

DAA Assignment 4

Name: Vishal Sule

Roll no.: 234

PRN: 0120190064

Problem statement: Design & Implement Prims Algorithm using Greedy Approach. Calculate the time complexity of the algorithm

Code:

```
#include<iostream>

#include <bits/stdc++.h>

#include <algorithm>

#include <chrono>


using namespace std;

using namespace std::chrono;


class disjointset
{
    public:
        int djset[20];
        disjointset(int v)
        {
            for (int i = 0; i <= v; i++)
```

```

    {
        djset[i] = i;
    }
}

int find_root(int v)
{
    while (v != djset[v])
    {
        v = djset[v];
    }
    return v;
}

void take_union(int v1, int v2)
{
    int r1 = find_root(v1);
    int r2 = find_root(v2);
    if (v1 == r1 && v2 == r2)
    {
        djset[v1] = v2;
    }
    else if (v1 != r1 && v2 == r2)
    {
        djset[v2] = v1;
    }
    else if (v1 == r1 && v2 != r2)
    {

```

```
        djset[v1] = v2;
    }
    else if (v1 != r1 && v2 != r2)
    {
        djset[r1] = r2;
    }
}

};
```

```
class edge
```

```
{
    public:
        int v1;
        int v2;
        int wt;
};
```

```
class prims_graph
```

```
{
    public:
        int v_p;
        int data[20][20];
        prims_graph(int vt)
        {
            v_p = vt;
        }
};
```

```

        void prims_algorithm();
};

void prims_graph::prims_algorithm()
{
    int sv;
    int visited[v_p];
    int i, j, k;
    edge ed[20];
    edge mst[20];
    edge discarded_edge[20];
    int mst_ctr = 0;
    int edge_ctr = 0;
    int mst_flag = 0;
    int discarded_ctr = 0;
    int discarded_flag = 0;
    disjointset d(v_p);
    for (i = 0; i < v_p; i++)
    {
        visited[i] = 0;
    }
    cout << "\n Enter the start vertex : ";
    cin >> sv;
    sv = sv - 1;
    visited[sv] = 1;
    while (1)

```

```

{
    int visited_flag = 0;
    for (i = 0; i < v_p; i++)
    {
        if (visited[i] == 1)
            visited_flag++;
    }
    if (visited_flag == v_p)
        break;
    edge_ctr = 0;
    for (i = 0; i < v_p; i++)
    {
        if (visited[i] == 1)
        {
            for (j = 0; j < v_p; j++)
            {
                if (data[i][j] != 999)
                {
                    // before adding that edge in ed array check whether it has
already
                    // been added in MST array
                    mst_flag = 0;
                    for (int k = 0; k < mst_ctr; k++)
                    {
                        if ((mst[k].v1 == i && mst[k].v2 == j) || (mst[k].v1 == j &&
mst[k].v2 == i))
                        {

```

```

        mst_flag = 1;
        break;
    }
}
discarded_flag = 0;
for (int k = 0; k < discarded_ctr; k++)
{
    if ((discarded_edge[k].v1 == i && discarded_edge[k].v2 == j) ||
(discarded_edge[k].v1 == j && discarded_edge[k].v2 == i))
    {
        discarded_flag = 1;
        break;
    }
}
// edge is not in MST array and is not present in discarded array
if (mst_flag == 0 && discarded_flag == 0)
{
    ed[edge_ctr].v1 = i;
    ed[edge_ctr].v2 = j;
    ed[edge_ctr].wt = data[i][j];
    edge_ctr++;
}
}
}
}
}
edge min_edge;

```

```

min_edge.v1 = 0;
min_edge.v2 = 0;
min_edge.wt = 999;
for (k = 0; k < edge_ctr; k++)
{
    if (ed[k].wt < min_edge.wt)
    {
        min_edge.v1 = ed[k].v1;
        min_edge.v2 = ed[k].v2;
        min_edge.wt = ed[k].wt;
    }
}

// we will get min wt edge in min_edge variable
int r1 = d.find_root(min_edge.v1);
int r2 = d.find_root(min_edge.v2);
if (r1 != r2)
{
    mst[mst_ctr].v1 = min_edge.v1;
    mst[mst_ctr].v2 = min_edge.v2;
    mst[mst_ctr].wt = min_edge.wt;
    mst_ctr++;
    d.take_union(min_edge.v1, min_edge.v2);
    visited[min_edge.v1] = 1;
    visited[min_edge.v2] = 1;
}

else // including the edge in MST will create a cycle so discard it

```

```

    {
        discarded_edge[discarded_ctr].v1 = min_edge.v1;
        discarded_edge[discarded_ctr].v2 = min_edge.v2;
        discarded_edge[discarded_ctr].wt = min_edge.wt;
        discarded_ctr++;
    }
}

int sum = 0;
cout << "\n MST is: ";
for (i = 0; i < mst_ctr; i++)
{
    cout << endl
        << " " << mst[i].v1 + 1 << " to " << mst[i].v2 + 1 << " ==> " << mst[i].wt;
    sum = sum + mst[i].wt;
}
cout << "\nTotal is " << sum;
}

```

```

class kruskal_graph
{
    public:
        int v_k;
        int e;
        edge ed[20];
        kruskal_graph(int vertices, int edges)
        {

```



```

        v_k = vertices;
        e = edges;
    }
    void accept_graph();
    void display_graph();
    void kruskal_mst();
    void sort_edges();
};

```

```

int main()
{
    int ch = 1;
    int v_k, e;
    int v_p;

    cout << "----->>> Prims Algorithm <<<----- " << endl;
    cout << "\n Enter the number of vertices in the graph: ";
    cin >> v_p;
    prims_graph g1(v_p);
    for (int i = 0; i < v_p; i++)
        g1.data[i][i] = 999;
    for (int i = 0; i < v_p; i++)
    {
        for (int j = i + 1; j < v_p; j++)
        {

```

```

        cout << "\n Enter the cost of edge between " << i + 1 << " to " << j + 1 <<
": ";

        cin >> g1.data[i][j];

        g1.data[j][i] = g1.data[i][j];

    }

}

auto start = high_resolution_clock::now();

    g1.prims_algorithm();

    auto stop = high_resolution_clock::now();
    auto duration = duration_cast<nanoseconds>(stop - start);

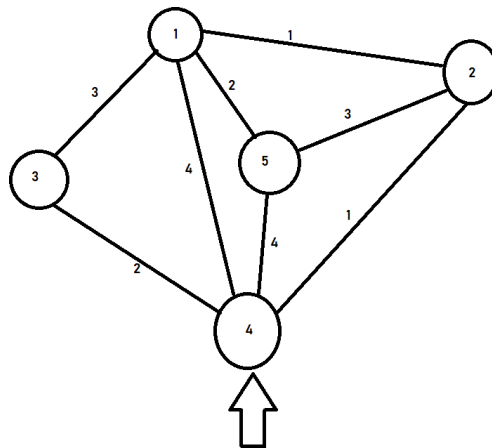
    cout << "\nTime taken by function: " << duration.count() << "
nanoseconds";

return 0;

}

```

Graph :



Output:

```
----->>> Prims Algorithm <<<-----
Enter the number of vertices in the graph: 5
Enter the cost of edge between 1 to 2 : 1
Enter the cost of edge between 1 to 3 : 3
Enter the cost of edge between 1 to 4 : 4
Enter the cost of edge between 1 to 5 : 2
Enter the cost of edge between 2 to 3 : 999
Enter the cost of edge between 2 to 4 : 1
Enter the cost of edge between 2 to 5 : 3
Enter the cost of edge between 3 to 4 : 2
< Enter the cost of edge between 3 to 5 : 999
Enter the cost of edge between 4 to 5 : 4
Enter the start vertex : 4

MST is:
4 to 2 ==> 1
2 to 1 ==> 1
1 to 5 ==> 2
4 to 3 ==> 2
Total is 6
Time taken by function: 2300200114 nanoseconds
...Program finished with exit code 0
GDB Press ENTER to exit console.
```