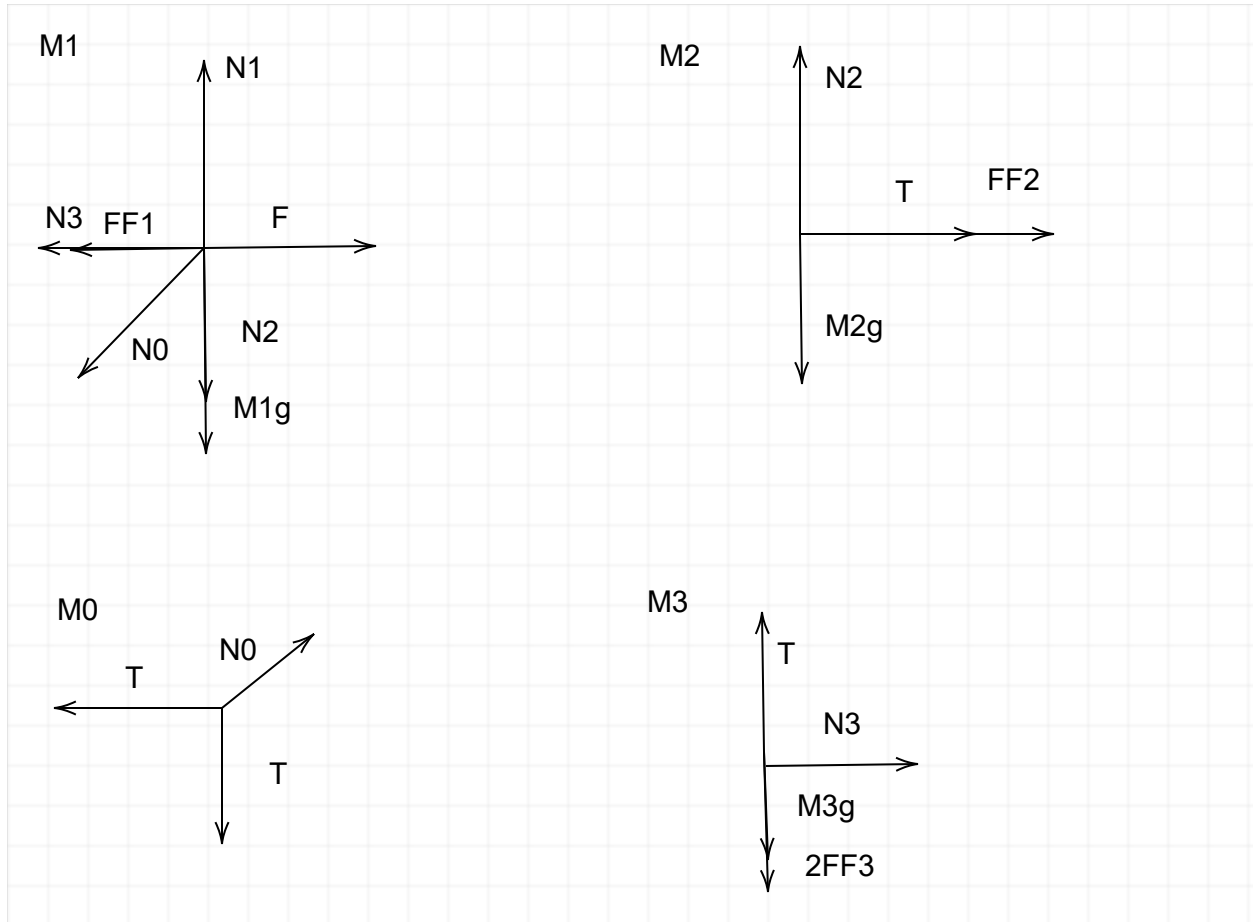


Mechanics  
Project 2  
Violeta Iskandaryan



*I have assumed  $F$  is positive*

*We have the following equations :*

$$M_1 \text{ in } x \text{ direction} : F - N_{0x} - F_{F1} - N_3 = M_1 a_1$$

$$M_1 \text{ in } y \text{ direction} : N_1 - M_1 g - N_2 - N_{0y} = 0 \text{ (doesn't move in } y \text{ direction)}$$

$$M_2 \text{ in } x \text{ direction} : F_{F2} + T = M_2 a_2$$

$$M_2 \text{ in } y \text{ direction} : N_2 - M_2 g = 0$$

$$M_3 \text{ in } x \text{ direction} : N_3 = M_3 a_{3x}$$

$$M_3 \text{ in } y \text{ direction} : T - M_3 g - 2F_{F3} = M_3 a_{3y}$$

$$M_0 \text{ in } x \text{ direction} : N_{0x} - T = M_0 g = 0 \implies N_{0x} = T$$

$$M_0 \text{ in } y \text{ direction} : N_{0y} - T = M_0 g = 0 \implies N_{0y} = T$$

*And the following constraints*

*The length of the rope is constant  $\implies a_1 - a_2 - a_{3y} = 0 \implies a_1 = a_2 + a_{3y}$*

*$M_3$  cannot escape the hole  $\implies a_1 = a_{3x}$*

*From the system of equations we will get that*

$$a_1 = \frac{(M_3 + M_2)(F - \mu_1(M_1 + M_2)g) - M_2M_3g(1 - \mu_2)(1 - \mu_1)}{(M_1 + M_3)(M_3 + M_2) + (1 - \mu_1)(2\mu_3M_3 + M_3)M_2}$$

$$T = \frac{M_2M_3g + (2\mu_3M_3 + M_3)a_1M_2 - \mu_2M_2gM_3}{M_3 + M_2}$$

$$a_2 = \frac{T - M_3g - 2\mu_3M_3a_1 - M_3a_1}{-M_3}$$

$$a_{3y} = a_1 - a_2$$

$$a_{3x} = a_1$$

*by having  $a_1, a_2, a_{3y}, a_{3x}, M_1, M_2, M_3, F_n, \mu_1, \mu_2, \mu_3, x_1, x_2, x_3, y_1, y_2, y_3, t_n$  we can find the coordinates after we use the  $F_n$  forces ( see the code).*