# Vishalkumar Patel

Mechatronics Engineering, University of Waterloo

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wishalp5.github.io

# **Summary of Qualifications**

- 4 years of AutoCAD and technical drawing experience from academic training and work
  - Designed and built a zip line racer as part of a team and placed first in a tournament
- 2 years of Solid Edge experience and 1 year of SolidWorks experience from school and personal projects
- 1 year of programming experience in C++ and RobotC developed through course assignments, personal projects, and autonomous snow plow project
- Experienced in 3D Printing, Geometric Dimensioning and Tolerancing, and using machine shop tools
- Basic understanding of Lean Six Sigma and TPM principles and lean tools such as Plan-Do-Check-Act (PDCA),
  Root Cause Analysis, Failure Mode Effects Analysis (FMEA), Kaizen, and A3 Project Summary

# **Experience**

• Engineering Co-op – Apollo Health and Beauty Care Inc.

Jun. 2017 – Aug. 2017

- Labelled production equipment with asset numbers and updated asset management system to improve efficiency of preventive maintenance program
- Designed a pipe cleaning tool using AutoCAD to clean pipes before hot work (welding) is performed
- Performed preventive maintenance on filling machines and case sealers to optimize performance and bring the machine back towards base condition
- Collected samples from a dilution system using standard sampling procedures to validate product and machine performance
- Minister of Finance Student Council Bramalea S.S.

Sept. 2015 - June 2016

- Allocated funds to school clubs using expenditure records to ensure fair distribution of resources
- Submitted cheque requisition forms to reimburse council members for their purchases
- Collaborated with the council to plan, promote, and run events and fundraisers

## **Projects**

• 3D Printed Cell Phone Case – Independent Project

Jan. 2017

- Measured an existing part using manual calipers and designed a cell phone case replacement using SolidWorks, which was successfully 3D printed using PC-ABS
- Obstacle Avoiding Robot Independent Project

Dec. 2016

- Programmed and assembled a robot using an Arduino Uno that detects objects, prevents collisions, and navigates using an ultrasonic sensor
- Autonomous Snow Plow Term Project

Oct. 2016 – Nov. 2010

 Designed a snow plow that autonomously navigates using multiple sensors and clears roads and driveways using a 3D printed mechanism (programmed using RobotC)

#### Education

 Candidate for Bachelor of Applied Science, Mechatronics Engineering – University of Waterloo Sept. 2016 – Present

 Relevant Courses: Introduction to Microprocessors and Digital Logic, Engineering Graphics and Design (AutoCAD, SolidWorks), Structure and Properties of Materials, Algorithms and Data Structures (C++)

### **Activities and Interests**

Autonomous cars, Cycling, Basketball