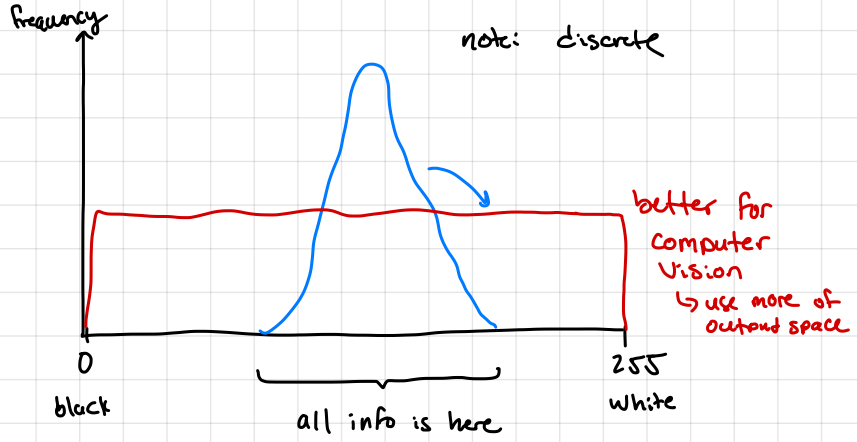
Histogram Equalization 1/21/2020

load image

```
plt.hist(
        img[:,:,1].ravel()
          R  C  color
                = G
        bins = list(range(256))
        )
```



Histogram equalization → uniform dist. target
... matching → arbitrary dist. target (Gaussian, etc.)

print(gray.shape) → (X, y)
(256, 256)

Color → grayscale is a LC of R, G, B channels

- note low spatial info in histogram
- poor contrast here
- point process to change histogram distribution

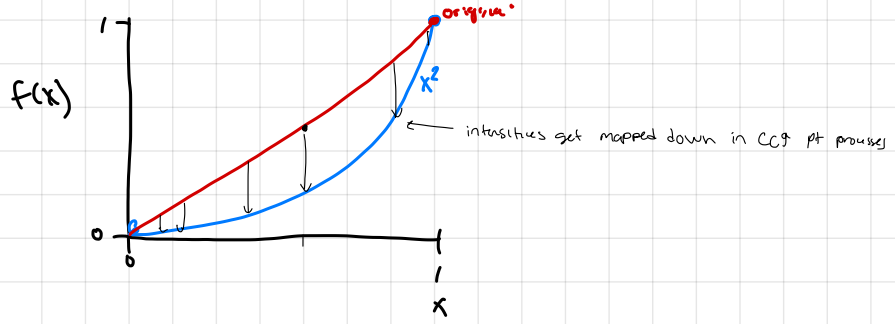
Pseudocode

```
gray = imread(image, cv2.imread_grayscale)

def point_process(x):
    """ apply pt. process to numpy array """
    return (x/255)**2 * 255
           int → float → int   .astype('uint8')
gray = point_process(gray)
```

- imshow scales things so it fills 255
- like imsc or soundsc in MATLAB
- fix: norm = NoNorm()

```
from matplotlib.colors import NoNorm
```



Histogram equalization pt. process

x	input intensity	[0, 1] (then ×255)
$y = f(x)$	output intensity	[0, 1]
$P_x(x)$	distribution on x	
$P_y(y)$	distribution on $y \simeq c$	

assume continuous for now

$$P(y) = \frac{P(x)}{\left|\frac{df}{dx}\right|}$$

($P(x)$ ← input dist; $\left|\frac{df}{dx}\right|$ ← const.)

output dist ↑ change of variable ↑ (dy/dx)

therefore

$$P_y(y) = P_x(x) \cdot \frac{1}{C P_x(x)}$$

$$P_y(y) = \frac{1}{C}$$

② then ↳ output dist is a constant

Example:

① If ∴ → output is cdf · constant (up to x)

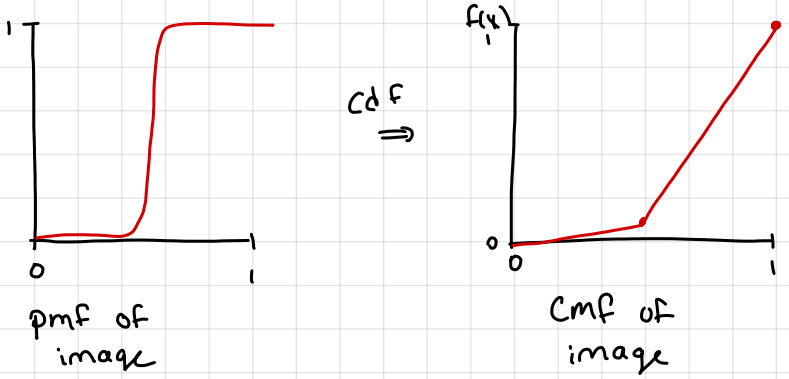
$$y = f(x) = C \cdot \underbrace{P(x \le X)}_{\text{cdf over } X}$$

$$= C \int_0^X P_x(v)\,dv$$

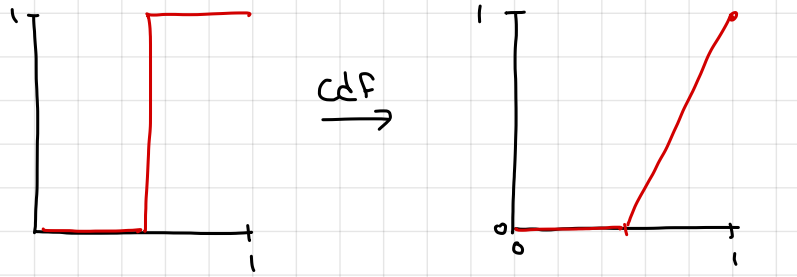
$$\frac{df}{dx} = \frac{d}{dx}\left[C \int_0^x P_x(v)\,dv\right]$$

$$= C \frac{d}{dx} \int_0^x P_x(v)\,dv$$

$$\frac{df}{dx} = C\,P_x(x)$$



output is cdf
↳ equalizes distribution



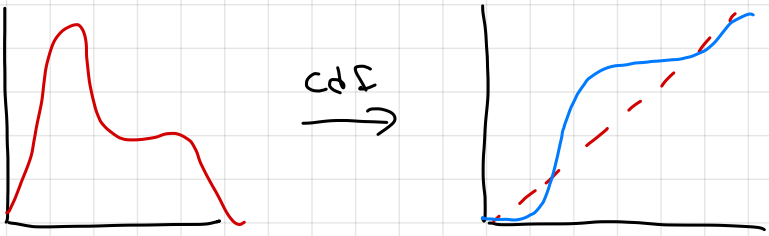


Image → pdf → $f(x) = c \cdot P(x \leq X)$ → equalized hist.
cdf

Some problems

Pt. process so all pts get processed the same
↳ exposure issues
↳ sunlight gets pushed down, no room for shadows to pull up

Soln → adaptive histogram equalization