## FLOOD MONITORING AND EARLY WARNING

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CODE:
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
#include <NewPing.h>
#include <SoftwareSerial.h>
// LCD Display
LiquidCrystal_I2C lcd(0x27, 16, 2);
// Ultrasonic Sensor
#define TRIGGER_PIN 12
#define ECHO_PIN 11
#define MAX_DISTANCE 200
NewPing sonar(TRIGGER_PIN, ECHO_PIN,
MAX_DISTANCE);
// Float Sensor
#define FLOAT_SENSOR_PIN 10
// GSM Module
SoftwareSerial gsmSerial(8, 9); // RX, TX
#define GSM_BAUDRATE 9600
```

```
// Thresholds
#define FLOOD_THRESHOLD 50 // Example threshold
in cm
// Phone Numbers
String phoneNumbers[] = { "+9188305848xx",
"+9188305848xx" }; // Example phone numbers
void setup() {
// Initialize LCD Display
lcd.begin(16, 2);
lcd.backlight();
// Initialize GSM Module
gsmSerial.begin(GSM_BAUDRATE);
delay(2000); // Give GSM module time to
initialize
sendCommand("AT"); // Check communication
sendCommand("AT+CMGF=1"); // Set SMS text mode
// Display Initialization Message
lcd.clear();
lcd.setCursor(0, 0);
lcd.print("Flood Monitoring");
lcd.setCursor(0, 1);
lcd.print("System");
```

```
delay(3000); // Display initialization message for 3
seconds
void loop() {
// Read Ultrasonic Sensor
unsigned int distance = sonar.ping_cm();
// Read Float Sensor
int floatSensorValue =
digitalRead(FLOAT_SENSOR_PIN);
// Calculate Flood Level
int floodLevel = distance;
// Update LCD Display
lcd.clear();
lcd.setCursor(0, 0);
lcd.print("Water Level: ");
lcd.print(floodLevel);
lcd.print("cm");
// Check Flood Threshold
if (floodLevel > FLOOD_THRESHOLD &&
floatSensorValue == HIGH) {
 // Send Alert SMS
 sendAlertSMS(floodLevel);
```

```
delay(500); // Delay for stability
void sendAlertSMS(int floodLevel) {
String message = "Flood Alert! Water level is ";
message += floodLevel;
message += "cm. Take necessary actions.";
for (int i = 0; i < sizeof(phoneNumbers) /
sizeof(phoneNumbers[0]); i++) {
 sendCommand("AT+CMGS=\"" + phoneNumbers[i] +
"\"");
 delay(1000);
 sendCommand(message);
 delay(100);
 sendCommand((String) char(26));
 delay(1000);
void sendCommand(String command) {
gsmSerial.println(command);
delay(1000);
while (gsmSerial.available()) {
 gsmSerial.read();
```

## **OUTPUT**







