Name: Vishal Kumar Mahatha

Reg. No.: 20BRS1168

LAB: 4

Smart Parking System Part 2

Aim : Smart Parking System and LED is given through motor opening and closing

Components:

- 1)Arduino
- 2)Servo motor
- 3)LED
- 4)Ultrasonic sensor
- 5) Jumper wires
- 6)IR sensor
- 7)Breadboard

Procedure:

- 1)Connect the sensors with the Arduino with the required pins as shown in the circuit diagram.
- 2)Place the LED as needed in the breadboard.
- 3)The code mentioned below is uploaded to the Arduino.

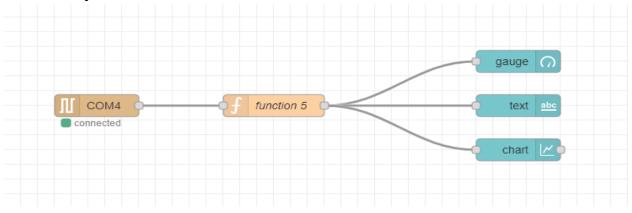
- 4)The flow in the node red is made with connecting the serial in block with the function block and then connect the function block to the gauge, text and chart blocks.
- 5)Deploy the flow.
- 6)Then open the dashboard of the node red where the output is visible.

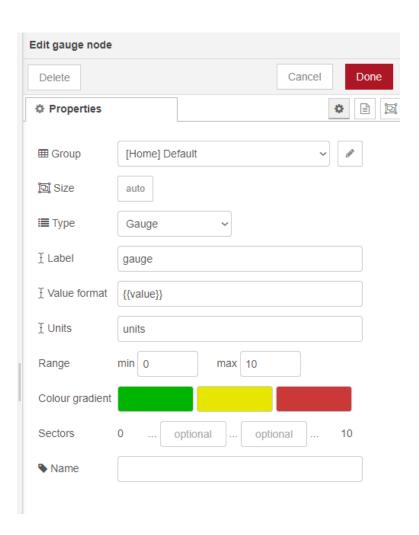
Code:

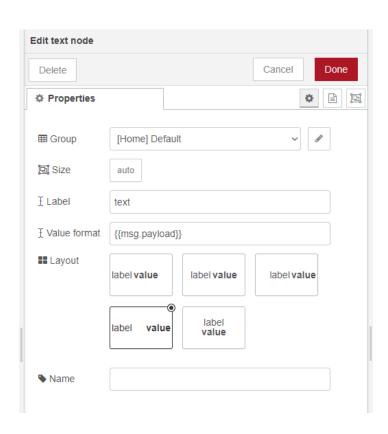
```
#include<Servo.h>
Servo servo;
#define servo 8
int trig = 4;
int echo = 5;
int ir = 6;
int led = 7;
int irRead;
int carStatus = 0;
float time, dist;
void setup() {
 // put your setup code here, to run once:
 pinMode(trig, OUTPUT);
 pinMode(echo, INPUT);
 pinMode(ir, INPUT);
 pinMode(led, OUTPUT);
 Serial.begin(9600);
```

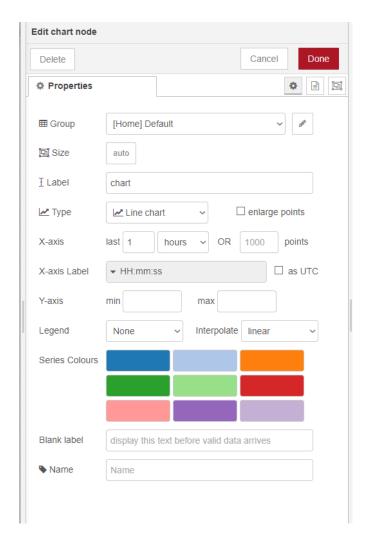
```
void loop() {
 // put your main code here, to run repeatedly:
 digitalWrite(trig, LOW);
 delay(5);
 digitalWrite(trig, HIGH);
 delay(5);
 digitalWrite(trig, LOW);
 time = pulseIn (echo, HIGH);
 dist = time * 0.034/2;
 if(dist<200)
  digitalWrite(led, HIGH);
  delay(4000);
  Serial.print("Door-open, ");
  Serial.print(dist);
  carStatus = 1;
 }
 if(carStatus = 1);
  irRead = digitalRead(ir);
  if(irRead == 1)
   {
   Serial.print(", Car-Pakeed");
   carStatus = 0;
 Serial.println();
```

NODE Layout:









Default

text Door-open, 0.00, Car-Pakeed

chart

gauge

Door-open, 0.00, Car-Pakeec

Circuit:

