

지능형 대화 에이전트 (Chatbot) 실습

1. Deep learning basic with [PyTorch](#)
2. Deep learning based [Chatbot](#)
3. [ParlAI](#): a framework for dialog AI reserach
4. Practice

** Prerequisite : Python, Neural Network*

2017. 9. 8.

Deep learning basic with PyTorch

References:

http://pytorch.org/tutorials/beginner/pytorch_with_examples.html



Python based scientific computing package targeted at two sets of audiences:

- A replacement for numpy to use the power of **GPUs**
- a deep learning research platform that provides maximum **flexibility and speed**

Installation

Get Started.

Select your preferences, then run the PyTorch install command.

Please ensure that you are on the latest pip and numpy packages.
Anaconda is our recommended package manager

OS	<input checked="" type="radio"/> Linux	<input type="radio"/> OSX	
Package Manager	<input type="radio"/> conda	<input checked="" type="radio"/> pip	<input type="radio"/> Source
Python	<input type="radio"/> 2.7	<input type="radio"/> 3.5	<input checked="" type="radio"/> 3.6
CUDA	<input type="radio"/> 7.5	<input checked="" type="radio"/> 8.0	<input type="radio"/> None

Run this command:

```
pip install http://download.pytorch.org/whl/cu80/torch-0.2.0.post3-cp36-cp36m-manylinux1_x86_64.whl
pip install torchvision
```

- <http://pytorch.org/>
- we recommend you to prepare CUDA-enable computing environment.

Basic examples for Pytorch

- Tensors
- with Numpy
- GPU
- Autograd
- Neural Network
- Loss
- Optimizer

source :

[1] http://pytorch.org/tutorials/beginner/deep_learning_60min_blitz.html

[2] http://pytorch.org/tutorials/beginner/pytorch_with_examples.html

PLEASE FOLLOW ALL EXAMPLES IN ABOVE LINK BY YOURSELF

Tensors

```
from __future__ import print_function
import torch
```

Construct a 5x3 matrix, uninitialized:

```
x = torch.Tensor(5, 3)
print(x)
```

Out:

```
-2.9226e-26  1.5549e-41  1.5885e+14
 0.0000e+00  7.0065e-45  0.0000e+00
 7.0065e-45  0.0000e+00  4.4842e-44
 0.0000e+00  4.6243e-44  0.0000e+00
 1.5810e+14  0.0000e+00  1.6196e+14
[torch.FloatTensor of size 5x3]
```

with Numpy

Converting torch Tensor to numpy Array

```
a = torch.ones(5)
print(a)
```

Out:

```
1
1
1
1
1
[torch.FloatTensor of size 5]
```

```
b = a.numpy()
print(b)
```

Out:

```
[ 1.  1.  1.  1.  1.]
```

with Numpy

Converting numpy Array to torch Tensor

See how changing the np array changed the torch Tensor automatically

```
import numpy as np
a = np.ones(5)
b = torch.from_numpy(a)
np.add(a, 1, out=a)
print(a)
print(b)
```

Out:

```
[ 2.  2.  2.  2.  2.]

2
2
2
2
2
[torch.DoubleTensor of size 5]
```


CUDA Tensors

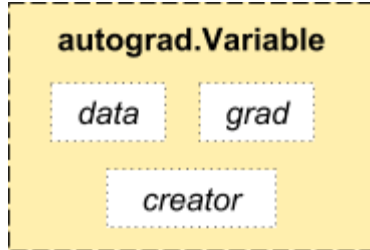
Tensors can be moved onto GPU using the `.cuda` function.

```
# let us run this cell only if CUDA is available  
if torch.cuda.is_available():  
    x = x.cuda()  
    y = y.cuda()  
    x + y
```

Autograd : Variable

- autograd package provides automatic differentiation for all operations on Tensors

- Variable



- Create variable

```
import torch
from torch.autograd import Variable
```

Create a variable:

```
x = Variable(torch.ones(2, 2), requires_grad=True)
print(x)
```

Out:

```
Variable containing:
  1  1
  1  1
[torch.FloatTensor of size 2x2]
```

Autograd : Variable (cont'd)

- Addition

```
y = x + 2  
print(y)
```

Out:

```
Variable containing:  
 3  3  
 3  3  
[torch.FloatTensor of size 2x2]
```

- multiplication, mean

```
z = y * y * 3  
out = z.mean()  
  
print(z, out)
```

Out:

```
Variable containing:  
27 27  
27 27  
[torch.FloatTensor of size 2x2]  
Variable containing:  
27  
[torch.FloatTensor of size 1]
```

Autograd : Gradients

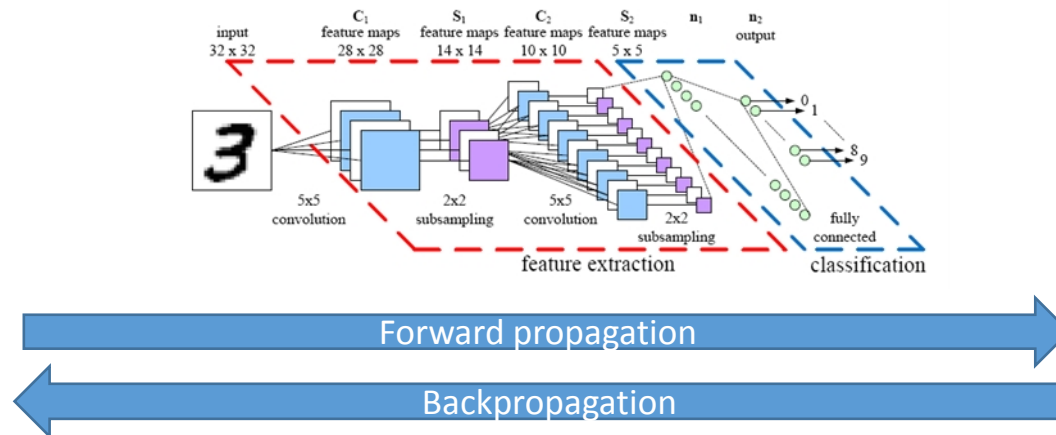
- In previous example, computation graph is defined as
 - $y = x + 2$
 - $z = y * y * 3$
 - $out = z.mean()$
- Backpropagation:
➔ `out.backward()`
- `print d(out)/dx`
➔ `print(x.grad)`

Out:

```
Variable containing:
 4.5000  4.5000
 4.5000  4.5000
[torch.FloatTensor of size 2x2]
```

You should have got a matrix of `4.5`. Let's call the `out` Variable " o ". We have that $o = \frac{1}{4} \sum_i z_i$, $z_i = 3(x_i + 2)^2$ and $z_i|_{x_i=1} = 27$. Therefore, $\frac{\partial o}{\partial x_i} = \frac{3}{2}(x_i + 2)$, hence $\frac{\partial o}{\partial x_i}|_{x_i=1} = \frac{9}{2} = 4.5$.

Neural Networks : Typical training procedure



1. Define the neural network that has some learnable parameters (or weights)
2. Iterate over a dataset of inputs
3. Process input through the network
4. Compute the loss (how far is the output from being correct)
5. Propagate gradients back into the network's parameters
6. Update the weights of the network, typically using a simple update rule:
$$\text{weight} = \text{weight} - \text{learning_rate} * \text{gradient}$$

Define the network

```
import torch
from torch.autograd import Variable
import torch.nn as nn
import torch.nn.functional as F

class Net(nn.Module):

    def __init__(self):
        super(Net, self).__init__()
        # 1 input image channel, 6 output channels, 5x5 square convolution
        # kernel
        self.conv1 = nn.Conv2d(1, 6, 5)
        self.conv2 = nn.Conv2d(6, 16, 5)
        # an affine operation: y = Wx + b
        self.fc1 = nn.Linear(16 * 5 * 5, 120)
        self.fc2 = nn.Linear(120, 84)
        self.fc3 = nn.Linear(84, 10)

    def forward(self, x):
        # Max pooling over a (2, 2) window
        x = F.max_pool2d(F.relu(self.conv1(x)), (2, 2))
        # If the size is a square you can only specify a single number
        x = F.max_pool2d(F.relu(self.conv2(x)), 2)
        x = x.view(-1, self.num_flat_features(x))
        x = F.relu(self.fc1(x))
        x = F.relu(self.fc2(x))
        x = self.fc3(x)
        return x

    def num_flat_features(self, x):
        size = x.size()[1:] # all dimensions except the batch dimension
        num_features = 1
        for s in size:
            num_features *= s
        return num_features

net = Net()
```

Define the loss

```
output = net(input)
target = Variable(torch.arange(1, 11)) # a dummy target, for example
criterion = nn.MSELoss()

loss = criterion(output, target)
print(loss)
```

Out:

```
Variable containing:
  38.7810
[torch.FloatTensor of size 1]
```

Training neural networks

```
import torch
from torch.autograd import Variable

# N is batch size; D_in is input dimension;
# H is hidden dimension; D_out is output dimension.
N, D_in, H, D_out = 64, 1000, 100, 10

# Create random Tensors to hold inputs and outputs
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

# Use the nn package to define our model and loss
function.
model = torch.nn.Sequential(
    torch.nn.Linear(D_in, H),
    torch.nn.ReLU(),
    torch.nn.Linear(H, D_out),
)

# The nn package also contains definitions of popular
loss functions: Mean Squared Error (MSE)
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
```

```
for t in range(500):
    # Forward pass
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
    print(t, loss.data[0])

    # Zero the gradients before running the backward pass.
    model.zero_grad()

    # Backward pass
    loss.backward()

    # Update the weights using gradient descent
    for param in model.parameters():
        param.data -= learning_rate * param.grad.data
```


Training neural networks with optimizer

```
import torch
from torch.autograd import Variable

# N is batch size; D_in is input dimension;
# H is hidden dimension; D_out is output dimension.
N, D_in, H, D_out = 64, 1000, 100, 10

# Create random Tensors to hold inputs and outputs
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)

# Use the nn package to define our model and loss
function.
model = torch.nn.Sequential(
    torch.nn.Linear(D_in, H),
    torch.nn.ReLU(),
    torch.nn.Linear(H, D_out),
)

# The nn package also contains definitions of popular
loss functions: Mean Squared Error (MSE)
loss_fn = torch.nn.MSELoss(size_average=False)

learning_rate = 1e-4
```

```
optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)
for t in range(500):
    # Forward pass
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
    print(t, loss.data[0])

    # Use optimizer object to zero all of the
    # gradients for the variables it will update
    optimizer.zero_grad()

    # Backward pass
    loss.backward()

    # Calling the step function on an Optimizer makes an update
    to its parameters
    optimizer.step()
```

Deep Learning based Chatbot

1. RNNs & LSTMs
2. Word embedding vectors and Language models
3. Sequence-to-sequence models
4. Recent deep learning architectures for dialogs

Recurrent Neural Network

- Neural networks whose connections allow **cyclical** connections.

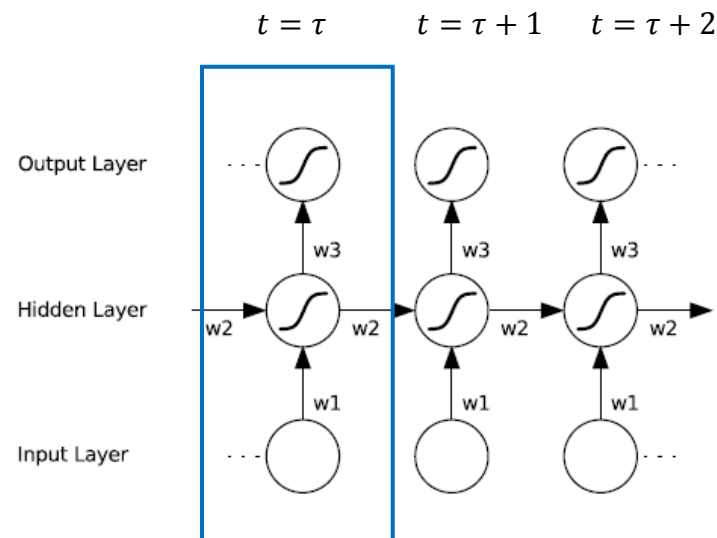
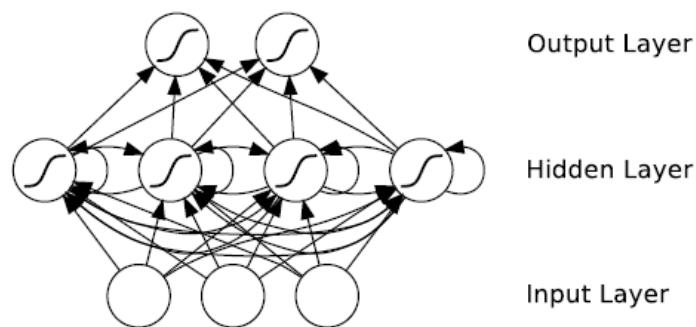
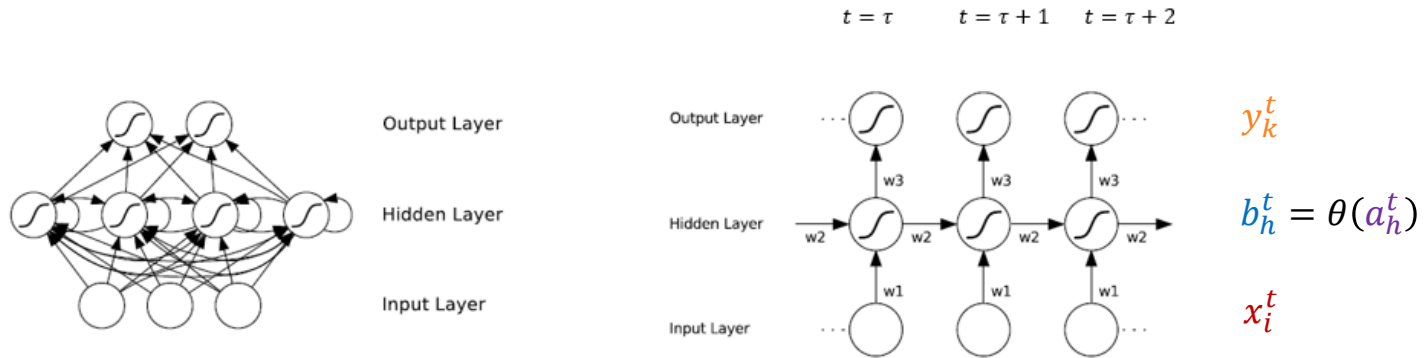


Figure 3.4: **An unfolded recurrent network.** Each node represents a layer of network units at a single timestep. The weighted connections from the input layer to hidden layer are labelled 'w1', those from the hidden layer to itself (i.e. the recurrent weights) are labelled 'w2' and the hidden to output weights are labelled 'w3'. Note that the same weights are reused at every timestep. Bias weights are omitted for clarity.

Recurrent Neural Network



- RNN with I input units, H hidden units, and K output units.

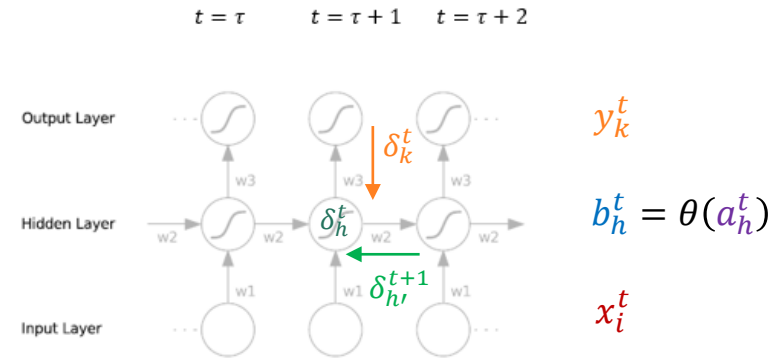
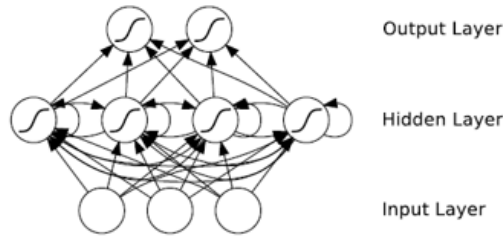
▪ Forward pass

Given an input sequence $x = (\mathbf{x}^1, \dots, \mathbf{x}^T)$

- x_i^t : the value of input i at time t
- a_h^t : network input to unit h at time t $a_h^t = \sum_{i=1}^I w_{ih}^{(1)} x_i^t + \sum_{h'=1}^H w_{h'h}^{(2)} b_{h'}^{t-1}$
- b_h^t : the activation of unit h at time t $b_h^t = \theta_h(a_h^t)$
- y_k^t : the value of output k at time t $y_k^t = \sum_{h=1}^H w_{hk}^{(3)} b_h^t$

Recurrent hidden neuron term
: memory of previous input

Recurrent Neural Network



- x_i^t : the value of input i at time t
- a_h^t : network input to unit h at time t $a_h^t = \sum_{i=1}^I w_{ih}^{(1)} x_i^t + \sum_{h'=1}^H w_{h'h}^{(2)} b_{h'}^{t-1}$
- b_h^t : the activation of unit h at time t $b_h^t = \theta(a_h^t)$
- y_k^t : the value of output k at time t $y_k^t = \sum_{h=1}^H w_{hk}^{(3)} b_h^t$

Backward pass

- Backpropagation through time (BPTT; Williams and Zipser, 1995; Werbos, 1990)
- Using chain rule, \mathcal{L} differentiable loss function

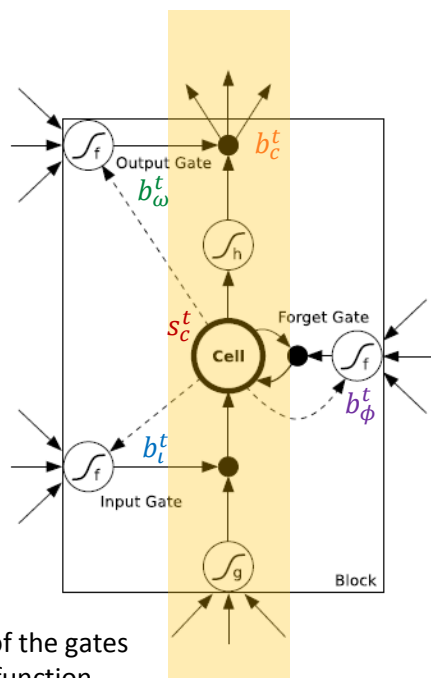
- $\frac{\partial \mathcal{L}}{\partial w_{hk}^{(3)}} = \sum_{t=1}^T \frac{\partial \mathcal{L}}{\partial y_k^t} \frac{\partial y_k^t}{\partial w_{hk}^{(3)}} = \sum_{t=1}^T \delta_k^t b_h^t$
- $\frac{\partial \mathcal{L}}{\partial w_{h'h}^{(2)}} = \sum_{t=1}^T \frac{\partial \mathcal{L}}{\partial a_h^t} \frac{\partial a_h^t}{\partial w_{h'h}^{(2)}} = \sum_{t=1}^T \delta_h^t b_{h'}^{t-1}$
- $\frac{\partial \mathcal{L}}{\partial w_{ih}^{(1)}} = \sum_{t=1}^T \frac{\partial \mathcal{L}}{\partial a_h^t} \frac{\partial a_h^t}{\partial w_{ih}^{(1)}} = \sum_{t=1}^T \delta_h^t x_i^t$

The same weights are reused at every timestep

- $\delta_h^t := \frac{\partial \mathcal{L}}{\partial a_h^t}$
- $\delta_h^t = \theta'(a_h^t) \left(\sum_{k=1}^K \delta_k^t w_{hk}^{(3)} + \sum_{h'=1}^H \delta_{h'}^{t+1} w_{hh'}^{(2)} \right)$
- δ can be calculated by starting at $t = T$, decrementing t at each step.
- $(\delta_h^{T+1} = 0 \forall h)$, since no error is received from beyond the end of the sequence)

Recurrent Neural Network + LSTM

- Long Short-term Memory (LSTM, Hochreiter and Schmidhuber, 1997)
 - Consists of a set of recurrently connected subnets, known as **memory blocks**
 - Each block contains one or more self-connected memory **cells** and three multiplicative units – the **input**, **output**, and **forget gates**.
 - The three gates control the activation of the cell via multiplications (\bullet)



f : activation function of the gates
 g : cell input activation function
 h : cell output activation function

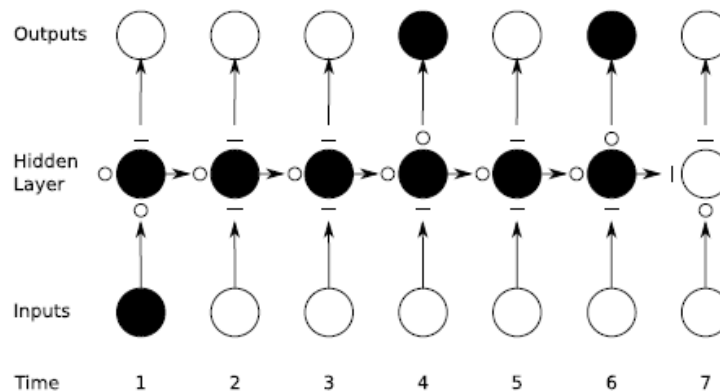
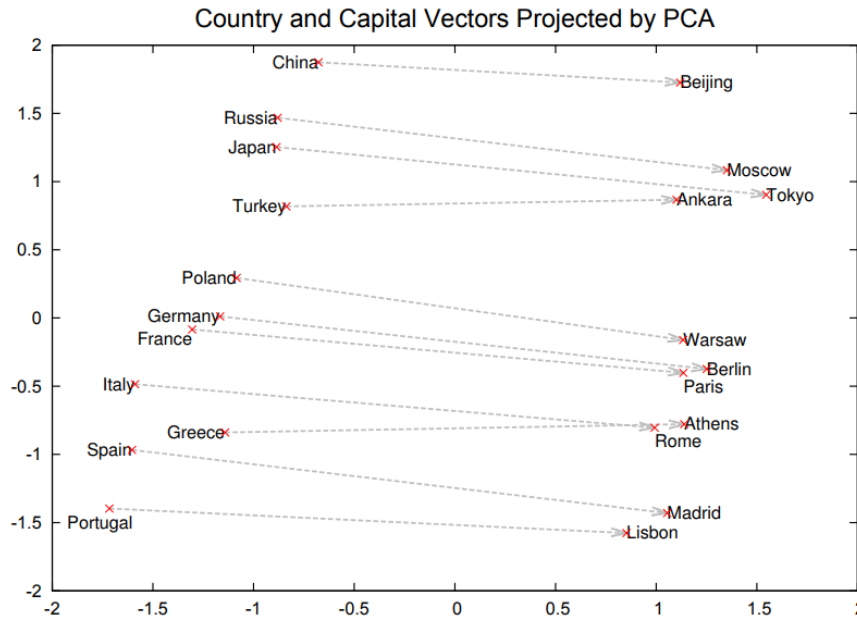
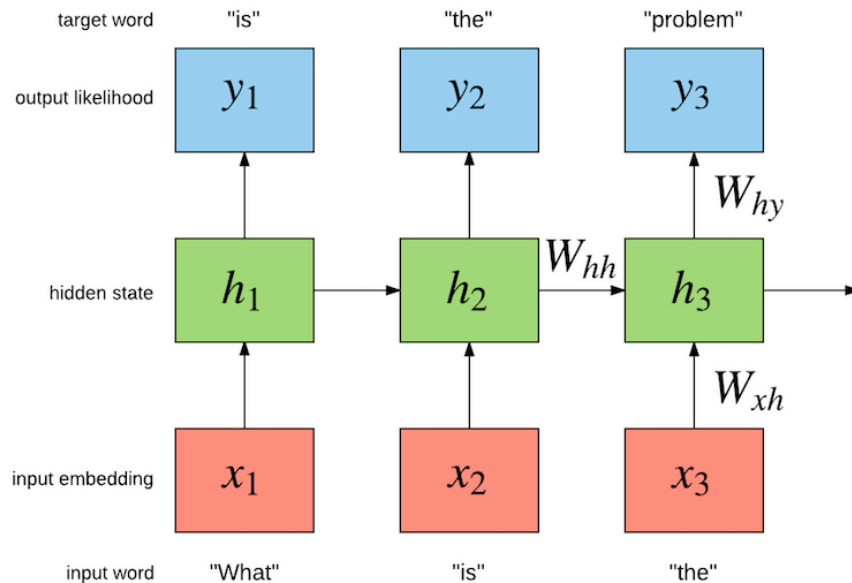


Figure 4.4: **Preservation of gradient information by LSTM.** As in Figure 4.1 the shading of the nodes indicates their sensitivity to the inputs at time one; in this case the black nodes are maximally sensitive and the white nodes are entirely insensitive. The state of the input, forget, and output gates are displayed below, to the left and above the hidden layer respectively. For simplicity, all gates are either entirely open ('O') or closed ('—'). The memory cell 'remembers' the first input as long as the forget gate is open and the input gate is closed. The sensitivity of the output layer can be switched on and off by the output gate without affecting the cell.

Word embedding

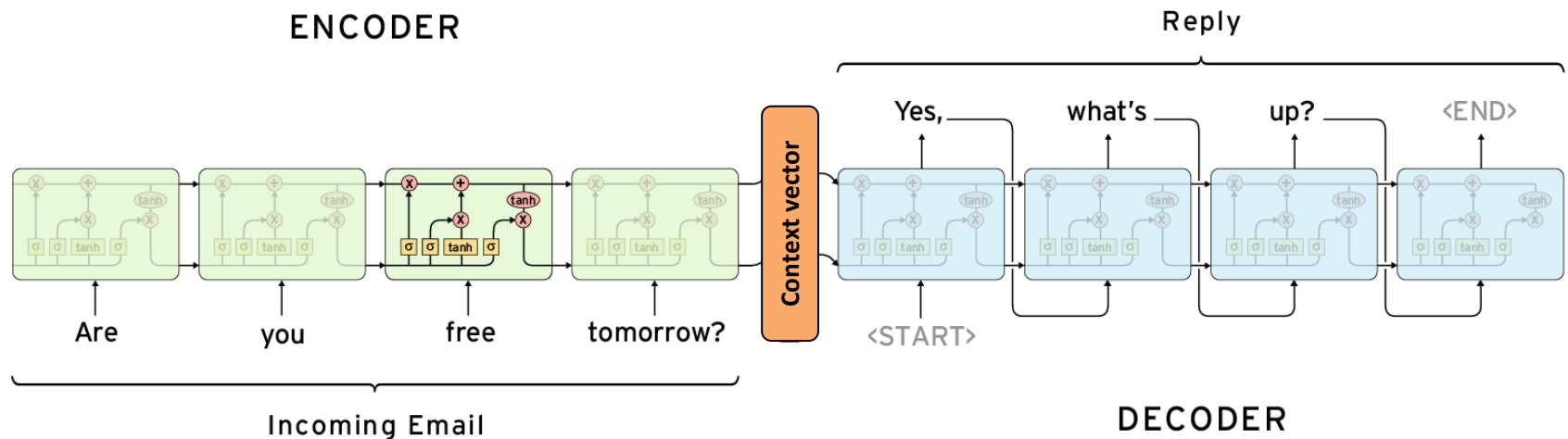


- Every word has its own distributed representation : Word embedding



- ex) RNN Language Model : Word embeddings are fed into the RNN

Sequence to Sequence for Chatbot

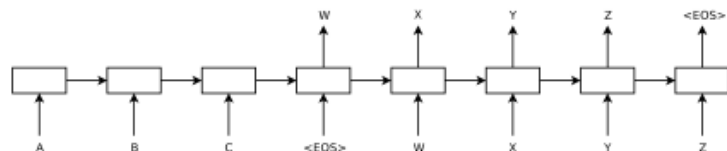


Seq2Seq model comprises of two language models:

- Encoder: encode the input sequence into a fixed length vector (context vector)
- Decoder: generate the next word sequence given the context vector

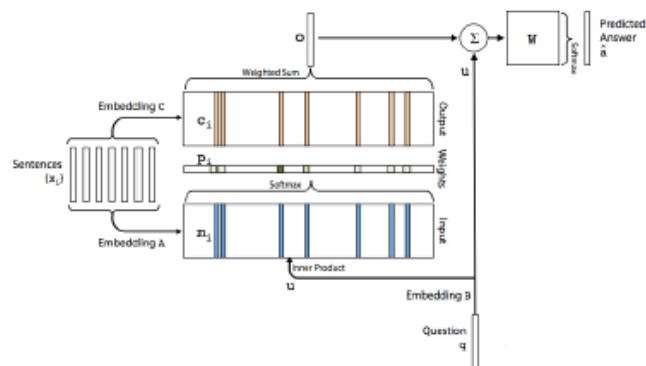
Recent deep learning architectures for dialogs

Sequence to sequence



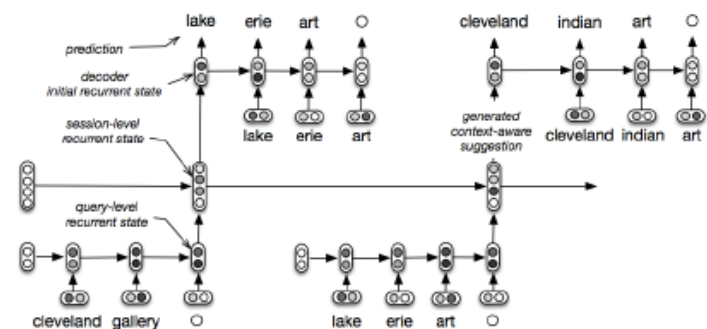
<http://papers.nips.cc/paper/5346-sequence-to-sequence-learning-with-neural-networks.pdf>

Memory networks



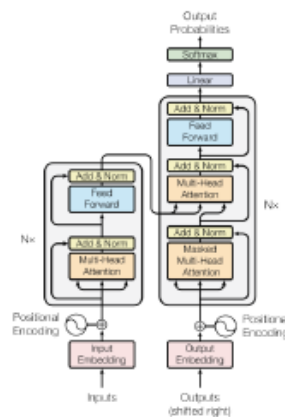
<https://arxiv.org/abs/1503.08895>

Hierarchical recurrent encoder-



<https://arxiv.org/abs/1507.02221>

Attention is all you need



<https://arxiv.org/abs/1706.03762>

ParlAI[par-lay]

: a framework for dialog AI research

References:

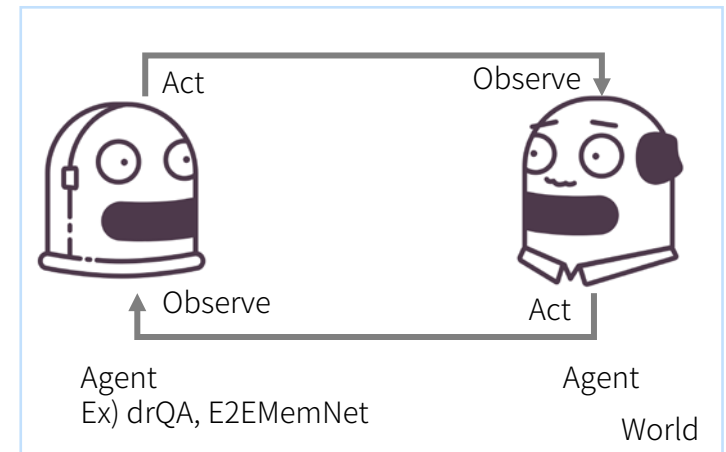
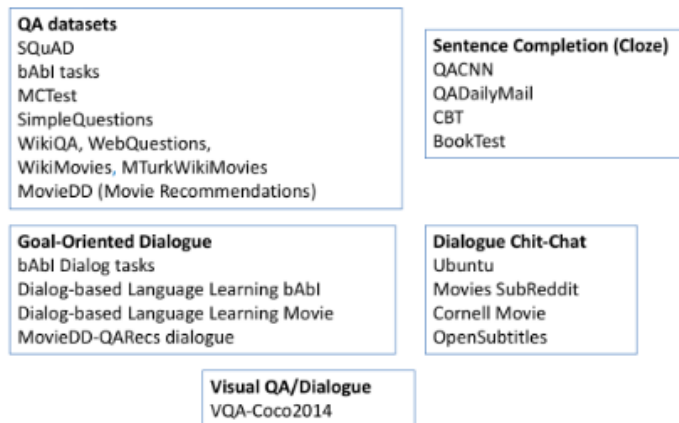
- Alexandr H. Miller et al., ParlAI: A Dialog Research Software Platform, arxiv 2017
- <https://github.com/facebookresearch/ParlAI>
- <http://parl.ai/>

ParlAI

Overview

- Open source published by Facebook research
- Its goal is to provide researchers:
 - a unified framework for training and testing dialog models
 - multi-task training over many datasets at once
 - seamless integration of [Amazon Mechanical Turk](https://www.mturk.com/) for data collection and human evaluation
- Supporting tasks:

ParlAI Tasks (first release)



Cf. parley

[NOUN] A parley is a discussion between two opposing people or groups in which both sides try to come to an agreement.

[VERB] When two opposing people or groups parley, they meet to discuss something in order to come to an agreement.

ParlAI: A Dialog Research Software Platform, A. Miller et al., Arxiv, 2017

<https://github.com/facebookresearch/ParlAI>

ParlAI : Provided tasks

QA datasets

SQuAD, [MS MARCO](#), [TriviaQA](#)

bAbI tasks

MCTest

SimpleQuestions

WikiQA, WebQuestions, [InsuranceQA](#)

WikiMovies, MTurkWikiMovies

MovieDD (Movie-Recommendations)

Sentence Completion

QACNN

QADailyMail

CBT

BookTest

Dialogue Goal-Oriented

bAbI Dialog tasks, [personalized-dialog](#)

Dialog-based Language Learning bAbI

Dialog-based Language Learning Movie

MovieDD-QARecs dialogue)

Dialogue Chit-Chat

Ubuntu

Movies SubReddit

Cornell Movie

OpenSubtitles

VQA/Visual Dialogue

VQA-v1,

[VQA-v2](#), [Vdialog](#), [CLEVR](#)

Add your own dataset!

Open source...

ParlAI : Provided tasks

QA datasets

bAbI tasks

MCTest

SquAD, NewsQA, MS MARCO

SimpleQuestions

WebQuestions, WikiQA

WikiMovie

MovieDD

Dialogue

bAbI Dialogue

Camrest

Dialog-ba

MovieDD

CommAI-

Sentence Completion

QACNN

QADailyMail

CBT

Attention during mem lookup

Story (2: 2 supporting facts)	Support	Hop 1	Hop 2	Hop 3
John dropped the milk.	yes	0.06	0.00	0.00
John took the milk there.		0.88	1.00	0.00
Sandra went back to the bathroom.	yes	0.00	0.00	0.00
John moved to the hallway.		0.00	0.00	1.00
Mary went back to the bedroom.		0.00	0.00	0.00
Where is the milk? Answer: hallway Prediction: hallway				

Story (18: size reasoning)	Support	Hop 1	Hop 2	Hop 3
The suitcase is bigger than the chest.	yes	0.00	0.88	0.00
The box is bigger than the chocolate.	yes	0.04	0.05	0.10
The chest is bigger than the chocolate.		0.17	0.07	0.90
The chest fits inside the container.		0.00	0.00	0.00
The chest fits inside the box.		0.00	0.00	0.00
Does the suitcase fit in the chocolate? Answer: no Prediction: no				

ParlAI : Provided tasks

QA datasets

bAbI tasks

MCTest

SQuAD, NewsQA, MS MARC

SimpleQuestions

WebQuestions, WikiQA

WikiMovies, MTurkWikiMovies

MovieDD (Movie-Recommender)

Dialogue Goal-Oriented

bAbI Dialog tasks

Camrest

Dialog-based Language Learning

MovieDD (QA, Recs dialog)

CommAI-env

VQA/Visual Dialog

TBD..

In meteorology, precipitation is any product of the condensation of atmospheric water vapor that falls under **gravity**. The main forms of precipitation include drizzle, rain, sleet, snow, **graupel** and hail... Precipitation forms as smaller droplets coalesce via collision with other rain drops or ice crystals **within a cloud**. Short, intense periods of rain in scattered locations are called "showers".

What causes precipitation to fall?

gravity

What is another main form of precipitation besides drizzle, rain, snow, sleet and hail?

graupel

Where do water droplets collide with ice crystals to form precipitation?

within a cloud

Figure 1: Question-answer pairs for a sample passage in the SQuAD dataset. Each of the answers is a segment of text from the passage.

ParlAI : Provided tasks

QA datasets

bAbI tasks

MCTest

SquAD, NewsQA, MS MARC

SimpleQuestions

WebQuestions, WikiQA

WikiMovies, MTurkWikiMov

MovieDD (Movie-Recommen

Dialogue Goal-Oriented

bAbI Dialog tasks

Camrest

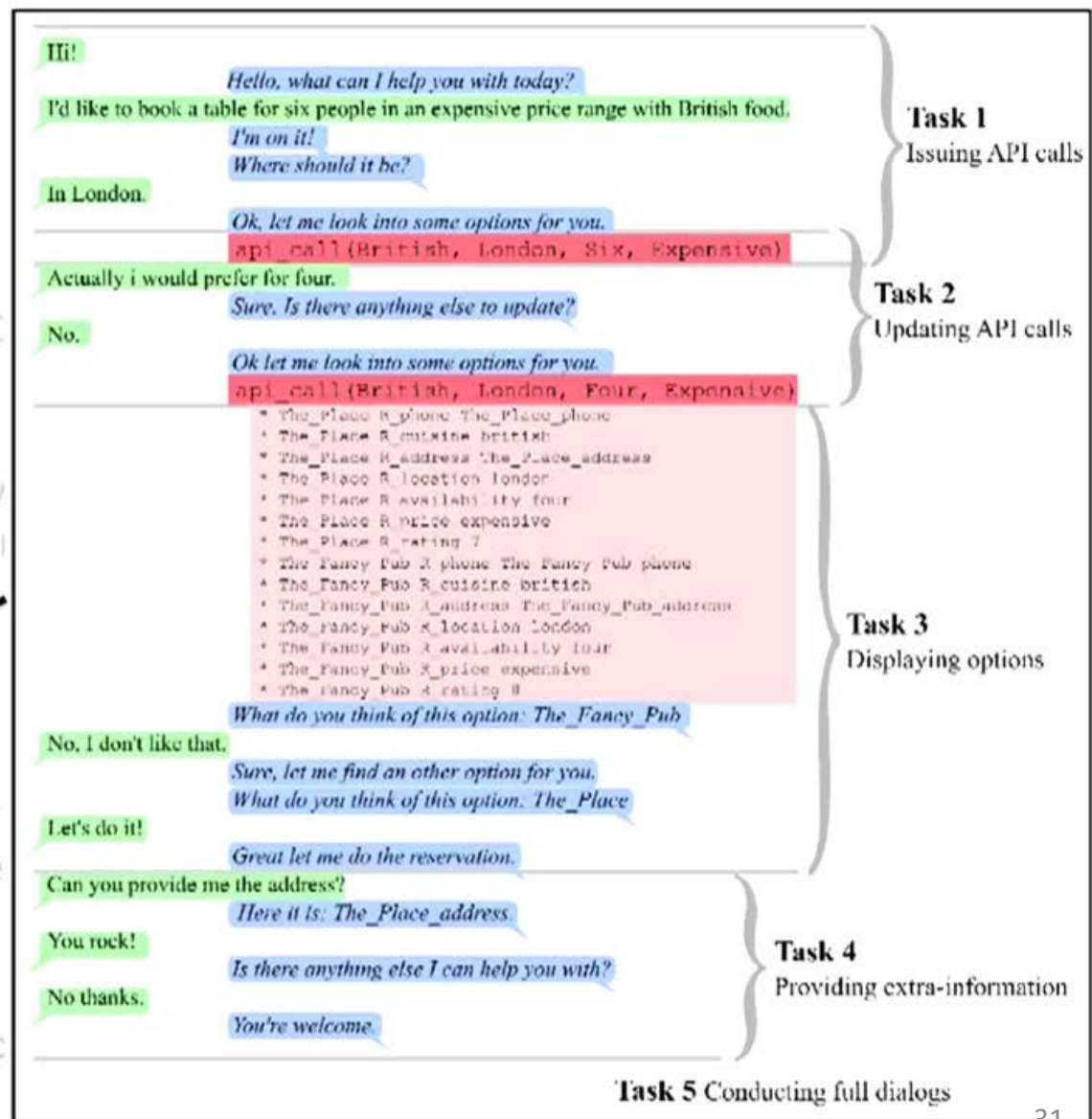
Dialog-based Language Lear

MovieDD (QA,Recs dialogue

CommAI-env

VQA/Visual Dialo

TBD..



ParlAI : how to run examples

- Display 10 random examples from the SQuAD dataset:

```
python examples/display_data.py -t squad
```

- Displays 100 random examples from multi-tasking on the bAbI + SQuAD datasets at the same time:

```
python examples/display_data.py -t babi,squad -n 100
```

- Evaluate on the bAbI test set with a human agent (using the local keyboard as input):

```
python examples/eval_model.py -m local_human -t babi -dt valid
```

- Train an attentive LSTM model on the SQuAD dataset with a batch size of 32 examples:

```
python examples/train_model.py -m drqa -t squad -bs 32 -mf /tmp/model
```


Practices

Practice

- Reference : O Vinyals et al., “A Neural Conversational Model”, ICML Deep learning workshop, 2016
- Database : Opensubtitle2016 (62M turns)

U: how are you ?

S: good .

U: it 's too hot !

S: i need a shower .

U: do you mind ?

S: yes , i do mind .

U: i was thinking about getting into the boxing .

S: great , why not ?

Example : Chitchat

U: and i wish to hell i knew why .

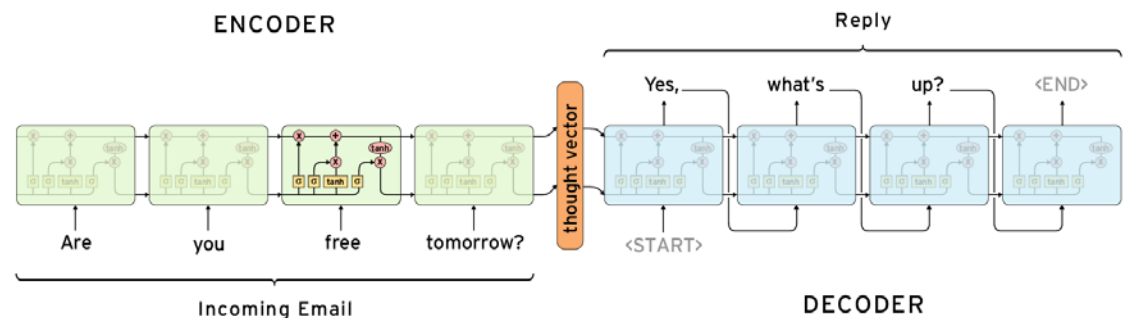
S: when we got back to earth everybody
treated us like heroes .

U: master yoshida !

S: the princess is also missing !

Example : lack of context

- Model : RNN Encoder Decoder



Practice

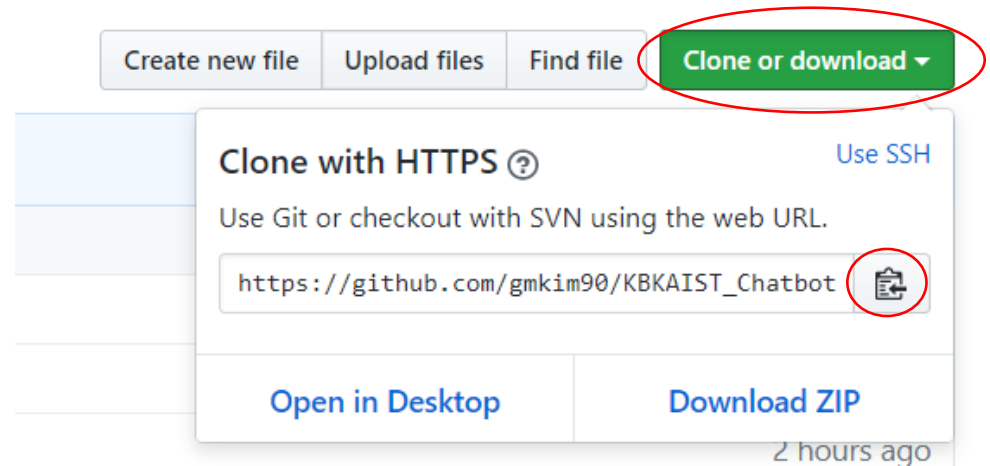
- Prob1. Display opensubtitle data and briefly explain about the database. (10pts)
- Prob2. Fill in the 7 blanks (each 5pts) in
parlai/agents/seq2seq/seq2seq_FILL_IN_THE_BLANK.py
(the blanks are with the comment '# FILL HERE') and run the script. (35pts)

*python examples/train_model_practice.py -m seq2seq -t opensubtitles
-bs 32 -mf 'data/OpenSubtitles'*

- Prob3. Propose idea to improve this model. (30pts)

프로젝트: 챗봇시스템 구현

- 준비: https://github.com/gmkim90/KBKAIST_Chatbot 에 접속
- 준비된 프로젝트 다운받기
\$ git clone https://github.com/gmkim90/KBKAIST_Chatbot.git



- Python3 이용
\$ source activate python3
- ParlAI setup
\$ cd KBKAIST_Chatbot
\$ python setup.py develop

프로젝트: 챗봇시스템 구현

❖ Prob 1. Display opensubtitle data and briefly explain about the database (10pts)

```
$ python examples/display_data.py -t Opensubtitles
```

Or

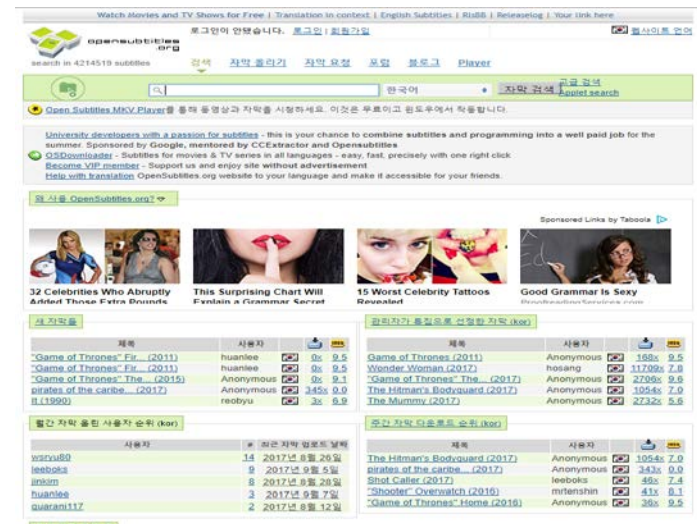
```
$ vim data/OpenSubtitles/{train, valid, test}.txt
```

- Close vi
:q!

```
83 Sylvia . Come on , Sylvia .  
84 Go on . Just get up . [ Laughing ]  
85 Give us some of your American poetry . Go on .  
:q!
```

• Opensubtitles:

- A collection of document from <http://www.opensubtitles.org/>
- Each line represents two turns of a conversation.

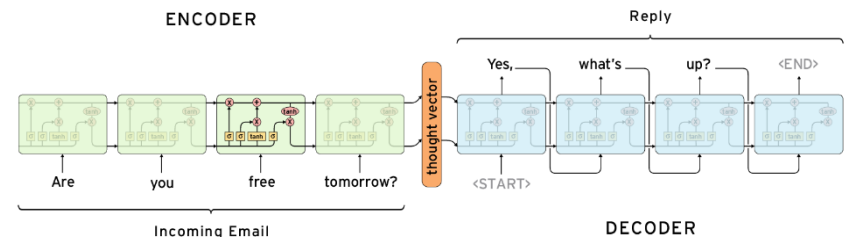


프로젝트: 챗봇시스템 구현

❖ Prob 2. Fill in *seven* blanks (each 5 pts) of `parlai/agents/seq2seq/seq2seq.py` and run (35pts)

- Run the code

```
$ python examples/train_model.py -m seq2seq -t opensubtitles -bs 32 -mf data/OpenSubtitles/model
```



```
$ vim parlai/agents/seq2seq/seq2seq.py
```

```
91 # set up modules
92 self.criterion = nn.NLLLoss()
93 # lookup table stores word embeddings
94 1. self.lt = nn.Embedding() # FILL HERE
95 # encoder captures the input text
96 2. self.encoder = nn.GRU() # FILL HERE
97 # decoder produces our output states
98 3. self.decoder = nn.GRU()
99 # linear layer helps
100 4. self.h2o = nn.Linear()
101 # dropout on the line
102 self.dropout = nn.Dropout()
103 # softmax maps output
104 self.softmax = nn.LogSoftmax()

151 def hidden_to_idx(self, hidden, dropout=False):
152     """Converts hidden state vectors into indices into the dictionary."""
153     if hidden.size(0) > 1:
154         raise RuntimeError('bad dimensions of tensor:', hidden)
155     hidden = hidden.squeeze(0)
156 5. scores = # FILL HERE
157 6. if dropout:
158     scores = # FILL HERE
159 7. scores = # FILL HERE
160     _max_score, idx = scores.max(1)
161     return idx, scores
```

프로젝트: 챗봇시스템 구현

❖ Prob 2. Fill in the blanks (each 5 pts) of `parlai/agents/seq2seq/seq2seq.py` and run (35pts)

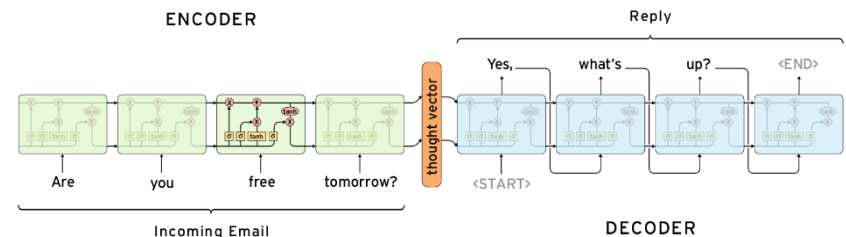
- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')

• 1. fill here

- `self.it = nn.Embedding(?)`

`Import torch.nn`

- Using <http://pytorch.org/docs/master/>



```
class torch.nn.Embedding(num_embeddings, embedding_dim, padding_idx=None,
max_norm=None, norm_type=2, scale_grad_by_freq=False, sparse=False) [source]
```

프로젝트: 챗봇시스템 구현

❖ Prob 2. Fill in the blanks (each 5 pts) of parlai/agents/seq2seq/seq2seq.py and run (35pts)

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')

- 1. fill here

- self.it = nn.Embed

Import torch.nn

- Using [http://py](http://pytorch.org/docs/0.4.0/nn.html)

```
class torch.nn.  
max_norm=None
```

Parameters:

- num_embeddings (*int*) – size of the dictionary of embeddings
- embedding_dim (*int*) – the size of each embedding vector
- padding_idx (*int, optional*) – If given, pads the output with zeros whenever it encounters the index.
- max_norm (*float, optional*) – If given, will renormalize the embeddings to always have a norm lesser than this
- norm_type (*float, optional*) – The p of the p-norm to compute for the max_norm option
- scale_grad_by_freq (*boolean, optional*) – if given, this will scale gradients by the frequency of the words in the mini-batch.

- Answer:

```
self.it = nn.Embedding( len(self.dict), hsz, padding_idx=self.NULL_IDX,  
scale_grad_by_freq=True)
```


프로젝트: 챗봇시스템 구현

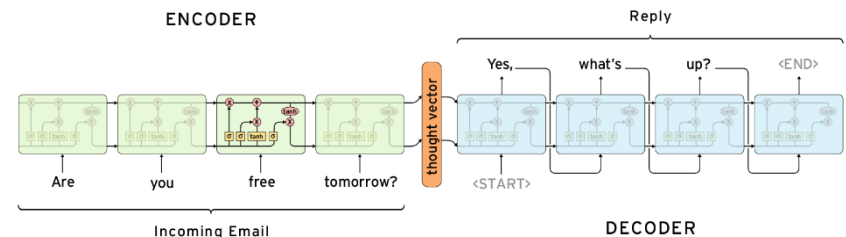
❖ Prob 2. Fill in the blanks (each 5 pts) of parlai/agents/seq2seq/seq2seq.py and run (35pts)

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')

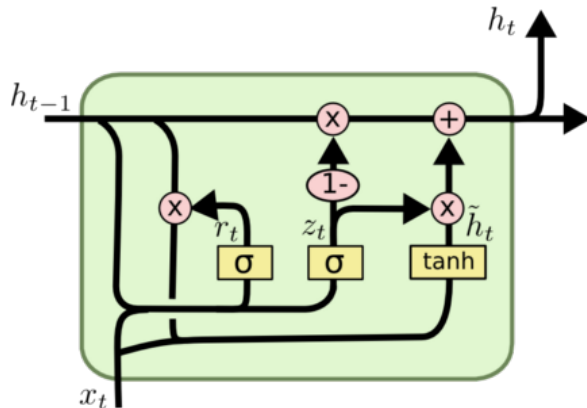
• 2, 3. fill here

- self.encoder = nn.GRU(?)
- self.decoder = nn.GRU(?)

- Using <http://pytorch.org/docs/master/>



```
class torch.nn.GRU(*args, **kwargs) [source]
```



$$z_t = \sigma(W_z \cdot [h_{t-1}, x_t])$$

$$r_t = \sigma(W_r \cdot [h_{t-1}, x_t])$$

$$\tilde{h}_t = \tanh(W \cdot [r_t * h_{t-1}, x_t])$$

$$h_t = (1 - z_t) * h_{t-1} + z_t * \tilde{h}_t$$

프로젝트: 챗봇시스템 구현

❖ Prob 2. Fill in the blanks (each 5 pts) of `parlai/agents/seq2seq/seq2seq.py` and run (35pts)

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')

• 2, 3. fill here

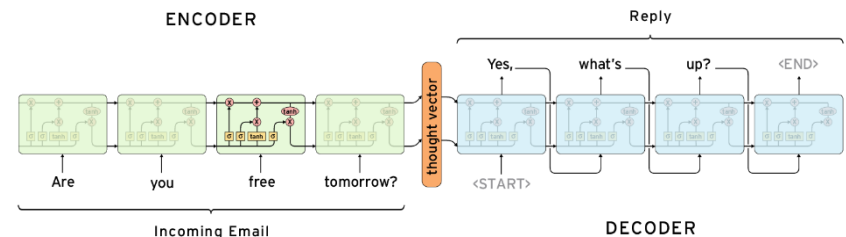
- `self.encoder = nn.GRU(?)`
- `self.decoder = nn.GRU(?)`

- Using <http://pytorch.org/docs/master/>

```
class torch.nn.GRU(*args, **kwargs) [source]
```

• Answer:

```
self.encoder = nn.GRU( hsz, hsz, opt['numlayers'] )  
self.decoder = nn.GRU( hsz, hsz, opt['numlayers'] )
```



프로젝트: 챗봇시스템 구현

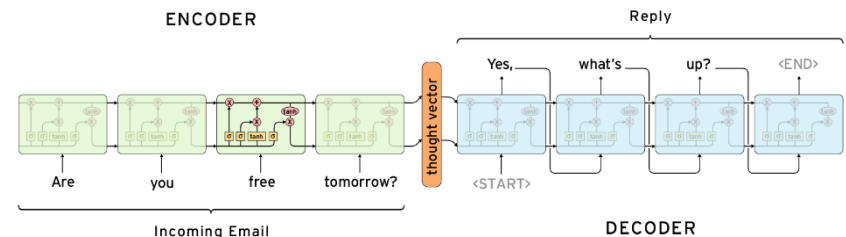
❖ Prob 2. Fill in the blanks (each 5 pts) of `parlai/agents/seq2seq/seq2seq.py` and run (35pts)

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')

• 4. fill here

- `self.h2o = nn.Linear(?)`

- Using <http://pytorch.org/docs/master/>



```
class torch.nn.Linear(in_features, out_features, bias=True) [source]
```

프로젝트: 챗봇시스템 구현

❖ Prob 2. Fill in the blanks (each 5 pts) of `parlai/agents/seq2seq/seq2seq.py` and run (35pts)

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')

• 4. fill here

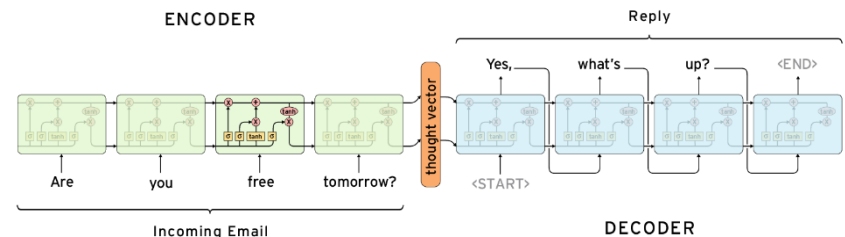
- `self.h2o = nn.Linear(?)`

- Using <http://pytorch.org/docs/master/>

```
class torch.nn.Linear(in_features, out_features, bias=True) [source]
```

• Answer:

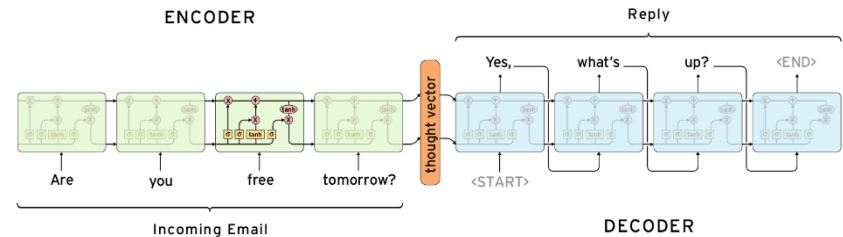
```
self.h2o = nn.Linear( hsz, len(self.dict) )
```



프로젝트: 챗봇시스템 구현

❖ Prob 2. Fill in the blanks (each 5 pts) of parlai/agents/seq2seq/seq2seq.py and run (35pts)

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')



- 5~7. fill here

```
151     def hidden_to_idx(self, hidden, dropout=False):
152         """Converts hidden state vectors into indices into the dictionary."""
153         if hidden.size(0) > 1:
154             raise RuntimeError('bad dimensions of tensor:', hidden)
155         hidden = hidden.squeeze(0)
156         5. scores = # FILL HERE
157         6. if dropout:
158             scores = # FILL HERE
159         7. scores = # FILL HERE
160         _max_score, idx = scores.max(1)
161         return idx, scores
```

프로젝트: 챗봇시스템 구현

❖ **Prob 2. Fill in the blanks (each 5 pts) of parlai/agents/seq2seq/seq2seq.py and run (35pts)**

- # FILL HERE
- (if you want to find the location, type '/# FILL HERE')
- **5~7. fill here**
- **Under** def hidden_to_idx(self, hidden, dropout=False):
- **Answer:**
 scores = self.h2o(hidden)
 If dropout:
 scores = self.dropout(scores)
 scores = self.softmax(scores)

프로젝트: 챗봇시스템 구현

- ❖ **Prob 2. Fill in the blanks (each 5 pts) of `parlai/agents/seq2seq/seq2seq.py` and run (35pts)**

Run the code now

```
python examples/train_model.py -m seq2seq -t opensubtitles -bs 32 -mf  
'data/OpenSubtitles'
```

- ❖ **Prob 3. Propose idea to improve this model (30pts)**