

## 习题 5-1

(1)

$$\begin{aligned}
 d^2x(t) &= d(dx(t)) \\
 &\approx d(x(t + \Delta t) - x(t)) \\
 &\approx x(t + \Delta t) - x(t) - (x(t) - x(t - \Delta t)) \\
 &= x(t + \Delta) + x(t - \Delta t) - 2x(t) \\
 &\approx x(t + 1) + x(t - 1) - 2x(t)
 \end{aligned}$$

(2)

$$\begin{aligned}
 \nabla^2 f(x, y) &= d_x^2 f(x, y) + d_y^2 f(x, y) \\
 &\approx f(x + 1, y) + f(x - 1, y) - 2f(x, y) \\
 &\quad + f(x, y + 1) + f(x, y - 1) - 2f(x, y)
 \end{aligned}$$

so,

$$w = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

## 习题 5-3

Efficiently change the dimensions of feature.

Ref: [What does 1x1 convolution mean in a neural network?](#)

## 习题 5-4

### (1) 3x3

time complexity:

$$\begin{aligned} & (100 * 100) * (3 * 3) * 256 * 256 \\ & = 5.89824e9 \end{aligned}$$

space complexity:

$$\begin{aligned} & 100 * 100 * 256 \\ & + (3 * 3) * 256 * 256 \\ & + 100 * 100 * 256 \\ & = 2560000 + 589824 + 2560000 \\ & = 5.709824e6 \end{aligned}$$

### (2) 1x1 then 3x3

time complexity:

$$\begin{aligned} & (100 * 100) * (1 * 1) * 256 * 64 \\ & + (100 * 100) * (3 * 3) * 64 * 256 \\ & = 1.6384e9 \end{aligned}$$

space complexity:

$$\begin{aligned} & (100 * 100) * 256 \\ & + (1 * 1) * 256 * 64 \\ & + (100 * 100) * 64 \\ & + (3 * 3) * 64 * 256 \\ & = 3.36384e6 \end{aligned}$$

## 习题 5-5

let

$$x = \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix}$$

$$w = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{bmatrix}$$

$$x' = [x_{11}, x_{12}, x_{13}, x_{21}, x_{22}, x_{23}, x_{31}, x_{32}, x_{33}]^T$$

then,

$$z = w \otimes x$$

$$= \begin{bmatrix} w_{11} & x_{12} & 0 & w_{21} & w_{22} & 0 & 0 & 0 & 0 \\ 0 & w_{11} & x_{12} & 0 & w_{21} & w_{22} & 0 & 0 & 0 \\ 0 & 0 & 0 & w_{11} & x_{12} & 0 & w_{21} & w_{22} & 0 \\ 0 & 0 & 0 & 0 & w_{11} & x_{12} & 0 & w_{21} & w_{22} \end{bmatrix} x'$$

$$= Cx'$$

## 习题 5-6

(1)

let

$$x = [x_1, \dots, x_D]^T$$

$$x_m = \max(x)$$

then,

$$\frac{\partial y}{\partial x} = \frac{\partial x_m}{\partial x}$$

$$= [0, \dots, 1, \dots, 0]^T$$

(2)

This post gives some discussion: [argmax differentiable?](#)