

Date: 21-02-2020 ; Time : 08:00-08:50 am ; Quiz - I (20 Marks) ; MA6270

- Q1. Using Crank-Nicolson F-D scheme, find $U(x, 0.1)$ for $x = 0, \frac{1}{3}$ and $\frac{2}{3}$ when $U(x, t)$ satisfies

$$\frac{\partial U}{\partial t} = \frac{1}{3} \frac{\partial^2 U}{\partial x^2}, 0 < x < 1; \frac{\partial U}{\partial x}(0, t) = U(0, t); U(1, t) = 0, t > 0;$$

$$U(x, 0) = 18x(1 - x), 0 \leq x \leq 1 \quad (8 \text{ M})$$

(Use forward difference formula for derivative boundary condition)

- Q2. Derive the stability condition of the explicit F-D scheme when applied to $\frac{\partial U}{\partial t} = \frac{1}{3} \frac{\partial^2 U}{\partial x^2}$, $0 < x < 1$ with $\Delta x = h, \Delta t = k$ and $r = \frac{k}{h^2}$, given that $U(x, t)$ is known at $t = 0$ and on $x = 0$ and $x = 1$ for $t > 0$. (Use matrix method) (6M)

- Q3. Derive the local truncation error $T_{i,j}$ when fully implicit backward time scheme is applied to $\frac{\partial U}{\partial t} = \frac{1}{2} \frac{\partial^2 U}{\partial x^2}$, $0 < x < 1$ with known initial and boundary values for $U(x, t)$. (6M)

Handwritten solution for Q3:

$$(2+2r) \frac{\partial^2 U}{\partial t^2} + (2-2r) \frac{\partial^2 U}{\partial t^2} = \frac{k^2}{6} \frac{\partial U}{\partial t} \left(\frac{\partial^2 U}{\partial t^2} - \frac{1}{2} \frac{\partial^4 U}{\partial t^2 \partial x^2} \right) - \frac{k^2}{6} \frac{\partial^5 U}{\partial t^3} - \frac{1}{2} \frac{k^2}{6} \frac{\partial^4 U}{\partial t^2 \partial x^2}$$

$$= \frac{k^2}{6} \frac{\partial U}{\partial t} \left(\frac{\partial^2 U}{\partial t^2} - \frac{1}{2} \frac{\partial^4 U}{\partial t^2 \partial x^2} \right) - \frac{k^2}{6} \frac{\partial^5 U}{\partial t^3} - \frac{1}{2} \frac{k^2}{6} \frac{\partial^4 U}{\partial t^2 \partial x^2}$$

$$\frac{\partial U}{\partial t} \left(\frac{\partial^2 U}{\partial t^2} - \frac{1}{2} \frac{\partial^4 U}{\partial t^2 \partial x^2} \right) - \frac{k^2}{6} \frac{\partial^5 U}{\partial t^3} - \frac{1}{2} \frac{k^2}{6} \frac{\partial^4 U}{\partial t^2 \partial x^2}$$