g(9R+r) = \frac{1}{2} \left[ \frac{7}{5} m r^2 \omega^2 \right]$$

$$\omega = \sqrt{\frac{10 g (9R+r)}{7 r^2}}$$

$$v_c = r \times \omega$$

$$v_c = \sqrt{\frac{\cancel{r} 10 g (9R+r)}{7 \cancel{r^2}}}$$

$$v_c = \sqrt{\frac{10 g (9R+r)}{7}}$$



$$\cancel{v}^2 = u^2 + 2gs$$

$$h = \frac{u^2}{2g}$$

$$h_{\text{max}} = \frac{10 g (9R+r)}{7 \times 2g}$$

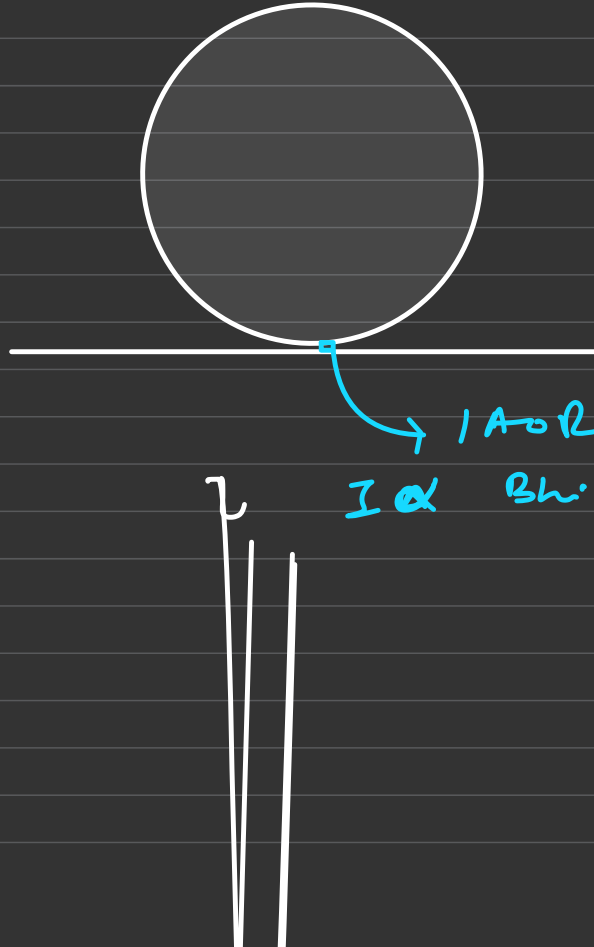
$$= 5 (9R+r)$$

$$h_{\max} = \frac{45R}{7} + \frac{5r}{7} + R \quad \underline{\underline{d}}$$

w.o. + gear.

$$h_{\max} = \frac{52R}{7} + \frac{5r}{7} \quad \underline{\underline{d_1}}$$

# Dynamics (IAOR)

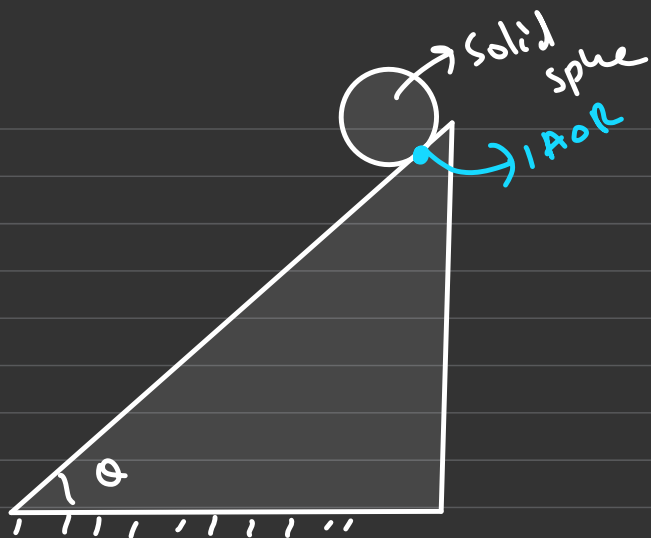


$$\tau_{FAOR} = I_{FAOR} \alpha$$

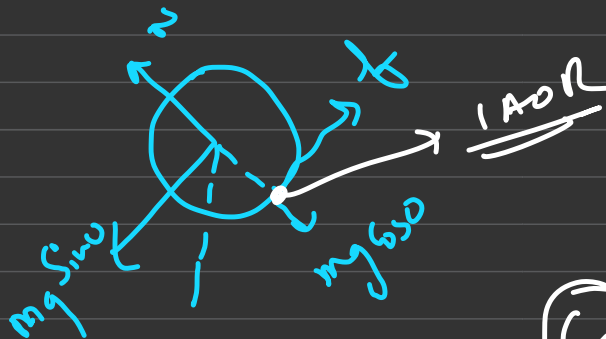
Sim.  $\tau_{IAOR} = I_{IAOR} \alpha$

$I \propto R^2$  Bh. valid here "

e)



find acceleration at  
any instant using  
 $\frac{1}{2}R$ ?



$$\Rightarrow \tau_{\frac{1}{2}R} = I_{\frac{1}{2}R} \alpha$$

$$mg \sin \theta \times R = \frac{7}{2} m R^2 \alpha$$

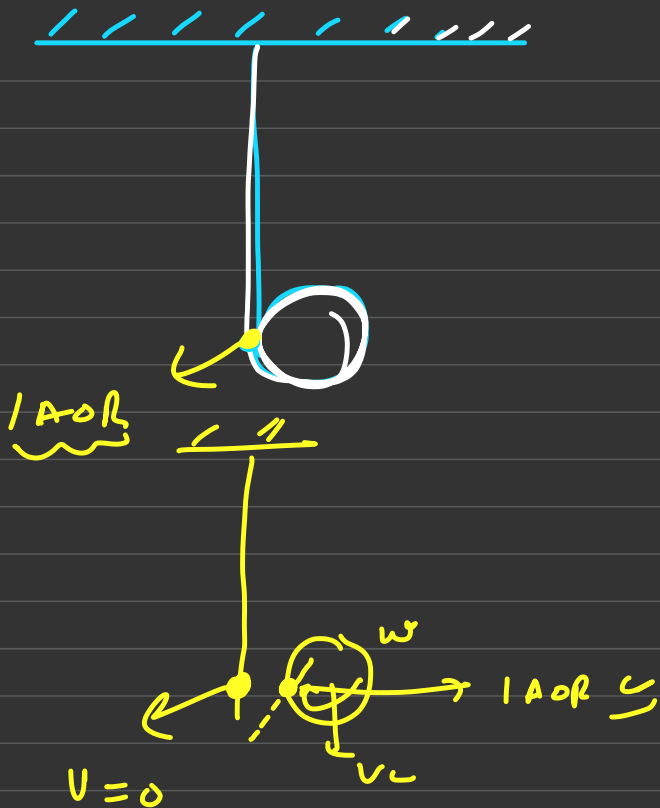
$$\alpha = \frac{5g \sin \theta}{7R}$$

$A$

$$A_c - R \alpha = 0$$

$$A_c = \frac{5g \sin \theta}{7}$$

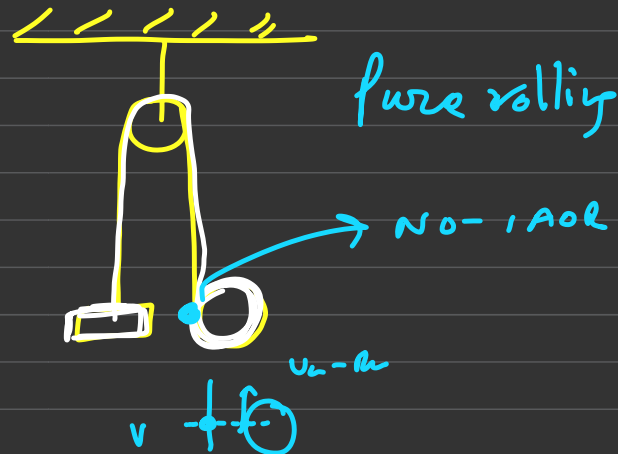
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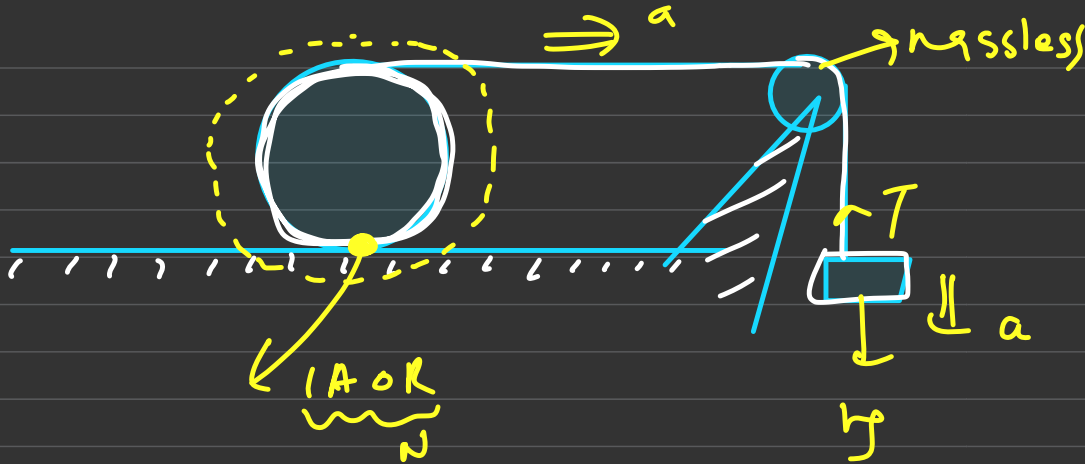
Identify 1AOR??

# Released from rest

=#

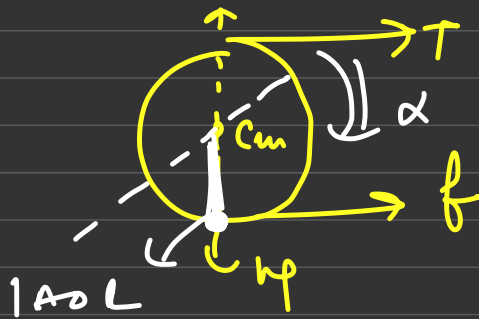


8)



$$m_p - T = m_p a \quad (1)$$

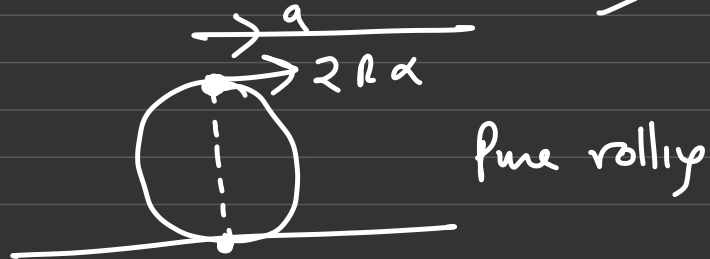
$$(2) \quad (1)$$



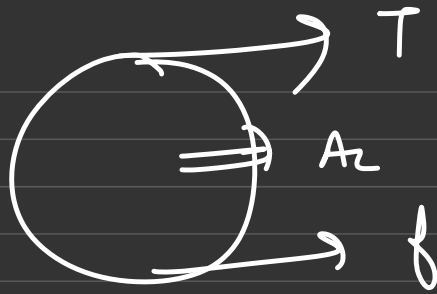
$$T_{I_{AOR}} = I_{AOR} \times \alpha$$

$$T \times 2R = (m_k^2 + m R^2) \times \alpha \quad (3) \quad (11)$$

$$2R \alpha = a \quad (111)$$

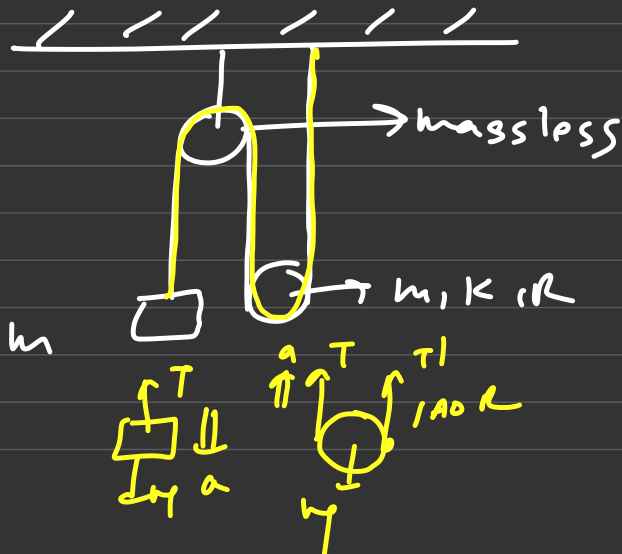






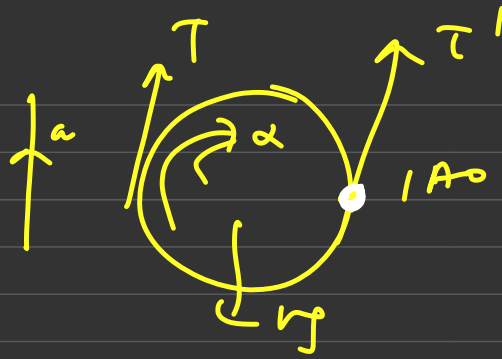
$$\left\{ \begin{array}{l} T + f = m A_L \quad (iv) \\ \underline{\underline{A_L = R \lambda}} \quad (v) \end{array} \right.$$

#



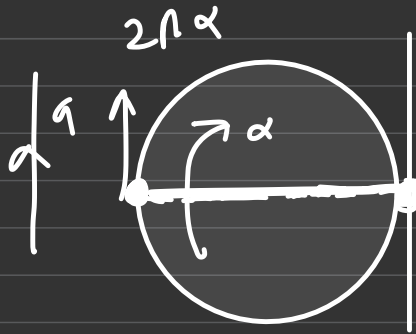
"Pure rolling"  
Rolling without  
slipping

$$mg - T = ma \quad \text{--- ①}$$



$$\tau_{AOR} = I_{AOR} \times \alpha$$

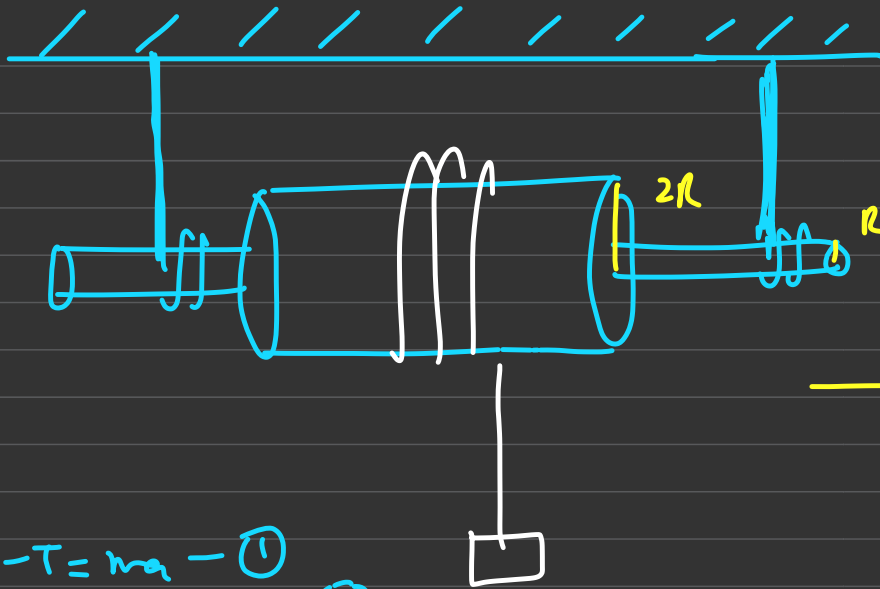
$$T \times 2R - mgr = (mk^2 + mR^2) \alpha$$



$$2R\alpha = a \quad \text{--- ②}$$

9)

g



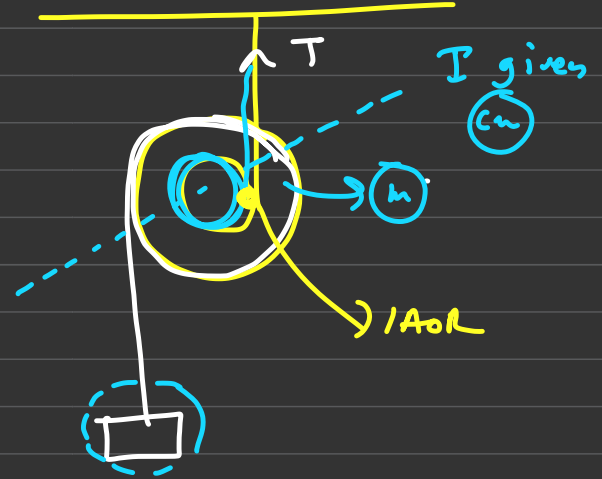
{ released from rest  
# pure rolling

$$mg - T = ma \quad (i)$$

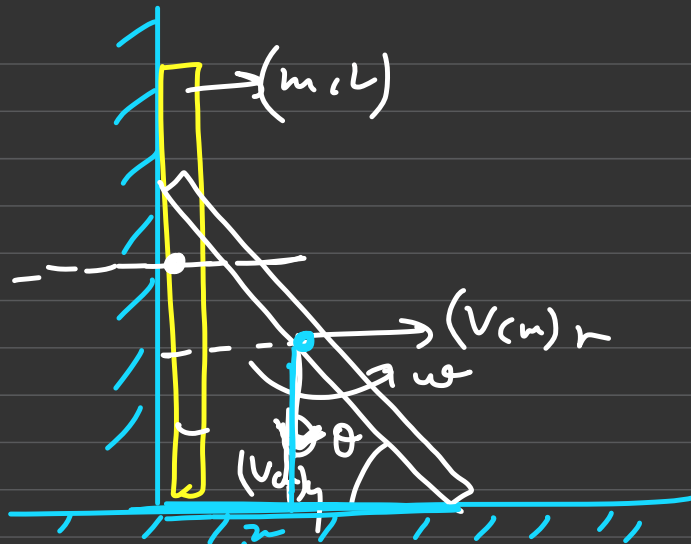


$$a = 3R\alpha \quad (ii)$$

$$T \times 3R + mg \times R = (I + mR^2) \alpha \quad (iii)$$



o)



" all the surfaces are smooth "

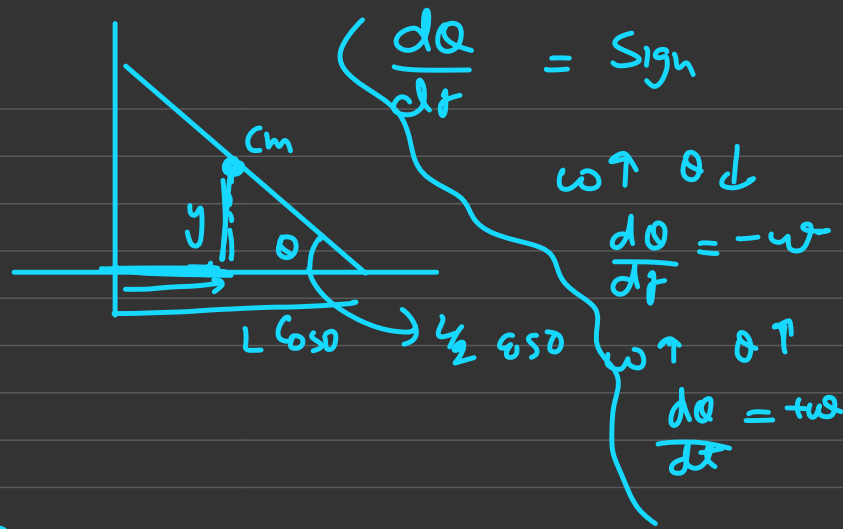
given  $[m, L, \theta]$   
 find  $\omega, (v_{cm}) = ?$   
 at this  $\theta$

Energy Conservation:

$$mg\left(\frac{L}{2}\right) - mg\left(\frac{L}{2}\right) \sin \theta = \frac{1}{2} m \underline{v_{cm}^2} + \frac{1}{2} I_a \times \underline{\omega^2} \quad (1)$$

$$\underline{x = \frac{L}{2} \cos \theta}$$

$$y_{cm} = \frac{L}{2} \sin \theta$$



$$(V_{cm})_x = \frac{L}{2} (-\sin \theta) \cdot \frac{d\theta}{dt}$$

$$(V_{cm})_y = \frac{L}{2} \cos \theta \cdot \frac{d\theta}{dt}$$

$$(V_{cm})_x = \frac{L}{2} (-\sin \theta) \cdot \omega$$

$$(V_{cm})_y = \frac{L}{2} \cos \theta \cdot \omega$$

$$(V_{cm})_{net} = \sqrt{(V_{cm})_x^2 + (V_{cm})_y^2} = \sqrt{\left(\frac{L}{2} \sin \theta \cdot \omega\right)^2 + \left(\frac{L}{2} \cos \theta \cdot \omega\right)^2}$$

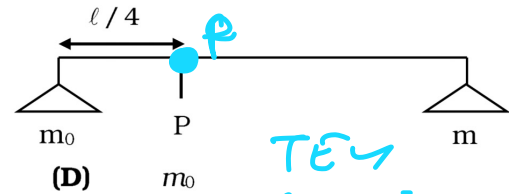
$$V_{cm} = \frac{L}{2} \omega \quad \underline{\underline{=}} \quad \text{--- (11)}$$

17. A light rod of length  $\ell$  is pivoted at distance  $\ell/4$  from the left end and has two masses  $m_0$  and  $m$  attached to its ends such that rod is in equilibrium. Find  $m$  in terms of  $m_0$ .

(A)  $\frac{m_0}{2}$

(B)  $\frac{m_0}{3}$

(C)  $2m_0$



✓# Rotation  
✓# Translation

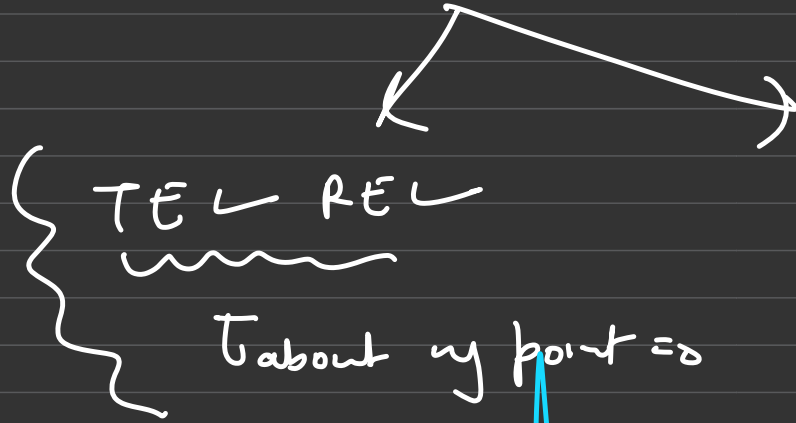
Equilibrium

$$\begin{cases} A_c = 0 \\ \alpha = 0 \end{cases}$$

if only  $\alpha = 0$  then that body is in Rotation Eq/b

if only Acceleration of all points are zero then is Translational Eq/b

if any body



$$\underline{\underline{TE \times Rot \xi}}$$

$$T_m = 0$$

$$T_p = 0$$

$$\cancel{mg} \times \cancel{\frac{l}{4}} - \cancel{mg} \times \frac{3l}{4} = 0$$

$A \cdot c \cdot \omega \quad \quad \quad C \cdot \omega$

$$m_0 = 3m$$

h

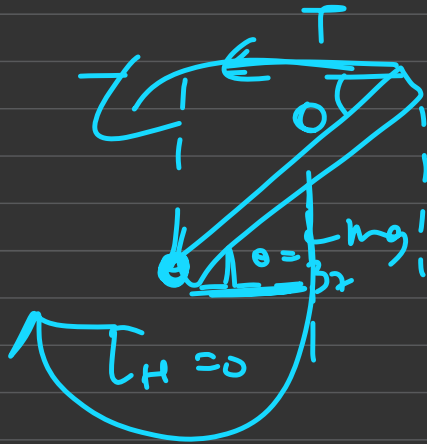
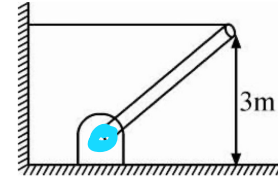
18. A uniform rod of mass 15 kg and length 5 m is pivoted at one end and is held stationary with the help of a light string as shown in the figure. The tension in the string is:

(A) 150 N

(C) 100 N

(B) 255 N

(D) None of the above



$$\begin{cases} T \leftarrow \\ R \rightarrow \end{cases}$$

$$\sin 37 = \frac{3}{5} = 37$$

$$mg \times \frac{5}{2} (\sin 37) - T (5 \sin 37) = 0$$

$$\frac{75}{2} \times \frac{3}{5} \times \frac{4}{5} - T \times 5 \times \frac{3}{5} = 0$$



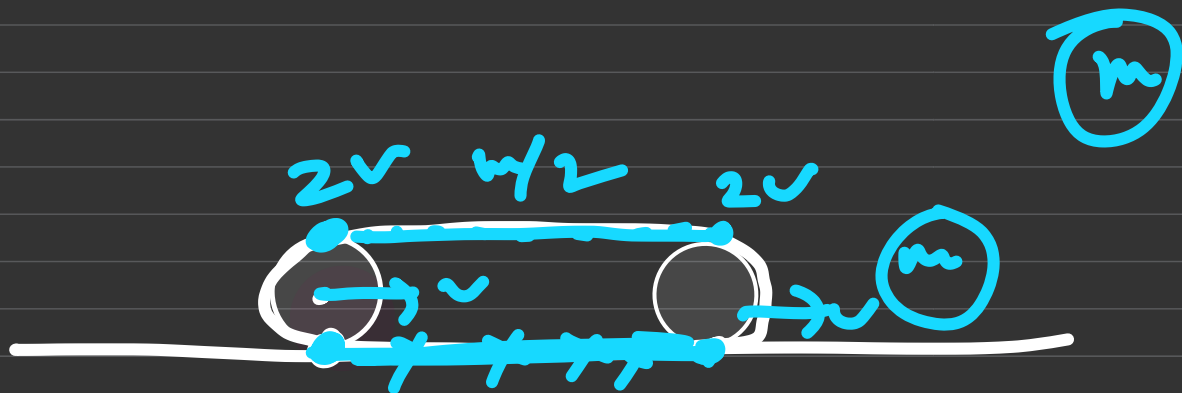
$$150 \times \frac{5}{2} \times \frac{4^2}{2} - T \times 5 \times \frac{3}{2} = 0$$

$$300 - 3 \times T = 0$$

$$\underline{\underline{T = 100 \text{ N}}}$$

# Complete work book 8 module #

except { toppling }



$$= \frac{1}{2} \left( \frac{m}{2} \right) \cdot (2v)^2$$

$$= m v^2$$

