

# System's percepts

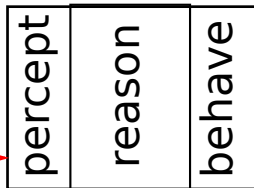
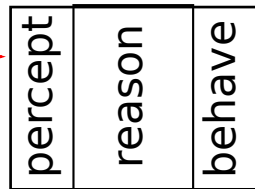
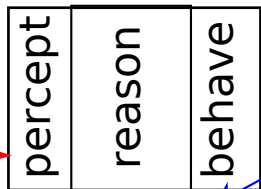
# Global reasoning

# System's decision

child's progress  
child's VFoA

robot's  
progress

child's feedback



$M_R[C]$

$M_R[R]$

$M_R[CR]$

repaire  
misunder-  
standing

