

Worksheet 10

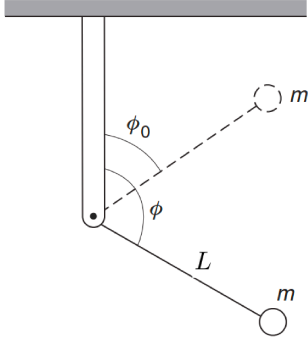
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Classical Mechanics II

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Problem 5.1



A pendulum consists of a light rigid rod of length L pivoted at one end with mass m attached at the other end. The pendulum is released from rest at angle φ_0 .

Obtain the speed of the mass m when the rod is at an angle φ from work-energy theorem.

Solution

Position vector of the mass:

$$\mathbf{r}(t) = L \sin \varphi(t) \hat{e}_y + L \cos \varphi(t) \hat{e}_z \Rightarrow d\mathbf{r} = L \cos \varphi(t) d\varphi \hat{e}_y - L \sin \varphi(t) d\varphi \hat{e}_z$$

Forces acting on the mass:

$$\mathbf{F}(t) = \mathbf{W}(t) + \mathbf{N}(t) = -mg\hat{e}_z - [N(t) \sin \varphi(t) \hat{e}_y + N(t) \cos \varphi(t) \hat{e}_z]$$

Work done by all forces:

$$\begin{aligned} W(\mathbf{r}(0) \rightarrow \mathbf{r}(t)) &= \int_{\mathbf{r}(0)}^{\mathbf{r}(t)} \mathbf{F}(t) \cdot d\mathbf{r} = \int_{\mathbf{r}(0)}^{\mathbf{r}(t)} \mathbf{W}(t) \cdot d\mathbf{r} + \int_{\mathbf{r}(0)}^{\mathbf{r}(t)} \mathbf{N}(t) \cdot d\mathbf{r} \\ &= \int_{\varphi(0)}^{\varphi(t)} -mgL \sin \varphi(t) d\varphi = mgL[\cos \varphi(0) - \cos \varphi(t)] \end{aligned}$$

Note

The constraint force $\mathbf{N}(t)$ is always perpendicular to the displacement, so:

$$\int_{\mathbf{r}(0)}^{\mathbf{r}(t)} \mathbf{N}(t) \cdot d\mathbf{r} = 0$$

Applying work-energy theorem:

$$\begin{aligned} T(t) - T(0) &= W(\mathbf{r}(0) \rightarrow \mathbf{r}(t)) \Rightarrow \frac{m}{2}v^2(t) - \frac{m}{2}v^2(0) = mgL[\cos \varphi(0) - \cos \varphi(t)] \\ \Rightarrow v(t) &= \sqrt{2gL[\cos \varphi(0) - \cos \varphi(t)] + v^2(0)} \end{aligned}$$

$$v(t) = \sqrt{2gL[\cos \varphi_0 - \cos \varphi(t)]}$$

Problem 5.2

Gravitational force acting on a mass m at a distance r from the center of Earth of mass M :

$$\mathbf{F}(\mathbf{r}) = -\frac{GMm}{r^2}\hat{\mathbf{e}}_r$$

Mass m is projected from the surface of the Earth $r = R_e$ with an initial speed v_0 at an angle α from the vertical.

Escape speed for the mass m to escape Earth's gravitational field is independent of the launching direction:

$$v_{\text{escape}} = \sqrt{2gR_e}$$

Obtain the expression for the escape speed from work-energy theorem. Assume gravitational force is the only force and ignore the rotation of the Earth.

Solution

Gravitational force and displacement:

$$\mathbf{F}(\mathbf{r}) = -\frac{GMm}{r^2}\hat{\mathbf{e}}_r$$

$$d\mathbf{r} = dr\hat{\mathbf{e}}_r + r d\theta\hat{\mathbf{e}}_\theta + r \sin\theta d\varphi\hat{\mathbf{e}}_\varphi$$

Work done by gravitational force:

$$\begin{aligned} W(\mathbf{r}_1 \rightarrow \mathbf{r}_2) &= \int_{r_1}^{r_2} \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = - \int_{r_1}^{r_2} \frac{GMm}{r^2} dr \\ &= -GMm \int_{r_1}^{r_2} \frac{1}{r^2} dr = -GMm \left[-\frac{1}{r} \right]_{r_1}^{r_2} \\ &= GMm \left[\frac{1}{r_2} - \frac{1}{r_1} \right] = GMm \left[\frac{1}{r(t)} - \frac{1}{r(0)} \right] \end{aligned}$$

Applying work-energy theorem:

$$\begin{aligned} T(t) - T(0) &= W(\mathbf{r}_0 \rightarrow \mathbf{r}) \Rightarrow \frac{m}{2}v^2(t) - \frac{m}{2}v^2(0) = GMm \left[\frac{1}{r(t)} - \frac{1}{r(0)} \right] \\ \Rightarrow v^2(0) &= v^2(t) - 2GM \left[\frac{1}{r(t)} - \frac{1}{r(0)} \right] \end{aligned}$$

For escape condition:

$$\begin{cases} r(t) \rightarrow \infty \\ v(t) = 0 \end{cases} \Rightarrow v^2(0) = \frac{2GM}{R_e}$$

Since $GM = gR_e^2$ at Earth's surface:

$$v^2(0) = \frac{2gR_e^2}{R_e} = 2gR_e$$

$$v_{\text{escape}} = \sqrt{2gR_e}$$

Problem 5.3

A point mass of mass m is attached at the end of the massless string of length L . It is released from $\theta = \theta_0$ with $\dot{\theta} = 0$ at $t = 0$.

Obtain the first-order differential equation for $\theta(t)$ governing the dynamics of the point mass. Assuming small angles, $\theta_0 \ll 1$, solve for $\theta(t)$.

Solution

Position and velocity vectors:

$$\begin{aligned}\mathbf{r}(t) &= L \sin \theta(t) \hat{e}_y + L \cos \theta(t) \hat{e}_z, & \mathbf{W}(t) &= mg \hat{e}_z \\ \dot{\mathbf{r}}(t) &= L \dot{\theta}(t) \cos \theta(t) \hat{e}_y - L \dot{\theta}(t) \sin \theta(t) \hat{e}_z\end{aligned}$$

Kinetic energy:

$$\Rightarrow T(t) = \frac{m}{2} \dot{\mathbf{r}}(t) \cdot \dot{\mathbf{r}}(t) = \frac{1}{2} m L^2 \dot{\theta}^2(t)$$

Forces acting on the mass:

$$\mathbf{F}(t) = \mathbf{W}(t) + \mathbf{N}(t) = mg \hat{e}_z + N(t) [-\sin \theta(t) \hat{e}_y - \cos \theta(t) \hat{e}_z]$$

Work done by all forces:

$$W(\mathbf{r}(0) \rightarrow \mathbf{r}(t)) = \int_{\mathbf{r}(0)}^{\mathbf{r}(t)} \mathbf{F}(t) \cdot d\mathbf{r} = - \int_{\theta(0)}^{\theta(t)} mgL \sin \theta(t) d\theta$$

Work-energy theorem:

$$T(t) - T(0) = W(\mathbf{r}(0) \rightarrow \mathbf{r}(t))$$

$$\Rightarrow \frac{1}{2} m L^2 \dot{\theta}^2(t) - \frac{1}{2} m L^2 \dot{\theta}^2(0) = mgL [\cos \theta(t) - \cos \theta(0)]$$

$$\Rightarrow \frac{1}{2} L \dot{\theta}^2(t) = g \cos \theta(t) - g \cos \theta_0$$

$$\Rightarrow \frac{d\theta}{dt} = -\sqrt{2 \frac{g}{L} [\cos \theta(t) - \cos \theta_0]}$$

$$\Rightarrow \sqrt{2 \frac{g}{L}} \int_{\theta_0}^{\theta(t)} dt = - \int_{\theta_0}^{\theta(t)} \frac{d\theta}{\sqrt{\cos \theta - \cos \theta_0}}$$

$$\Rightarrow \sqrt{2 \frac{g}{L}} \int_0^t dt = -\sqrt{2} \int_{\theta_0}^{\theta(t)} \frac{d\theta}{\sqrt{\theta_0^2 - \theta^2}} \quad \left[\because \cos \theta \approx 1 - \frac{\theta^2}{2} \right]$$

$$\Rightarrow \sqrt{\frac{g}{L}} \int_0^t dt = - \int_{\theta_0}^{\theta(t)} \left(\sqrt{1 - \frac{\theta^2}{\theta_0^2}} \right)^{-1} d\left(\frac{\theta}{\theta_0} \right)$$

$$\Rightarrow \sqrt{\frac{g}{L}} t = -\sin^{-1} \left(\frac{\theta(t)}{\theta_0} \right) + \frac{\pi}{2}$$

$$\theta(t) = \theta_0 \cos \left(\sqrt{\frac{g}{L}} t \right)$$