

LAB 4

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admin1@admin1-VirtualBox: ~/PX4-Autopilot
admin1@admin1-VirtualBox: ~/PX4-Autopilot
admin1@admin1-VirtualBox:~/PX4-Autopilot$ make px4_sitl gazebo
[0/4] Performing build step for 'sitl_gazebo-classic'
ninja: no work to do.
[3/4] cd /home/admin1/PX4-Autopilot/bu...1/PX4-Autopilot/build/px4_sitl_default
SITL ARGS
sitl_bin: /home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4
debugger: none
model: iris
world: none
src_path: /home/admin1/PX4-Autopilot
build_path: /home/admin1/PX4-Autopilot/build/px4_sitl_default
GAZEBO_PLUGIN_PATH :/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
GAZEBO_MODEL_PATH :/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models
LD_LIBRARY_PATH /home/admin1/catkin_ws/devel/lib:/opt/ros/noetic/lib:/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
empty world, setting empty.world as default
Using: /home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models/iris/iris.sdf
Warning [parser.cc:833] XML Attribute[version] in element[sdf] not defined in SDF, ignoring.
Warning [parser.cc:833] XML Attribute[version] in element[sdf] not defined in SDF, ignoring.
Warning [parser.cc:833] XML Attribute[version] in element[sdf] not defined in SDF, ignoring.
SITL COMMAND: "/home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4" "/home/admin1/PX4-Autopilot/build/px4_sitl_default/etc

PX4

px4 starting.
INFO [px4] startup script: /bin/sh etc/init.d-posix/rcs 0
INFO [init] found model autostart file as SYS_AUTOSTART=10016
INFO [param] selected parameter default file parameters.bson
INFO [param] importing from 'parameters.bson'
INFO [parameters] BSON document size 316 bytes, decoded 316 bytes (INT32:13, FLOAT:3)
INFO [param] selected parameter backup file parameters_backup.bson

INFO [mavlink] MAVLink only on localhost (set param MAV_[i]_BROADCAST = 1 to enable network)
INFO [mavlink] MAVLink only on localhost (set param MAV_[i]_BROADCAST = 1 to enable network)
INFO [px4] Startup script returned successfully
pxh> Gazebo multi-robot simulator, version 11.11.0
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Released under the Apache 2 License.
http://gazeboosim.org

[Msg] Waiting for master.
[Msg] Connected to gazebo master @ http://127.0.0.1:11345
[Msg] Publicized address: 10.0.2.15
[Wrn] [Event.cc:61] Warning: Deleting a connection right after creation. Make sure to save the ConnectionPtr from a Connect call
INFO [health_and_arwing_checks] Preflight Fail: No manual control input
INFO [tone_alarm] home set
INFO [health_and_arwing_checks] Preflight Fail: No manual control input
INFO [health_and_arwing_checks] Preflight Fail: No manual control input
INFO [commander] Ready for takeoff!
INFO [health_and_arwing_checks] Preflight Fail: No manual control input

pxh> commander takeover
Invalid command: commander
type 'help' for a list of commands
pxh> help
Builtin Commands:
  actuator_test
  airship_att_control
  airspeed_selector
  attitude_estimator_q
  battery_simulator
  bsondump
  camera_feedback

admin1@admin1-VirtualBox:~/PX4-Autopilot$ make px4_sitl gazebo_rover_sonoma_raceway
[0/1] cd /home/admin1/PX4-Autopilot/bu... gazebo-classic_rover_sonoma_raceway
WARNING gazebo_rover_sonoma_raceway target DEPRECATED, please use gazebo-classic_rover__sonoma_raceway
[0/4] Performing build step for 'sitl_gazebo-classic'
ninja: no work to do.
[3/4] cd /home/admin1/PX4-Autopilot/bu...1/PX4-Autopilot/build/px4_sitl_default
SITL ARGS
sitl_bin: /home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4
debugger: none
model: rover
world: sonoma_raceway
src_path: /home/admin1/PX4-Autopilot
build_path: /home/admin1/PX4-Autopilot/build/px4_sitl_default
GAZEBO_PLUGIN_PATH :/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
GAZEBO_MODEL_PATH :/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models
LD_LIBRARY_PATH /home/admin1/catkin_ws/devel/lib:/opt/ros/noetic/lib:/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
Using: /home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models/rover/rover.sdf
SITL COMMAND: "/home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4" "/home/admin1/PX4-Autopilot/build/px4_sitl_default/etc
INFO [px4] PX4 daemon already running for instance 0 (Success)
/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_run.sh: line 173: kill: (12692) - No such process
```

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admin1@admin1-VirtualBox:~/PX4-Autopilot$ HEADLESS=1 make px4_sitl gazebo_plane
[0/1] cd /home/admin1/PX4-Autopilot/bu...4_sitl_default -- gazebo-classic_plane
WARNING gazebo_plane target DEPRECATED, please use gazebo-classic_plane
[0/4] Performing build step for 'sitl_gazebo-classic'
ninja: no work to do.
[3/4] cd /home/admin1/PX4-Autopilot/bu...1/PX4-Autopilot/build/px4_sitl_default
SITL ARGS
sitl_bin: /home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4
debugger: none
model: plane
world: none
src_path: /home/admin1/PX4-Autopilot
build_path: /home/admin1/PX4-Autopilot/build/px4_sitl_default
GAZEBO_PLUGIN_PATH :/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
GAZEBO_MODEL_PATH :/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models
LD_LIBRARY_PATH /home/admin1/catkin_ws/devel/lib:/opt/ros/noetic/lib:/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
empty world, setting empty.world as default
Using: /home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models/plane/plane.sdf
not running gazebo gui
SITL COMMAND: "/home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4" "/home/admin1/PX4-Autopilot/build/px4_sitl_default"/etc
INFO [px4] PX4 daemon already running for instance 0 (Success)
/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_run.sh: line 173: kill: (12792) - No such process

admin1@admin1-VirtualBox:~/PX4-Autopilot$ HEADLESS=1 make px4_sitl gazebo-classic_plane
[0/4] Performing build step for 'sitl_gazebo-classic'
ninja: no work to do.
[3/4] cd /home/admin1/PX4-Autopilot/bu...1/PX4-Autopilot/build/px4_sitl_default
SITL ARGS
sitl_bin: /home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4
debugger: none
model: plane
world: none
src_path: /home/admin1/PX4-Autopilot
build_path: /home/admin1/PX4-Autopilot/build/px4_sitl_default
GAZEBO_PLUGIN_PATH :/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
GAZEBO_MODEL_PATH :/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models
LD_LIBRARY_PATH /home/admin1/catkin_ws/devel/lib:/opt/ros/noetic/lib:/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
empty world, setting empty.world as default
Using: /home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models/plane/plane.sdf
not running gazebo gui
SITL COMMAND: "/home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4" "/home/admin1/PX4-Autopilot/build/px4_sitl_default"/etc
INFO [px4] PX4 daemon already running for instance 0 (Success)
/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_run.sh: line 173: kill: (12880) - No such process

admin1@admin1-VirtualBox:~/PX4-Autopilot$ export PX4_HOME_LAT=28.452386
admin1@admin1-VirtualBox:~/PX4-Autopilot$ export PX4_HOME_LON=-13.867138
admin1@admin1-VirtualBox:~/PX4-Autopilot$ export PX4_HOME_ALT=28.5
admin1@admin1-VirtualBox:~/PX4-Autopilot$ HEADLESS=1 make px4_sitl gazebo
[0/4] Performing build step for 'sitl_gazebo-classic'
ninja: no work to do.
[3/4] cd /home/admin1/PX4-Autopilot/bu...1/PX4-Autopilot/build/px4_sitl_default
SITL ARGS
sitl_bin: /home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4
debugger: none
model: iris
world: none
src_path: /home/admin1/PX4-Autopilot
build_path: /home/admin1/PX4-Autopilot/build/px4_sitl_default
GAZEBO_PLUGIN_PATH :/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
GAZEBO_MODEL_PATH :/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models
LD_LIBRARY_PATH /home/admin1/catkin_ws/devel/lib:/opt/ros/noetic/lib:/home/admin1/PX4-Autopilot/build/px4_sitl_default/build_gazebo-classic
empty world, setting empty.world as default
Using: /home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_gazebo-classic/models/iris/iris.sdf
not running gazebo gui
SITL COMMAND: "/home/admin1/PX4-Autopilot/build/px4_sitl_default/bin/px4" "/home/admin1/PX4-Autopilot/build/px4_sitl_default"/etc
INFO [px4] PX4 daemon already running for instance 0 (Success)
/home/admin1/PX4-Autopilot/Tools/simulation/gazebo-classic/sitl_run.sh: line 173: kill: (12970) - No such process

```

