# Variance reduction by importance sampling

а

Suppose we want to compute  $\alpha \equiv \mathrm{E}(g(W))$  with g non-negative and  $W \sim f_W$ . Let X be a random variable  $X \sim f_X$ , then

$$\alpha = E\left(g\left(X\right)\frac{f_W\left(X\right)}{f_X\left(X\right)}\right). \tag{1}$$

Proof:

$$\alpha = \int_{\mathbb{R}} g(x) f_W(x) dx \tag{2}$$

$$= \int_{\mathbb{R}} g(x) \frac{f_X(x)}{f_X(x)} f_W(x) dx$$
 (3)

$$= \int_{\mathbb{R}} g\left(x\right) \frac{f_W\left(x\right)}{f_X\left(x\right)} f_X\left(x\right) dx \tag{4}$$

$$= \mathbb{E}\left(g\left(X\right) \frac{f_W\left(X\right)}{f_X\left(X\right)}\right). \tag{5}$$

 $_{\rm b,c}$ 

The above result allows solving  $\alpha$  by Monte Carlo (MC) methods. When we sample from distribution  $f_X$  to estimate  $\alpha$ , the mean square error (MSE) of the MC estimator

$$MSE \propto \int_{\mathbb{R}} \left( \left( g(x) \frac{f_W}{f_X}(x) \right)^2 - \alpha^2 \right) f_X(x) dx.$$
 (6)

The integrand is zero by choosing  $f_X(x) = f_X^*(x) = \frac{f_W(x)g(x)}{\alpha}$ , and thus the variance of the MC estimator is minimised by choosing  $f_X = f_X^*$ . In practice, this result is of little significance, since if we knew the exact value of  $\alpha$ , there would be no need for the MC estimator in the first place.

 $\mathbf{d}$ 

Suppose we wish to evaluate P ( $\mathcal{N}(0,1) > 3.75$ ). The naive MC estimator would be given by  $g(x) = \mathbf{1}_{x > \frac{15}{4}}(x)$  and  $f_W(x) = \sqrt{2\pi} \exp\left(-\frac{x^2}{2}\right)$ . Alternatively, using an affine change of variables, we may choose for any  $\delta \in \mathbf{R}$ :  $g_{\delta}(x) = \mathbf{1}_{x > \frac{15}{4} + \delta}$  and  $f_W = \sqrt{2\pi} \exp\left(-\frac{(x - \delta)^2}{2}\right)$  and obtain the correct result.

In order to use the MC estimate, we need to be able to sample numbers, from the distribution  $\mathcal{N}(\delta, 1)$ . And evaluate g for each of those realisations. An example implementation of this is given in https://github.com/

${ m M}$	$M = 10^4$	$M = 10^{5}$
Naive MC	[0.000000, 0.000433] (116 %)	[0.000055, 0.000165] (50 %)
Refined MC	[0.000084, 0.000090] (3%)	[0.000088, 0.000089] $(1%)$
Exponential	[0.000086, 0.000103] (9%)	[0.000085, 0.000091] (3%)

Table 1: Confidence intervals for the MC estimators and relative errors when sampling from  $\mathcal{N}(0,1)$  and from  $\mathcal{N}(5.75,1)$ . Note that the reference value is  $\Phi(5.75) = 0.000088$  so that there is almost 40% that none of the realisations of of a random sample of  $M = 10^4$  exceed 5.75, leading to an estimate of zero, and vanishing variance.

Virtakuono/SME\_HW3\_Example/blob/master/examples.py The MC estimator is given by:

$$\overline{\alpha} = \sum_{m=1}^{M} \frac{g_{\delta}(X)}{M},\tag{7}$$

with  $X_m \sim N(\delta, 1)$  i.i.d. In the example we set  $\delta = 2$ . Since  $E(X_m) = \delta$ ,  $E(\overline{\alpha}) = \alpha$ . Central limit theorem guarantees that  $\overline{\alpha}$  is approximately normally distributed. To estimate the confidence interval, we compute the sample variance as

$$\overline{\sigma}^2 = \sum_{m=1}^M \frac{(g_\delta(x) - \overline{\alpha})}{M - 1}.$$
 (8)

Let

$$\Phi_{\mu,\sigma}(z) = \left(2\pi\sigma^2\right)^{-1} \int_{-\infty}^{z} \exp\left(\frac{(x-\mu)^2}{2\sigma^2}\right). \tag{9}$$

Then, there are ready implementations for the inverse of  $\Phi_{\mu,\sigma}$ , that allow us to compute  $z^*$  such that  $\Phi_{0,1}(z^*)=0.95$ . Using this together with the fact that our MC estimator is approximately normally distributed, we set  $\eta=z^*\sqrt{\frac{\overline{\sigma}^2}{M}}$  and obtain the confidence interval  $[\overline{\alpha}-\eta,\overline{\alpha}+\eta]$ . For the precise results, see table 1.

 $\epsilon$ 

We may, of course, use an exponential density too. To ensure that half of the samples generated exceed 5.75, we may set

$$\lambda = \frac{\ln 2}{5.75}.\tag{10}$$

. Further improvements can naturally be made, optimising over  $\lambda$  as well as making affine transformation of the random variable.

# Generate non-uniformly distributed random numbers given uniform

a

A mean zero unit variance random variable X has a Laplace distribution if its pdf is  $f(x) = \frac{1}{2}e^{-|x|}$ .

**Algorithm** to generate such random variable:

- $u \sim U(0,1)$
- $X \sim F_U^{-1}(u)$ , where

$$F_X(x) = \begin{cases} 1 - \frac{1}{2}e^{-x}, & x \ge 0\\ \frac{1}{2}e^{-x}, & x < 0 \end{cases}$$

$$F_U^{-1}(u) = \begin{cases} \log(2u), \ 0 < u \le \frac{1}{2} \\ -\log(2(1-u)), \ \frac{1}{2} \le u < 1. \end{cases}$$

 $\mathbf{b}$ 

Algorithm to generate  $Y \sim N(\mu, \sigma)$  random variables using the result above. Assume that there exists  $\epsilon \in (0, 1]$  such that  $\epsilon \frac{f_Y(X_k)}{f_X(X_k)} \leq 1$ .

#### Algorithm (acceptance-rejection)

- Set k=1
- Sample two independent random variables  $X_k$  and  $U_k \sim U(0,1)$
- If  $U_k \leq \epsilon \frac{f_Y(X_k)}{f_X(X_k)}$ , then accept  $Y = X_k$  as sample from  $N(\mu, \sigma)$ . Otherwise, reject  $X_k$ , increment k by 1 and go back to previous step.

 $\mathbf{c}$ 

Let U and V be two independent standard Gaussian random variables. Prove that the ratio  $\frac{U}{V}$  is a Cauchy random variable.

that the ratio  $\frac{U}{V}$  is a Cauchy random variable. **Proof** Let  $Z = \frac{U}{V}$  then cdf of Z is given by

$$F_{Z}(z) = P(\frac{U}{V} \le z),$$

$$= P(U \le zV|V > 0) + P(U \ge zv|V < 0),$$

$$= \int_{0}^{\infty} \left( \int_{-\infty}^{zv} f_{U}(u) \right) f_{V}(v) dv + \int_{-\infty}^{0} \left( \int_{zv}^{-\infty} f_{U}(u) \right) f_{V}(v) dv.$$

Then, the pdf of Z is given by

$$f_{Z}(z) = \frac{dF_{Z}(z)}{dz},$$

$$= \int_{0}^{\infty} v f_{U}(zv) f_{V}(v) dv + \int_{-\infty}^{0} v f_{U}(zv) f_{V}(v) dv,$$

$$= 2 \int_{0}^{\infty} v f_{U}(zv) f_{V}(v) dv = \frac{1}{\pi (1 + z^{2})}$$

### Algorithm

- Generate samples from independent standard Gaussian random variables U and V.
- Compute the samples  $Z = \frac{U}{V}$ .

## Kernel Density Estimator (KDE)

 $\mathbf{a}$ 

We propose to estimate a density function  $\rho(y)$  based on a MC sample of realisations  $y_i \in \mathbb{R}^d$  from the density  $\rho$  as follows

$$\hat{\rho}(y) = \frac{1}{Mh^{-d}} \sum_{m=1}^{M} K\left(\frac{y - y_i}{h}\right),\tag{11}$$

with

$$K(x) = 2^{-d} \mathbf{1}_{||x||_{L_2}}(x)$$
 (12)

In this estimation, we commit two errors.

#### bias error

$$\rho(u) - \mathrm{E}(\hat{\rho}(y)) \tag{13}$$

$$=\rho\left(y\right)\int_{\mathbb{R}^{d}}h^{-d}K\left(\frac{y-z}{h}\right)\rho\left(z\right)dz\tag{14}$$

$$= \int_{\mathbb{R}^d} \left( \rho(y) - \rho(y - hz) \right) K(z) dz \tag{15}$$

$$\approx \int_{\mathbb{R}^d} \left( \rho\left(y\right) - \left(\rho\left(y\right) - hz_i \partial_{y_i} \rho\left(y\right) + \frac{1}{2} h^2 z_i z_j \partial_{z_i, z_j}^2 \rho\left(y\right) \right) \right) K\left(z\right) dz \quad (16)$$

$$=\frac{h^{2}}{2}\partial_{y_{i}y_{j}}\rho\left(u\right)\int_{\mathbb{R}^{d}}z_{i}z_{j}K\left(z\right)dz\propto h^{2}$$
(17)

#### statistical error

The variance is bounded by

$$V\left(K\left(\frac{y-z}{h}\right)\right) \le E\left(K^2\left(\frac{y-z}{h}\right)\right) \tag{18}$$

and

$$E\left(K^{2}\left(\frac{y-z}{h}\right)\right) \approx \int_{\mathbb{R}^{d}} K^{2}\left(z\right) h^{d}\left(\rho\left(y\right) - hz_{i}\partial_{y_{i}}\rho\left(y\right) + \frac{h^{2}}{2}z_{i}z_{j}\partial_{y_{i}y_{j}}^{2}\rho\left(y\right)\right) dz,\tag{19}$$

thus

$$V\left(\hat{\rho}\left(y\right)\right) = M^{-1}h^{-2d}V\left(K\left(\frac{y-z}{h}\right)\right) \tag{20}$$

$$\geq M^{-1}h^{-2d}h^d\rho(y)\int_{\mathbb{R}^d} K^2(z) dz \propto M^{-1}h^d$$
 (21)

#### Total error

With undefined constants A and B we have that the total error squared (TSE) is given as

$$TSE \approx Ah^4 + \frac{B}{Mh^d}.$$
 (22)

The critical point of the total square error is thus given by

$$h^{4+d} \propto M^{-1}. (23)$$

This choice implies that the bias and sampling errors are of the same order

$$\sqrt{\text{TSE}} = \mathcal{O}\left(M^{-\frac{2}{d+4}}\right) \tag{24}$$

With the above analysis, we produce the set of three images (1) for varying M for a one-dimensional KDE and an example of two-dimensional gaussian example (2).

## KDE for conditional expectation

 $\mathbf{a}$ 

Consider the Nadaraya-Watson estimator (cf. [1])  $\hat{g}(x)$  for E[Y|X=x] which is derived as follows:

$$g(x) = E[Y|X = x] = \frac{\int yf(y,x)dy}{f(x)},$$

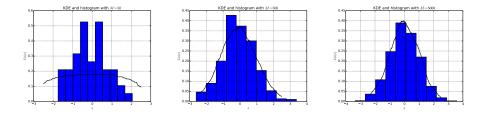


Figure 1: One-dimensional multivariate Gaussian and corresponding KDEs.

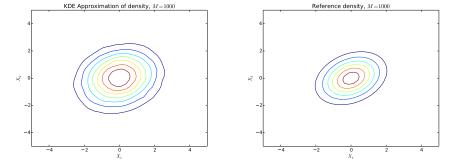


Figure 2: Two-dimensional multivariate Gaussian estimated (left) and exactly computed (right). M=100 samples, h=0.5

using the KDE for both f(y, x) and f(x)

$$\hat{f}(y,x) = \frac{1}{n} \sum_{i=1}^{n} \kappa_h(y - Y_i) \kappa_H(x - X_i),$$

$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^{n} \kappa_H(x - X_i),$$

and the fact that  $\int z \kappa_h(z) dz = 0$ , we obtain

$$\hat{g}(x) = \frac{\sum_{i=1}^{n} \kappa_{H}(x - X_{i}) Y_{i}}{\sum_{i=1}^{n} \kappa_{H}(x - X_{i})}.$$

Optimal rate of convergence Note we have

$$Y_i = g(X_i) + \epsilon_i,$$
  

$$Y_i = g(x) + (g(X_i) - g(x)) + \epsilon_i,$$

where  $E(\epsilon_i|X_i) = 0$  and  $E(\epsilon_i^2|X_i = x) = \sigma^2(x)$ . Therefore, the estimator can be written as

$$\hat{g}(x) = g(x) + \frac{\hat{m}_1(x)}{\hat{f}_X(x)} + \frac{\hat{m}_2(x)}{\hat{f}(x)},$$

where

$$\hat{m}_{1}(x) = \frac{1}{n} \sum_{i=1}^{n} \kappa_{H}(x - X_{i})(g(X_{i}) - g(x)),$$

$$\hat{m}_{2}(x) = \frac{1}{n} \sum_{i=1}^{n} \kappa_{H}(x - X_{i})\epsilon_{i}.$$

If d = 1, we can show that

$$E(\hat{m}_1(x)) = \frac{1}{h} \int k \left(\frac{x-u}{h}\right) (g(u) - g(x)) f(u) du$$

$$= \int k(z) (g(x+hz) - g(x)) f(x+hz) dz$$
(Taylor expansion)
$$= h^2 B(x) f(x) \int k(z) z^2 dz + o(h^2),$$

where  $B(x) = \frac{1}{2}g''(x) + \frac{g'(x)}{f(x)}f'(x)$ . Similarly, we can obtain  $Var(\hat{m}_1(x)) = O(\frac{1}{nh})$ .

$$E(\hat{m}_2(x)) = 0,$$

$$Var(\hat{m}_2(x)) = \frac{1}{nh^2} \int k \left(\frac{x-u}{h}\right)^2 \sigma^2(u) f(u) du$$

$$= \frac{1}{nh} \int k(z) \sigma^2(x+hz) f(x+hz) dz$$
(Taylor expansion)
$$= \frac{\sigma^2(x) f(x)}{nh} \int k(z)^2 dz + o(h^2),$$

The asymptotic mean square error (AMSE) when d=1 is

$$\left(h^2B(x)\right)^2\left(\int k(z)z^2dz\right)^2+\frac{\sigma(x)^2f_X(x)}{nh}\left(\int k(z)^2dz\right).$$

In General, the asymptotic mean square error (AMSE) is given by

$$\left(\sum_{j=1}^d h_j^2 B_j(x)\right)^2 \left(\int k(z)z^2 dz\right)^2 + \frac{\sigma(x)^2 f_X(x)}{n|H|} \left(\int k(z)^2 dz\right)^d,$$

where  $B_j(x) = \frac{1}{2} \partial_{x_j}^2 g(x) + f(x)^{-1} \partial_{x_j} g(x) \partial_{x_j} f(x)$  and the optimal value for h is proportional to  $N^{-\frac{1}{d+4}}$ .

#### b

Let us reuse the sample from the last exercise and show an illustration of the performance of the algorithm in figure 3

## Monte Carlo and Variance Reduction

The task at hand is to evaluate an option on an underlying that is an arithmetic mean of a log-normal random variable. No closed form solution exists. However, we do have a closed form expression for the arithmetic mean of normal variables. Based on a visual inspection (cf. fig 4), the distribution of the underlying is, however, somewhat close to a Gaussian and especially the relevant part, the right tail of the distribution could be approximated with a Gaussian with a decent fidelity. We have

$$V_N = V_0 \prod_{n=1}^{N} R_n. (25)$$

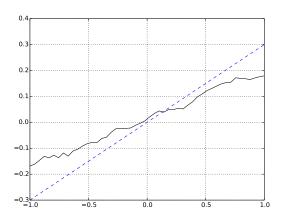


Figure 3: The conditional expectation of y, given x. The sample data is generated from M=400 realisations of i.i.d. Gaussian random variables  $z_1$  and  $z_2$ .  $x_2=z_2$ ,  $x_1=z_1+0.3z_2$ . The blue dashed line indicates the reference at slope 0.3. h =0.2.

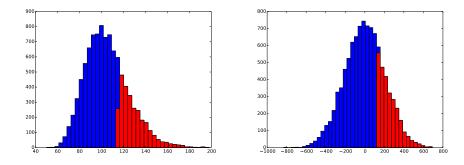


Figure 4: The distribution of the underlying of the Asian Option (left) and a control variate (right). The right tail of the distribution is coloured left to indicate realisations in the money with strikes K and  $\tilde{K}$ .

Empirically, we see that the probability  $P_{otm}$  of  $V_N$  being out of the money is approximately 72 per cent. Define

$$Q = \sum_{n=1}^{N} (50 - n) (\ln R_n - r\Delta t), \qquad (26)$$

we note that both Q and  $V_N$  are increasing in all the random variables  $R_n$ . Furthermore, we know that Q entered and normally distributed with  $\tilde{\sigma}^2 = \sum_{n=1}^N (50-n)^2$ . With the inverse cumulative distribution  $\Phi^{-1}$  we can define

$$\tilde{K} = \tilde{\sigma}\Phi^{-1}(P_{otm}). \tag{27}$$

Then our control variate is

$$G = \left(Q - \tilde{K}\right)^{+}.\tag{28}$$

We have

$$\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2\tilde{\sigma}^2}\right) (x-k)^+ = \frac{\tilde{\sigma}}{\sqrt{2\pi}} \exp\left(-\frac{k^2}{2\tilde{\sigma}^2}\right) + k \left(\Phi\left(k\right) - 1\right). \tag{29}$$

We have that the correlation coefficient  $\rho$  between G and  $C = \left(\sum_{n=1}^{N} \frac{V_n}{K} - K, 0\right)^+$  exceeds 0.99, see fig 5.

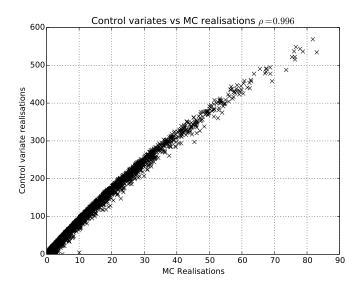


Figure 5: The MC realisations and corresponding control variates show a near-perfect correlation

We can form the estimators

$$\overline{C}_{1} = \sum_{m=1}^{M} \frac{\left( \left( \sum_{n=1}^{N} V_{0} \prod_{m=1}^{n} R_{n} \right) - K \right)^{+}}{M}$$
(30)

$$\overline{C}_{2} = \sum_{m=1}^{2M} \frac{\left( \left( \sum_{n=1}^{N} V_{0} \prod_{m=1}^{n} \tilde{R}_{n,m} \right) - K \right)^{+}}{M} + \sum_{m=1}^{2M} \frac{\left( \left( \sum_{n=1}^{N} V_{0} \prod_{m=1}^{n} \tilde{R}_{n,m} \right) - K \right)^{+}}{M}$$
(31)

$$\overline{C}_{3} = \sum_{n=1}^{M} \frac{\left(\left(\sum_{n=1}^{N} V_{0} \prod_{m=1}^{n} R_{n}\right) - K\right)^{+} + \beta \left(G_{m} - \operatorname{E}\left(Q\right)\right)}{M}$$
(32)

$$\overline{C}_{4} = \sum_{m=1}^{2M} \frac{\left(\left(\sum_{n=1}^{N} V_{0} \prod_{m=1}^{n} R_{n}\right) - K\right)^{+} + \beta \left(G_{m} - \operatorname{E}\left(Q\right)\right)}{M}$$

$$\sum_{m=1}^{2M} \frac{\left( \left( \sum_{n=1}^{N} V_0 \prod_{m=1}^{n} R_n \right) - K \right)^{+} + \beta \left( Q_m - \mathbb{E} \left( Q \right) \right)}{M}, \tag{33}$$

Plain vanilla	Antithetic	Control variate	Hybrid
0.15 %	0.10 %	0.012 %	0.0085 %

Table 2: Widths of 95 % confidence bands for different Monte Carlo estimators for M = 1000. Modified option price approximately 4.3.

for the plain vanilla, antithetic, control variate, and combination methods, respectively. The  $R_{n,m}$  are understood to be independent realisations of the incrementation for nth time step for realisation m The antithetic variables are defined as

$$\tilde{R}_{n,m} = \exp\left(-\log R_{n,m} + \Delta tr\right) \tag{34}$$

and

$$\tilde{Q}_m = \sum_{n=1}^{N} (50 - n) \left( \ln \tilde{R}_{nm} - r\Delta t \right), \tag{35}$$

$$G_m = \left(Q_m - \tilde{K}\right)^+ \tag{36}$$

$$\tilde{G}_m = \left(\tilde{Q}_m - \tilde{K}\right)^+. \tag{37}$$

In order to minimise the variance of the estimators, we set  $\beta = \rho \sqrt{\frac{\sigma_C^2}{\sigma_Q^2}}$  with  $\sigma_C^2$  being the variance of the plain vanilla MC realisations and  $\sigma_Q^2$  the variance of the control variate realisations. With M=10000, we obtain the results in table 2: The exact computational cost of each estimator depends on how computationally costly it is to generate time steps compared to the cost of generating random numbers. For a rough approximation, we may state that the computational cost of the antithetic and control variate estimators are twice that of the plain vanilla and the hybrid method requires four-fold computational effort.

# Confidence interval, Bootstrapping

In order to compute the expected shortfall we reuse the MC sample from the previous exercise. Let our MC estimator  $\overline{C}$  be given as:

$$\overline{C} = \sum_{m=1}^{M} \frac{X_i}{M}.$$
(38)

Then let us draw  $N \times M$ ,  $N, M \in \mathbb{Z}$  random variables  $k_i \in \{1, 2, 3, ...M\}$ . Then define  $S_j$  such that

$$\#A_j = \#\{k_i : X_{k_i} > S_j, (j-1)M \le i \le jM-1\} = \lfloor pM \rfloor$$
 (39)

p	0.9	0.95	0.99
Confidence interval	[28.28, 30.01]	[36.51, 38.80]	[52.34, 57.68]

Table 3: Confidence intervals for the Expected Shortfall for problem 5 example for various quantiles. The width of the confidence interval tends to increase as a function of q.

for  $j \in \{1, 2, 3, 4, ..., N\}$  and

$$Q_j = \sum_{i \in A_j} \frac{X_i \mathbf{1}_{x > S_j} (X_i)}{\# A_j}$$

$$\tag{40}$$

then the estimated confidence interval can be noted as  $[Q^-, Q^+]$  as

$$\#\left\{j:Q_{j}< Q^{-}\right\} = \left|\frac{qN}{2}\right| \tag{41}$$

$$\#\{j: Q_j < Q^+\} = \left|\frac{qN}{2}\right|.$$
 (42)

Setting N = 1000, we obtain the results in the table 3

## References

- [1] Nadaraya-Watson estimator http://www.maths.manchester.ac.uk/~peterf/MATH38011/NPR%20N-W%20Estimator.pdf
- [2] Example code in python. https://github.com/Virtakuono/SME\_HW3\_Example/blob/master/examples.py