# **HumanityLink 2.0 aka HLDeuce**

vDM Challenge3: Deploy, Manage & Expand



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## 1 DOCUMENT CONTROL

## **Preparation**

Action	Name	Date
Technical Content	Nigel Hickey	7/1/2017
Formatting	Nigel Hickey	7/4/2017

## Release

Version	Date Released	Change Notice	Pages Affected	Remarks	
1.0	7/15/2017	Internal	All	Initial Draft	
1.1	7/18/2017	VDM Release	All	VDM Release	

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#### 2 PROJECT OVERVIEW

#### 2.1 INTRODUCTION & SCOPE

Things have changed...

vCenterNerd Consulting had to do the one thing they never wanted to even think of doing, activating Operation MegaDeath. It was not ideal, but necessary and effective.

Since all datacenter employees who had hands on-site access to facilities at MAC & DNB had to be physically terminated from the earth, our efforts are now even more complex as we scale our environment from three sites to many. The only people left behind after the EatBrains virus are myself and two other trusted engineers who have completed extensive DNA testing for zombie infectious disease as well as completed a comprehensive interrogation after being injected with Candor's Truth Serum.

The three of us must now maintain our current 3 site architecture as well as continue to explore future sites for deployment. We are actively bringing new men & women on board one by one into our new faction after undergoing the same testing as the others. We have located and hired armed security guards from the vDM Season 1 datacenter in Bratislava, Slovakia that was masterminded by the infamous Katarina Wagnerova (VDM004). This new security team will help enforce our new standards going forward, as well as help us find & onboard new datacenter engineers as required.

Our new security team has already began proving their worth in recent weeks. One of the security soldiers who only goes by the name 'Josh01', has recovered what looks to be the remains of a chip used in a T-800 Skynet bot. The chip is said to still contain traces of cybernetic organisms.

Josh01 and his team have been granted approval to continue building their new "robot". The only thing that he kept mentioning over and over was that we must let him design this robot based from the template shown below. He has also dubbed this new cyborg GP-900, something about GingerPower-900 series processors...I am not fully understanding this just yet, but we could use the unit in future missions for sure.





## 2.2 REQUIREMENTS, CONSTRAINTS, ASSUMPTIONS, AND RISKS

## 2.2.1 Requirements

Number	Description
R01	Centralized remote operations for datacenters
R02	Operations Procedures for managing version control of code
R03	Expansion beyond 3 sites is needed

## 2.2.2 Constraints

Number	Description
C01	Future sites for new DCs have not yet been declared Zombie-Free-Zones
C02	DC staff has been reduced to a handful after Operation MegaDeath
C03	Design must include currently available products, no futures

## 2.2.3 Assumptions

Number	Description	
A01	FCC does not exist to police drone flight regulations	
A02	Modular datacenters are available from vendor	
A03	Open Source applications are available for download/use	
A04	Robot Army has yet to be fully deployed	
A05	WAN connections between datacenters are at least 100mbps & redundant	
A06	Deployment Drivers/Pilots have been trained to verify DC components in working order	
A07	Cobbler installation & configuration is out of scope for this document	

## 2.2.4 Risks

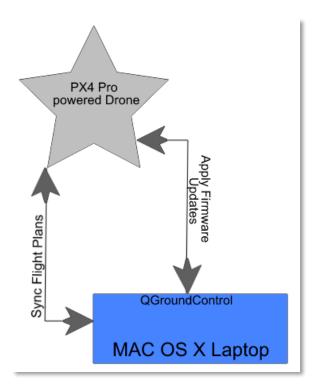
Number	Description	Mitigation
RS01	New DC deployments in may occur near Zombie infested areas	DC deployments will be modular with minimal human interaction required.
RS02	Off-Earth datacenters are being consider for future growth	Earth DCs will always be considered 1st, and off-Earth sites only when absolutely needed.
R03	Datacenter Admins may not be able to learn how to code apps or infrastructure without many hours of training	Terraform was chosen as the Infra-as-code application as it does not take much learning of new tech. Direction & training will be minimal

#### 3 FUTURE SITE DESIGN

#### 3.1 SITE DISCOVERY

#### 3.1.1 Unmanned Aerial Vehicles (UAV)

As we move to expand our datacenter locations, we must be careful as many of these future sites are still considered dangerous and have not been declared zombie free zones. Because of this we are considering the use of Unmanned Aerial Vehicles (UAV) for recon missions to potential new site locations that could still have Zombie activity. These PX4 Pro powered drones will allow us to plan autonomous flight missions to areas of interest. The use of the application QGroundControl will provide full flight control and vehicle setup for PX4 powered UAVs.



#### 3.1.2 PX4

PX4 is platform independent autopilot software (or a software stack/firmware) that can fly Unmanned Aerial Vehicles (UAV). It is loaded (flashed) on vehicle control hardware and together with Ground Control Station it makes a fully autonomous autopilot system.

#### 3.1.3 QGroundControl

The PX4 ground control software is called QGroundControl and is integral part of the PX4 Autopilot System. QGroundControl will run on OS X or Linux systems within our DCs. With the help of QGroundControl you can load (flash) the PX4 on to the vehicle control hardware, you can setup the vehicle, change different parameters, get real-time flight information and create and execute fully autonomous missions.

#### **QGroundControl Key Features:**

- Full setup/configuration of PX4 Pro powered vehicles
- Flight support for vehicles running PX4
- Mission planning for autonomous flight
- Flight map display showing vehicle position, flight track, waypoints and vehicle instruments
- Video streaming with instrument display overlays
- Support for managing multiple vehicles
- QGC runs on Windows, OS X, Linux platforms, iOS and Android devices

"Fly View": QGroundControl



## Justification

The use of Unmanned Aerial Vehicles (UAV) for recon missions was the best way to get visuals on possible site locations for placing our new datacenters. Using an UAV was easier than losing another member of our already short staffed team. [C01]

#### 3.2 SITE DEPLOYMENT

#### 3.2.1 Modular Datacenters

We have chosen to use Modular Datacenters similar to what IO Datacenters provides (DC in a box) with the D-MODULE (Up to 18 Racks Power – Up to 180kW Dedicated – Cooling, power, fire suppression, security) systems.

D-Module DCs



These modular datacenters can be delivered to our new site locations and be ready to come online once powered up. To assist the delivery & power up of these modular datacenters, the delivery driver or pilot will also carry a payload of human remains (AKA Zombie-Treats) leftover from Operation MegaDeath. Delivery drivers will be instructed to use Zombie-Treats at least 1 mile outside of the intended new datacenter location for distraction purposes while the D-MODULE is positioned & powered up, and connected to uplinks.

Delivery drivers/pilots will have access to two PX4 drones and a Linux laptop running QGroundControl. The drivers/pilots can then leverage the PX4 drone to survey the area prior to physical D-MODULE placement.

#### 3.2.2 Modular Configuration

Prior to these modular datacenters being shipped and at a minimum, vSphere 6.5 will be preinstalled on the 1<sup>st</sup> three Dell R730's and configured with a Mgmt Cluster to limit the amount of work that needed to be completed after these data centers are powered up on site. The same Networking & Storage used at the MAC & DNB Datacenters will be used within these modular datacenters. Site-to-Site VPN is also part of the pre-configuration.

## 3.2.3 Modular Deployment

The Operational Procedures for deployment of our modular datacenters is as follows:

- 1. Deployment driver and/or pilot will drop Zombie-Treats for distraction
- 2. Deploy modular datacenter to physical site location

- 3. Verify physical site security with PX4 drone prior bringing online with power connects
- 4. Verify network connectivity at uplinks
- 5. Verify Site-Site VPNs between existing datacenters come online with new Modular DC
- 6. Deployment driver will then contact site admins in MAC & DNB datacenters to verify connectivity to new Modular DC
- 7. Deployment driver will leave the area immediately after he/she receives confirmations from site admins in MAC or DNB DCs.
- 8. Deployment driver may leave area ASAP if in danger from Zombies or other threats, but not until at least power has been provided to the Modular DC.

#### Justification

The use Modular Datacenters will allow us to have a fully operational datacenter "pod" in areas that may still be potentially unsafe from Zombies. These are easily repeatable building blocks that can be scaled up or down as we grow or migrate to different areas of Earth and even possibly Off-Earth locations.

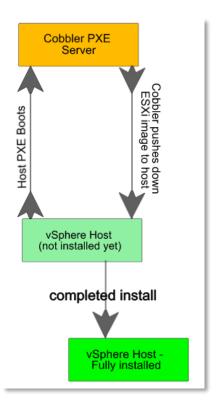
[R03], [A06], [C01], [C02], [RS01], [RS02]

## 4 FUTURE SITE MANAGEMENT

#### 4.1 SITE PROVISIONING

#### 4.1.1 Cobbler

Cobbler 2.8 will be leveraged to PXE boot any VMware host that was not preinstalled with vSphere for us within our modular datacenters. Cobbler is a Linux installation server that allows for the rapid setup of network installation environments and can help with provisioning, managing DNS and DHCP, package updates, power management, configuration management orchestration, etc.



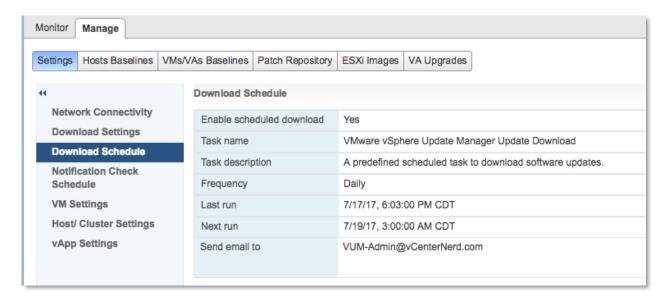
Cobbler will be installed on a CentOS 6.5 Linux virtual machine within the first vSphere Management cluster that is prebuilt in our modular DC and will serve to be the PXE boot target for deploying additional ESXi hosts. The Cobbler server will reside on a permanent VLAN (500) in order to prevent any production systems from booting from Cobbler by mistake.

VM	Description	vCPU	RAM	Disk	VLAN
MOD-COBB01	Cobbler PXE Target (CentOS)	4	4GB	20GB	500

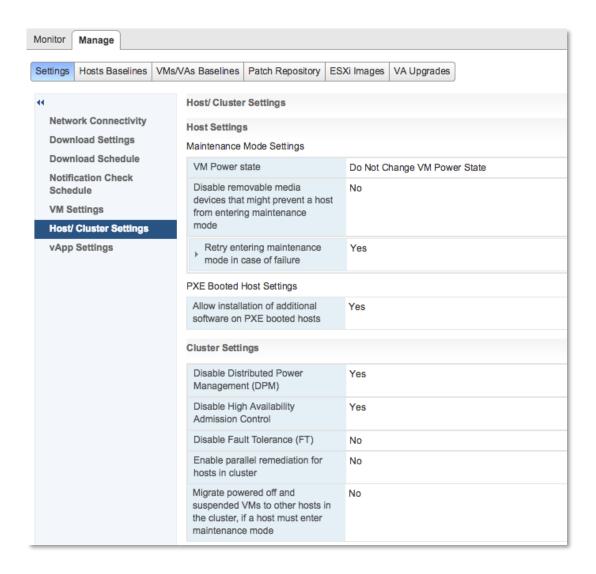
#### 4.1.1.1 vSphere Management Cluster

The vSphere Management cluster will contain the same systems setup as our other datacenters in MAC & DNB. These three Dell R730XD servers in our vSphere 6.5 cluster will also leverage VMware Update Manager (VUM) as well as Host Profiles to keep settings consistent as well as have easy access to vSphere & third party software updates, patches, and upgrades.

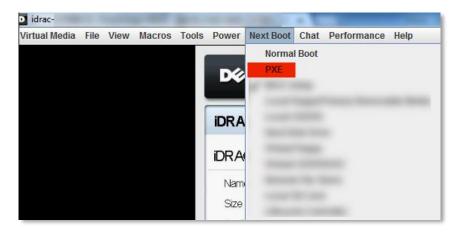
VUM is setup to download new updates daily at 3AM; seen below in the Download Schedule screen



The following Host settings are also configured in VUM



Additionally, each Dell system outside of the 1<sup>st</sup> vSphere cluster will be configured via iDRAC to have a "Next Boot" point to PXE. This will allow the future ESXi hosts to boot via PXE and see the Cobbler server to get its config.



#### **Justification**

Cobbler was chosen to best help with the automation of ESXi vSphere installations on hosts within each Modular DC. Since we may not be able to have humans at every new Modular DC, this can help satisfy the need for remote management & provisioning. [R01], [A07]

#### 4.1.2 Terraform

Terraform will be leveraged to design and provision our infrastructure virtual machines as well as help manage version control. Installing of infrastructure virtual machines will require terraform configurations as well terraform variables held in .tf files. Terraform can be used for both our vSphere & AWS datacenters if required.

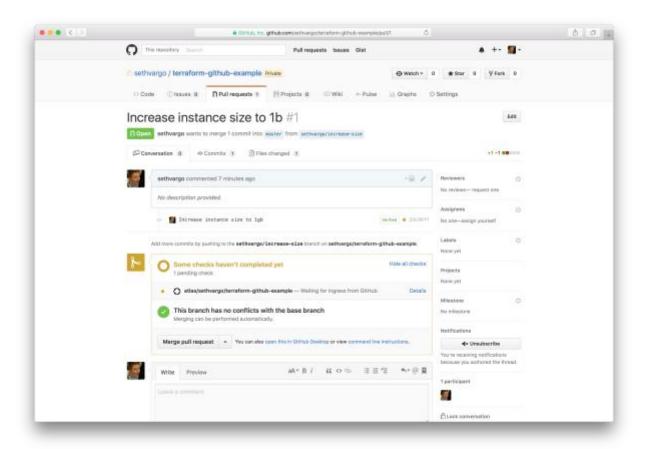
<u>From Terraform's site</u>: "Terraform enables you to safely and predictably create, change, and improve production infrastructure. It is an open source tool that codifies APIs into declarative configuration files that can be shared amongst team members, treated as code, edited, reviewed, and versioned."

Terraform is distributed as a binary package for all supported platforms and architectures. Terraform can be installed on Windows, Linux, Solaris, OpenBSD. We will be installing Terraform on a MAC OS X & Linux systems ONLY and saving our Terraform configs (\*.tf files) in GitHub for versioning control.

Terraform (Pro version can do this) can connect to GitHub, GitHub can automatically notify Terraform Pro of changes to code at the Version Control Software (VCS) layer. These change notifications, in the form of webhooks, automatically trigger a plan phase. Terraform Pro controls the version of Terraform, the ingress and egress permissions, and securely stores and manages provider credentials. After linking, when new branches are created on this repository, Terraform Pro will automatically execute a dry-run on the configuration changes and report back the results to GitHub through a Pull Request.

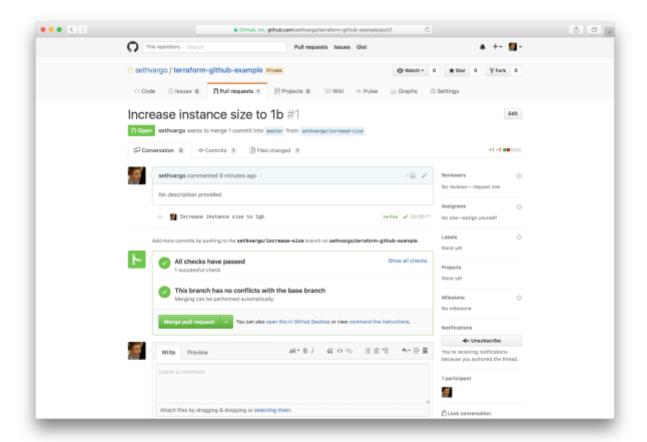
Here is an example below of a GitHub Pull Request that shows Terraform executing the plan phase of changes. Notice the pre-check (terraform plan) & then the Green Checkmark when the changes would apply successfully.



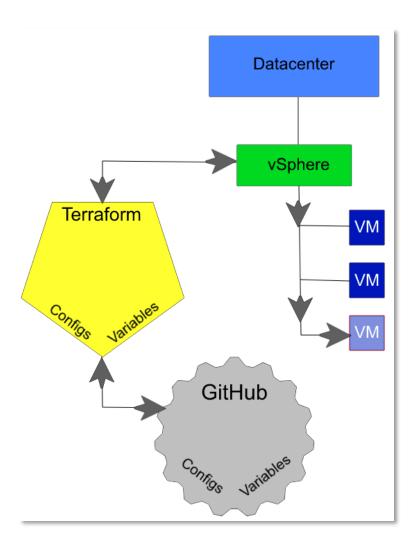


From GitHub you can then jump to Terraform Pro (shown below) to see the output from the Terraform Plan. Once changes are approved from datacenter team members, the code can be merged in GitHub, confirmed in Terraform, then the infrastructure is created or changed as you would/could do manually at the command line.

## Example: \$ terraform apply



Example: Terraform Logical Flow creating vSphere VM



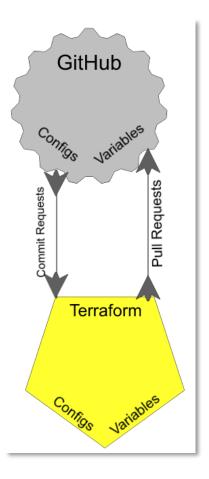
## Justification

To have a safe, predictable, and repeatable infrastructure as code deployment model, Terraform Pro was chosen. It is more designed for teams or collaboration than the standard Terraform version which does not scale well. Terraform Pro also allows our teams to meet the requirements of version control by connecting Terraform Pro to GitHub. [R01], [R02]

#### 4.1.3 Version Control

GitHub will be used for maintaining version control of our Infrastructure and Application code. GitHub will also allow our Engineers to work together on code and be remotely dispersed from each other. To hit the ground running, we will leverage the Business version of GitHub because it will allow us to have multiple users in Git,

create Private repositories to share code securely, as well as the Business plan guarantees 99.95% uptime which is always a positive.



#### **Justification**

GitHub fit the need for simple setup & configuration of code repositories that can be shared, secured, and versioned without much human effort and learning curve. [R01], [R02], [A03], [C03]

#### 4.2 OPERATIONAL PROCEDURES

#### 4.2.1 GitHub

Following this procedure will enable GitHub to be used for a code repository. Access for all MAC & DNB administrators has been granted already to the vCenterNerd Consulting account. Admins have also been given the proper credentials to login prior to following these steps.

- 1. Login to our GitHub account for vCenterNerd Consulting at: https://github.com/
- 2. Create a Repository for your datacenter (use MAC for Machrihanish & DNB for Devonport)
  - a. Click the "+" symbol near the upper right corner of the page, and select New Repository
  - b. Name the Repository

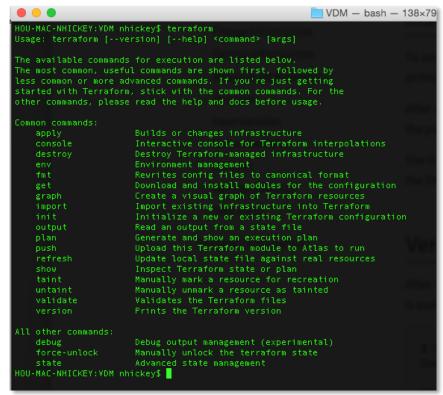
- c. Type a short description (enter DC name & admin who created)
- d. Choose Private as the type
- e. Select the checkbox Initialize this repository with a README
- f. Click Create Repository to finish
- 3. Next we need to create a Branch within the new Repository you have just made. The Branch will be used when testing or editing before committing the changes to the Master branch
  - a. From your DC named Repository (MAC or DNB), click the drop down list that reads **branch**: **master**
  - b. In the drop down, begin typing the new Branch name
  - c. When done typing the Branch name, click the blue bar that appears showing **Create branch:** "branch-name" or simply hit **Enter**
- 4. At this point the needed GitHub setup is completed for the DC admin(s).

#### 4.2.2 Terraform

Following this procedure will enable the use of Terraform on your systems (laptop/desktop). These steps go over Creating, Changing, and Destroying infrastructure via Terraform.

- 1. Browse to https://www.terraform.io/downloads.html to obtain the proper install package for your operating system (OS).
  - a. NOTE: Our datacenters in will only use approved devices to perform Terraform functions. At this time, Mac OS X & Linux (64bit preferred) are approved OS
- 2. Create a Terraform directory on your OS and save the ZIP file in this location
- 3. Terraform runs as a single binary named *terraform*, so we need to make sure that the *terraform* binary is available on the PATH of your OS

4. After you have set the PATH to the terraform location in your OS, open a terminal session and run terraform at the command line to verify installation (should look similar to the example below)

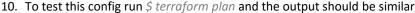


- 5. Next we will need to create our Terraform config file using any plain text editor
- 6. Open your text editor and create a new file named "vSphere.tf" (all terraform files are named \*.tf and they are all loaded when terraform is executed)

7. Use the code example here to build your Terraform config file;

```
~/Desktop/VDM/vSphere_Terra.tf ...
        # Configure the VMware vSphere Provider
   2
        provider "vsphere" {
           user = "${var.vsphere_user}"
password = "${var.vsphere_password}"
   3
          user
   4
           vsphere_server = "${var.vsphere_server}"
   5
           # if you have a self-signed cert
          allow_unverified_ssl = true
   8
   9
  10
        # Create a folder
  11
        resource "vsphere_folder" "HumanityLink" {
  12
          path = "HumanityLink"
  13
  14
  15
  16
        # Create a file
  17
        resource "vsphere_file" "ubuntu_disk_UPload" {
                         = "local"
= "/VDM/my_disks/HumanityLink_ubuntu.vmdk"
  18
          datastore
  19
           source_file
          destination_file = "/MAC_DC/disks/HumanityLink_ubuntu.vmdk"
  20
  21
  22
  23
        # Create a disk image
  24
         resource "vsphere_virtual_disk" "extraStorage" {
  25
          size
                     = 2
           vmdk_path = "myDisk.vmdk"
  26
           datacenter = "MAC Datacenter"
  27
  28
          datastore = "VSAN_MAC"
        }
  29
  30
  31
        # Create a virtual machine within the folder
        resource "vsphere_virtual_machine" "Web01" {
  32
           name = "MAC-HLD-WEB01"
  33
           folder = "${vsphere_folder.HumanityLink.path}"
  34
           vcpu = 8
  35
           memory = 16384
  36
  37
  38
          network_interface {
             label = "VM Network"
  39
  40
  41
           disk {
  42
            template = "centos-7"
  43
  44
        }
  45
```

- 8. This is a complete configuration that Terraform is ready to apply and create a vSphere VM.
- 9. We are also using a config file to hold Variables that Terraform may need
  - a. This file has been loaded in to the vCenterNerd Consulting GitHub acct under the Test-Branch (https://github.com/vCenterNerd/VDM/tree/Test-Branch) and should be copied to your local Terraform directory in your OS



```
VDM - bash - 138x79
          MAC-NHICKEY: VDM mhickey$ terraform plan
    Enter a value:
 var vsphere server
Enter a value: vcsa
Refreshing Terraform state in-memory prior to plan...
The refreshed state will be used to calculate this plan, but will not be persisted to local or remote state storage.
The Terraform execution plan has been generated and is shown below. Resources are shown in alphabetical order for quick scanning. Green resources will be created (or destroyed and then created if an existing resource exists), yellow resources are being changed in-place, and red resources will be destroyed. Cyan entries are data sources to be read.
Note: You didn't specify an "-out" parameter to save this plan, so when 
"apply" is called, Terraform can't guarantee this is what will execute.
         phere_file.ubuntu_disk_0
datastore: "local"
destination_file: "/MAC_DC/disks/MumanityLink_ubuntu.vmdk"
source_file: "/VDM/my_disks/MumanityLink_ubuntu.vmdk"
          existing_path: "<computed>"
path: "HumanityLink"
     vsphere_virtual_disk.extraStorage
adapter_type: "ide"
datacenter: "MAC Datacenter"
datastore: "VSAN_MAC"
size: "2"
type: "eagerZeroedThick"
wadk_nath: "addisk_wadk"
           vedk_path: "ayDisk.vadk
       sphere_virtual_machine.Web01
_detach_unknown_disks_on_deleter
          disk.#:
disk.177764663.bootable:
         disk.177764603.controller_type:
disk.177764603.datastore:
disk.177764603.tops:
disk.177764603.keep_on_remove:
         disk 177764683 keep_on_remove;
disk 177764683 key;
disk 177764683 name;
disk 177764683 size;
disk 177764683 template;
disk 177764683 type;
disk 177764683 uuid;
disk 177764683 vmdk;
                                                                                                                     'vsphere.local"
'false'
          dowain:
enable_disk_uuid:
                                                                                                                     "HumanityLink"
"false"
          linked clone:
                                                                                                                   *<computed**
          network_interface.0.ip_address:
network_interface.0.ipv4_address:
         network interface.8.ipv4_address: "computed" "computed" network interface.8.ipv4_prefix_length: "computed" network interface.8.ipv6_address: "computed" network interface.8.ipv6_ateway: "computed" network interface.8.ipv6_ateway: "computed" network interface.8.ipv6_prefix_length: "computed" network interface.8.label: "WM Network network interface.8.label: "wM Network network interface.8.subnet_mask: "computed" "computed" skip_customization: "false" "Etc/UTC"
                                                                                                                       "Etc/UTC"
 Plan: 4 to add, 0 to change, 0 to destroy.
```

- 11. The last steps are to setup the OAuth settings for GitHub to access Terraform
  - a. Access https://github.com/settings/developers
  - b. Click Register a new application to begin this process
  - c. Follow the steps here with those given in the email you have received from vCenterNerd consulting that includes; Homepage URL, App descriptions, and Authorization Callback URL.
- 12. Setup of Terraform & GitHub integration is complete

- 13. These steps can also be followed for creating a .tf file for adding/changing/editing infrastructure at our AWS or MAC & DNB datacenters. If this was for AWS you would need to obtain the AWS access key and secret key, available from your DC site Admin upon request.
  - a. An AWS terraform config would look similar to this:

```
provider "aws" {
   access_key = "ACCESS_KEY_HERE"
   secret_key = "SECRET_KEY_HERE"
   region = "us-east-1"
}

resource "aws_instance" "example" {
   ami = "ami-2757f631"
   instance_type = "t2.micro"
}
```

b. Saving this code to an *AWS.tf* file and then placing it in your Terraform directory is all that is needed to utilize it.

#### **Changing Infrastructure**

The next steps will be for Changing infrastructure with Terraform. As you change Terraform configurations, Terraform builds an execution plan that only modifies what is necessary to reach your desired state. Preforming changes this way allows for version control of your configurations and also your desired state so you can see how the infrastructure evolved over time.

1. If we use the sample code from Step 13a in the previous section, we will focus on editing the AMI reference to change from an Ubuntu 16.04 LTS AMI to an Ubuntu 16.10 AMI.

```
provider "aws" {
   access_key = "ACCESS_KEY_HERE"
   secret_key = "SECRET_KEY_HERE"
   region = "us-east-1"
}

resource "aws_instance" "example" {
   ami = "ami-2757f631"
   instance_type = "t2.micro"
}
```

2. Next run \$ terraform plan to see the changes that could be applied

a.

a.

- b. The prefix "-/+" means that Terraform will destroy and recreate the resource, versus updating it in-place. While some attributes can do in-place updates (which are shown with a "~" prefix), changing an AMI on EC2 instance requires a new resource altogether.
- 3. The last step here would be to push the changes via \$ terraform apply

a.

#### **Destroying Infrastructure**

The last procedure is to be only used when all datacenter admins have been first notified. These steps are samples, and real production code changes will be managed via GitHub with proper approvals. The purpose here is to demonstrate the simplicity of changing and destroying environment via terraform.

- 1. Destroying sites or infrastructure may be required in extreme situations to satisfy needs during Zombie or Rouge intruders to our datacenters
- 2. Run \$ terraform plan -destroy to see how the plan will work 1st (the "-" indicates removal)

```
$ terraform plan -destroy
# ...
- aws_instance.example
```

a.

3. Run \$\xi\$ terraform destroy to do just that, destroy your infrastructure

```
$ terraform destroy
aws_instance.example: Destroying...
Apply complete! Resources: 0 added, 0 changed, 1 destroyed.
# ...
```

a.

4. The terraform *destroy* command should ask you to verify that you really want to destroy the infrastructure. Terraform only accepts the literal "**yes**" as an answer as a safety mechanism. Once entered, Terraform will go through and destroy the infrastructure.

## 4.2.3 HumanityLink

Since we are leveraging Terraform for infrastructure code, we will also use it for as much application means as we know how to. Terraform Provisioners will be used to execute scripts on the remote instances we create in our datacenters. The examples below are referencing AWS resources, but can also be used to run scripts in out vSphere environments also.

#### Installing HL on an AWS instance:

- 1. Create a new .tf file called "HL.tf" can save it to the Terraform directory used in previous steps
- 2. Edit the new HL.tf file to include the below code snipet:

```
VCenterNerd Add files via upload
1 contributor
18 lines (16 sloc) | 454 Bytes
   # This file is used to Upload HumanityLink install script and then execute script
  3 resource "aws_instance" "App" {
       # ...
  5 # Upload HumanityLink install script
      provisioner "file" {
        source = "Install_HL.sh"
  8
         destination = "/tmp/HL/Install_HL.sh"
  9 }
 10 # Execute HumanityLink install script on remote instance
      provisioner "remote-exec" {
        inline = [
          "chmod +x /tmp/HL/Install_HL.sh",
 14
           "/tmp/HL/Install_HL.sh args",
        ]
 16
      }
 17 }
```

The code saved in this file should be added to your main terraform config that deploys infrastructure so that once the instance is stood up, the scripts you wish to run will kick off after terraform has built the instance(s). a. Example of this Provisioner within a full AWS terraform config file:

```
Name of the second content of the second con
1 contributor
23 lines (22 sloc) | 544 Bytes
            provider "aws" {
          2 access_key = "ACCESS_KEY_HERE"
          3 secret_key = "ACCESS_KEY_HERE"
                             region = "eu-west-1"
          5 }
         6 resource "aws_instance" "App" {
         7 ami = "ami-2757f631"
         8 instance_type = "t2.micro"
       10 # ...
       # Upload HumanityLink install script
       12 provisioner "file" {
                         source = "Install_HL.sh"
       13
       14
                               destination = "/tmp/HL/Install_HL.sh"
       15 }
       16 # Execute HumanityLink install script on remote instance
                     provisioner "remote-exec" {
                     inline = [
       18
                                   "chmod +x /tmp/HL/Install_HL.sh",
       19
                                        "/tmp/HL/Install_HL.sh args",
       20
                              ]
                         }
       23 }
```

#### 5 REFERENCES

#### Version-Controlled Infrastructure with GitHub & Terraform

https://www.hashicorp.com/blog/version-controlled-infrastructure-with-github-and-terraform/

#### **Terraform Install**

https://www.terraform.io/intro/getting-started/install.html

### **Terraform Providers (AWS & vSphere)**

https://www.terraform.io/docs/providers/aws/index.html https://www.terraform.io/docs/providers/vsphere/index.html

#### Managing GitHub with Terraform

https://www.hashicorp.com/blog/managing-github-with-terraform/

#### Cobbler Manual - Version 2.8.x

http://cobbler.github.io/manuals/2.8.0/

#### Using Cobbler to Rapidly Deploy ESXi With Zero Touch Configuration

http://www.nerdknobs.net/using-cobbler-to-rapidly-deploy-esxi-with-zero-touch-configuration-2/

#### **Dronecode**

https://www.dronecode.org/documentation/

#### **PX4 Autopilot User Guide**

https://docs.px4.io/en/

## **QGroundControl User Guide**

https://www.gitbook.com/book/donlakeflyer/qgroundcontrol-user-guide/details

## vCenterNerd GitHub

https://github.com/vCenterNerd