

Batch - 3.

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Subject AI IOT Lab. (Batch - 3).

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① Age program:

```
age = int(input("Enter age: "))
```

($\text{age} = \text{int}(\text{input}(\text{"Enter age: "}))$) (convert string to int) + if - word
(Age) (marks) square plus sign
if age <= 12:
 → print("child")
elif age > 12 and age <= 17:
 → print("Teenager")
elif age > 18 and age < 65:
 print("Adults")
else:
 print("Older Adults")

Output:

Enter the age : 12
child.

② Multiplication table:

```
num = int(input("Enter no.: "))  
for i in range(1, 11, 1)  
    print(num, "*", i, "=", num * i)
```

Output:

Enter no.: 2

$2 * 1 = 2$
 $2 * 2 = 4$
 $2 * 3 = 6$
 $2 * 4 = 8$
 $2 * 5 = 10$
 $2 * 6 = 12$
 $2 * 7 = 14$
 $2 * 8 = 16$
 $2 * 9 = 18$
 $2 * 10 = 20$

③ Pattern 1: (2, 22, 333, ...)

```
num = int(input("Enter no: "))

for x in range(num)
    n = x + 1
    for y in range(x + 1)
        print(n, end = " ")
    print("\n")
```

Output:

```
1
2 2
3 3 3
```

④ Pattern 2 (1, 12, 123, ...)

```
num = int(input("Enter no: "))

for x in range(num)
    n = 1
    for y in range(x + 1)
        print(n, end = " ")
        n = n + 1
    print("\n")
```

Output:

```
1
1 2
1 2 3
```

⑤ Integer reversal:

```
num = int(input("Enter the int: "))

new = 0

while(num > 0)
    numrev = numrev + num % 10
    num = num // 10

print(new)
```

Ans/
12121

Tic Tac Toe game :

17/12/2023

import math

list = [[1, 2, 3], [4, 5, 6], [7, 8, 9]]

c = 0

def create_board(list):
 print("n n n")

for i in range(3):

for j in range(3):

print(" " + list[i][j], " ", end="|")

def check_winner(list):

for i in range(2):

if (list[i][0] == list[i][1] and list[i][1] == list[i][2]):
 return True

elif (list[0][i] == list[1][i] and list[1][i] == list[2][i]):
 return True

x = list[0][0]

y = list[0][2]

count = 0

count1 = 0

for i in range(3):

for j in range(3):

if (i == j and list[i][j] == x):

count += 1

if (i+j == 2 and list[1][i] == x):

count1 += 1

def play(r, c):

r = r/3

c = (c % 3)

if (list[r][c] == 'x' or list[r][c] == 'o'):

print("Player", r, c, "is free")

c = c - 1

else:

list[r][c] = 'x'

1	2	3
4	5	6
7	8	9

while(1):

 create_board(list)

 print("Player", cy, "x", "chance to play 1")

 print("Enter pos ")

 n = int(input())

 play(n, cy, 2 + 1)

1 swap set up

Max

WV

1 (final) board with W

(W, W, W) 4 W

1 (E) square at 3rd

1 (E) square at 6th

1 (E) friend

8 puzzle problem using BFS

1	2	3
4	5	6
7	8	-

1	2	3
4	5	6
7	8	-

S (no left moves at moment)

right move

up move

down move

level 0

1	2	3
4	5	6
7	8	-

-	2	3	1
1	4	6	-
7	5	8	-

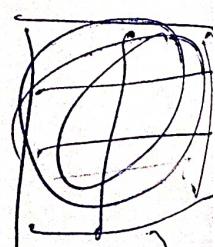
1	2	3
7	4	6
-	5	8

1	-	3
4	2	6
7	5	8

1	2	3
4	5	6
7	-	8

1	2	3
4	6	-
7	5	8

1	2	3
4	5	6
7	8	-



R

level 1

1	2	3
4	5	6
7	8	-

24/11/11

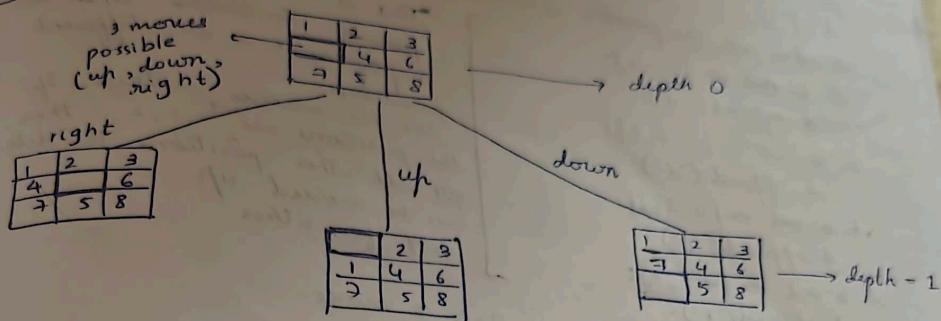
first search
)- Uninformed approach

columns)
state) will be
ivation.

the single

depth factor - initially will be 0
As we explore the nodes, the depth factor increases
Every time, we check the possible moves
to branch at, pose consider all possible cases and finally

For example:



Will continue branching these nodes.
Since this is breadth first search, branch for possibilities of 'right' node, then 'up' node, then 'down' node and then only move to branch in the next level.

Code:

```
import numpy as np
import pandas as pd
import os
```

```
def bfs(src, target):
    queue = []
    queue.append(src)
    exp = []
```

```
    while len(queue) > 0:
        source = queue.pop(0)
```

```
        exp.append(source)
```

```
        print(source)
```

```
        if source == target:
            print("success")
```

```
            return
```

```
poss_moves_to_do = []
```

```
poss_moves_to_do = possible_moves(source, exp)
```

```
for move in poss_moves_to_do:
```

```
    if move not in exp and move not in queue:
```

```
        queue.append(move)
```

Same BFS code

```
def possible_moves(state, b, m, d):
```

index of empty spot

b = state.index(0)

directions array

d = []

add all the possible directions

if b is not in [0,1,2]:

d.append('u')

if b not in [6,7,8]:

d.append('d')

if b not in [0,3,6]:

d.append('l')

if b not in [2,5,8]:

d.append('r')

if direction is possible, add state to move

pos_moves_it_can = []

for all possible directions, find the state if that move is played by calling 'gen' function

for i in d:

Now for each direction, I want to generate

pos_moves_it_can.append(gen(state, i, b)) different states of the matrix which is append in pos-moves

return [move_it_can for move_it_can in pos_moves_it_can if move_it_can not in visited_states]

- here, once I get a state which is not in visited-states, I return

```
def gen(state, m, b):
```

temp = state.copy()

if m == 'd':

temp[b+3], temp[b] = temp[b], temp[b+3]

elif m == 'u':

temp[b-3], temp[b] = temp[b], temp[b-3]

elif m == 'l':

temp[b-1], temp[b] = temp[b], temp[b-1]

elif m == 'r':

temp[b+1], temp[b] = temp[b], temp[b+1]

return temp

src = [1, 2, 3, 4, 5, 6, 0, 7, 8]

target = [1, 2, 3, 4, 5, 6, 7, 8, 0]

bfs(src, target).

0	1	2
3	0	5
6	7	8

This is ~~base~~ to find possible directions when empty node is at different positions.

see the above matrix. If the positions are ~~not~~ 0, 1, 2, then for all other positions, the tile can be moved up, similarly for others.

(0,2) down, down

To move down, I shift 3 indices front.

If I am at position 5, and I want to move down, I do 5+3 = 8.

(0,1) down, down

(0,0) down, down

(1,1) down, down

(1,0) down, down

(0,0) down, down

Output

[1, 2, 3, 4, 5, 6, 0, 7, 8]

[1, 2, 3, 0, 5, 6, 4, 7, 8]

[1, 2, 3, 4, 5, 6, 7, 0, 8]

[1, 2, 3, 1, 5, 6, 4, 7, 8]

[0, 2, 3, 5, 0, 6, 4, 7, 8]

[1, 2, 3, 0, 6, 7, 5, 8]

[1, 2, 3, 4, 0, 6, 7, 8, 0]

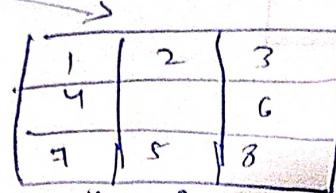
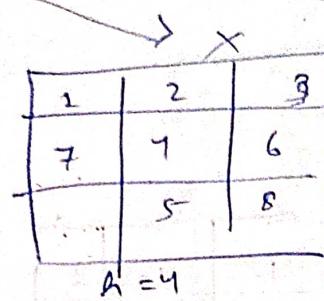
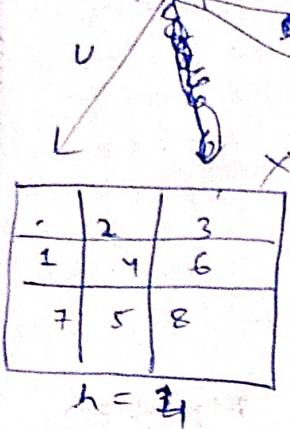
[1, 2, 3, 4, 5, 6, 7, 8, 0]

~~cess~~ - n

1	2	3
4	6	
7	5	8

1	2	3
4	5	c
7	8	

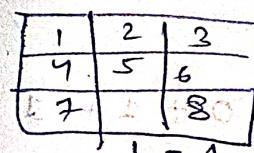
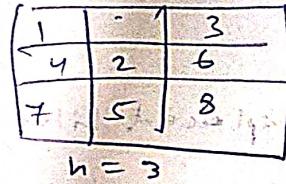
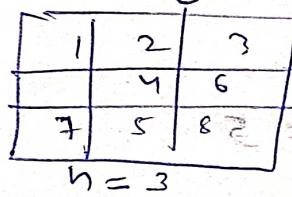
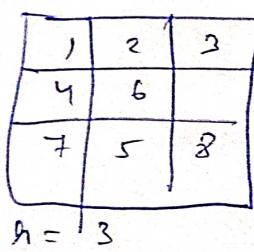
characteristic value
 $(h) = \infty$
 = no. of misplaced tiles
 based on goal state
 $= 3$



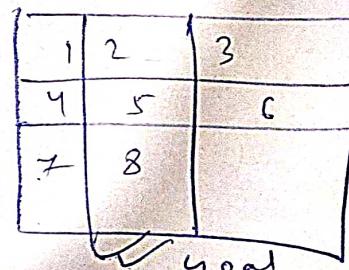
$h = 2$
 (minimum value)

\Rightarrow calculate heuristic values based on min value

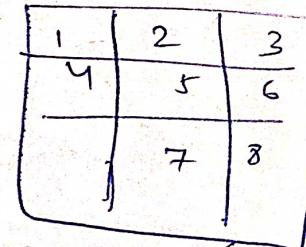
h , explore that node



$h = 1$
 (minimum)



goal state (h)



Goal state

Intelligent Agents

code:

class Node:

```
def __init__(self, data, level, fval):
    self.data = data
    self.level = level
    self.fval = fval
```

def generate_child(self):

```
y = self.find(self.data, '-')

val_list = [[x, y - 1], [x, y + 1], [x - 1, y], [x + 1, y]]

children = []

for i in val_list:
    child = self.shuffle(self.data, x, y, i[0], i[1])

    if i is not None:
        child_node = Node(child, self.level + 1, 0)

    children.append(child_node)

return children
```

def shuffle(self, puz, x1, y1, x2, y2):

if x2 >= 0 & x2 < len(self.data) and y2 >= 0

```
temp_puz = []
temp_puz = self.copy(puz)
temp_puz[x2][y2] = self.data[x1][y1]
return temp_puz
```

else:

return None

def process(self):

print("Enter the start state matrix " "n")

start = self.accept()

print("Enter goal state matrix " "n")

goal = self.accept()

self.open()

self.open.append(start)

W
STW

Output:

Enter start state matrix

$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ - & 7 & 8 \end{matrix}$$

Enter goal state matrix

$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & - \end{matrix}$$

↓
Enter aij, bi and ej and ej

$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ - & 7 & 8 \end{matrix}$$

↓
Enter aij, bi and ej and ej

$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & - & 8 \end{matrix}$$

↓

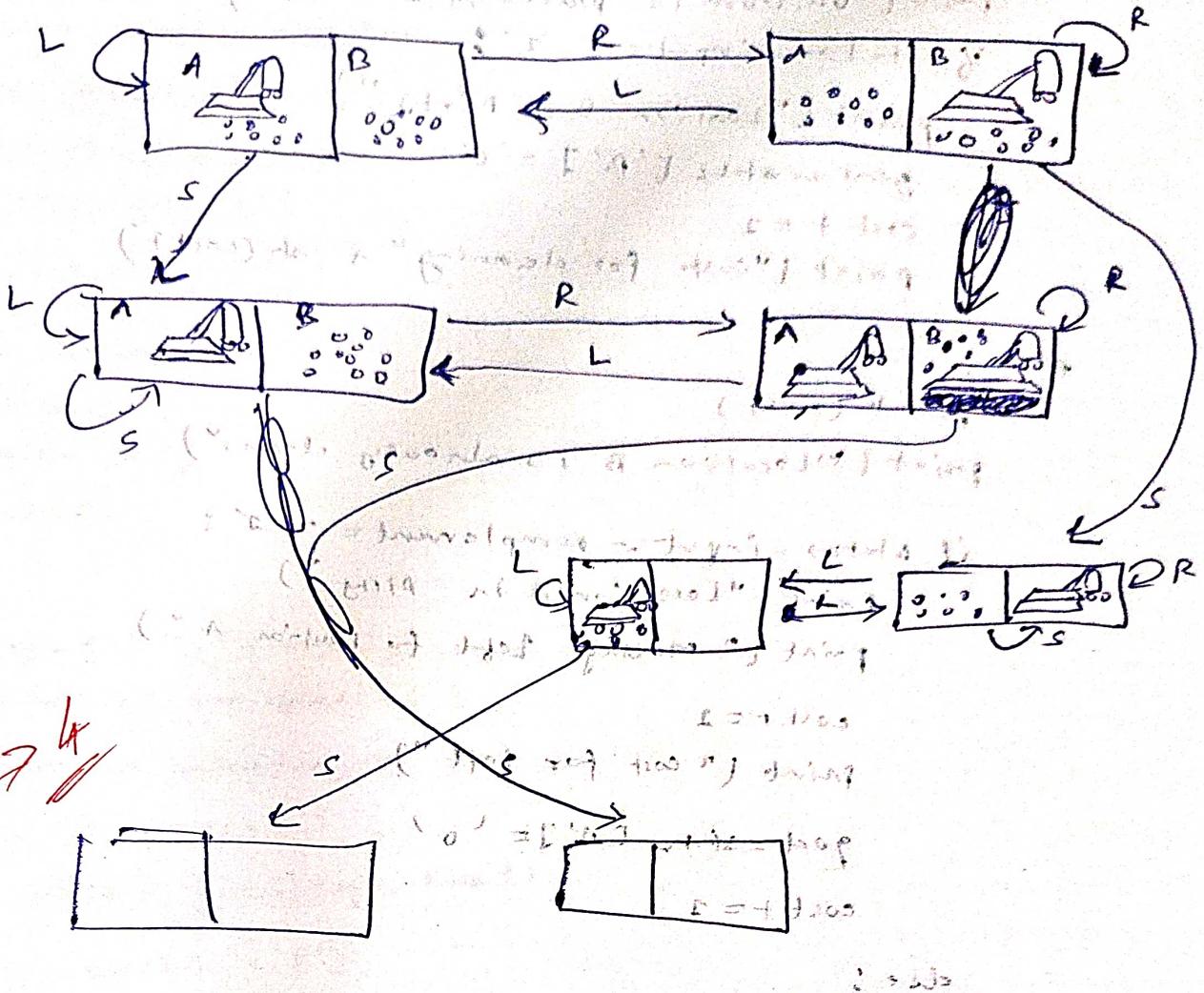
$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & - \end{matrix}$$

$$\begin{matrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & - \end{matrix}$$

Vacuum cleaner program:

2×2^2 states = 8 states.

Actions: $\rightarrow L, R, Suck$.



Proceed

Code:

```

def vacuum_world():
    goal_state = {'A': '0', 'B': '0'} # initial state
    cost = 0
    location_input = input("Enter loc of vacuum: ")
    status_input = input("Enter status of " + location_input)
    status_input_complement = input("Enter status of other room")
    print("Initial location condition: " + str(goal_state))
    if location_input == 'A':
        print("vacuum is placed on location A")
        if status_input == '1':
            print("Location A is dirty")
            goal_state['A'] = '0'
            cost += 1
            print("cost for A")
    
```

else: print("Vacuum is placed in loc B")

if status-input = 2 "2"

print("Location B is Dirty")

goal-state["B"] = "0"

costt = 1

print("cost for cleaning" + str(cost))

else:

print(cost)

print("Location B is already clean")

if status-input = complement = 2 "2"

if status-input = 1 "1"

print("Location A is dirty")

print("Moving left to location A")

costt = 1

print("cost for left")

goal-state["A"] = "0"

costt = 1

else:

print("No action" + str(cost))

(1) known environment

print("Goal state is")

print(goal-state)

vacuum-world(1) world-number) step 1 = single iteration

(step 2 = next-step + "to world number") the grid = the grid contains

output of 3 worlds number) step 3 = third world number output

(4 enter location of vacuum D

Enter status of 0 (worlds numbered location) being

Enter status of other room 1

Initial location condition { 1, 0, 0, 0, 0, 0 } (worlds numbered) being

Performance

measuring

1/2 = 1/2 / 1/2 = 1/2

1/2 = 1/2 / 1/2 = 1/2

C = f(x)

b) Knowledge-Based Entailment:

(29/12/23)

from sympy import symbols

def create_knowledge_base():

p = symbols('p')

q = symbols('q')

r = symbols('r')

knowledge_base_and =

implied(p, r)

implies(q, r)

not(r)

)

def query_entails(knowledge_base_query):

entailment = satisfiable()

return not entailment

if __name__ == "__main__":

kb = create_knowledge_base()

query = symbols('p')

print("Query:", query)

print("Query entails knowledge base", result)

def tell(kb, rule):

kb.append(rule)

combinations = [(T, T, T), (T, T, F), (T, F, T), (T, F, F), (F, T, T),
(F, T, F), (F, F, T), (F, F, F)]

def ask(kb, q):

for c in combinations:

s = all(rule(c)) for rule in kb

f = q(c)

print(c, f)

if s != f & s != False

return "does not entail"

entails().

output:

(satisfy)

Entails (satisfy)

knowledge base: implies($p, w \wedge q, r$)

query = p

query entails knowledge base : False

8) KB Resolution:

```
def tell(kb, rule):  
    kb.append(rule)
```

combinations = [(T, T, T, S), (T, T, F), (T, F, T),
(T, F, F), (F, T, T), (F, T, F)]

```
def ask(kb, q):  
    for c in combinations:
```

s = all(mvc(c) for rule in kb)

f = q(c)

print(s, f)

kb = []

rule-str = input("Enter rule 1 as lambda func: ")

r1 = eval(rule-str)

tell(kb, r1)

query-str = input("Enter query as lambda: ")

q = eval(query-str)

result = ask(kb, q)

print(result)

Output:

Base: (q, +)

No entailed.

Sneha
29/12/23

25/12/23

8) FOL to CNF:

Create a list of all common constraints.

import re

def fol_to_cnf(fol):

statement = fol.replace("=>", "—")

while '—' in statement:

i = statement.index('—')

new_statement = '[' + statement[:i] + '=>' + statement[i+1:] + ']' & '[' +

statement = statement.replace("=>", '—')

expr = 'I [(& A)] +) \]'

statements = nc.find_all(expr, statement)

for i in enumerate(statements):

If '[' in s & ']' not in s:

statements[i] = ']'

for s in statements:

statement = st.replace(s, fol_to_cnf(s))

while '—' in statements:

i = statement.index('—')

br = (t) if 't' in brms

Output:

[romantic(y) | loves(x,y)] & [~loves(z,y) | animal(z)]
[animal(g(y)) & whores(x,y(x))] | [loves(F(u),u)]

Explanation:

$\forall x \text{ king}(x) \wedge \text{greedy}(x) \Rightarrow \text{will}(x)$

king(Richard) \wedge greedy(Richard) \Rightarrow will(Richard)

$A \Rightarrow B$

\hookrightarrow replaced with $(A \Rightarrow B) \wedge (\neg B \Rightarrow A)$

Disha
1/2/24

Q) unification:

def unify(x, y, bindings = [])

if bindings is None:

return None

elif x == y:

return bindings

elif isinstance(x, str) and x.startswith('['):

return unify_var(x, y, bindings)

elif isinstance(x, str) and instance(y, list):

return unify_var(x, y, bindings)

elif isinstance(x, str) and isinstance(y, str):

bindings = unify(x, y, bindings)

else:

return None

def unify_var(var, x, bindings):

if var in bindings:

return unify(bindings[var], x)

elif x in bindings:

return unify(bindings[x], var)

else:

new_bindings = bindings.copy()

new_bindings[var] = x

return new_bindings

Output:

[('A', 'y'), ('mother(f)', 'x')]

Done
19/1/24

Forward Chaining

27.

class Fact:

def __init__(self, expression):

self.expression = expression

self.predicate, params = self.splitExpression(expression)

self.predicate = predicate

self.params = params

self.result = any(self.getConstants())

def splitExpression(self, expression):

predicate = getPredicate(expression)[0]

params = getAttributes(expression)[0].strip('()').split(',')

return [predicate, params]

def getResult(self):

return self.result

def getConstants(self):

return [None if isVariable(c) else c for c in self.params]

def getVariables(self):

return [v if isVariable(v) else None for v in self.params]

def substitute(self, constants):

c = constants.copy()

f = f.replace(self.predicate, (' ' + join([constants.pop(0) if
isVariable(p) else p for p in self.params])))

return Fact(f)

Class Implication:

def __init__(self, expression):

self.expression = expression

l = expression.split('=>')

self.lhs = [Fact(f) for f in l[0].split('&')]

self.rhs = Fact(l[1])

```

def evaluate(self, facts):
    constants = []
    new_rhs = []
    for fact in facts:
        for val in self.lhs:
            if val.predicate == fact.predicate:
                for i, v in enumerate(val, getVariables):
                    if v in constants[v] == fact.getConstants():
                        new_rhs.append(fact)
    predicate_attributes = getPredicates(self.rhs.expression)[0]
    str(getAttribute(self.rhs.expression)[0])
    for key in constants:
        if constants[key]:
            attributes = attributes.replace(key, constants[key])
    expr = f'{predicate} {attributes}'
    return Fact(expr) if len(new_rhs) and all([f.getResult() for f in new_rhs]) else None

```

Class KB:

```

def __init__(self):
    self.facts = set()
    self.implications = set()

def tell(self, e):
    if e in self:
        self.implications.add(Implication(e))
    else:
        self.facts.add(Fact(e))

for i in self.implications:
    res = i.evaluate(self.facts)
    if res:
        self.facts.add(res)

def query(self, e):

```

$\text{facts} = \text{set}([\text{f-expression for } f \text{ in self-facts}])$

29

$\text{print}(f' \text{Querying } \{c\};')$

for f in facts:

if $\text{Fact}(f). \text{predicate} = \text{Fact}(e). \text{predicate}$:

$\text{print}(f' \backslash t\{1y . \{f\}\})$

$i + = 1$

def display(sclj):

$\text{print}("All \text{ facts}:")$

for i, f in enumerate($\text{set}([\text{f-expression for } f \text{ in self-facts}])$):

$\text{print}(f' \backslash t\{i+1\}. \{f\})$

$\text{kb} = \text{KB}()$

$\text{kb.tell}(\text{'missile}(x) \Rightarrow \text{weapon}(x))$

$\text{kb.tell}(\text{'missile}(M1))$

$\text{kb.tell}(\text{'enemy}(x, America) \Rightarrow \text{hostile}(x))$

$\text{kb.tell}(\text{'american}(west))$

$\text{kb.tell}(\text{'enemy}(Nono, America))$

$\text{kb.tell}(\text{'owns}(Nono, M1))$

$\text{kb.tell}(\text{'missile}(x) \& \text{owns}(Nono, x) \Rightarrow \text{self}(west, x, Nonon))$

$\text{kb.tell}(\text{'missile}(x) \& \text{owns}(Nono, x) \Rightarrow \text{cells}(x, y, z) \&$

$\text{kb.tell}(\text{'american}(x) \& \text{weapon}(y) \& \text{cells}(x, y, z) \&$

$\text{hostile}(z) \Rightarrow \text{criminal}(x))$

$\text{kb.query}(\text{'criminal}(x))$

$\text{kb.display}()$

Output:

Querying criminal(x):

1) criminal(west)

All facts:

1. american(west)
2. sells(west, M1, Nonon)
3. Missile(M1)
4. enemy(Nono, America)
5. criminal(west)
6. weapon(M1)
7. owns(Nono, M1)
8. hostile(Nono).

Forward chaining:

Starts with the base state and uses the inference rules and available knowledge in the forward direction till it reaches the end state. The process is iterated till the final state is reached.

$A \wedge B \Rightarrow C$

A

B

Query: C