VIPUL RAMTEKKAR

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Interests _

- Computer Vision, Machine Learning, Deep Learning, Robotics
- **Key Courses**: Machine Learning, Deep Learning and Practices, Reinforcement Learning, Medical Image Computing, Optimization, Operating Systems, Data System and Security, Data Structure and Algorithms, Logic in CS

EDUCATION .

Indian Institute of Technology Bombay

Bachelor of Technology, Department of Chemical Engineering

Mumbai, India July 2016 - June 2020

• **GPA**: 8.81/10.0

• Minor Degree: Computer Science and Engineering

Publication _

 $\bullet\,$ pyTAG: python-based interactive training data generation for visual tracking algorithms

Geospatial Informatics X (Conference Presentation)

Ekincan Ufuktepe, **Vipul Ramtekkar**, Ke Gao, Noor Al-Shakarji, Joshua Fraser, Hadi AliAkbarpour, Guna Seetharaman, and Kannappan Palaniappan

Industrial Research Experience —

Computer Vision Research Engineer | Honda Research & Development, Japan Robot Development, Honda Life Creation

Winter 2020 - Present Tokyo, Japan

- Worked in collaborative research with leading universities to improve perception for autonomous robots
- Achieved drastic improvement in the performance of semantic segmentation in adverse environment by developing novel framework to utilise the synthetic images using Deep Generative Models to bridge the domain gap
- Implemented localization and vision nodes in ROS 2 to accelerate performance in unknown environments

ACADEMIC RESEARCH EXPERIENCE

Video Object Tracking in UAVs | University of Missouri-Columbia, USA

Prof. Kannappan Palaniappan, Electrical Engineering & Computer Science Dept [LOR]

Summer 2019 MU, USA

- Worked in **collaborative research** with the **US Army Research Lab** on embedded software and algorithm development for computer vision and machine learning applications for **Autonomous Unmanned Aerial Vehicle**
- Developed state-of-art video object tracker with 67% higher robustness & accuracy compared to current trackers by fusing siamese deep network with motion flux and YOLO object detection for low-power embedded processing systems
- Worked on enhancing the tracking speed of **Spatial Pyramid Context Aware Tracker** by leveraging its multi-feature extractor and adding a deep learning component to it to achieve persistent detection and tracking of vehicles
- Developed a python based tool to analyse trackers and benchmarked them based on their accuracy and robustness

Transposon Classifier | University of Tokyo, Japan Prof. Shinichi Morishita, Computational Biology Dept

Summer 2018 UTokyo, Japan

- Proposed a model to identify transposable elements by training a Support Vector Machine classifier with cosine similarity kernel. Achieving a 1.2x better accuracy and 10x better training time compared to the traditional classifier
- Implemented algorithms for sequence alignment and created data visualisations using JavaScript and D3 library
- Showcased the research project in the IIT Bombay's Research and Technology Symposium, ResTech 2018

Major Projects .

Computer Vision Head | SeDriCa, Self Driving Car | UMIC IIT Bombay Prof. Amit Sethi, Electrical Engineering Dept

Autumn 2018 - Spring 2020 IIT Bombay

- Leading a team of four students to implement various deep learning methods for object detection, object classification and image segmentation of the acquired visual input from the vehicle to achieve level 4 autonomy
- Amongst the top 11 teams out of 259 to be awarded Mahindra e2o car for the Mahindra Rise Driverless Car Challenge
- Implemented (in tensorflow) and analysed various encoder-decoder based CNN architectures for image segmentation
- Developed various python based tools to annotate, correct and remove incorrect instances from the datasets [news]

Chief Engineer | Matsya, Autonomous Underwater Vehicle (AUV)

Prof. Leena Vachhani, System and Control Dept

RoboSub, AUVSI & US Office of Naval Research

Autumn 2016 - Spring 2018

- Designed and developed a state-of-the-art unmanned **Autonomous Underwater Vehicle (AUV)** that localises itself and performs realistic missions based on feedback from visual, inertial, acoustic and depth sensor using thrusters/propellers
- Achieved **2nd position in the world** in **Robosub 2016** amongst 44 teams from 10 different countries and **National Winner** of Student AUV Competition, **SAVe 2017**, conducted by the National Institute of Ocean Technology (NIOT)
- Optimised and implemented design of pneumatically driven 2-DOF gripper picking a wide range of geometrical objects and enhanced the torpedo's design to create a locking mechanism for better pressure buildup
- Represented the team in various tech and research expositions and conducted interviews for the team recruitment [video]

Team Lead | Autonomous Strawberry Picking Bot | Inter IIT Technical Meet Autumn 2018-Winter 2018 Led a team of 4 to build a prototype after conducting field surveys to identify automation solutions in farming to reduce labour

- Designed a bot which costs 84% lower than annual labour cost & picks strawberries 6x faster than manual picking
- Retrained a tiny yolo classifier with **transfer learning** to detect strawberries using Fruit-360 dataset and performed image augmentation using various computer vision methods like histogram equalization and linear transformations
- Awarded Bronze Medal based on prototype and pitch of the business model to a panel of professors and investors

User Mimicking ChatBot

Autumn 2018

Prof. P Balamurugan, Industrial Engineering and Operations Research Dept

IIT Bombay

- Created a chatbot by using a Sequence to Sequence Model that learns to converse like the user inspired from the popular show Black Mirror by training on his/her data from various social media accounts like Facebook, WhatsApp & LinkedIn
- Improved the model by adding Cornell Movie-Dialogs Corpus and used adaptive optimizers to reduce training time

Autonomous Sanitation and Cleanliness Bot

Autumn 2017-Winter 2017 IIT Madras

Inter-IIT Technical Meet

- Designed a state of the art, light weight & compact toilet cleaning bot with 1-DOF arm to clean stains and a rotation flap
- to pick trash. Minimized the cost by 57% and improved the cleaning time by 2.5x against manual controlled machines
- Trained a Haar Cascade Classifier to detect the toilet, and detected the stains and trash using edge detection and colour thresholding, implemented communication between arduino & raspberry pi using pySerial to establish arm control

SCHOLASTIC ACHIEVEMENTS _

- Selected for HPAIR'19 conference at Havard University in Cambridge, Massachusetts from a pool of 10,000+ applicants
- Awarded an Academic Proficiency grade (Top 1%) for performing exceptionally well in Solid Mechanics
- ullet Recipient of the \mathbf{UTSIP} Scholarship and JST Travel Fund to pursue research in University of Tokyo, Japan
- Awarded the Institute Technical Color for exceptional contribution towards the growth of tech in the Institute

TECHNICAL SKILLS _

Programming

Python, C/C++, JavaScript, Java, HTML

Frameworks & Tools

Pytorch, Tensorflow, JAX, Keras, OpenCV, Matlab, LATEX, Git, ROS

Positions of Responsibility

- Editorial Board Member | Insight | Official Student Media Body of IIT Bombay Spring 2019 Spring 2020 1 of the 20 editors heading 200+ journalists | 160+ articles | 50+ videos | 350k+ web views | 1.5 million+ online reach
 - Spearheading myriad of projects like analyzing research in the institute, reportage and worked on various initiatives like University Series blogs to help students make a more informed decision for graduate & post graduate programs
 - o Surveyed 10k+ students to understand their inclination towards politics during the 2019 Lok Sabha elections
- Academic Mentor | Department Academic Mentorship Program

Spring 2018 - Spring 2020

- \circ Selected as a Mentor (1/24 of 108) based on academics, ethics and peer reviews to guide sophomores to accelerate their performance by leveraging the resources in the department and to help them cope with the curriculum
- Assisting academically weak students clear their backlogs by closely monitoring their performance & progress

Extracurriculars _____

- Ranked 4th out of 92 teams from IITB at WorldQuant's International Quant Challenge-Stage 1 [2019]
- Achieved 2nd position in Scientific Computation Blitz Competition participated by students institute-wide

[2018]

[2016]

• Completed 80+ hours social work under NSS which involved conducting events for underprivileged children in collaboration with different NGOs and spreading awareness regarding various social issues

[2016-17]

• Hobbies: travelling (100+ cities in 9 countries spread across three continents), trekking, reading and chess