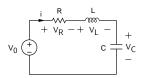
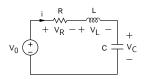
# EE101: RLC Circuits (with DC sources)



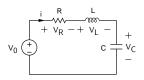
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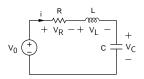
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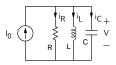
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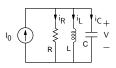
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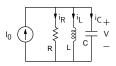
i.e., 
$$\frac{d^2i}{dt^2} + \frac{R}{L}\frac{di}{dt} + \frac{1}{LC}i = 0$$
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a second-order ODE with constant coefficients.





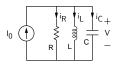
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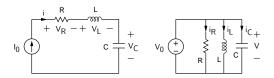
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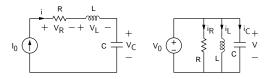
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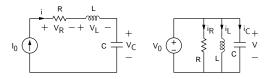
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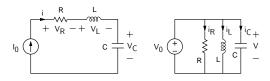


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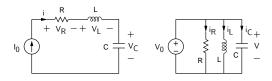
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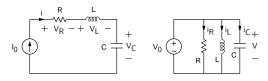
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$$i_R = V/R, \ i_C = C \frac{dV}{dt}, \ i_L = \frac{1}{L} \int V \, dt \, .$$





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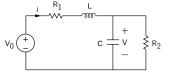
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\* The above equations hold even if the applied voltage or current is not constant, and the variables of interest can still be easily obtained without solving a differential equation.

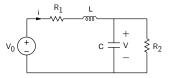


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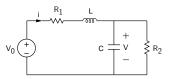


$$V_0 = R_1 i + L \frac{di}{dt} + V$$

$$i = C \frac{dV}{dt} + \frac{1}{R_2} V$$
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Substituting (2) in (1), we get

$$V_0 = R_1 \left[ CV' + V/R_2 \right] + L \left[ CV'' + V'/R_2 \right] + V, \tag{3}$$

$$V''[LC] + V'[R_1C + L/R_2] + V[1 + R_1/R_2] = V_0.$$
(4)

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$$\frac{d^2y}{dt^2} + a\frac{dy}{dt} + by = K \text{ (constant)}.$$

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The general solution y(t) can be written as,

$$y(t) = y^{(h)}(t) + y^{(p)}(t),$$

where  $y^{(h)}(t)$  is the solution of the homogeneous equation,

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In the context of *RLC* circuits,  $y^{(p)}(t)$  is the steady-state value of the variable of interest, i.e.,

$$y^{(p)} = \lim_{t \to \infty} y(t),$$

which can be often found by inspection.



For the homogeneous equation,

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we first find the roots of the associated characteristic equation,

$$r^2 + a r + b = 0$$
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- \*  $r_1$ ,  $r_2$  are complex,  $r_{1,2} = \alpha \pm j\omega$  ("underdamped")  $y^{(h)}(t) = \exp(\alpha t) \left[ C_1 \cos(\omega t) + C_2 \sin(\omega t) \right].$

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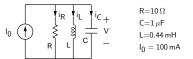
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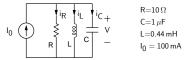
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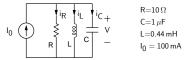
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- \*  $r_1 = r_2 = \alpha$  ("critically damped")
  - $y^{(h)}(t) = \exp(\alpha t) [C_1 t + C_2].$



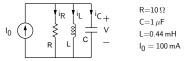




$$i_L(0^-) = 0 A \Rightarrow i_L(0^+) = 0 A.$$
  
 $V(0^-) = 0 V \Rightarrow V(0^+) = 0 V.$ 



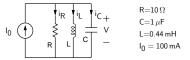
$$\begin{split} &i_L(0^-)=0\,A\Rightarrow i_L(0^+)=0\,A.\\ &V(0^-)=0\,V\Rightarrow V(0^+)=0\,V.\\ &\frac{d^2V}{dt^2}+\frac{1}{RC}\,\frac{dV}{dt}+\frac{1}{LC}\,V=0 \quad \text{(as derived earlier)} \end{split}$$



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The roots of the characteristic equation are (show this):

$$r_1 = -0.65 \times 10^5 \, s^{-1}$$
,  $r_2 = -0.35 \times 10^5 \, s^{-1}$ .



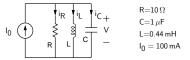
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The general expression for V(t) is,

$$V(t) = A \exp(r_1 t) + B \exp(r_2 t) + V(\infty),$$



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i.e., 
$$V(t) = A \exp(-t/\tau_1) + B \exp(-t/\tau_2) + V(\infty)$$
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where 
$$\tau_1 = -1/r_1 = 15.4 \,\mu\text{s}$$
,  $\tau_2 = -1/r_1 = 28.6 \,\mu\text{s}$ .

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$$A + B = 0.$$
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From (1) and (2), we get the values of A and B, and

$$V(t) = -3.3 \left[ \exp(-t/\tau_1) - \exp(-t/\tau_2) \right] V.$$
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(SEQUEL file: ee101\_rlc\_1.sqproj)

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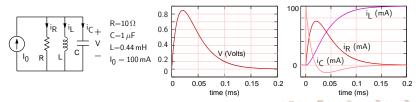
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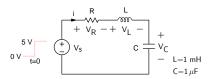
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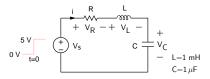
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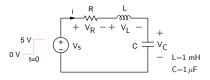
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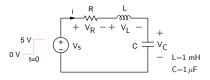




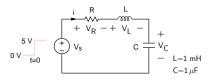
(a) Show that the condition for critically damped response is  $R=63.2\,\Omega$ .



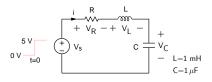
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- (b) For  $R=20\,\Omega$ , derive expressions for i(t) and  $V_L(t)$  for t>0 (Assume that  $V_C(0^-)=0\,V$  and  $i_L(0^-)=0\,A$ ). Plot them versus time.



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