

AI HEALTHCARE IMAGING

GROUP 4

TEACHER:
PAIROTE SATIRACOO

LIVER
SEGMENTATION
USING MONAI
AND PYTORCH

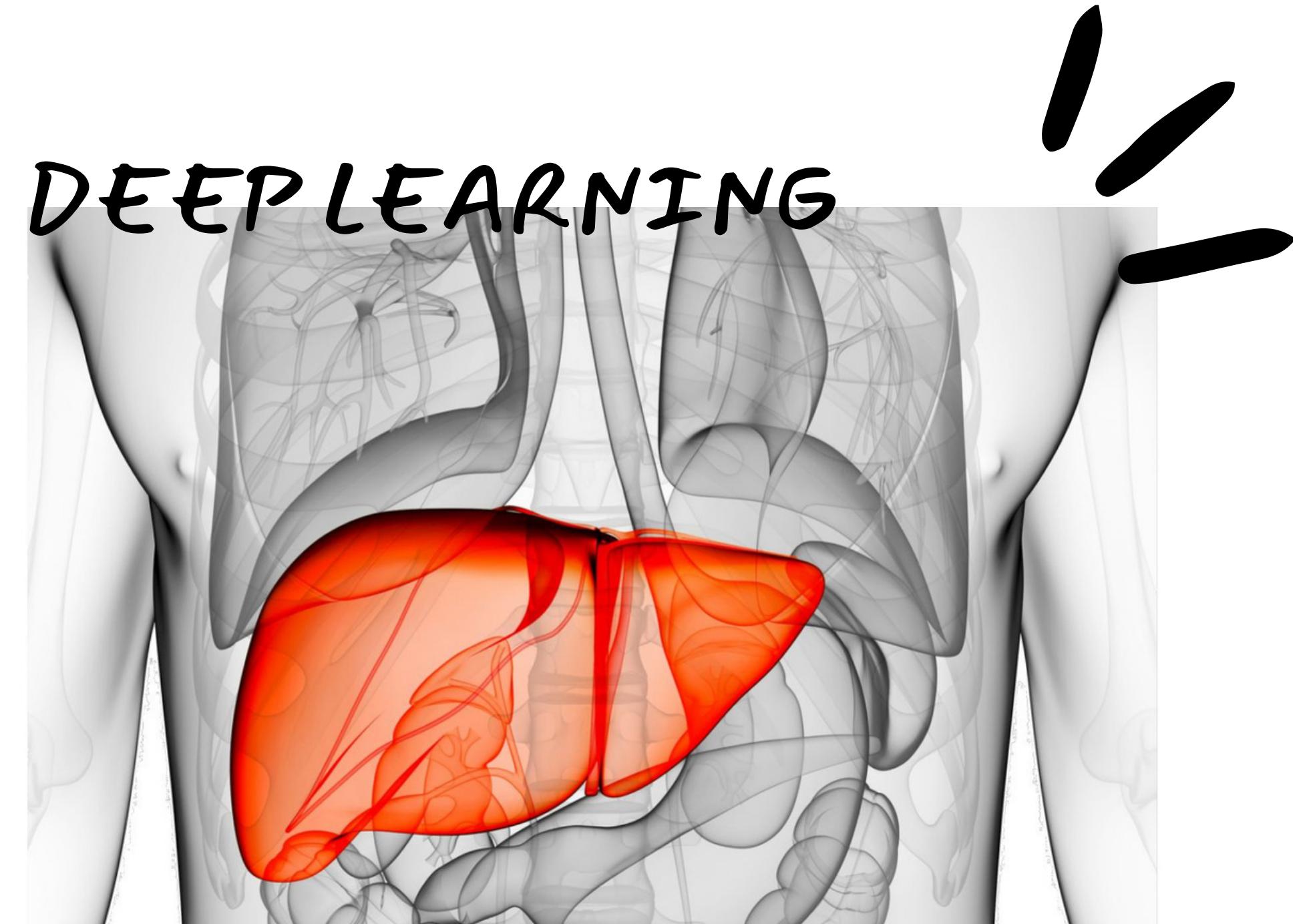
WELCOME TO → TODAY'S CLASS!

TODAY'S
AGENDA

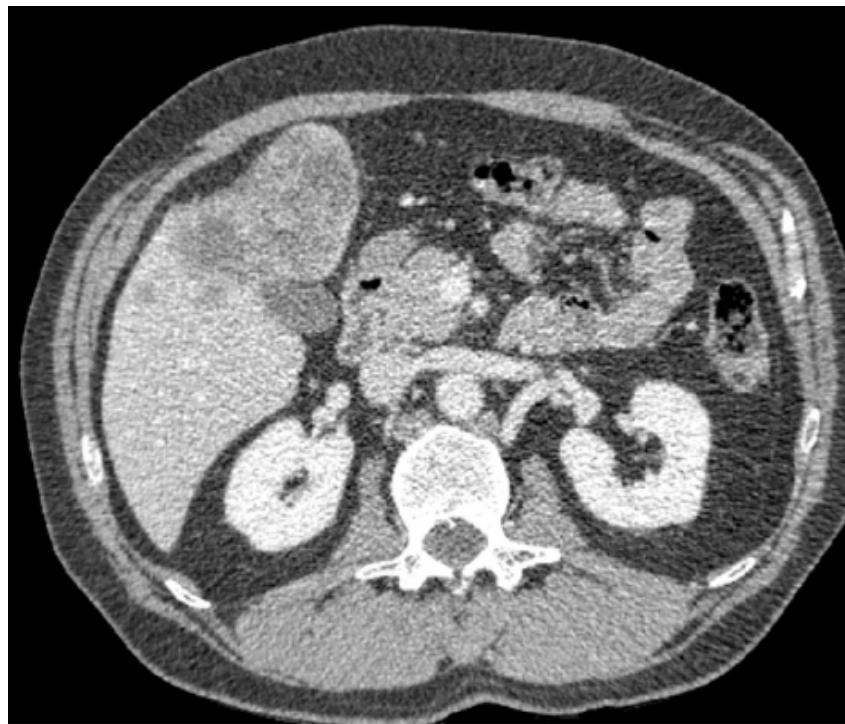
- 1 INTRODUCTION
- 2 SOFTWARE INSTALLATION
- 3 ABOUT THIS DATASET
- 4 PREPARE AND PREPROCESS THE DATA.
- 5 TRAINING AND TESTING
- 6 RESULT

LIVER SEGMENTATION

INTRODUCTION



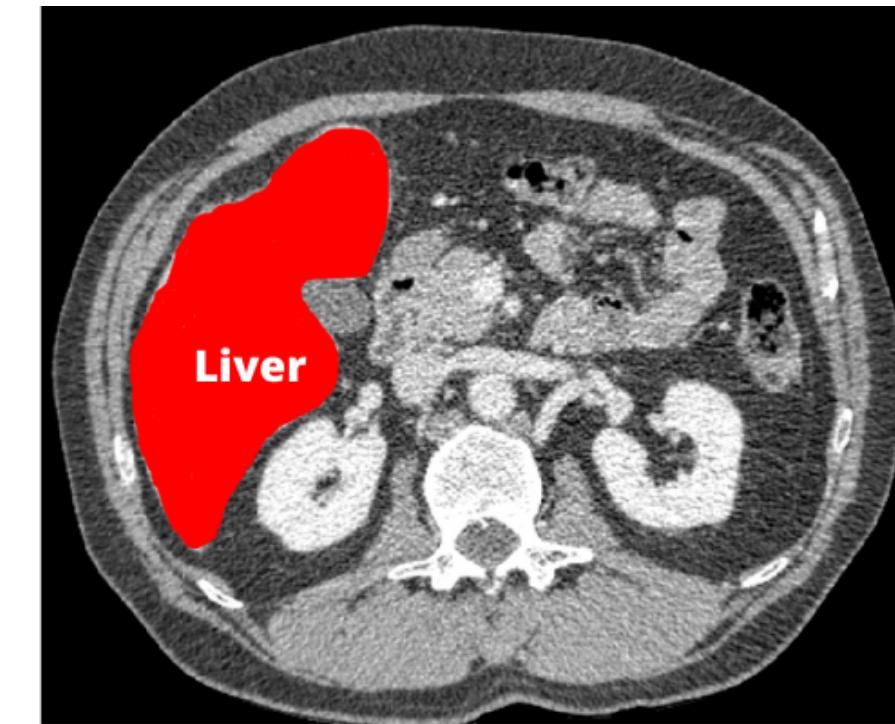
WHAT IS THERE IN
IMAGE AND WHERE?



Classification

Liver: 99.99%

WHICH PIXELS BELONGS
TO WHICH OBJECT?



Segmentation

IMAGE
CLASSIFICATION



Object Detection



IMAGE
DETECTION

IMAGE
SEGMENTATION

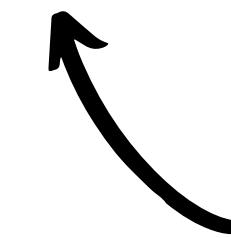


IMAGE SEGMENTATION TYPES



**Semantic
Segmentation**

Tumor/No Tumor



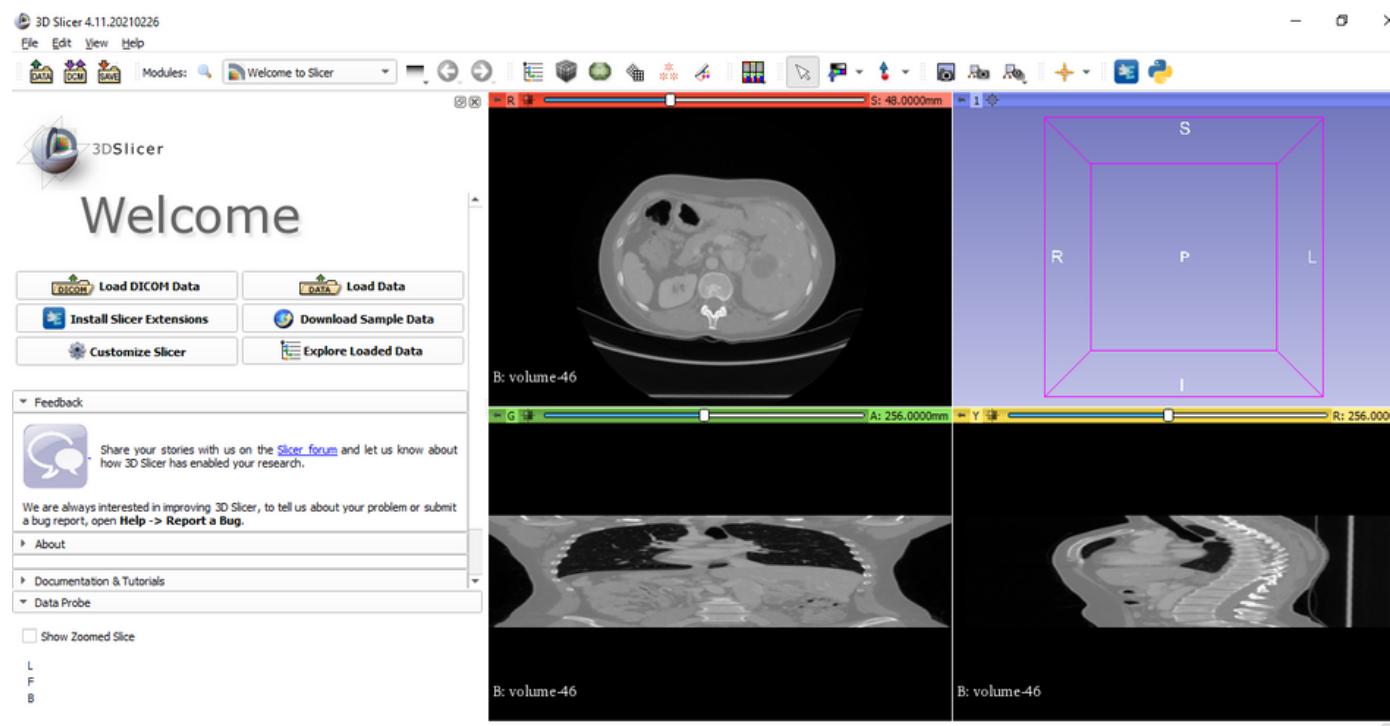
**Instance
Segmentation**

Tumor/No Tumor/How many

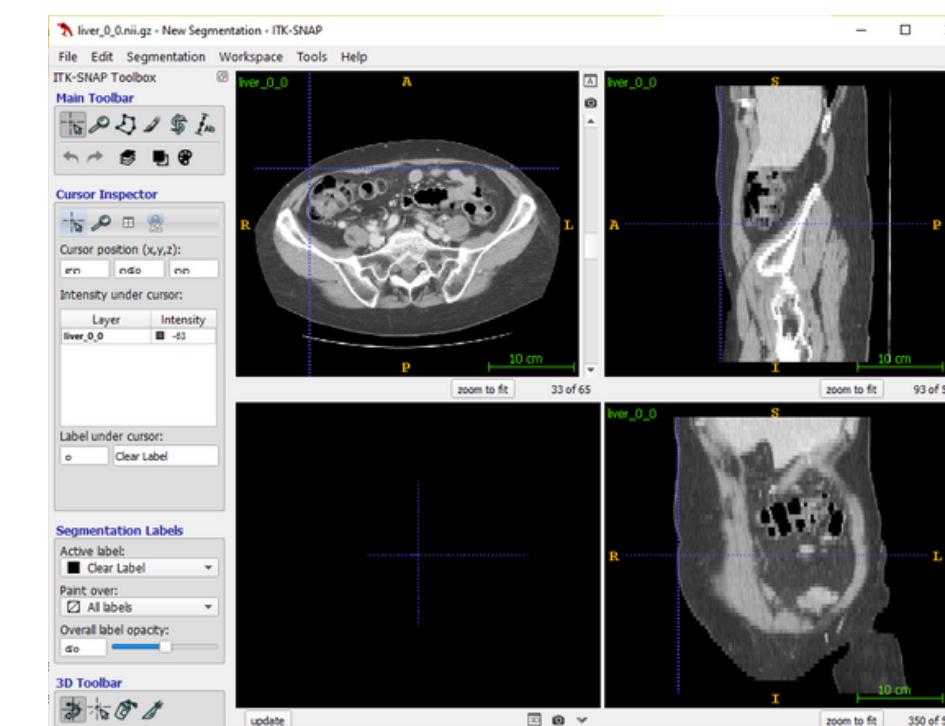
IN OUR CASE, SEMANTIC SEGMENTATION WILL BE USED BECAUSE WE NEED TO KNOW WHETHER THE SLICE CONTAINS A LIVER OR NOT.

SOFTWARE *INSTALLATION*

- ***PROGRAMMING LANGUAGE: PYTHON***
- ***3D VISUALIZATION: 3D SLICER***
- ***TOOL FOR SEGMENTATION: ITK SNAP***



3D SLICER



ITK SNAP

INSTALLATION

INCLUDES

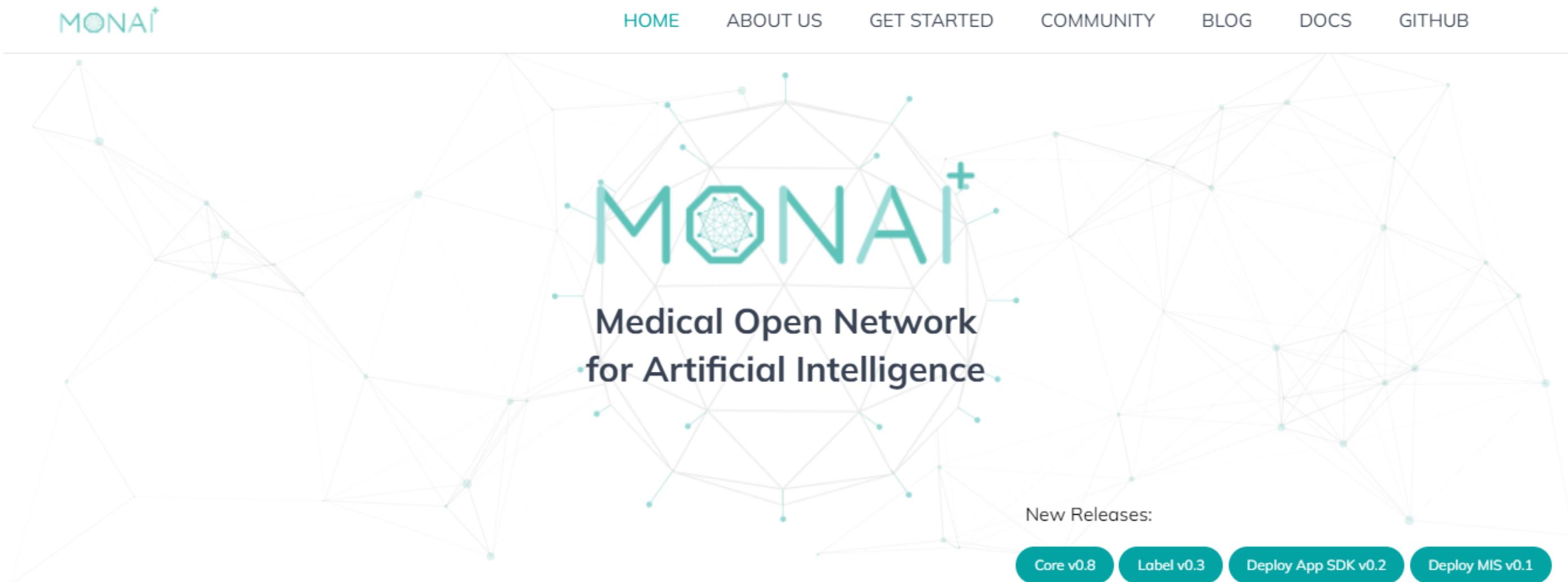
AND



- INSTALL CUDA
- INSTALL CUDNN
- INSTALL MONAI
- INSTALL PYTORCH

*requirements

MATPLOTLIB
NUMPY
TQDM
GLOB2
DICOM2NIFTI
PYTEST-SHUTIL
NIBABEL



WHAT IS MONAI?

NVIDIA เปิดตัว MEDICAL OPEN NETWORK FOR AI (MONAI) เฟรมเวิร์ค
โอเพนซอร์สสำหรับ AI วิเคราะห์ภาพถ่ายทางการแพทย์ (MEDICAL IMAGING
เช่น X-RAY, CT, MRI, ULTRASOUND) ตัวมันเองพัฒนาจาก PYTORCH

การเตรียมข้อมูล

PREPARING DATA



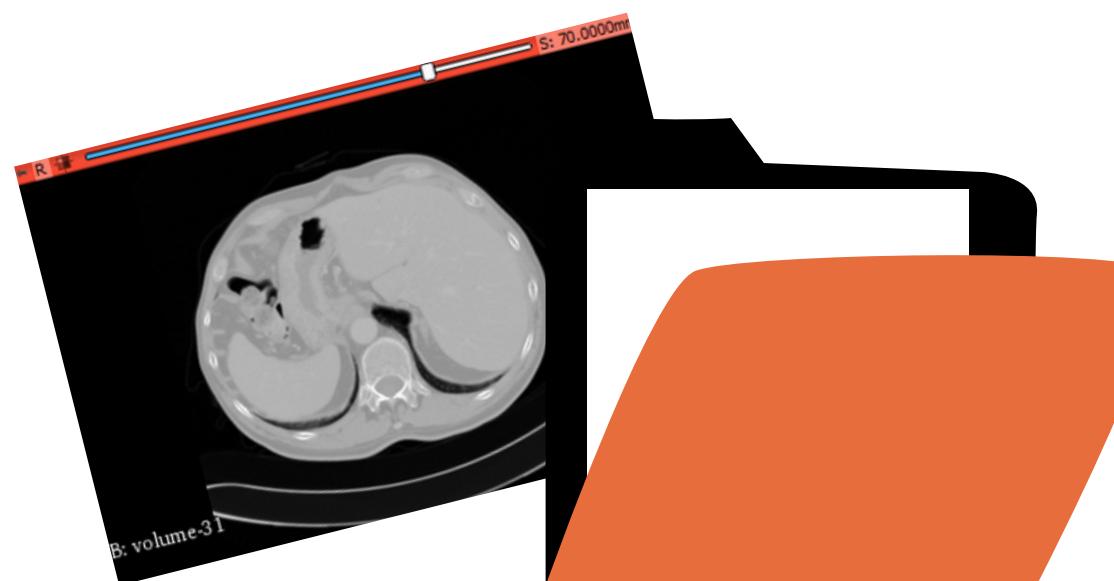
*STEP 1:

- 1 Download Dataset
- 2 Dividing the data into train/test folders
- 3 Convert nifties into dicom files
- 4 Move every 65 slices into a folder
- 5 Reconvert the groups of 65 slices into nifti files
- 6 Delete the empty volumes

DOWNLOAD DATASET

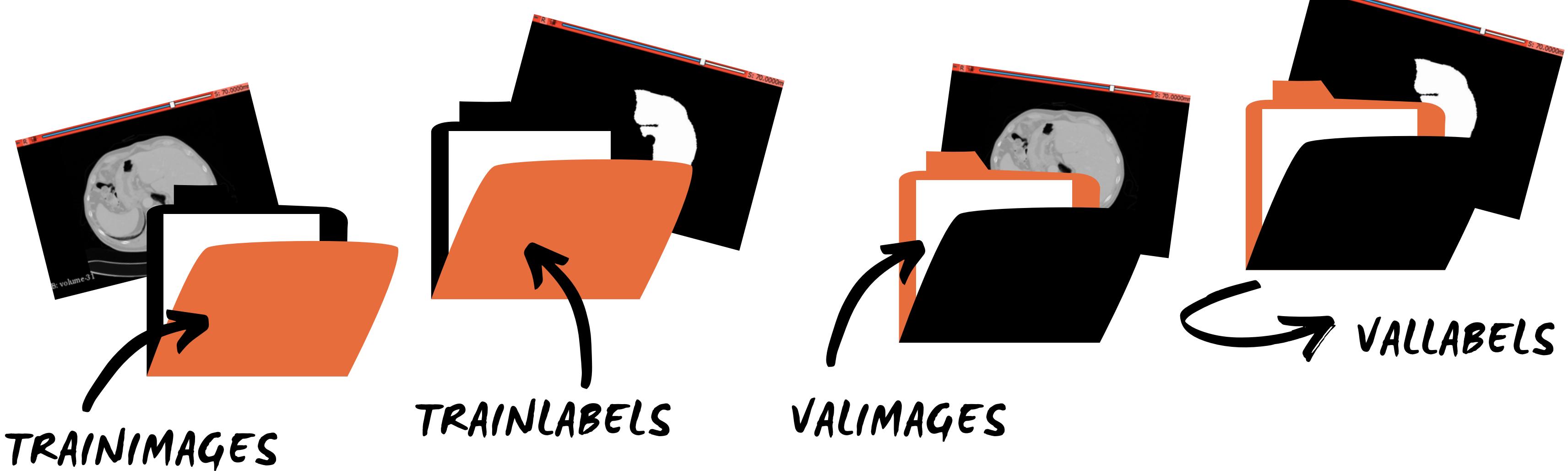
FROM KAGGLE

SEGMENTATIONS



VOLUME

DIVIDING THE DATA INTO TRAIN/TEST FOLDERS





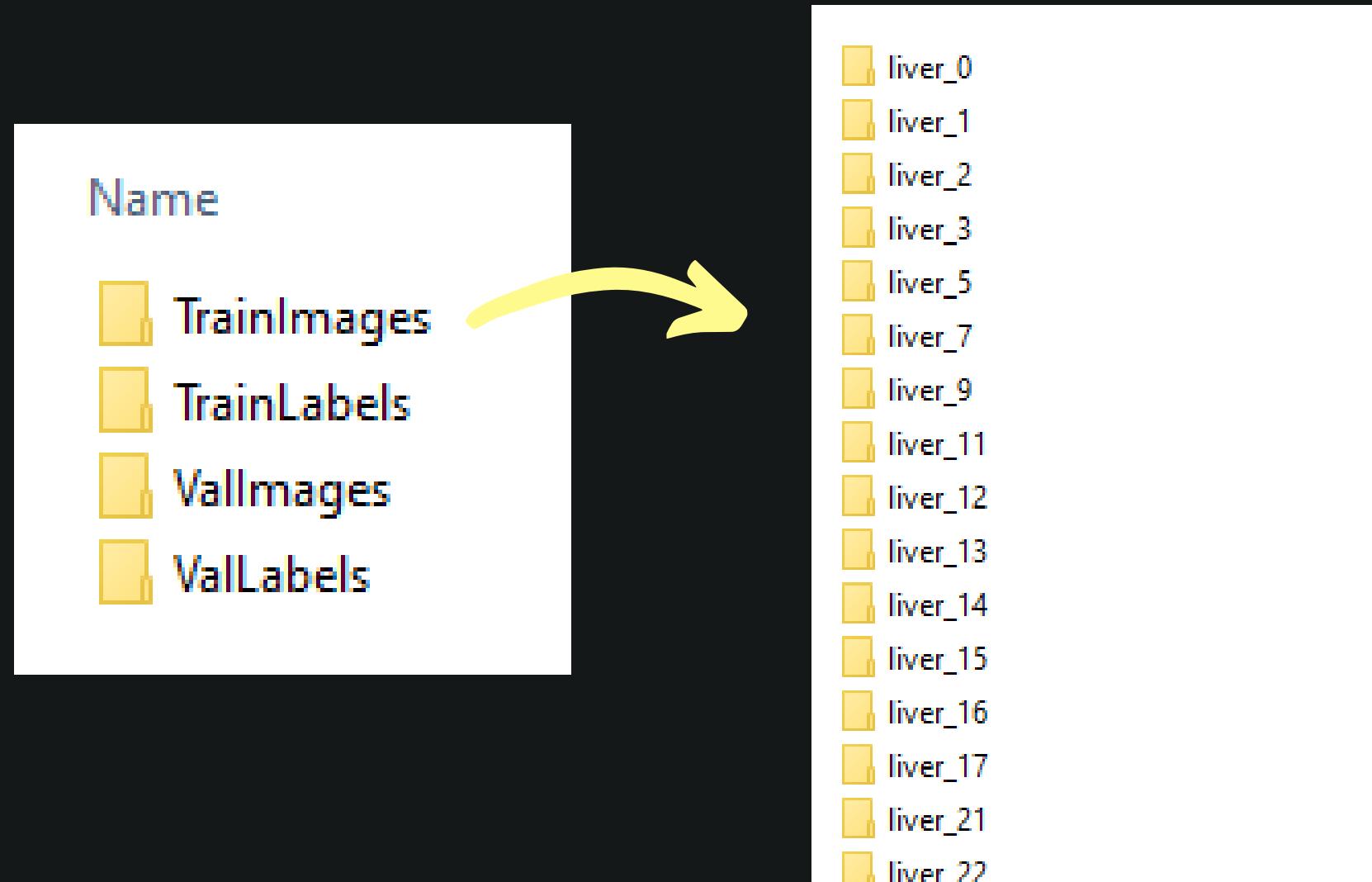
```
from glob import glob
import shutil
import os
import numpy as np
import pandas as pd
from sklearn.model_selection import train_test_split

labels_path = 'D:/Liver Segmentation/Kaggle/nifti_raw/segmentations'
images_path = 'D:/Liver Segmentation/Kaggle/nifti_raw/volume'
data = {'Labels': glob(labels_path + '/*'),
        'Images': glob(images_path + '/*')}
df = pd.DataFrame(data)

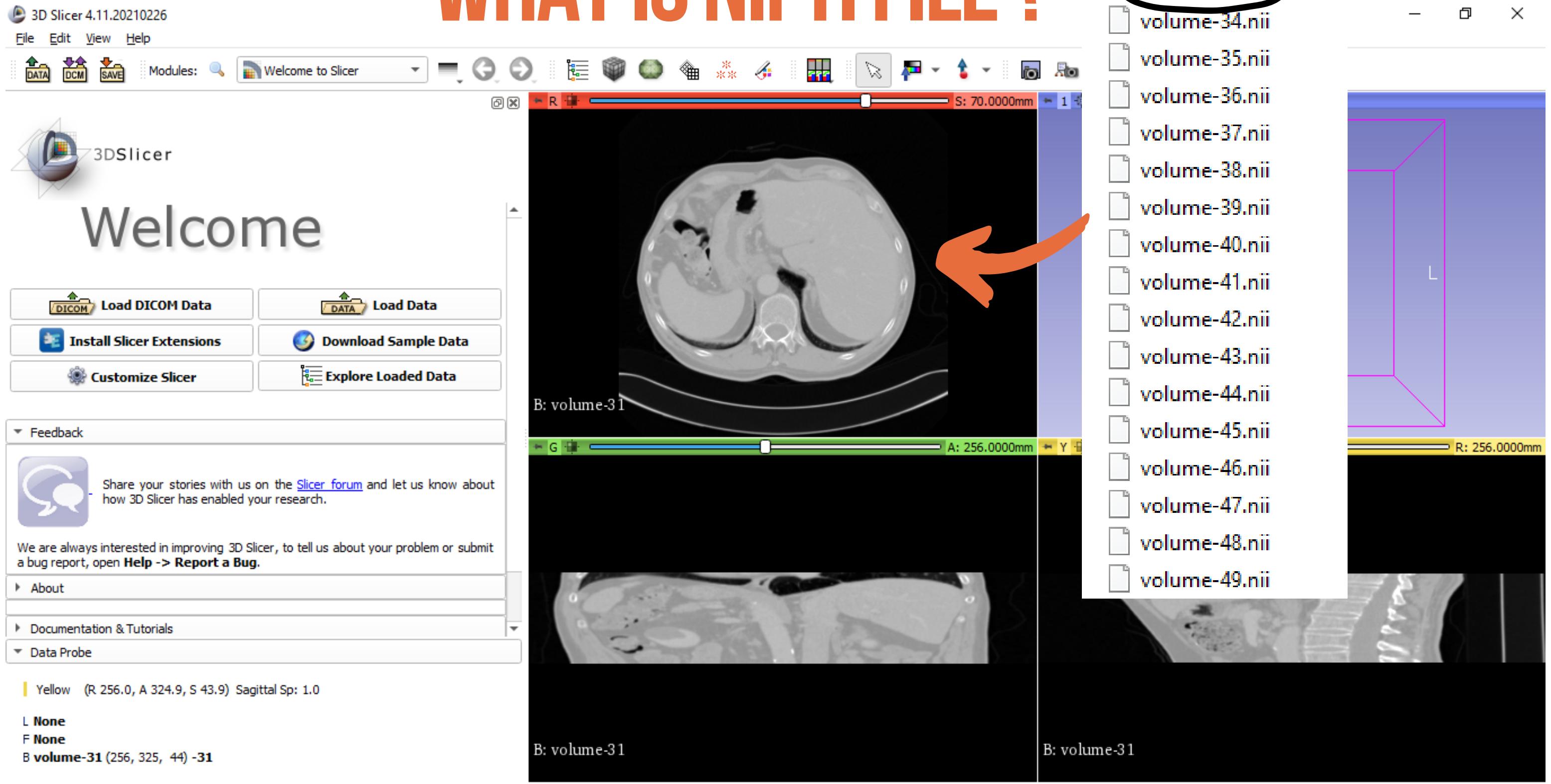
Images = df[['Images']]
Labels = df['Labels']
TrainImages, ValImages, TrainLabels, ValLabels = train_test_split(Images, Labels, test_size=0.06,
random_state=6305093)

def move_directory(path_name, path, destination):
    os.mkdir(destination)
    for sorce in path:
        patient_name = os.path.basename(os.path.normpath(sorce))
        letter = [char for char in patient_name]
        num = [int(s) for s in letter if s.isdigit()]
        string = map(str, num)
        index = ''.join(string)
        os.mkdir(os.path.join('D:\Liver Segmentation\Kaggle\Dicom_sep', path_name, 'liver_'+ index))
        shutil.move(sorce, destination)
```

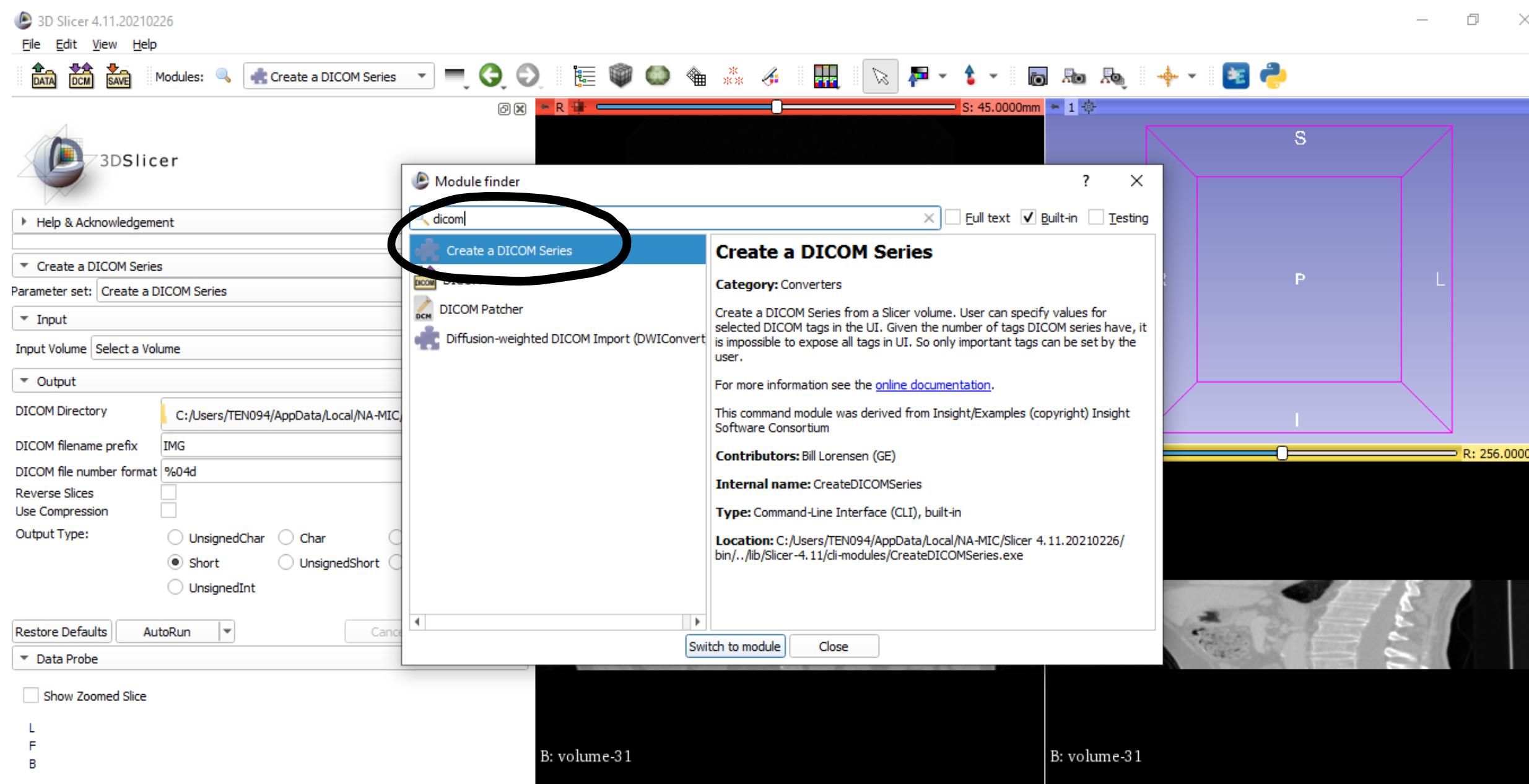
```
move_directory('TrainImages', TrainImages['Images'], 'D:/Liver  
Segmentation/Kaggle/nifti_sep/TrainImages')  
  
move_directory('ValImages', ValImages['Images'], 'D:/Liver Segmentation/Kaggle/nifti_sep/ValImages')  
  
move_directory('TrainLabels', TrainLabels, 'D:/Liver Segmentation/Kaggle/nifti_sep/TrainLabels')  
  
move_directory('ValLabels', ValLabels, 'D:/Liver Segmentation/Kaggle/nifti_sep/ValLabels')
```



WHAT IS NIFTI FILE ?



CONVERT NIFTIES INTO DICOM FILES



MOVE EVERY 65 SLICES INTO A FOLDER

```
for patient in glob(in_path + '/*'):
    patient_name = os.path.basename(os.path.normpath(patient))
    number_folders = int(len(glob(patient + '/*'))/65)

    for i in range(number_folders):
        output_path_name = os.path.join(out_path, patient_name + '_' + str(i))
        os.mkdir(output_path_name)
        for i, file in enumerate(glob(patient + '/*')):
            if i == 65+1:
                break
            shutil.move(file, output_path_name)
```

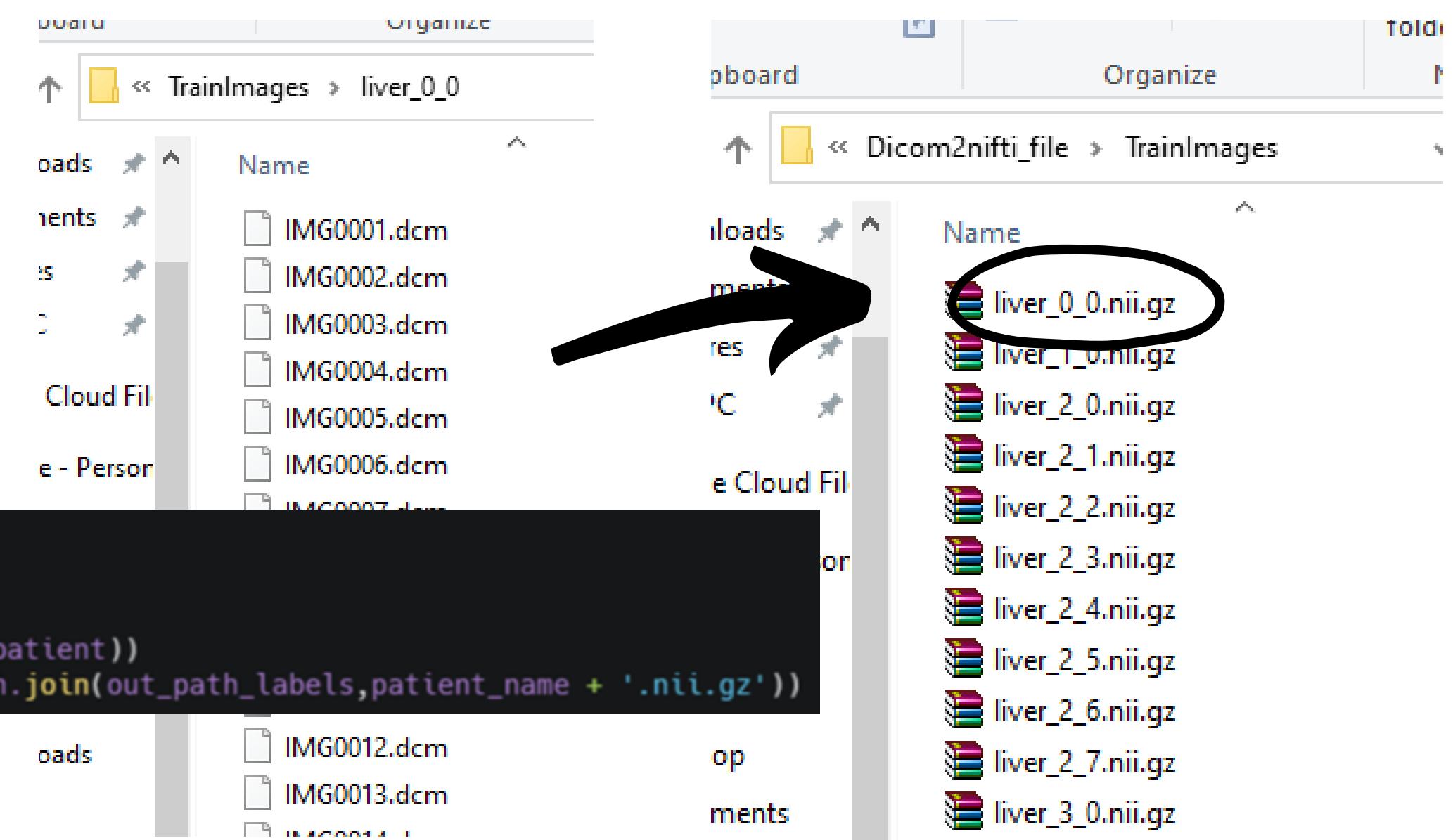
Dicom_group << TrainImages >>	
	Name
liver_0	liver_0_0
liver_1	liver_1_0
liver_2	liver_2_0
liver_2	liver_2_1
liver_2	liver_2_2
liver_2	liver_2_3
liver_2	liver_2_4
liver_2	liver_2_5
liver_2	liver_2_6
liver_2	liver_2_7
liver_3	liver_3_0
liver_3	liver_3_1

RECONVERT THE GROUPS OF 65 SLICES INTO NIFTI FILES

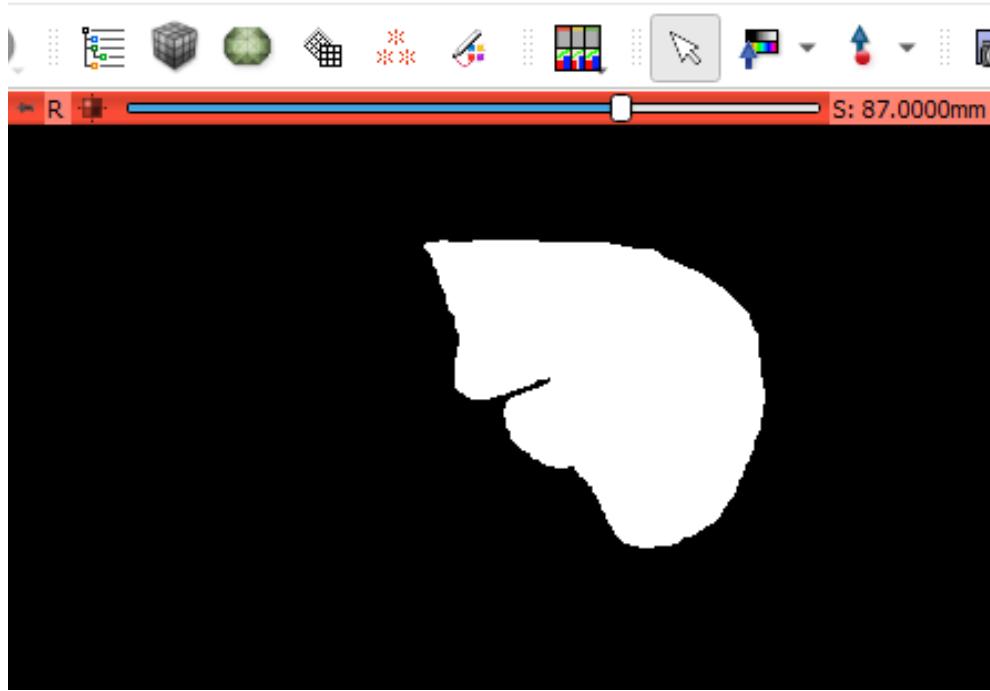
PACKAGE : *DICOM2NIFTI*



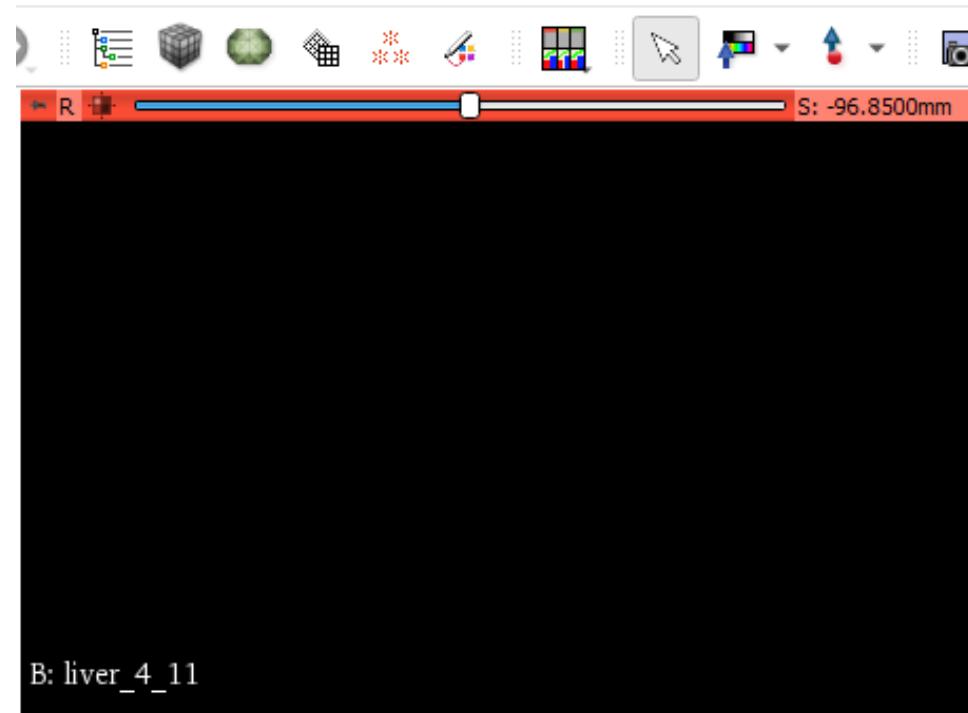
```
for patient in list_labels:  
    patient_name = os.path.basename(os.path.normpath(patient))  
    dicom2nifti.dicom_series_to_nifti(patient, os.path.join(out_path_labels, patient_name + '.nii.gz'))
```



DELETE THE EMPTY FILE



$\text{LEN}(\text{NP_UNIQUE}) \neq 1$
NOT EMPTY



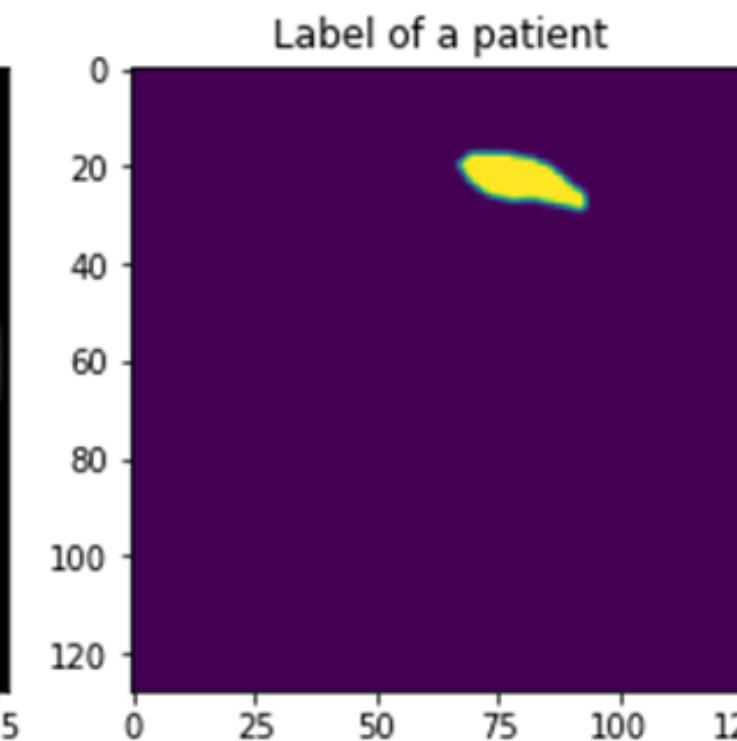
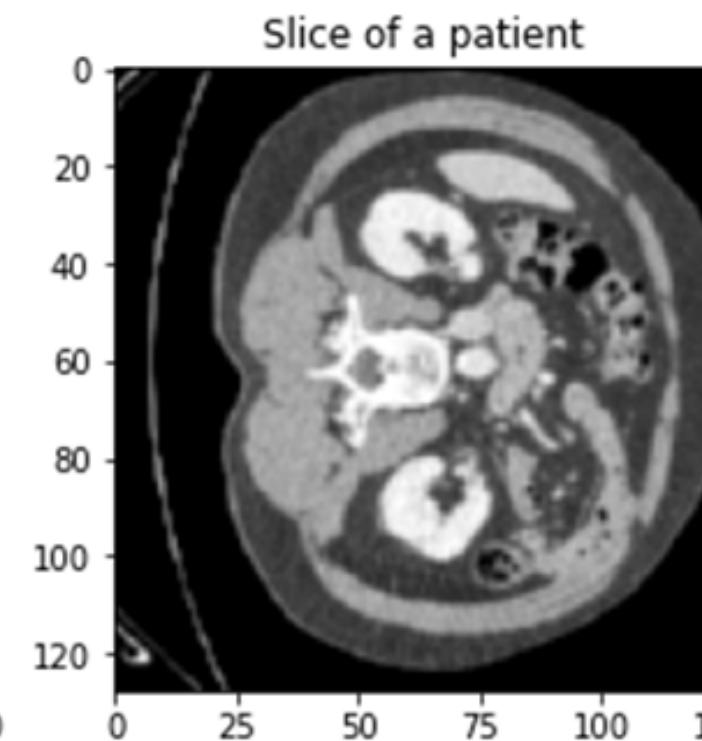
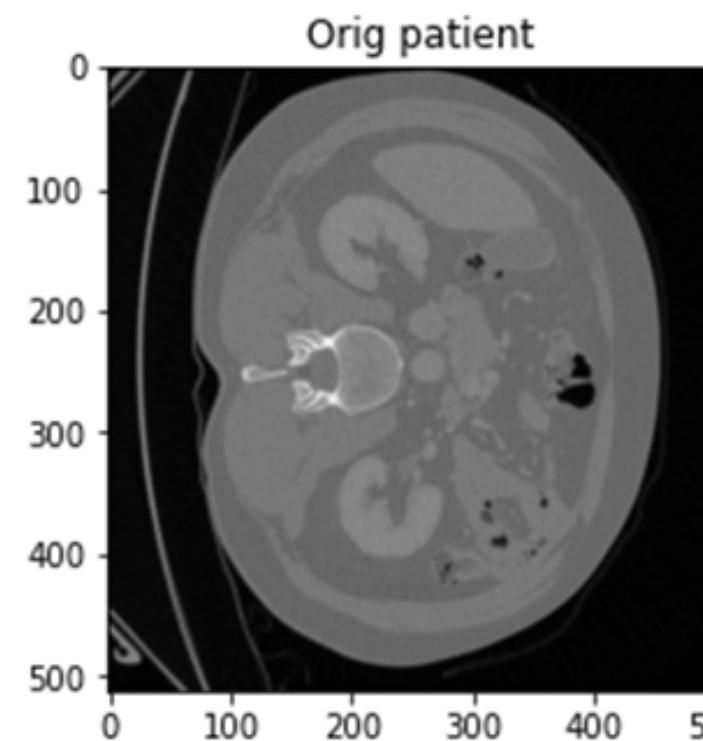
EMPTY FILE
 $\text{LEN}(\text{NP_UNIQUE}) == 1$

```
for patient in list_labels:  
    nifti_file = nib.load(patient)  
    fdata = nifti_file.get_fdata()  
    np_unique = np.unique(fdata)  
    if len(np_unique) == 1:  
        shutil.move(patient, Output_bin_path)
```

ปรับแต่งข้อมูลก่อนนำไปTRAIN

PREPOCESSING

*STEP 2:



```

def prepare(in_dir, pixdim=(1.5, 1.5, 1.0), a_min=-200, a_max=200, spatial_size=[128,128,64],
cache=False):
    set_determinism(seed=0)

    path_train_volumes = sorted(glob(os.path.join(in_dir, "TrainVolumes", "*.nii.gz")))
    path_train_segmentation = sorted(glob(os.path.join(in_dir, "TrainSegmentation", "*.nii.gz")))

    path_test_volumes = sorted(glob(os.path.join(in_dir, "TestVolumes", "*.nii.gz")))
    path_test_segmentation = sorted(glob(os.path.join(in_dir, "TestSegmentation", "*.nii.gz")))

    train_files = [{"vol": image_name, "seg": label_name} for image_name, label_name in
zip(path_train_volumes, path_train_segmentation)]
    test_files = [{"vol": image_name, "seg": label_name} for image_name, label_name in
zip(path_test_volumes, path_test_segmentation)]

    train_transforms = Compose([
        LoadImaged(keys=["vol", "seg"]),
        AddChanneld(keys=["vol", "seg"]),
        Spacingd(keys=["vol", "seg"], pixdim=pixdim, mode=("bilinear", "nearest")),
        Orientationd(keys=["vol", "seg"], axcodes="RAS"),
        ScaleIntensityRanged(keys=["vol"], a_min=a_min, a_max=a_max, b_min=0.0, b_max=1.0,
clip=True),
        CropForegroundd(keys=["vol", "seg"], source_key="vol"),
        Resized(keys=["vol", "seg"], spatial_size=spatial_size),
        ToTensord(keys=["vol", "seg"]),
    ])
)
test_transforms = Compose([
    LoadImaged(keys=["vol", "seg"]),
    AddChanneld(keys=["vol", "seg"]),
    Spacingd(keys=["vol", "seg"], pixdim=pixdim, mode=("bilinear", "nearest")),
    Orientationd(keys=["vol", "seg"], axcodes="RAS"),
    ScaleIntensityRanged(keys=["vol"], a_min=a_min, a_max=a_max, b_min=0.0, b_max=1.0,
clip=True),
    CropForegroundd(keys=['vol', 'seg'], source_key='vol'),
    Resized(keys=["vol", "seg"], spatial_size=spatial_size),
    ToTensord(keys=["vol", "seg"]),
])
)

```

train_transforms = Compose() เป็นฟังก์สำหรับรวมการเปลี่ยนแปลงทั้งหมดแล้วนำไปใช้กับรูปภาพในครั้งเดียว



- **ADDCHANNELD**- เพิ่มชีนแนลสำหรับแยกพื้นหลังกับพื้นที่ระบบ
- **LOADIMAGED**- เป็นการโหลดข้อมูลมาก่อนเริ่มปรับแต่ง
- **RESIZED**- ปรับขนาดรูปภาพ(รูปภาพในที่นี้หมายถึงกลุ่มของสไลด์)
- **TOTENSORD**- แปลงเป็น **TENSOR**เตรียมสำหรับขั้นตอน **TRAIN**
- **SPACINGD**- ใช้สำหรับปรับ **VOXEL SPACING**ให้เท่ากันทั้งหมด
- **ORIENTATIOND**- หมุนรูปภาพ
- **SCALEINTENSITYRANGED**- กำس่องอย่างด้วยกันคือปรับสีภาพให้ชัดขึ้น และกำหนดค่าความเข้มแสงให้อยู่ระหว่าง 0 ถึง 1
- **CROPFOREGROUNDD**- ตัดส่วนว่างที่ไม่จำเป็นออกจากรูปภาพจะเห็นได้ว่า ข้างหลังฟังก์จะลงท้ายด้วยตัว **D**เพื่อใช้กับข้อมูล **DICTIONARY**

TRAIN / TEST THE MODEL

*STEP 3:



- 1 The U-Net Model
- 2 Loss Function
- 3 Train/Test the Model

THE U-NET MODEL

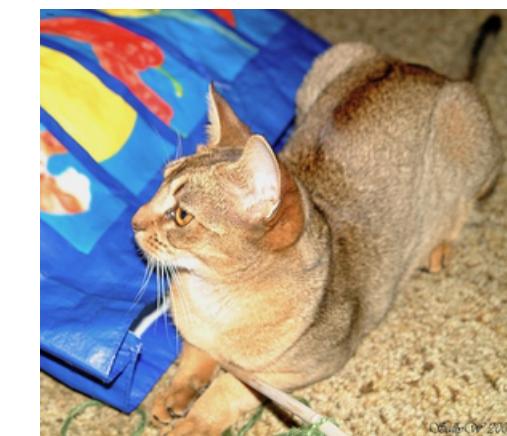
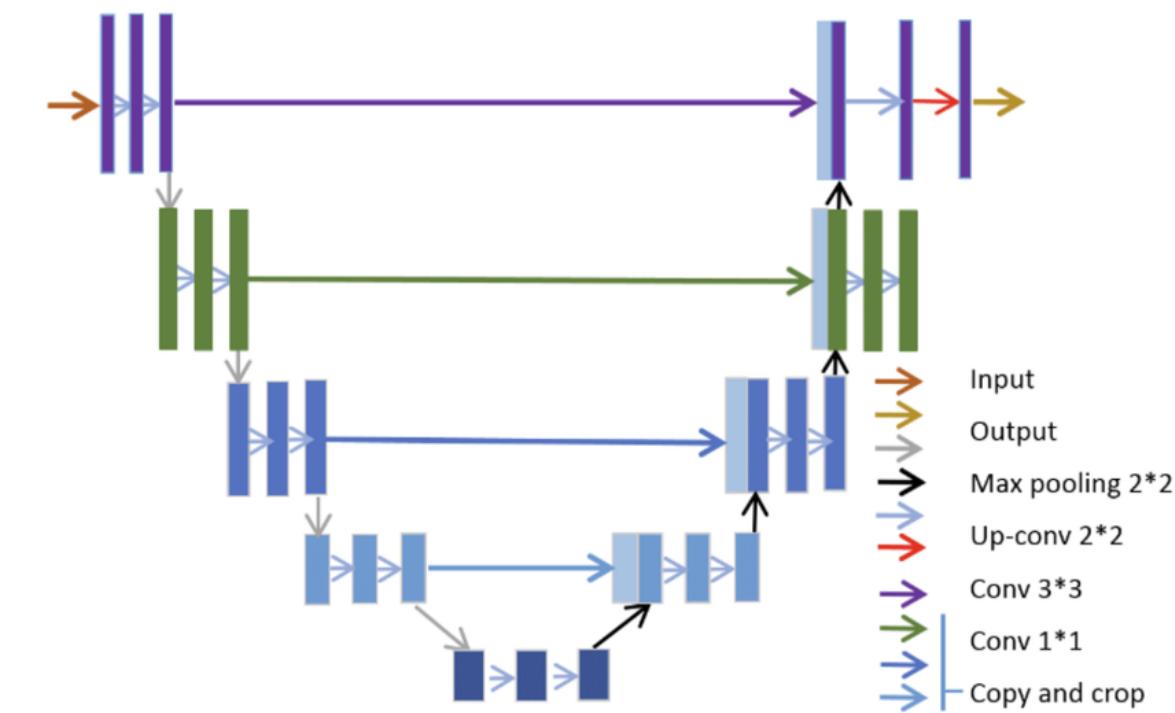
FROM MONAI



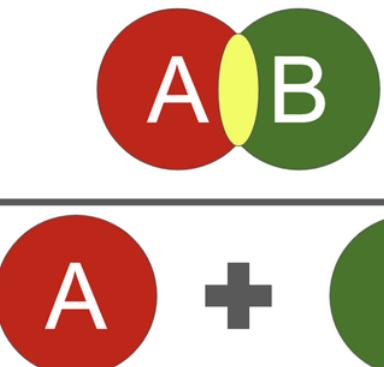
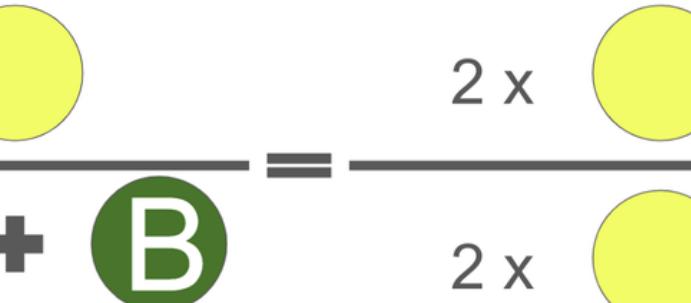
```
model = UNet(  
    dimensions=3,  
    in_channels=1,  
    out_channels=2,  
    channels=(16, 32, 64, 128, 256),  
    strides=(2, 2, 2, 2),  
    num_res_units=2,  
    norm=Norm.BATCH,  
).to(device)
```

UNET ถูกนำมาแก้ปัญหานี้โดยเฉพาะ เพราะว่า เทคนิคนี้ สามารถระบุพื้นที่และแยกเส้นขอบได้ดี ในระดับ PIXEL SPACE จึงเหมาะสมการโจทย์ IMAGE SEGMENTATION หรือ IMAGE CLASSIFICATION โดย INPUT และ OUTPUT ของ UNET เป็นขนาดเท่ากัน

UNET คือหนึ่ง NEURAL NETWORK ARCHITECTURE ที่ พัฒนามาจาก CONVOLUTIONAL NEURAL NETWORK แบบ ดั้งเดิม เพื่อวิเคราะห์โรคหรือระบุจุดของความผิดปกติในภาพถ่าย โดยรูปแบบสถาปัตยกรรมของ NETWORK นี้ มีรูปแบบที่ย่อและขยายข้อมูลในแต่ละ LAYERS ลักษณะคล้ายรูปตัว U



DICE

$$DICE = \frac{2 \times \frac{\text{A} \cap \text{B}}{\text{A} + \text{B}}}{\frac{\text{A} + \text{B}}{2}}$$

$$= \frac{2 \times \frac{\text{A} \cap \text{B}}{\text{A} + \text{B}}}{\frac{\text{A} + \text{B}}{2}} = \frac{2 \times \frac{\text{A} \cap \text{B}}{\text{A} + \text{B}}}{\frac{2 \times \text{A} \cap \text{B}}{\text{A} + \text{B}}}$$


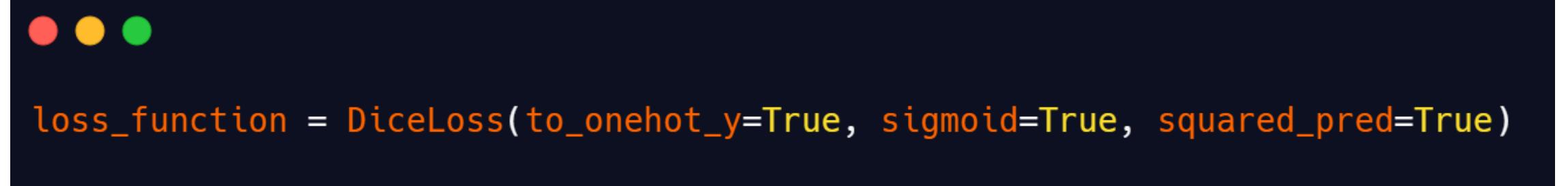
$$DICE LOSS = 1 - DICE$$

LOSS FUNCTION

DICE LOSS
FROM MONAI

ทางด้านการ grenของโนเดลที่เราสร้างคือการหา **DICE COEFFICIENT** หรือเรียกอีกอย่างนึงคือ **F1 SCORE** สามารถเขียนได้เป็นสมการ โดย **TP** คือ **TRUE POSITIVE** **FP** คือ **FALSE POSITIVE** และ **FN** คือ **FALSE NEGATIVE**

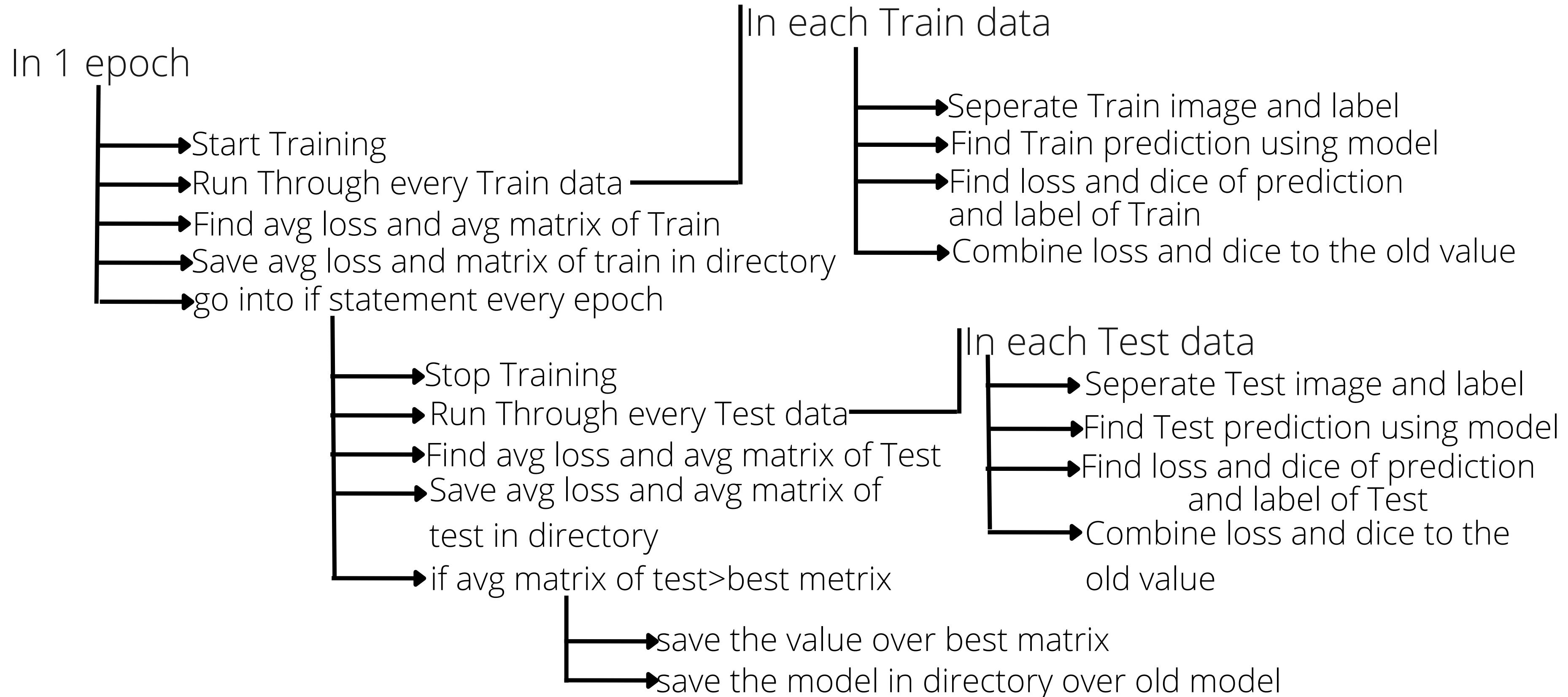
$$Dice = \frac{2 \times TP}{(TP + FP) + (TP + FN)}$$



```
loss_function = DiceLoss(to_onehot_y=True, sigmoid=True, squared_pred=True)
```

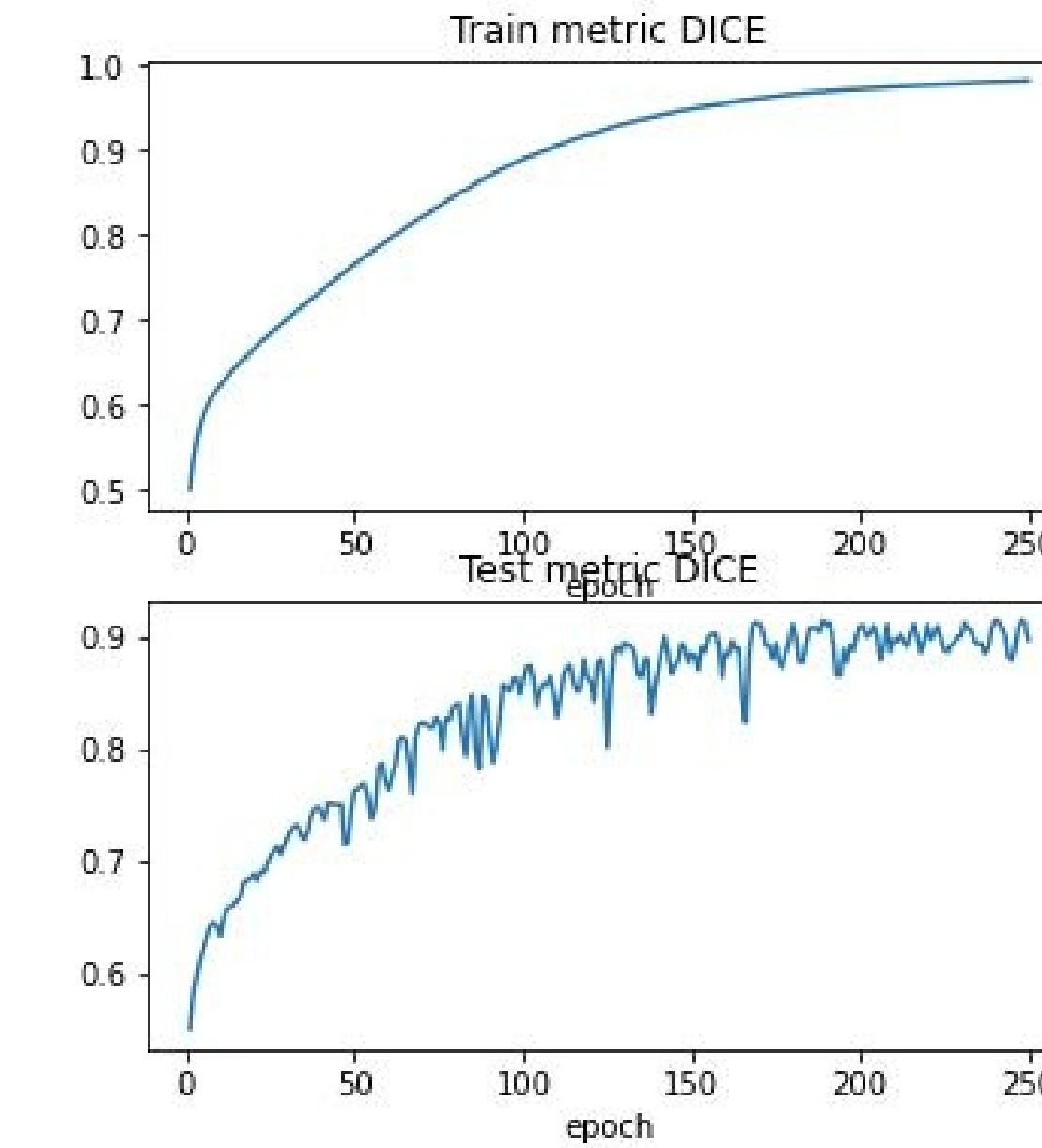
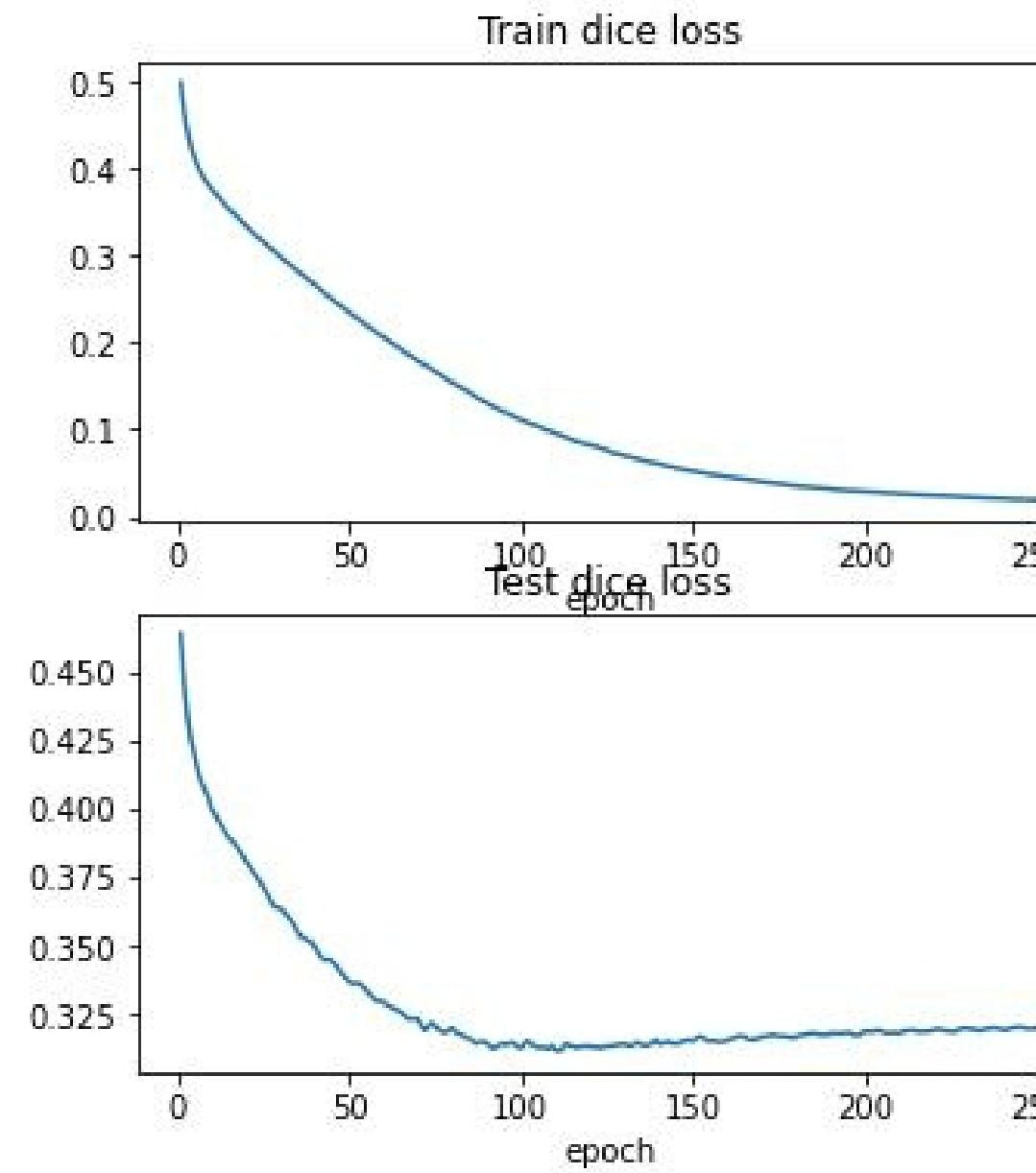
หลักการคือ yิ่งภาพมีการเหมือนกันมากค่าจะเข้าใกล้ 1 ยิ่งภาพที่เรา **PREDICT** ออกมาจากภาพ **MRI** มีความคล้ายภาพที่ **LABEL** **DICE COEFFICIENT** จะมีค่ามาก ส่วน **DICE LOSS** คือการเอา 1 ไปลบกับ **DICE COEFFICIENT** ยิ่งค่าเข้าใกล้ 0 แสดงว่า **MODEL** ที่ทำมามีประสิทธิภาพดี ในงานนี้เราจะใช้ฟังก์ชัน **DICELOSS()** ในการหา **DICE LOSS**

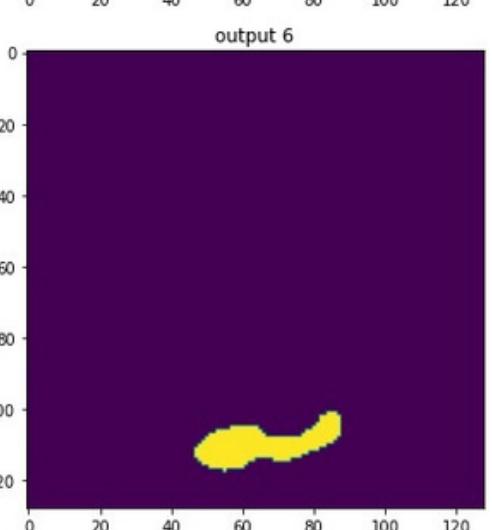
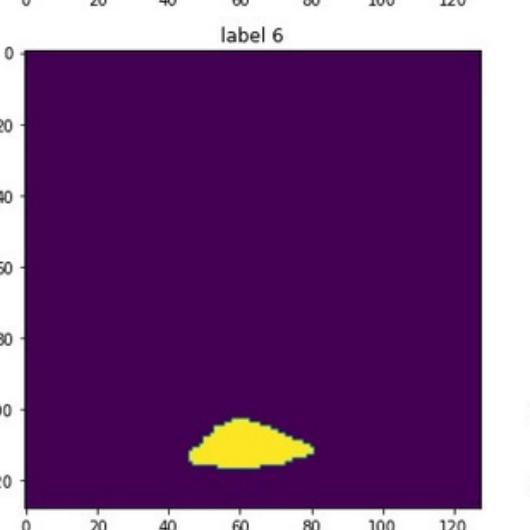
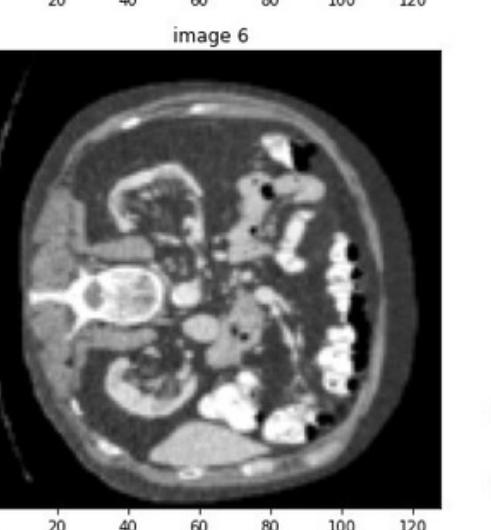
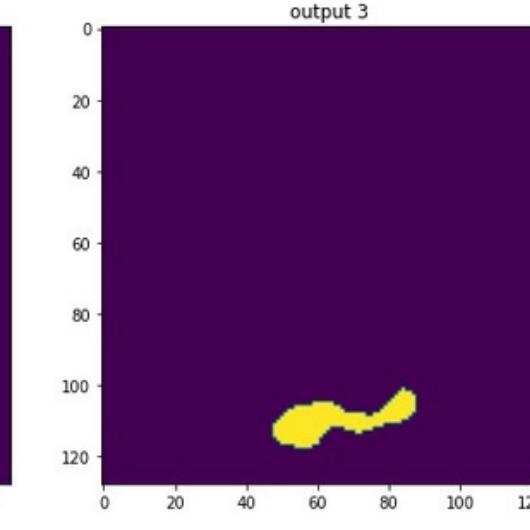
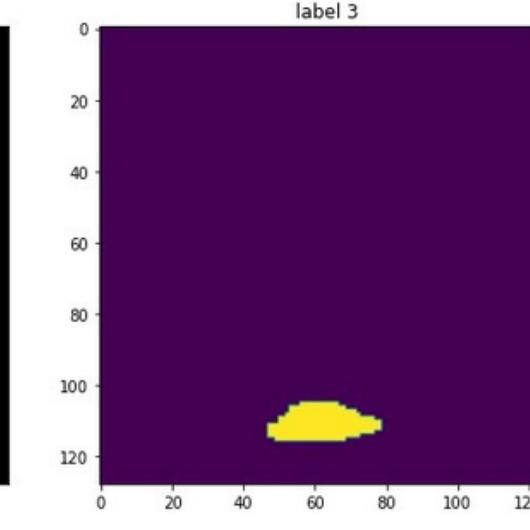
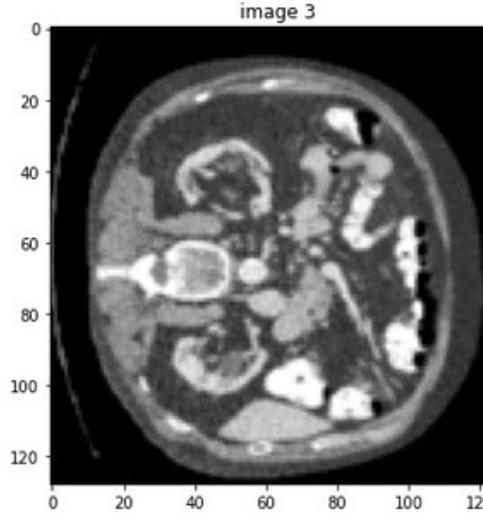
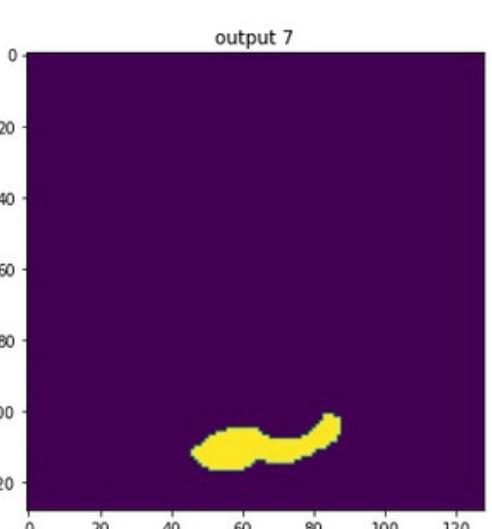
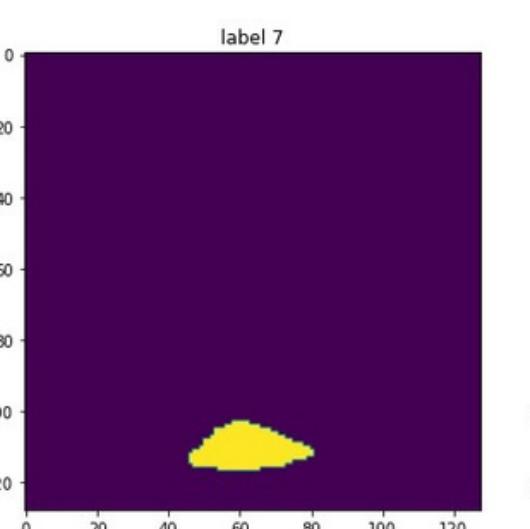
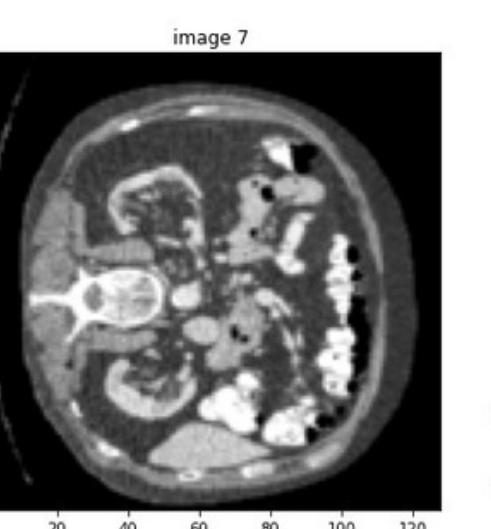
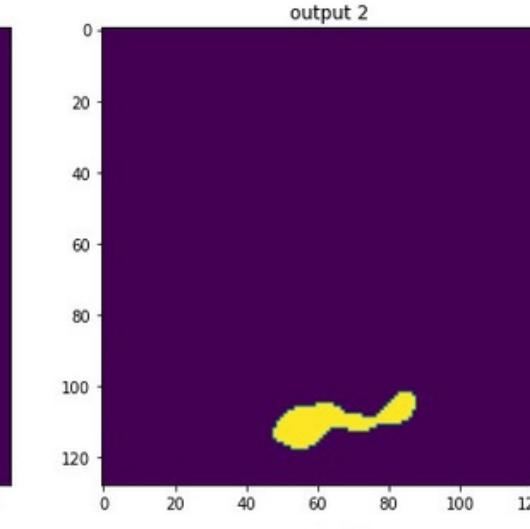
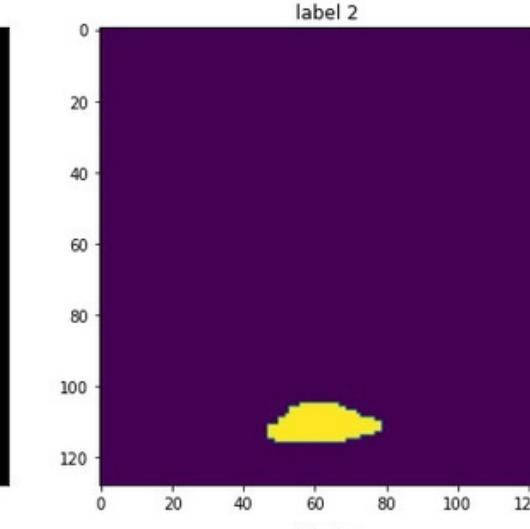
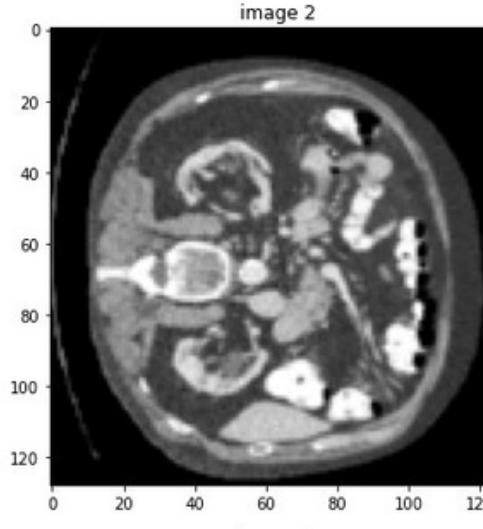
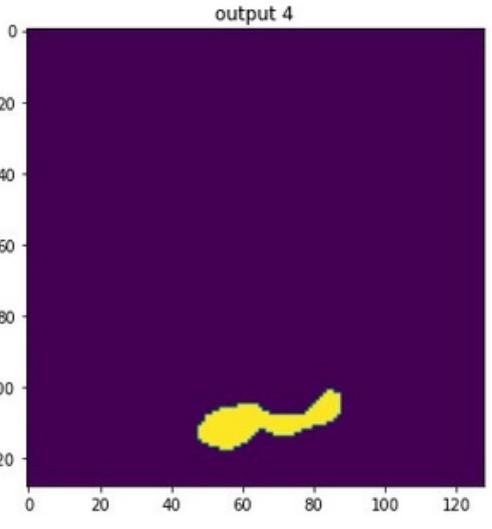
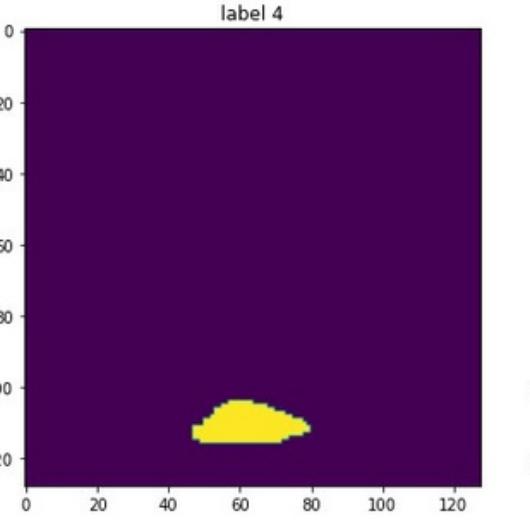
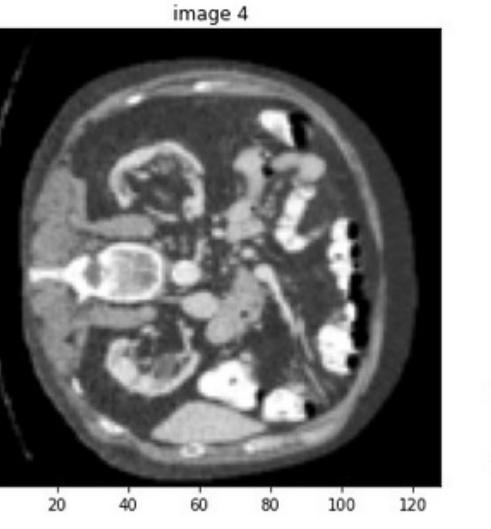
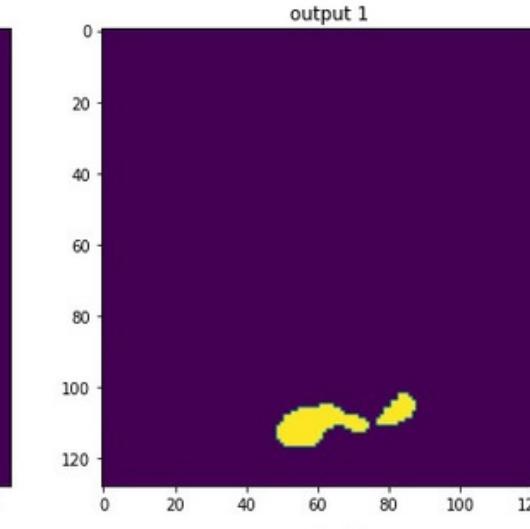
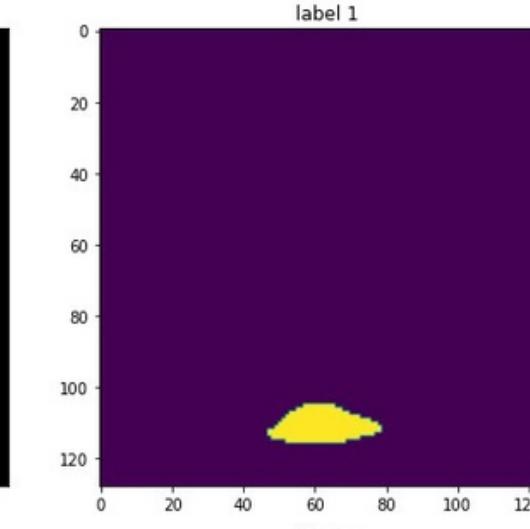
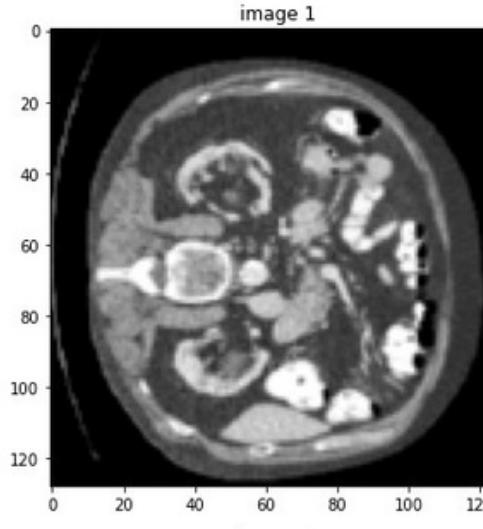
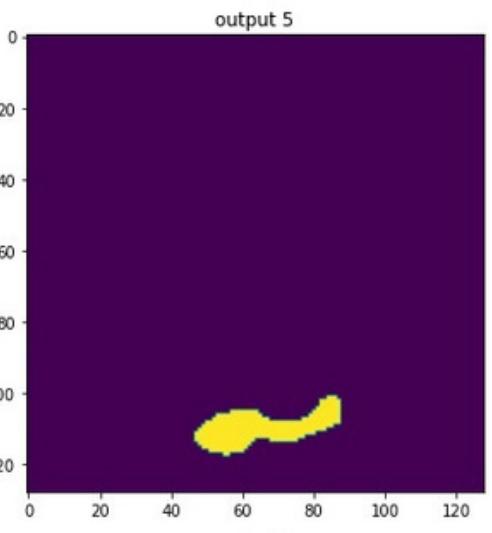
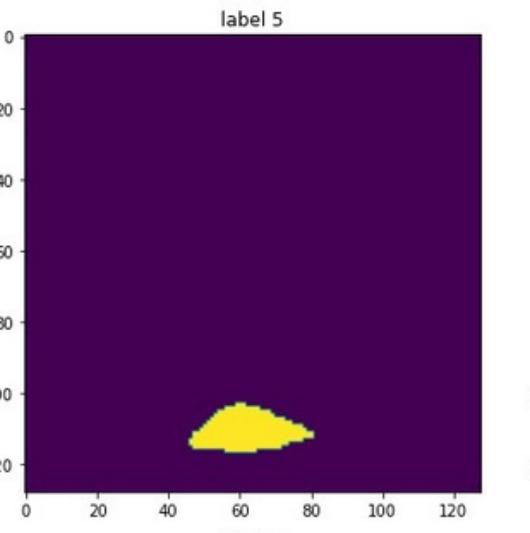
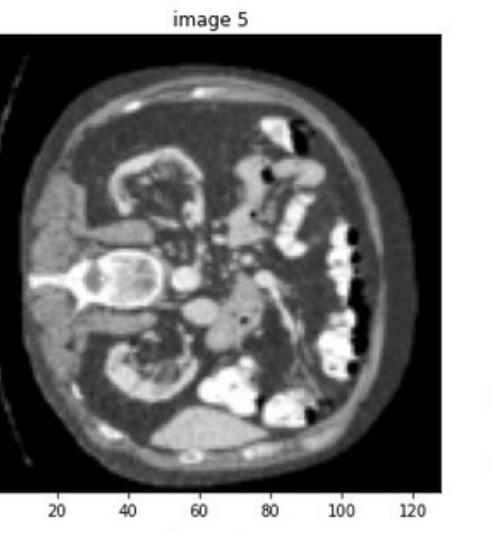
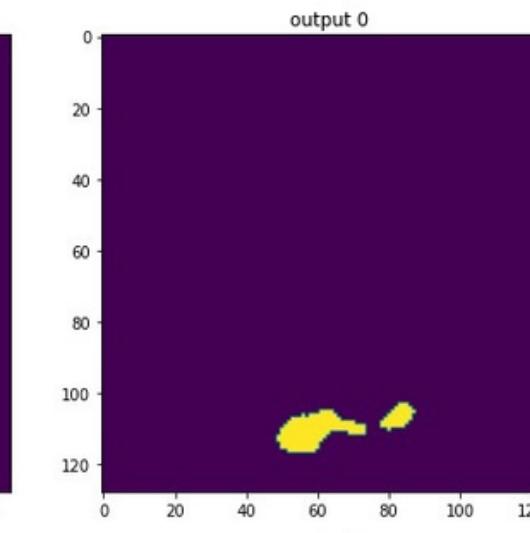
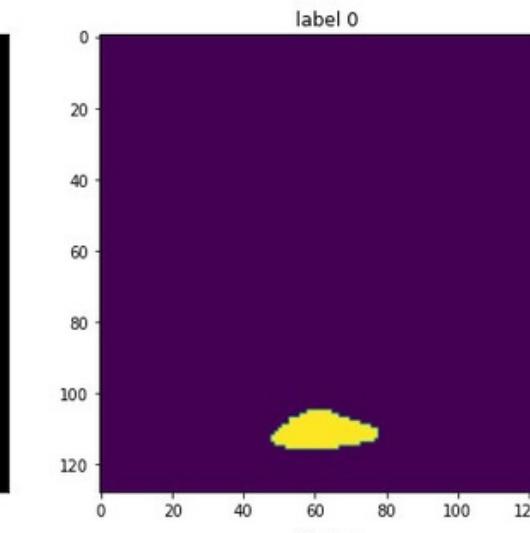
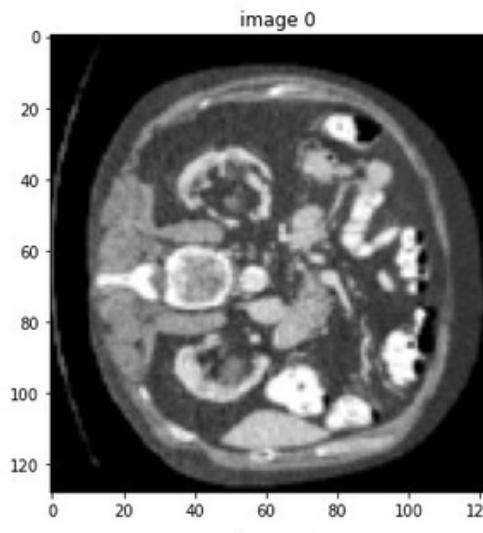
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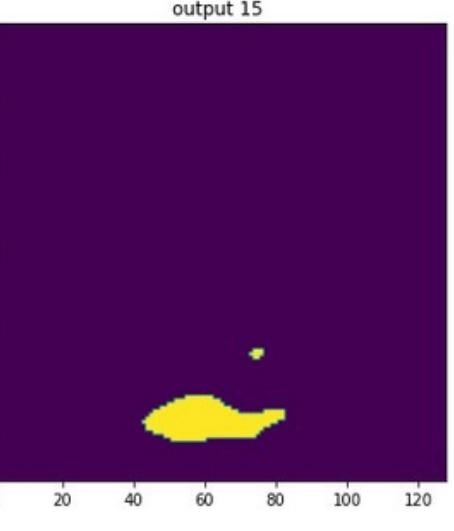
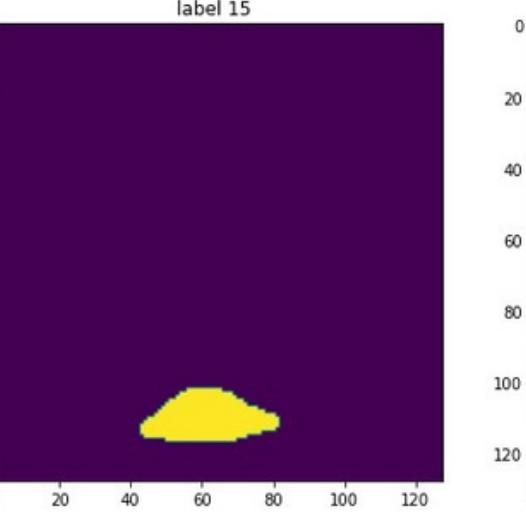
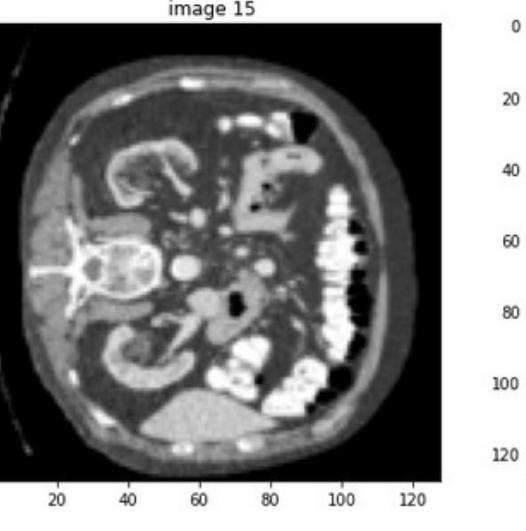
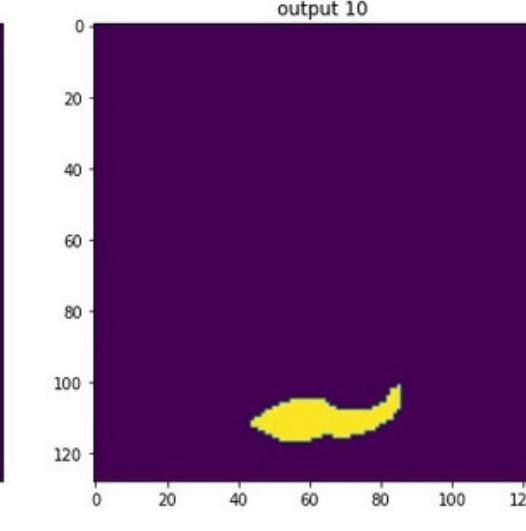
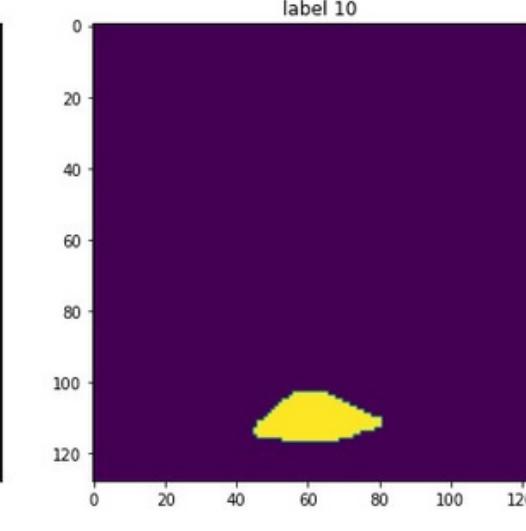
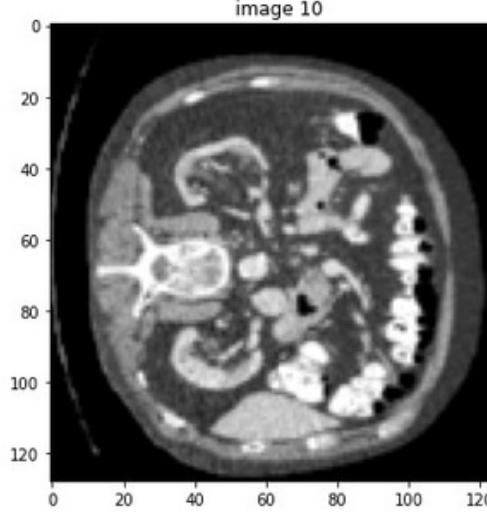
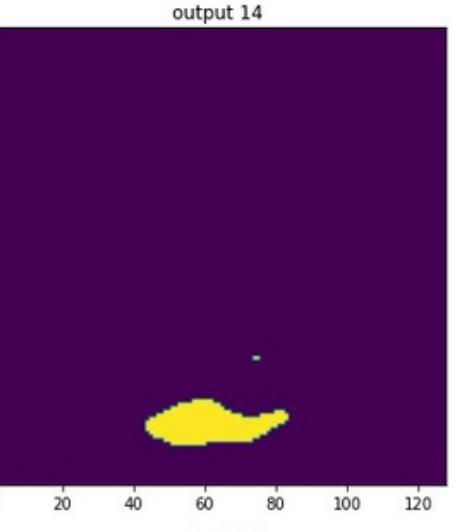
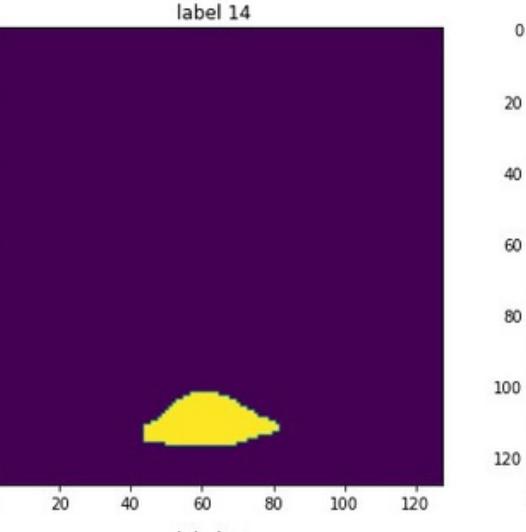
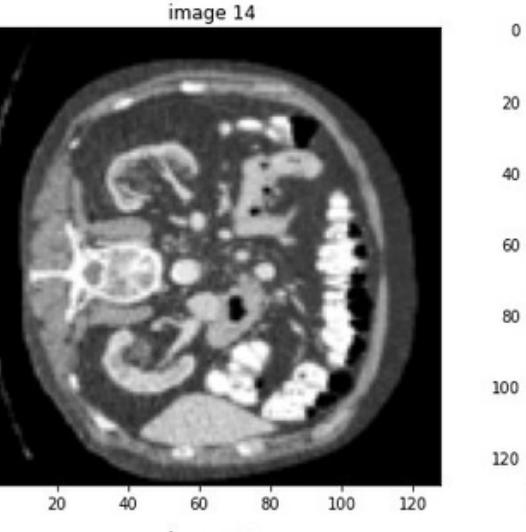
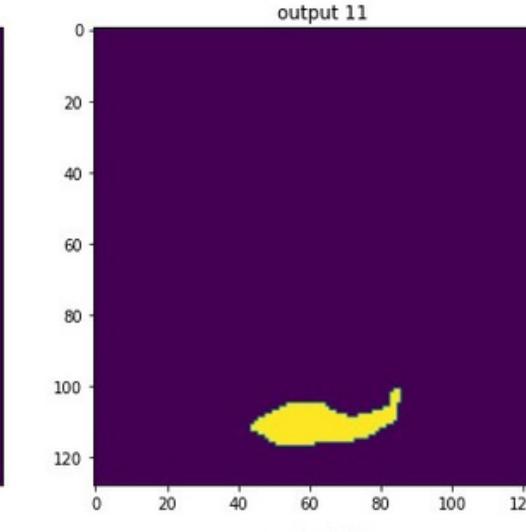
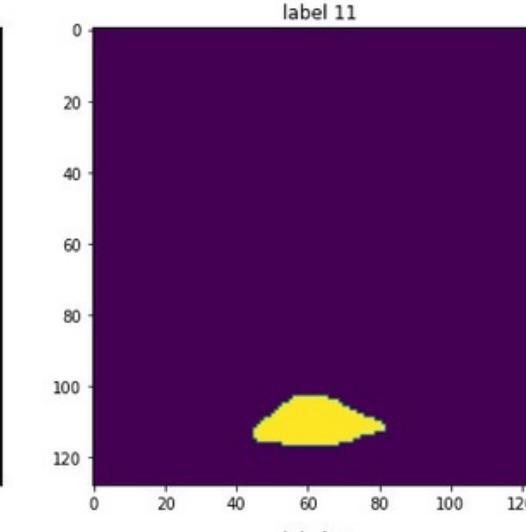
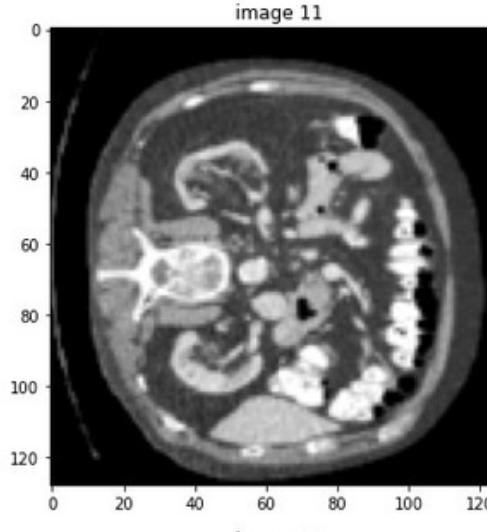
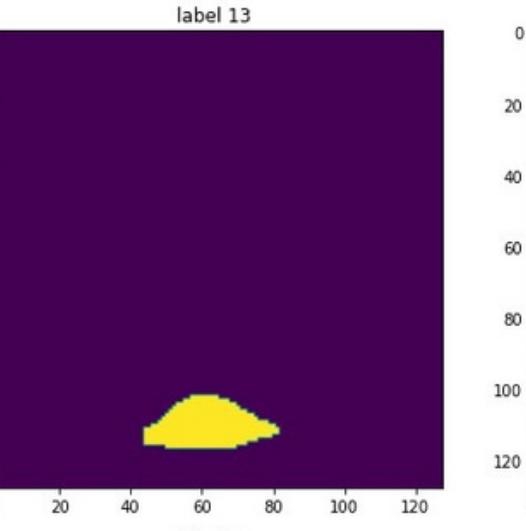
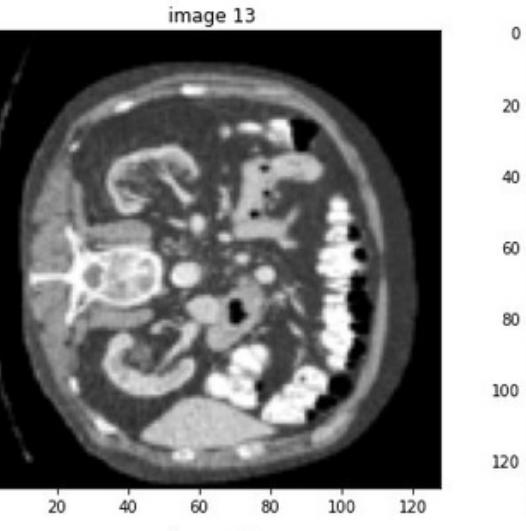
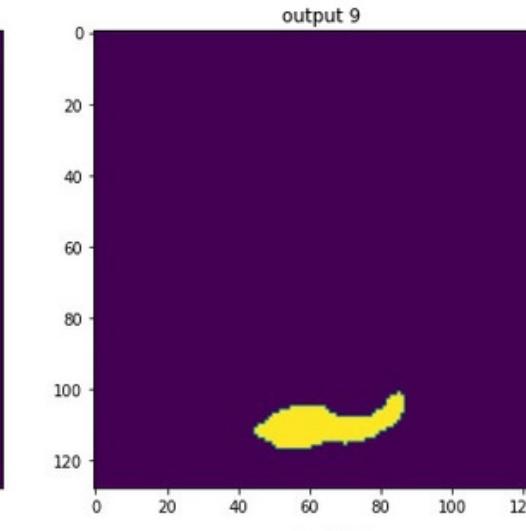
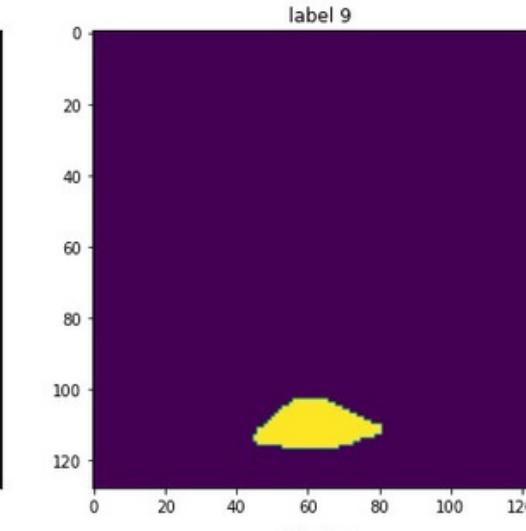
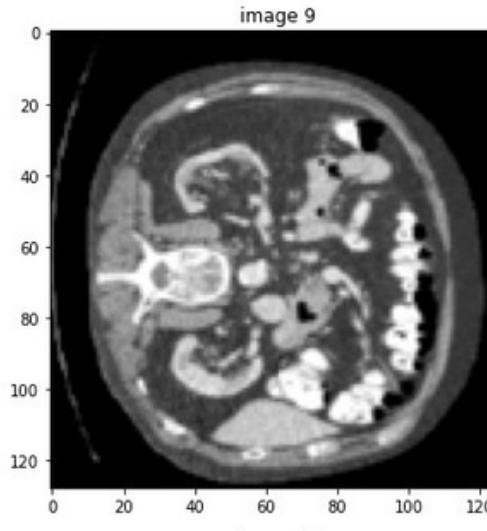
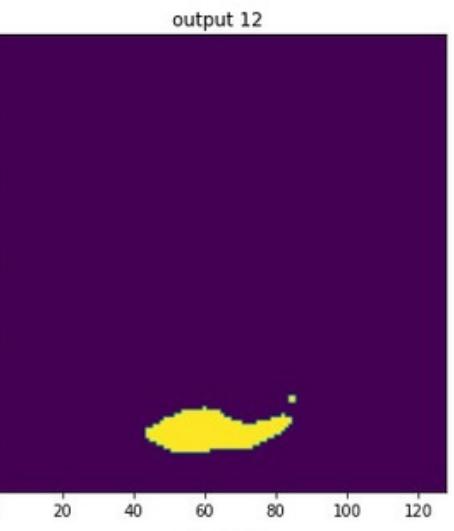
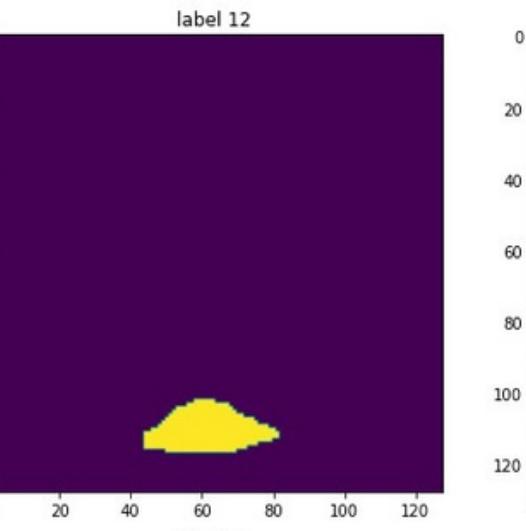
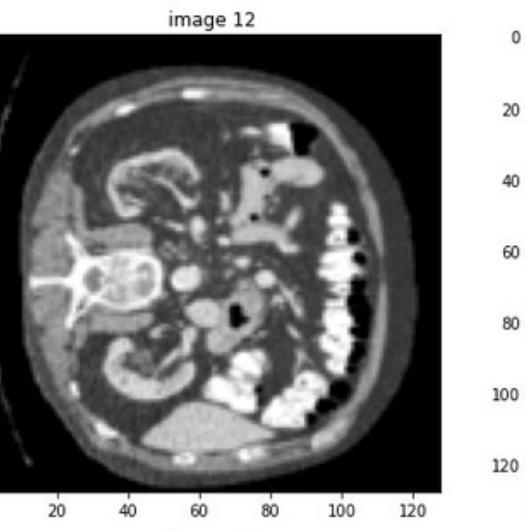
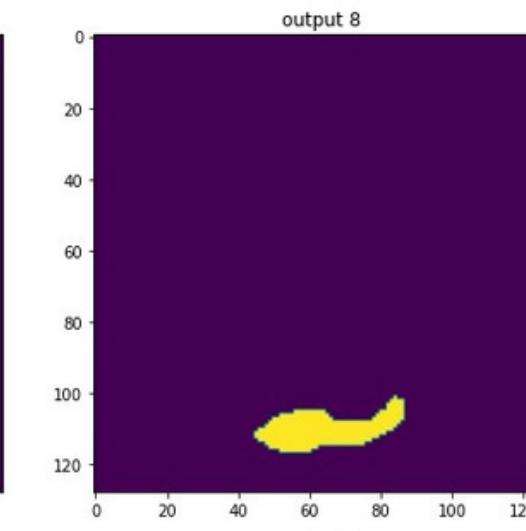
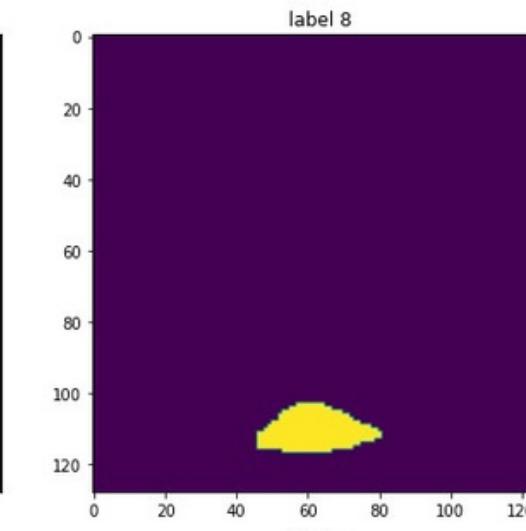
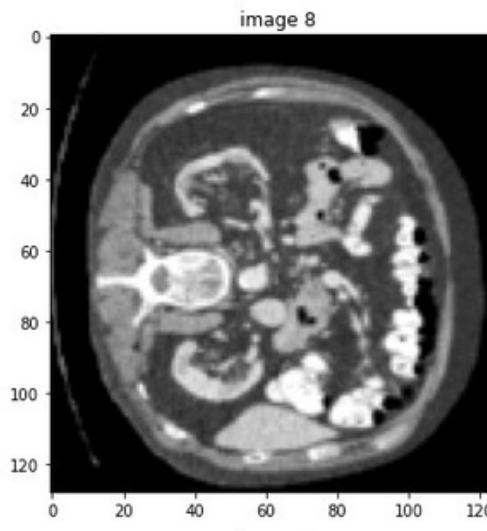


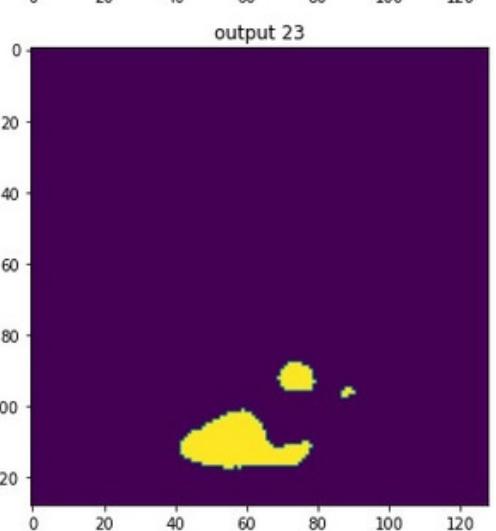
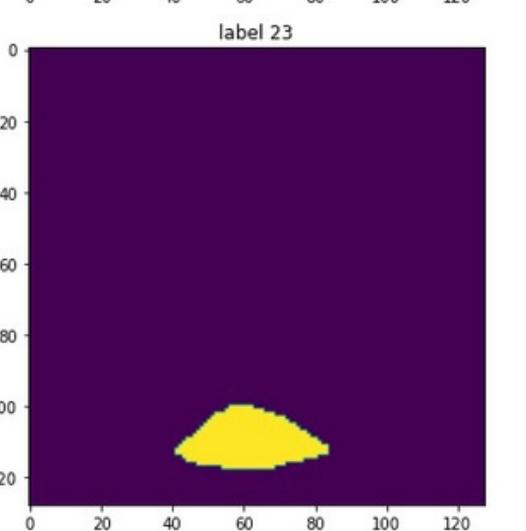
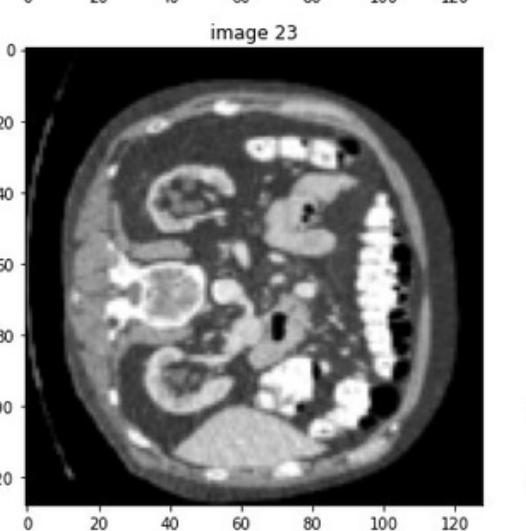
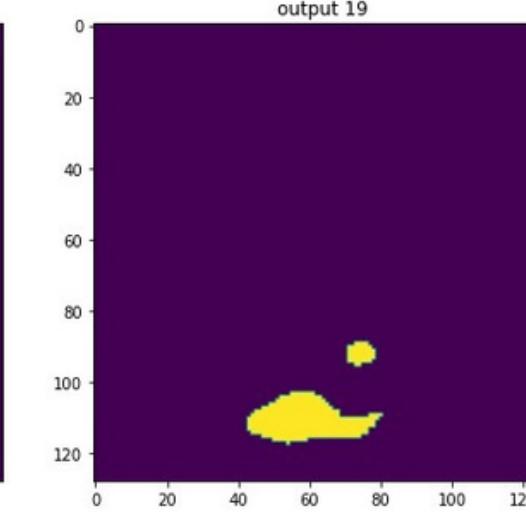
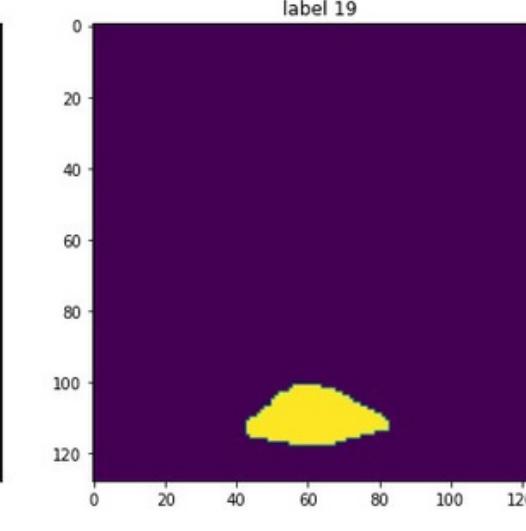
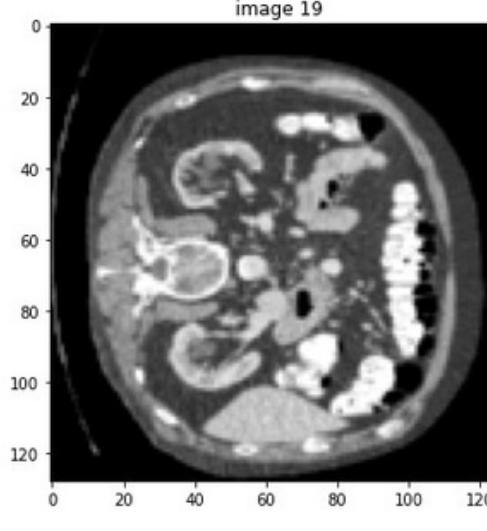
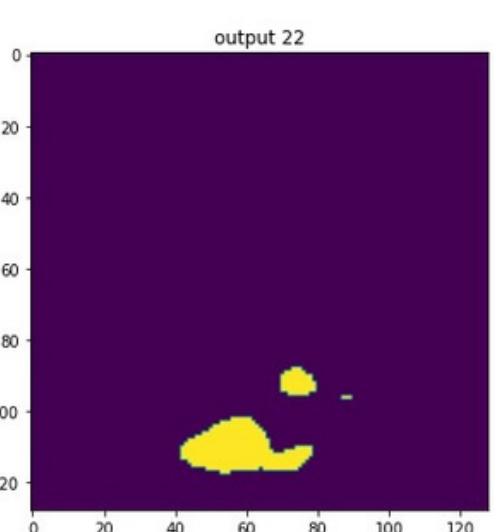
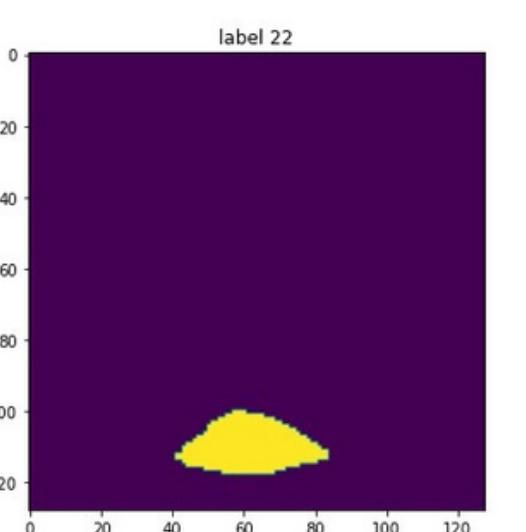
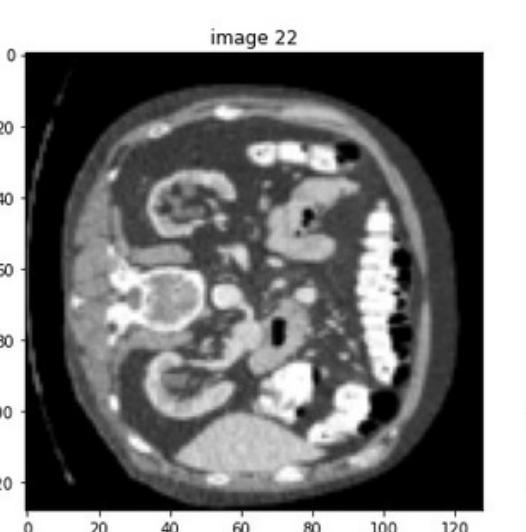
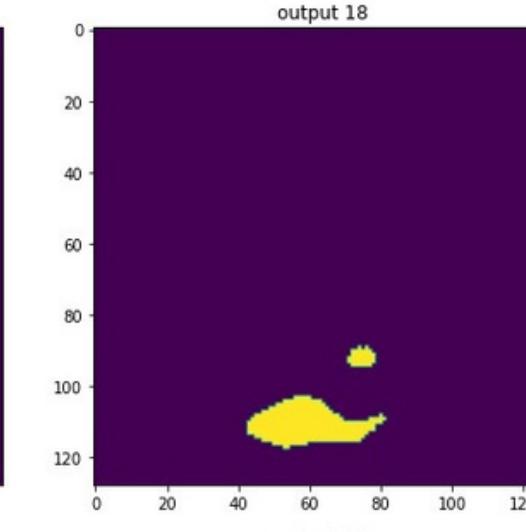
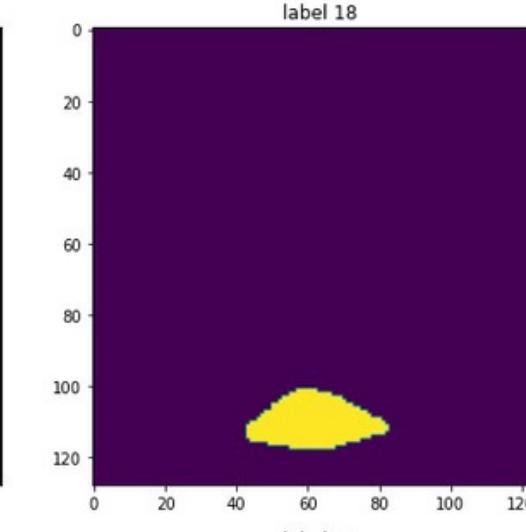
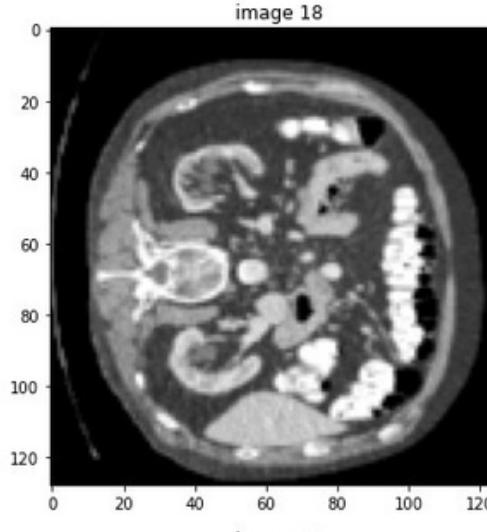
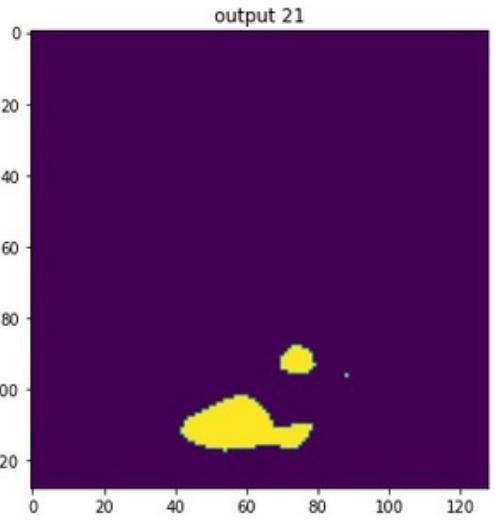
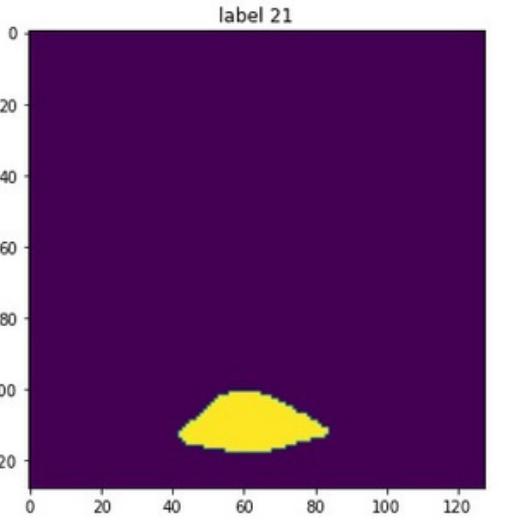
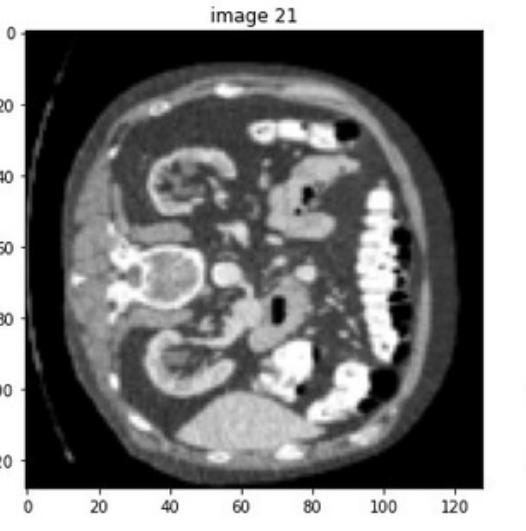
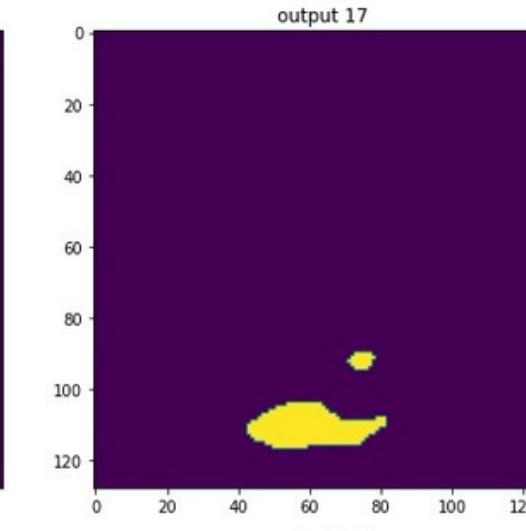
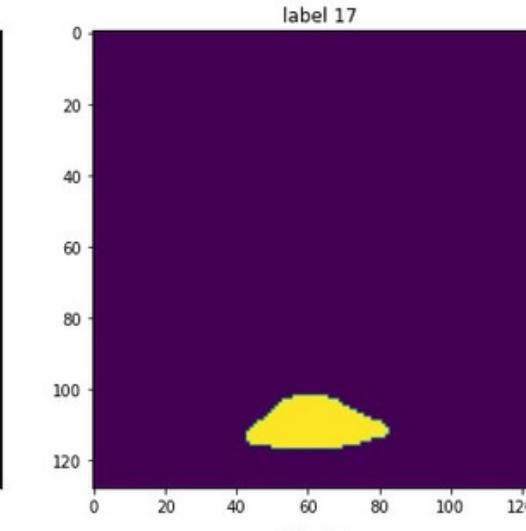
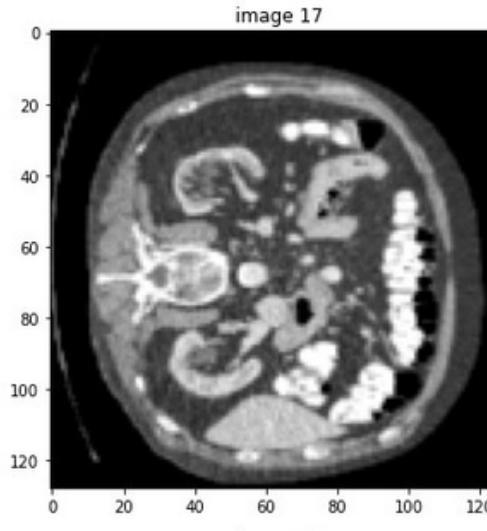
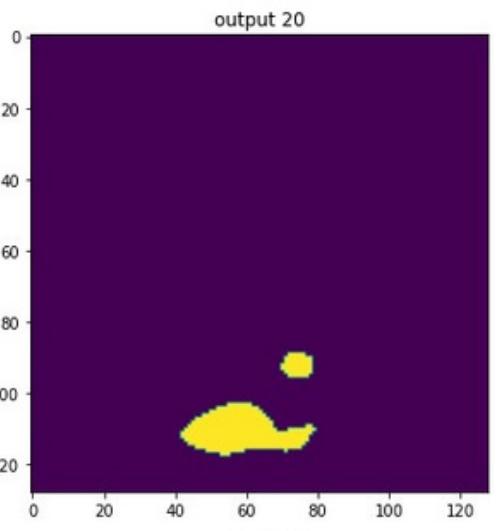
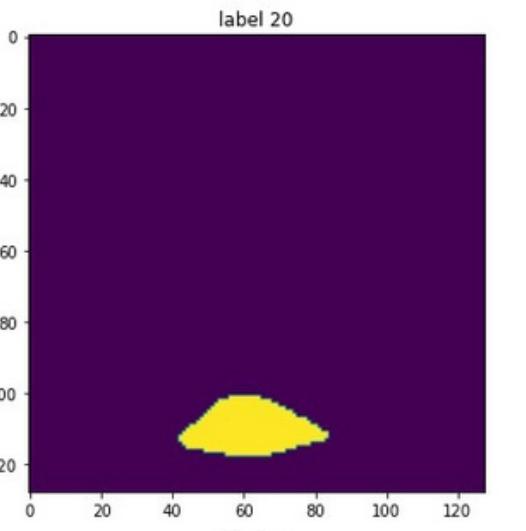
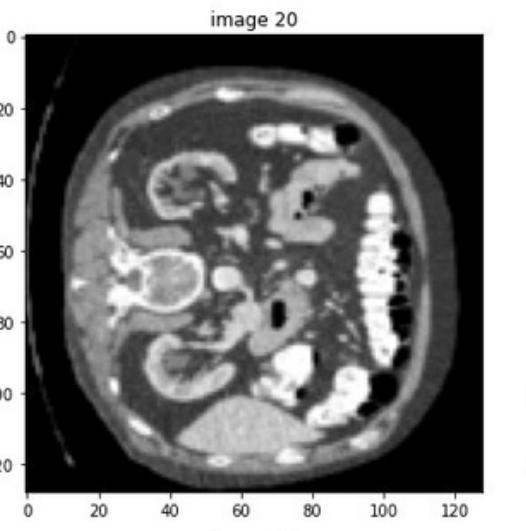
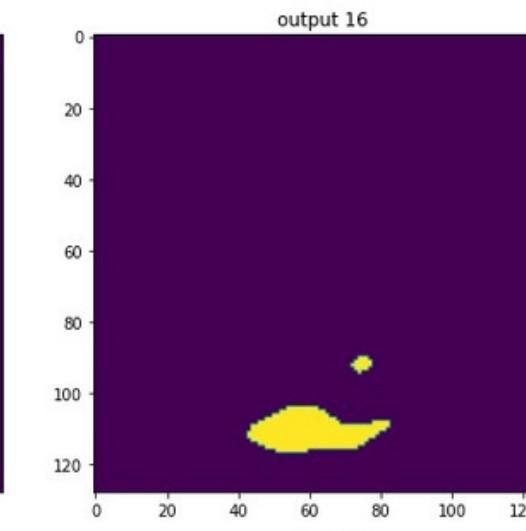
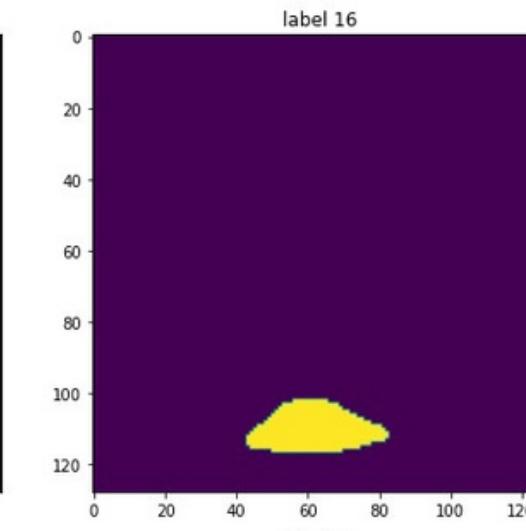
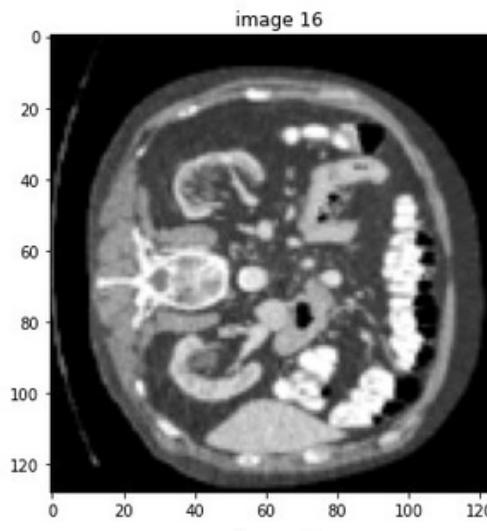
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Train_dice: 0.9374
107/110, Train_loss: 0.0324
Train_dice: 0.9676
108/110, Train_loss: 0.0358
Train_dice: 0.9642
109/110, Train_loss: 0.0096
Train_dice: 0.9904
110/110, Train_loss: 0.0099
Train_dice: 0.9901
-----
Epoch_loss: 0.0191
Epoch_metric: 0.9809
test_loss_epoch: 0.3199
test_dice_epoch: 0.8971
current epoch: 250 current mean dice: 0.9195
best mean dice: 0.9147 at epoch: 248
train completed, best_metric: 0.9147 at epoch: 248
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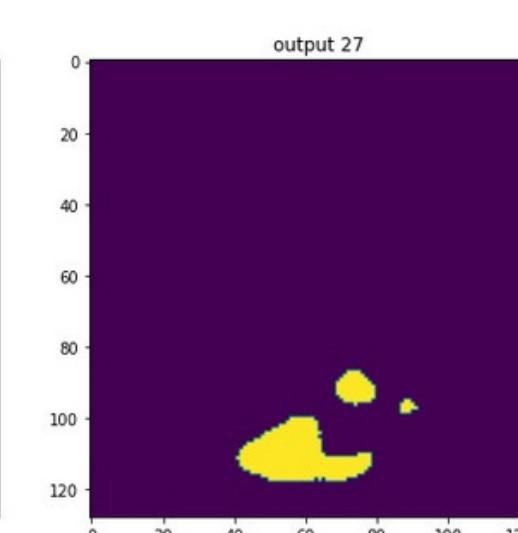
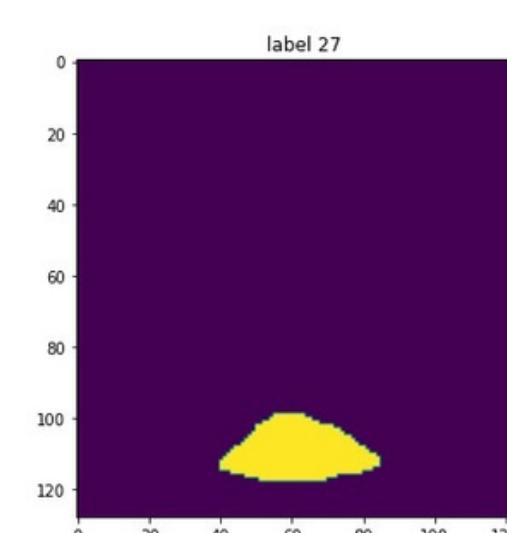
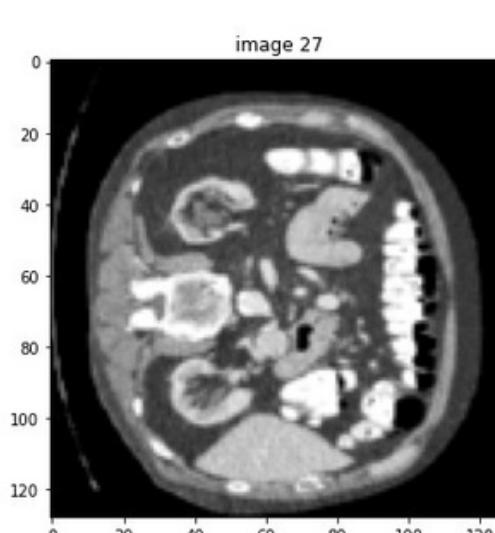
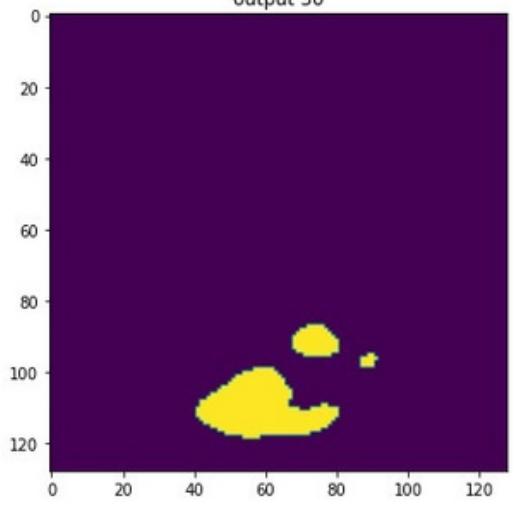
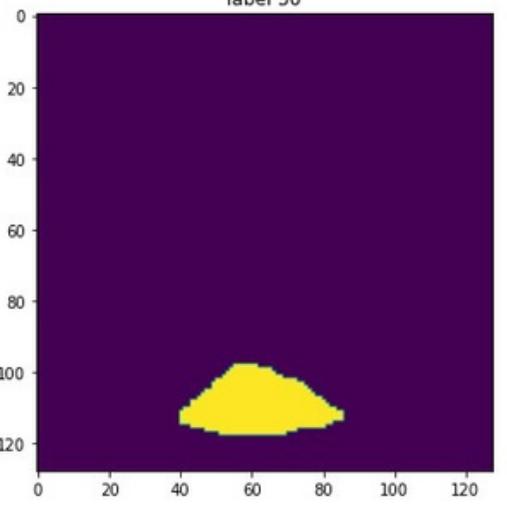
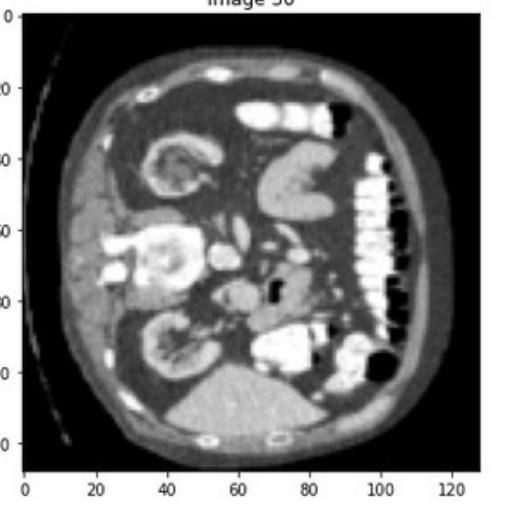
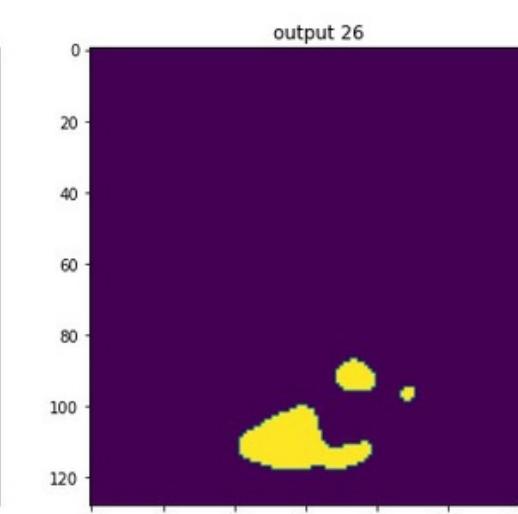
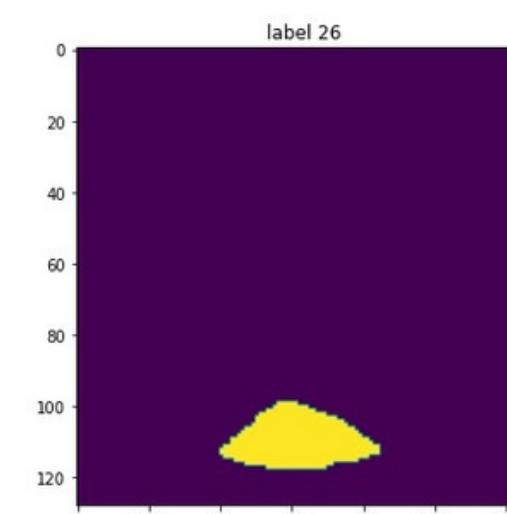
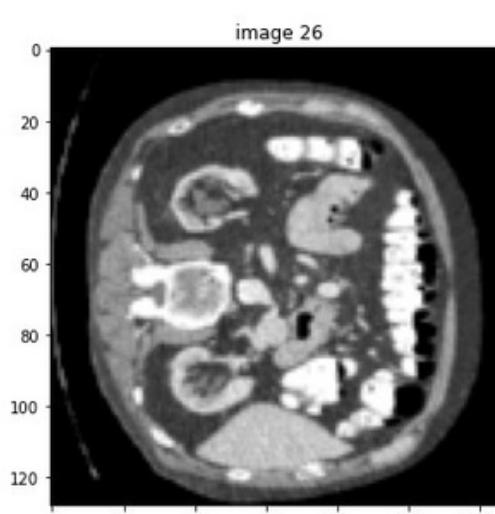
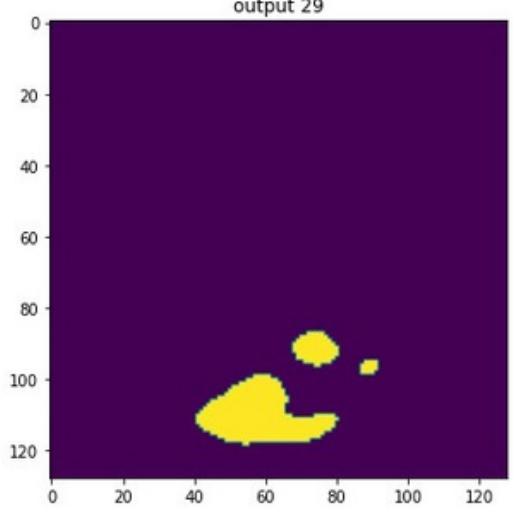
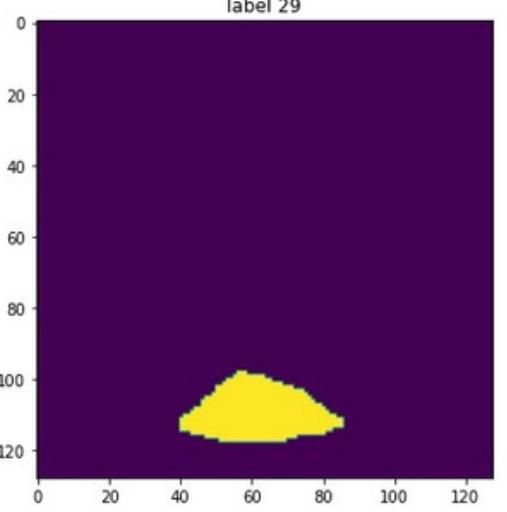
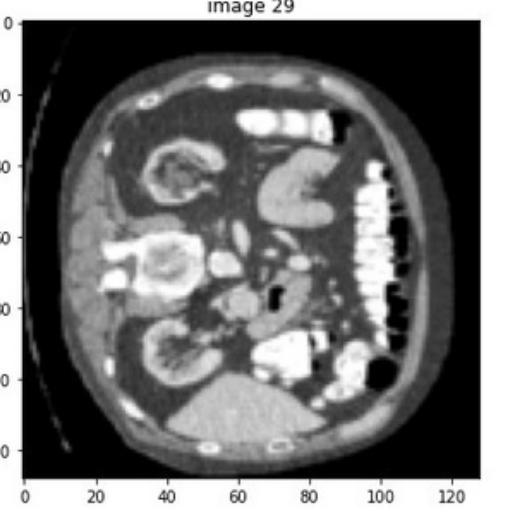
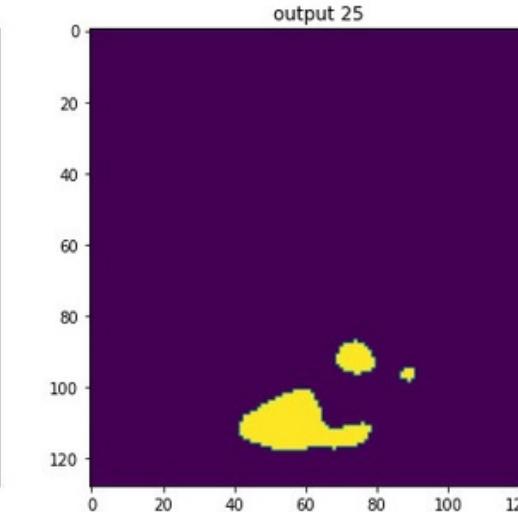
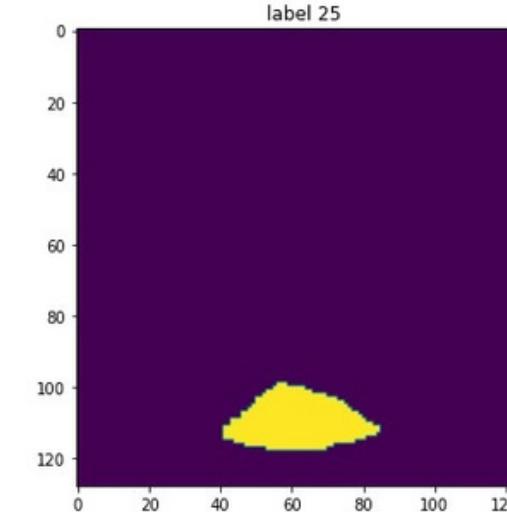
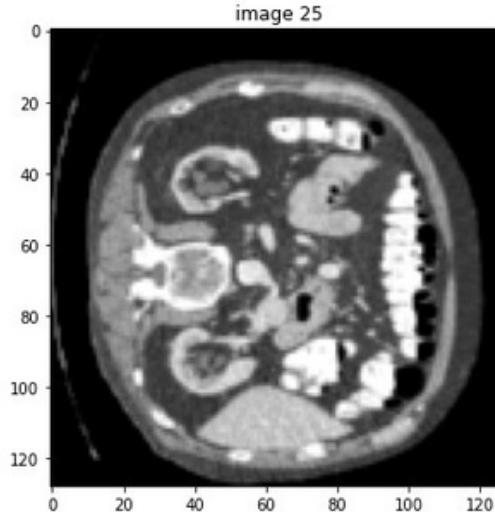
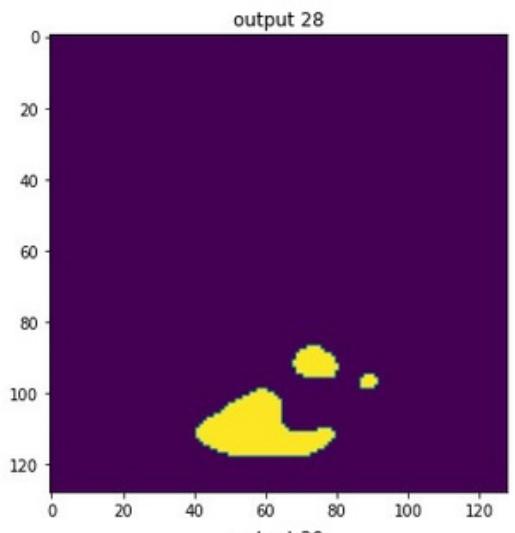
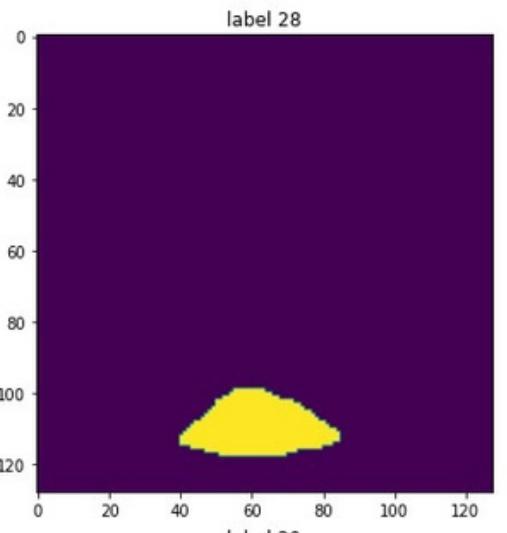
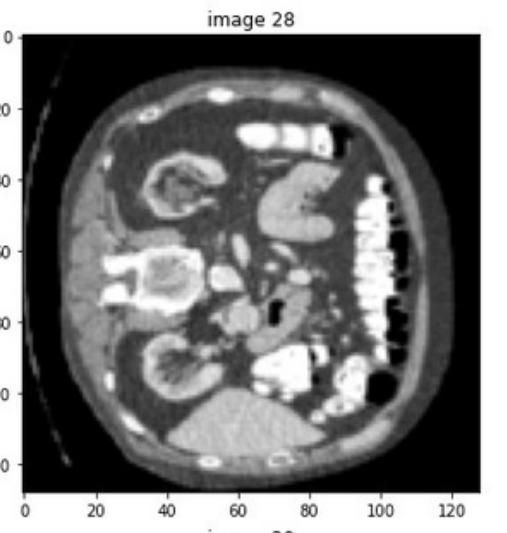
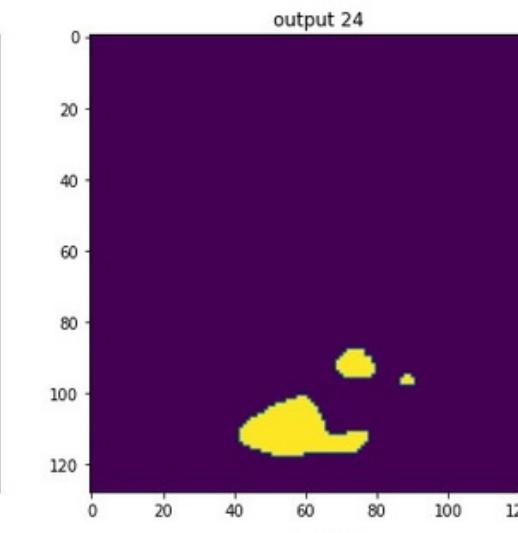
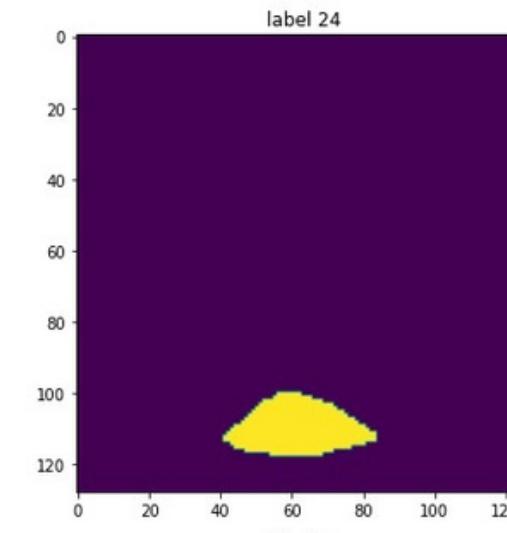
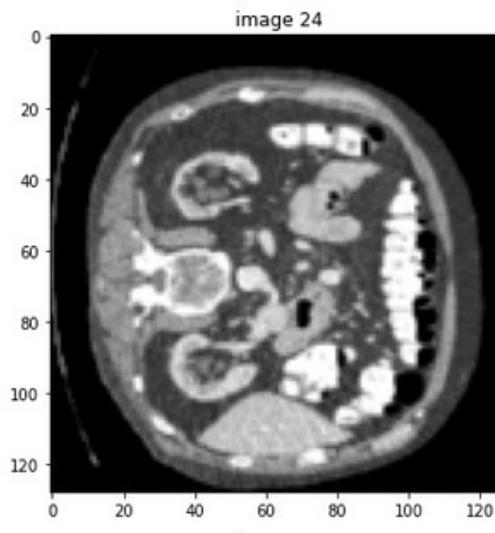
*STEP 4: RESULT











FIRST PAGE

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DO YOU HAVE
ANY QUESTIONS?



Feel free to make this an open
discussion for questions or
clarifications before proceeding.

