

GNR 602: Project no: 20

Implementing Canny edge detector

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2 Source code

2.1 Guassian kernel

```
1 def generate_gaussian_kernel(size, sigma):
2     x, y = np.mgrid[-size:size+1, -size:size+1]
3     normal = 1 / (2.0 * np.pi * sigma**2)
4     g = np.exp(-((x**2 + y**2) / (2.0 * sigma**2))) * normal
5     return g
```

Code Listing 1: Guassian kernel

The above code gives out a Gaussian operator which can be used to smoothen the image and reduce the noise based on the sigma and size given as input.

2.2 Apply convolution

```
1 def apply_convolution(img, kernel):
2     M, N = img.shape
3     m, n = kernel.shape
4     padding = np.zeros((M+m-1, N+n-1))
5     padding[m//2:M+m//2, n//2:N+n//2] = img
6
7     output = np.zeros_like(img)
8     for i in range(M):
9         for j in range(N):
10             output[i, j] = np.sum(padding[i:i+m, j:j+n] * kernel)
11
12     return output
```

Code Listing 2: Convolution

This applies any given filter(matrix) to convolute on the whole image and gives out the resultant image as output.

2.3 Double Thresholding and Hysteresis

```
1  def hysteresis_thresholding(img, t1, t2):
2
3      weak = np.zeros_like(img)
4      strong = np.zeros_like(img)
5      strong_threshold = np.max(img) * t2
6      weak_threshold = np.max(img) * t1
7
8      strong[img >= strong_threshold] = 255
9      weak[(img >= weak_threshold) & (img < strong_threshold)] = 128
10
11     # perform connectivity analysis to determine strong edges
12     M, N = img.shape
13     edge_map = np.uint8(strong)
14     for i in range(1, M-1):
15         for j in range(1, N-1):
16             if weak[i,j] == 128:
17                 if (strong[i-1:i+2, j-1:j+2] == 255).any():
18                     edge_map[i,j] = 255
19             else:
20                 edge_map[i,j] = 0
21
22     return edge_map
```

Code Listing 3: Double Thresholding and Hysteresis

This part of the code does the double thresholding part of the canny edge detector, first finds the strong edges (pixels with intensity greater than the higher threshold), and checks if the pixel with greater than the lower threshold has any pixels with a strong edge in its neighbors and if present makes it also a strong edge.

2.4 Sobel

```
1  def sobel_op(img):
2      dx_kernel = np.array([[ -1,  0,  1],
3                             [ -2,  0,  2],
4                             [ -1,  0,  1]], dtype=np.float32)
5
6      dy_kernel = np.array([[ -1, -2, -1],
7                             [  0,  0,  0],
8                             [  1,  2,  1]], dtype=np.float32)
9
10     dx = np.zeros_like(img, dtype=np.float32)
11     dy = np.zeros_like(img, dtype=np.float32)
12
13     height, width = img.shape
14
15
16     for i in range(1, height - 1):
```

```

17     for j in range(1, width - 1):
18         dx[i, j] = np.sum(img[i-1:i+2, j-1:j+2] * dx_kernel)
19         dy[i, j] = np.sum(img[i-1:i+2, j-1:j+2] * dy_kernel)
20     return dx, dy

```

Code Listing 4: Sobel operator

This part of the code uses the Sobel operator and applies it to the image given as input using for loops and gives out the resulting image which has gradients as outputs.

2.5 Non maximum suppression

```

1 def non_maximum_suppression(G, theta):
2     # Finding dimensions of the image
3     N, M = G.shape
4     # Parsing through all the pixels
5     for i_x in range(M):
6         for i_y in range(N):
7
8             grad_ang = theta[i_y, i_x]
9             grad_ang = abs(grad_ang-180) if abs(grad_ang)>180 else
abs(grad_ang)
10
11             # selecting the neighbours of the target pixel
12             # according to the gradient direction
13             # In the x axis direction
14             if grad_ang<= 22.5:
15                 neighb_1_x, neighb_1_y = i_x-1, i_y
16                 neighb_2_x, neighb_2_y = i_x + 1, i_y
17
18             # top right (diagonal-1) direction
19             elif grad_ang>22.5 and grad_ang<=(22.5 + 45):
20                 neighb_1_x, neighb_1_y = i_x-1, i_y-1
21                 neighb_2_x, neighb_2_y = i_x + 1, i_y + 1
22
23             # In y-axis direction
24             elif grad_ang>(22.5 + 45) and grad_ang<=(22.5 + 90):
25                 neighb_1_x, neighb_1_y = i_x, i_y-1
26                 neighb_2_x, neighb_2_y = i_x, i_y + 1
27
28             # top left (diagonal-2) direction
29             elif grad_ang>(22.5 + 90) and grad_ang<=(22.5 + 135):
30                 neighb_1_x, neighb_1_y = i_x-1, i_y + 1
31                 neighb_2_x, neighb_2_y = i_x + 1, i_y-1
32
33             # Now it restarts the cycle
34             elif grad_ang>(22.5 + 135) and grad_ang<=(22.5 + 180):
35                 neighb_1_x, neighb_1_y = i_x-1, i_y
36                 neighb_2_x, neighb_2_y = i_x + 1, i_y
37
38             # Non-maximum suppression step
39             if M>neighb_1_x>= 0 and N>neighb_1_y>= 0:
40                 if G[i_y, i_x]< G[neighb_1_y, neighb_1_x]:
41                     G[i_y, i_x]= 0
42                     continue

```

```

43
44         if M>neighb_2_x>= 0 and N>neighb_2_y>= 0:
45             if G[i_y, i_x]< G[neighb_2_y, neighb_2_x]:
46                 G[i_y, i_x]= 0
47
48     return G

```

Code Listing 5: Non maximum suppression

This part of the code does the Nonmaximum suppression, which means it removes all pixels which are having pixels with greater intensity that themselves in the direction of its gradient.

2.6 Canny edge detector

```

1  def Canny_detector(img, sigma, t1, t2):
2      # Step 1: Convert given image to grayscale image
3      img_gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
4      img = img_gray
5
6      # Step 2: Apply Gaussian filter to smooth the image
7      kernel_size = 7
8      gaussian_kernel = generate_gaussian_kernel(kernel_size, sigma)
9      img_smooth = apply_convolution(img, gaussian_kernel)
10     smooth_img = img_smooth
11
12     # Step 3: Compute gradient magnitude and direction using Sobel
13     # operators
14     gx, gy = sobel_op(img)
15     G_mag, G_dir = cv2.cartToPolar(gx, gy, angleInDegrees = True)
16
17     # Step 4: Perform non-maximum suppression to thin the edges
18     G_suppressed = non_maximum_suppression(G_mag, G_dir)
19
20     # Step 5: Perform hysteresis thresholding to detect strong and
21     # weak edges
22     edge_image= hysteresis_thresholding(G_suppressed, t1, t2)
23
24     # returns a grayscale image, smoothened image, edge image
25     return img_gray, smooth_img, edge_image

```

Code Listing 6: Canny *edge_detector*

This brings all the functions into one place and does them one by one as specified by canny edge detection, in the following order

- Converting to grayscale
- Gaussian smoothening
- Finding Gradient using Sobel
- Non-Maximum suppression
- Double thresholding and hysteresis