



# Bayesian Machine Learning

14/06/21 - François HU

<https://curiousml.github.io/>

# Outline

1 Bayesian statistics

2 Latent variable models

3 Variational Inference

4 **Markov Chain Monte Carlo**

- Monte Carlo Estimation
- MCMC and differences with VI

5 Extensions and oral presentations

0 Remarks

# 1 Monte Carlo estimation

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Yes with usual simulations or MCMC

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**Starting point** : we know how to simulate a pseudo-random uniform  $U \sim \mathcal{U}(0,1)$

**For « usual » distributions** : both **discrete** and **continuous r.v.** can be sampled thanks to the uniform distribution

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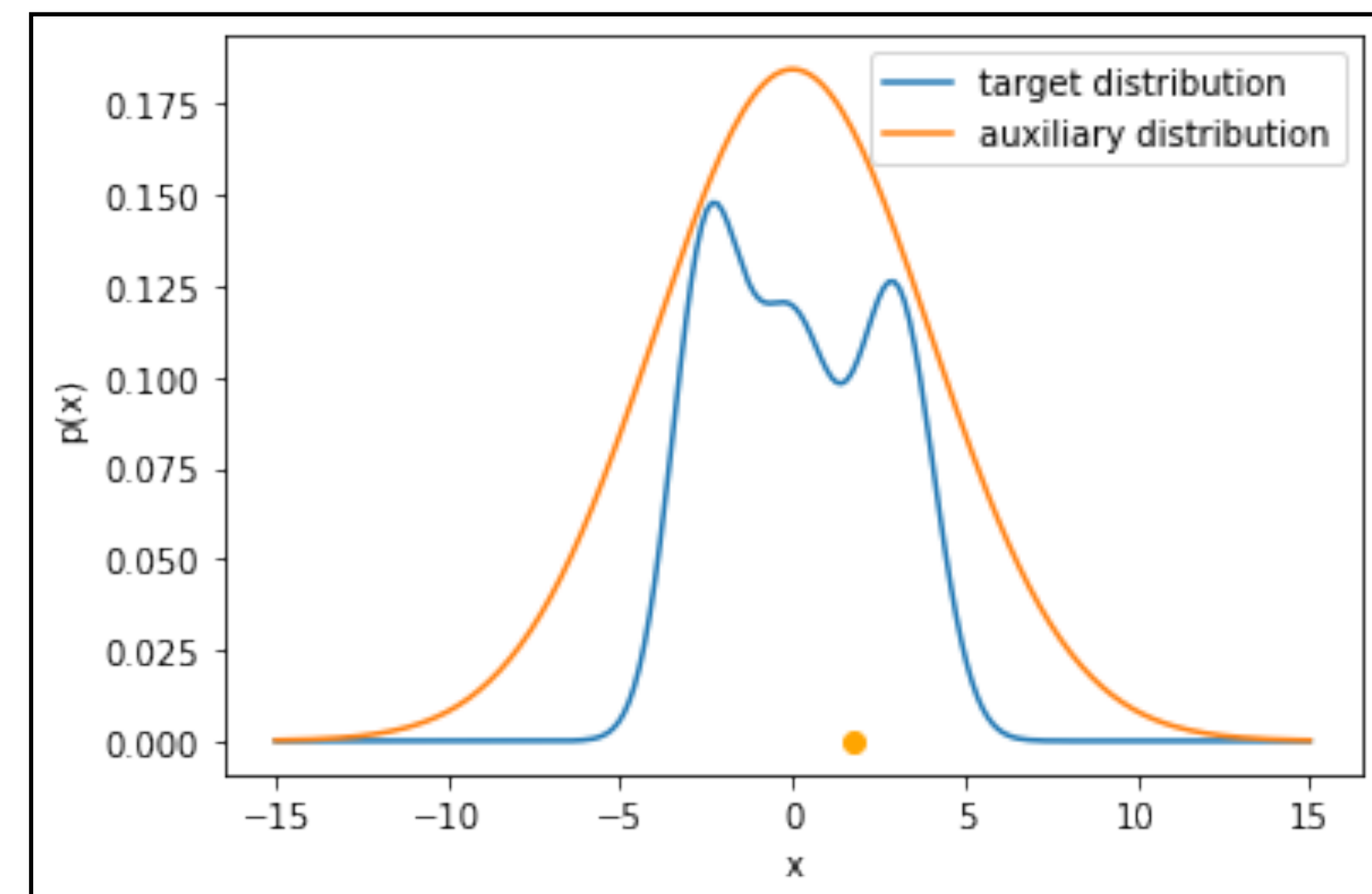
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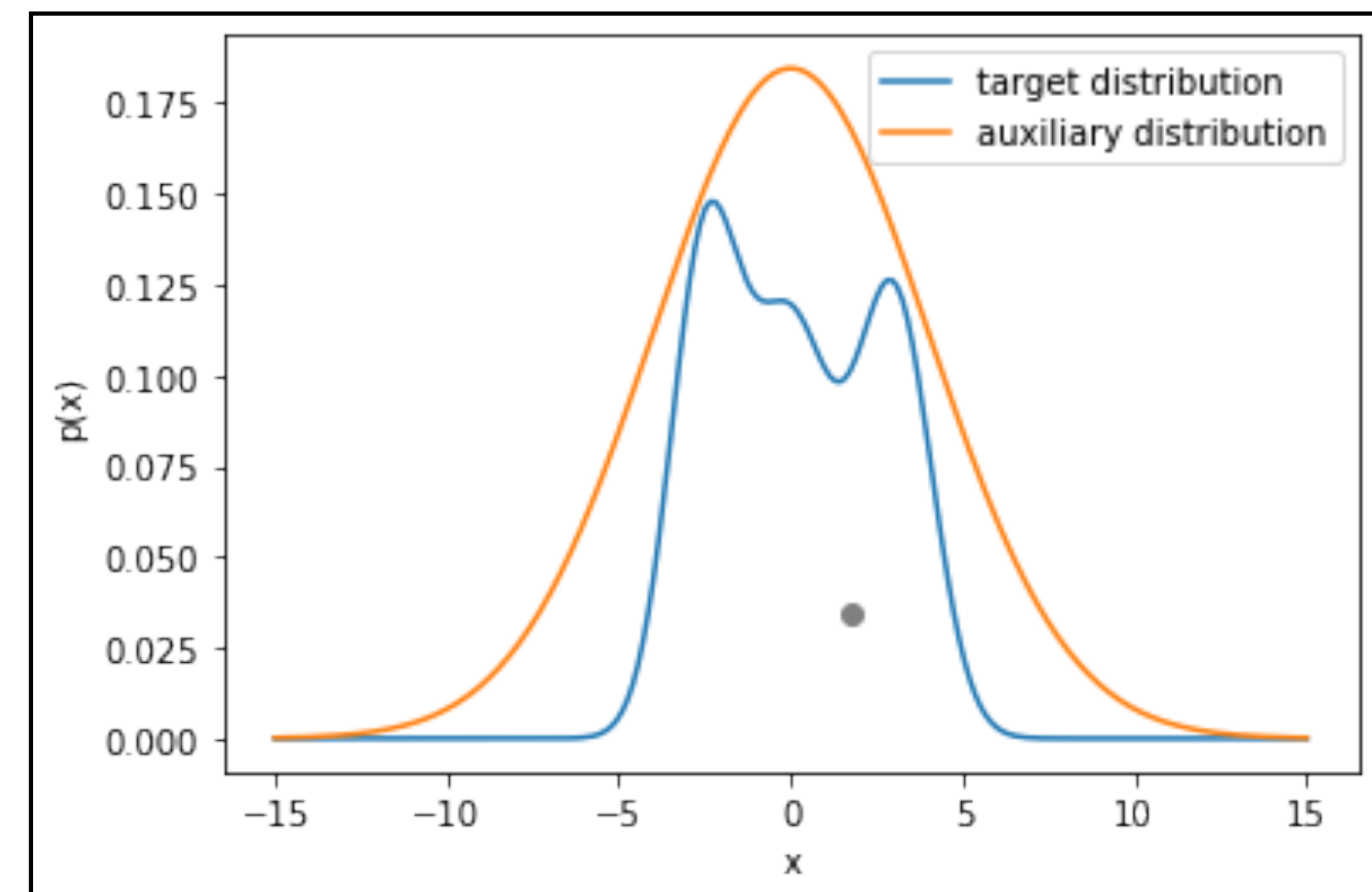
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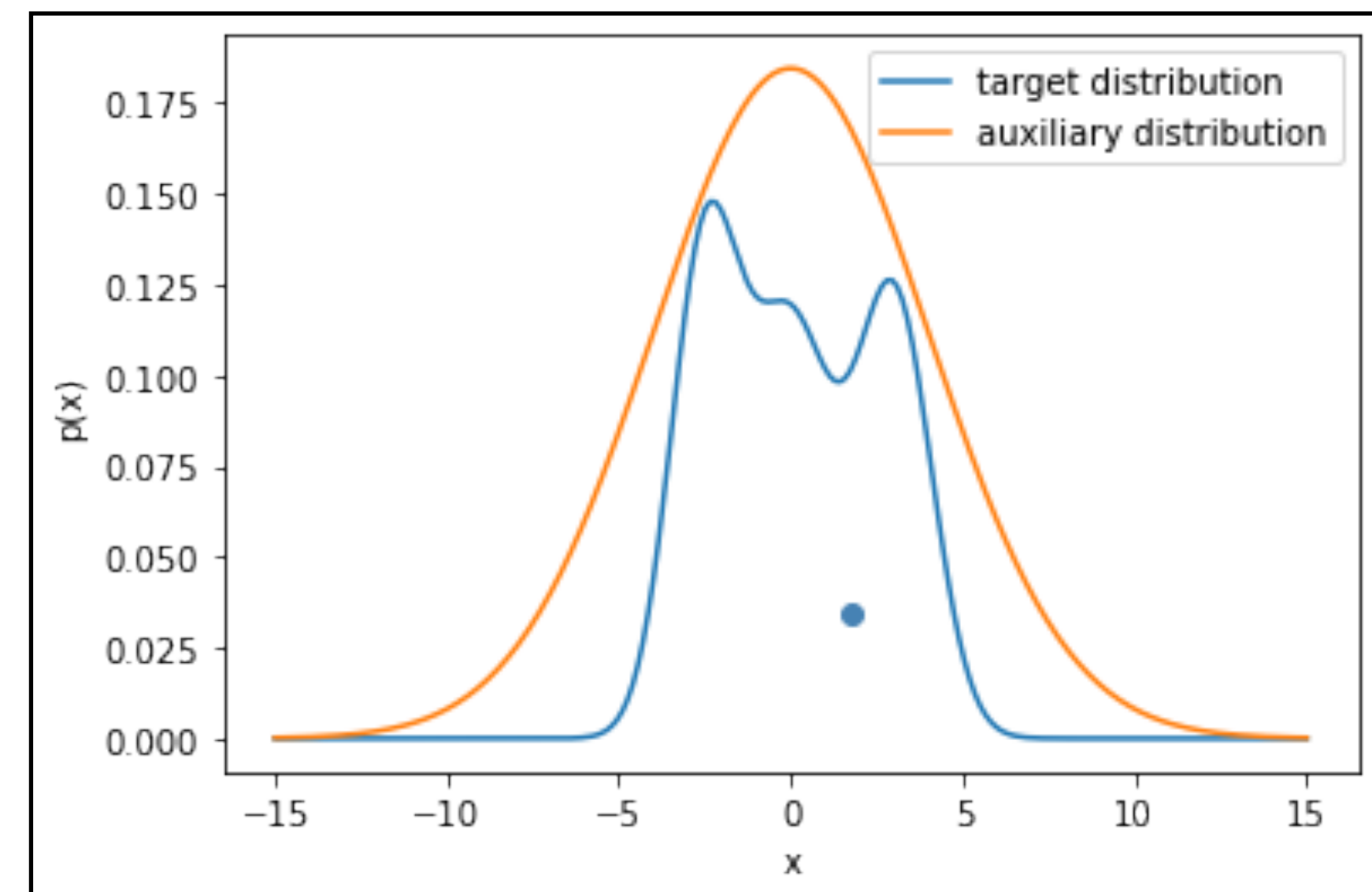
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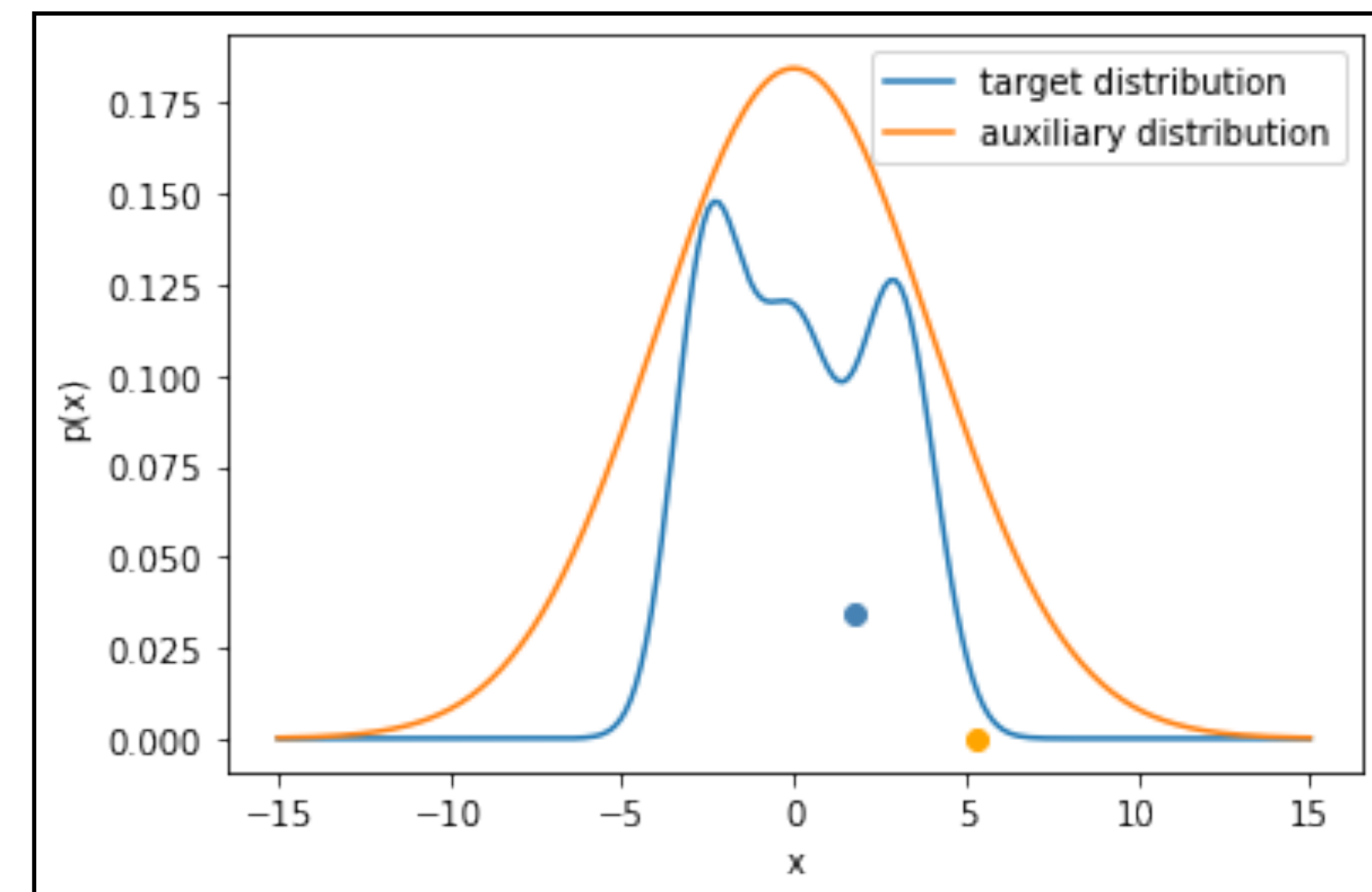
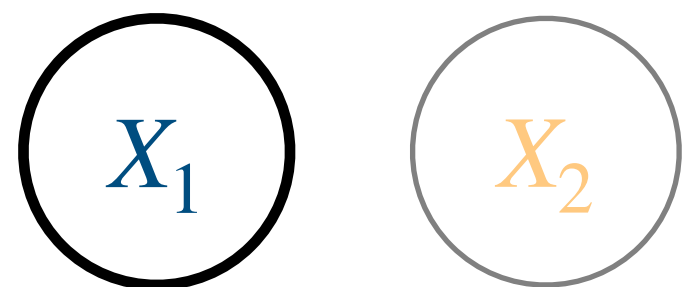
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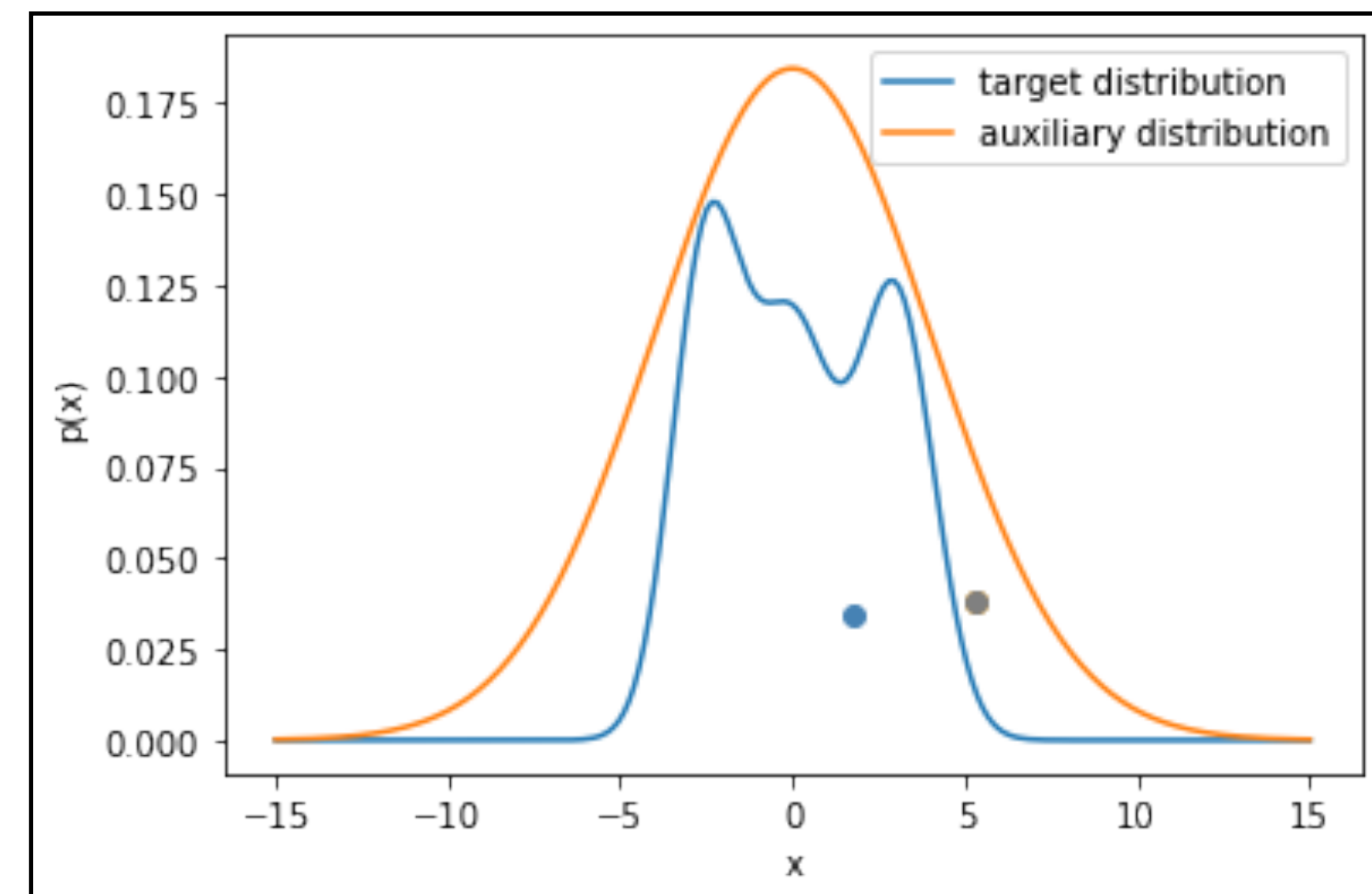
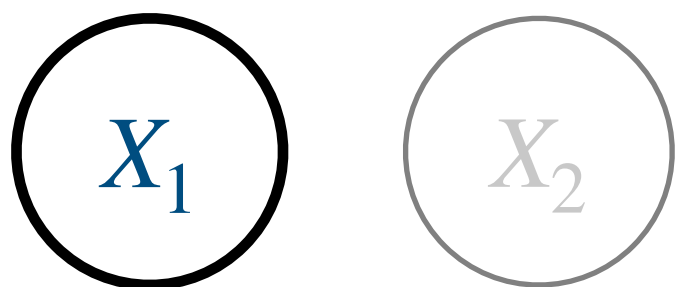
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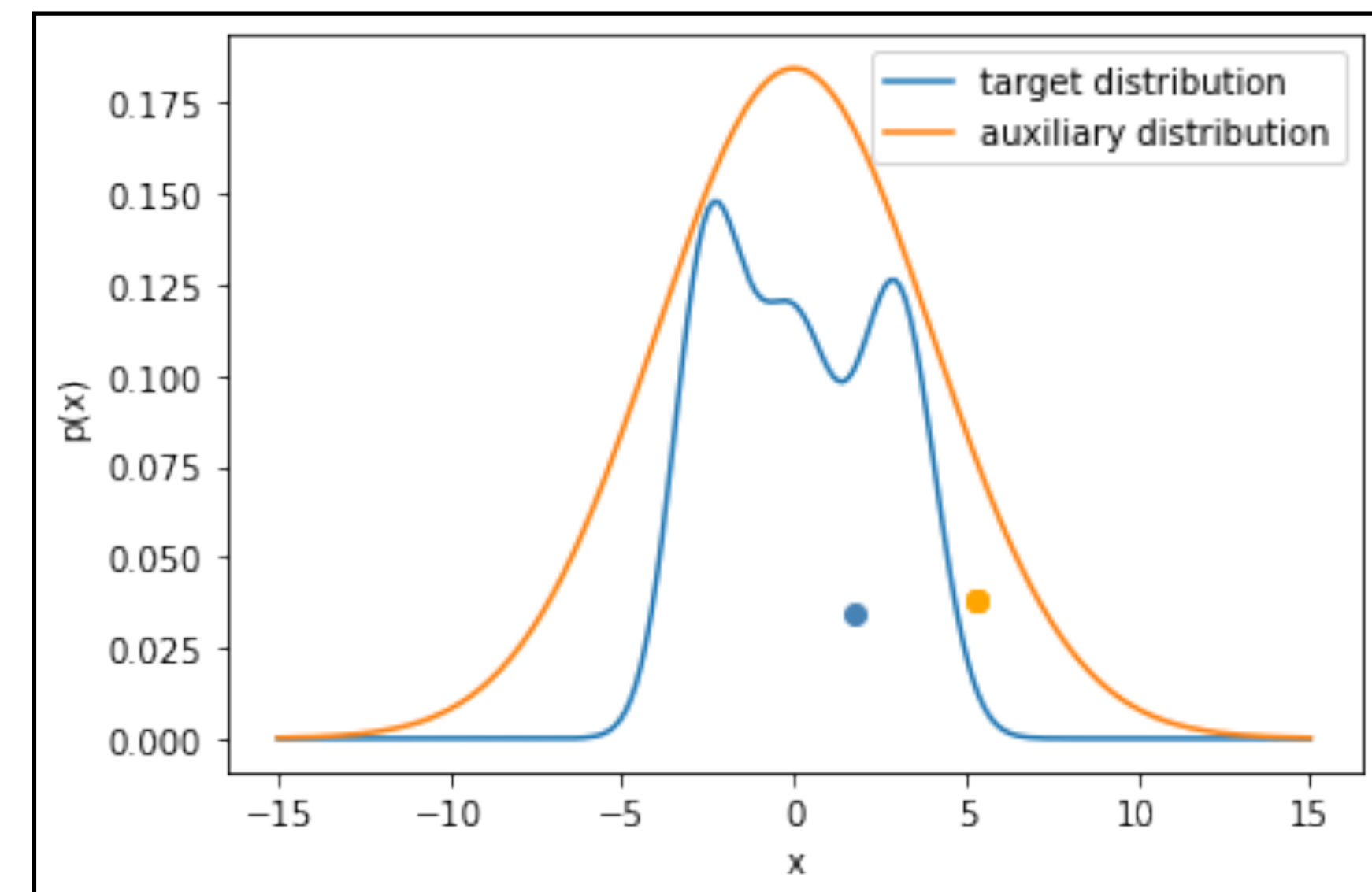
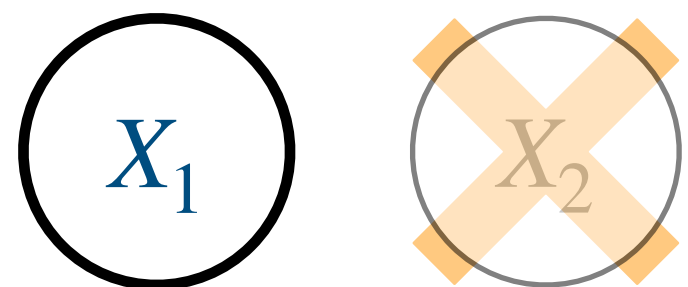
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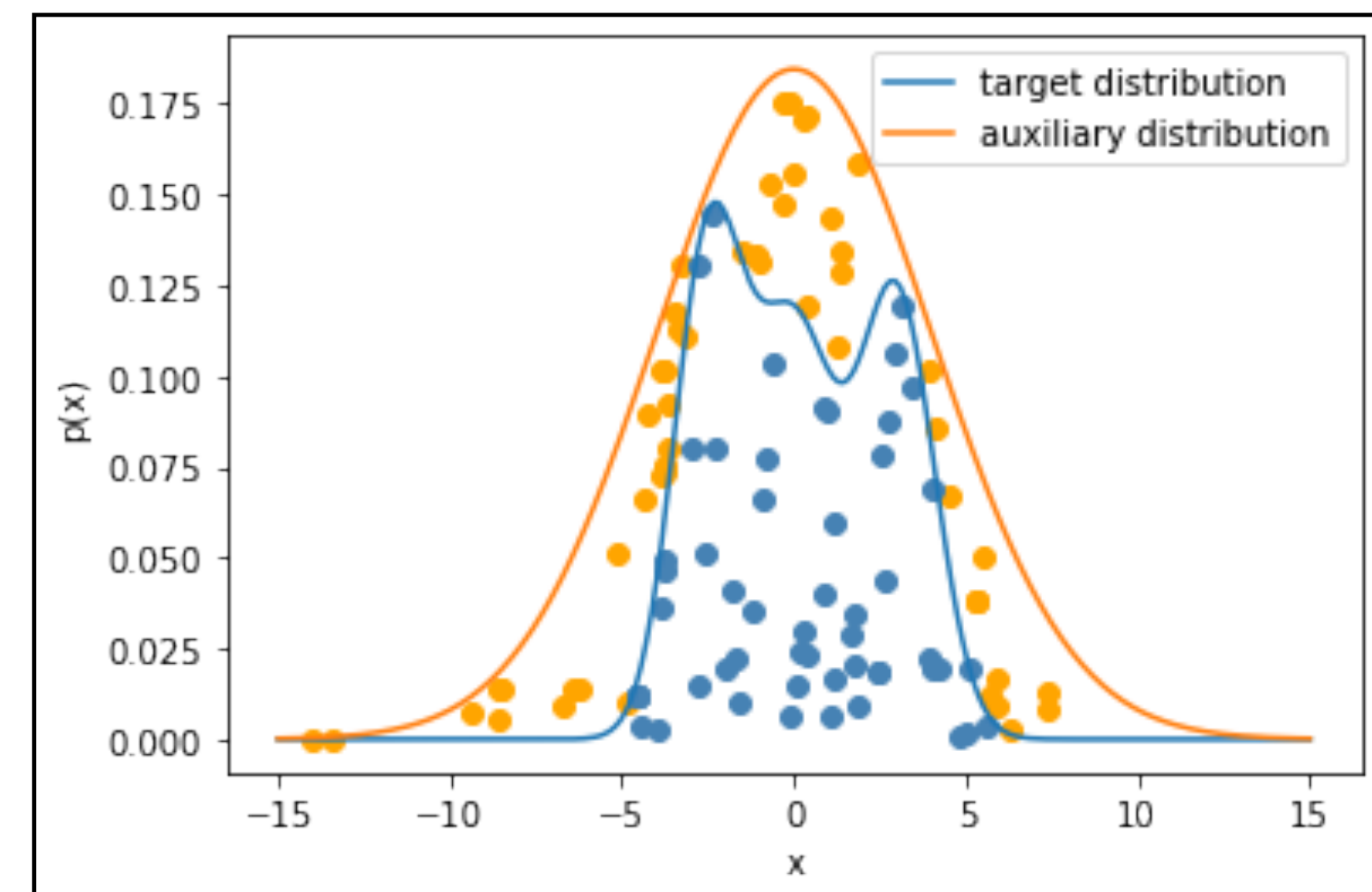
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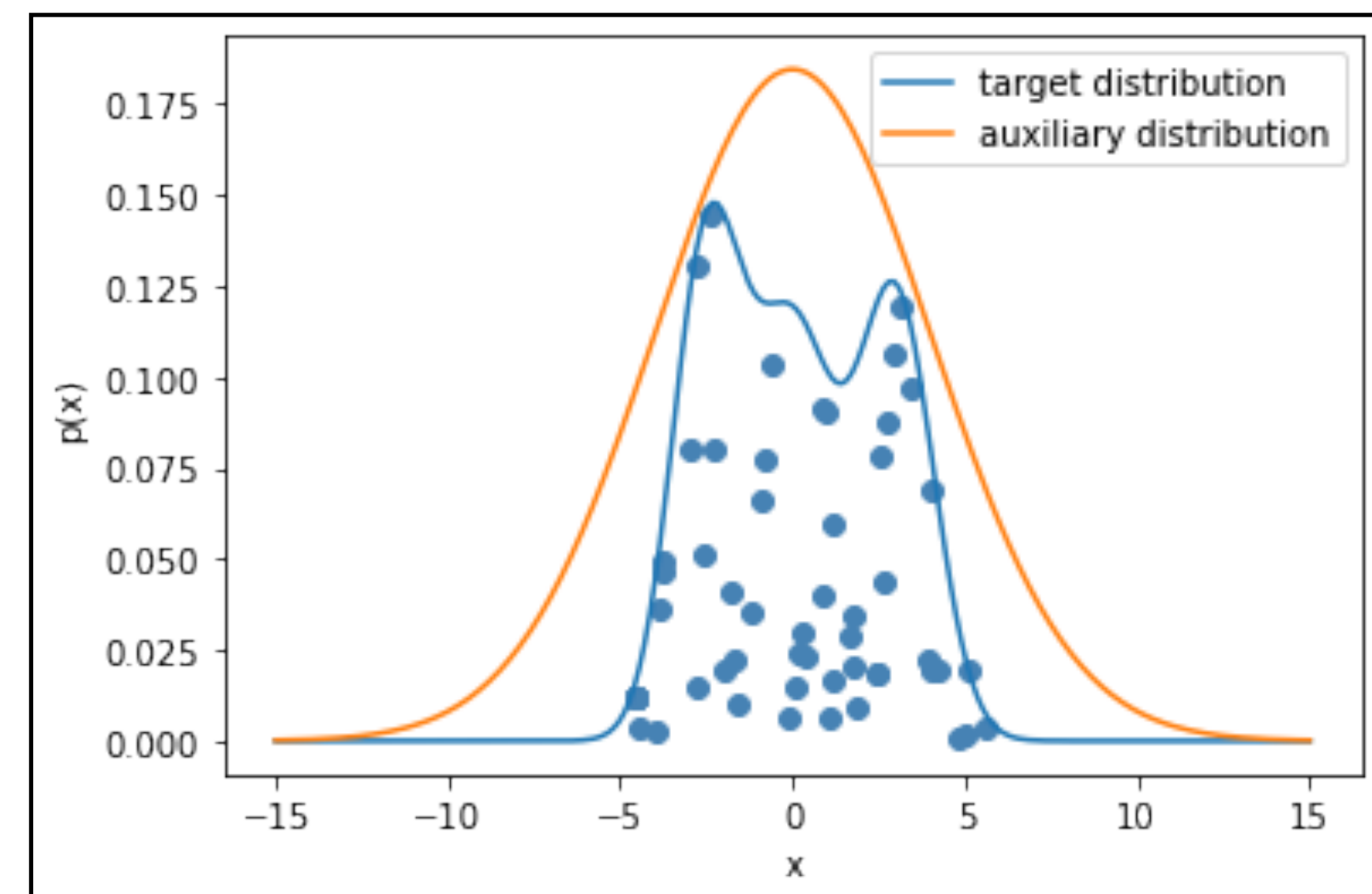
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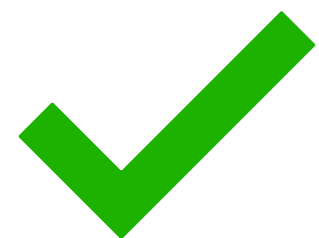
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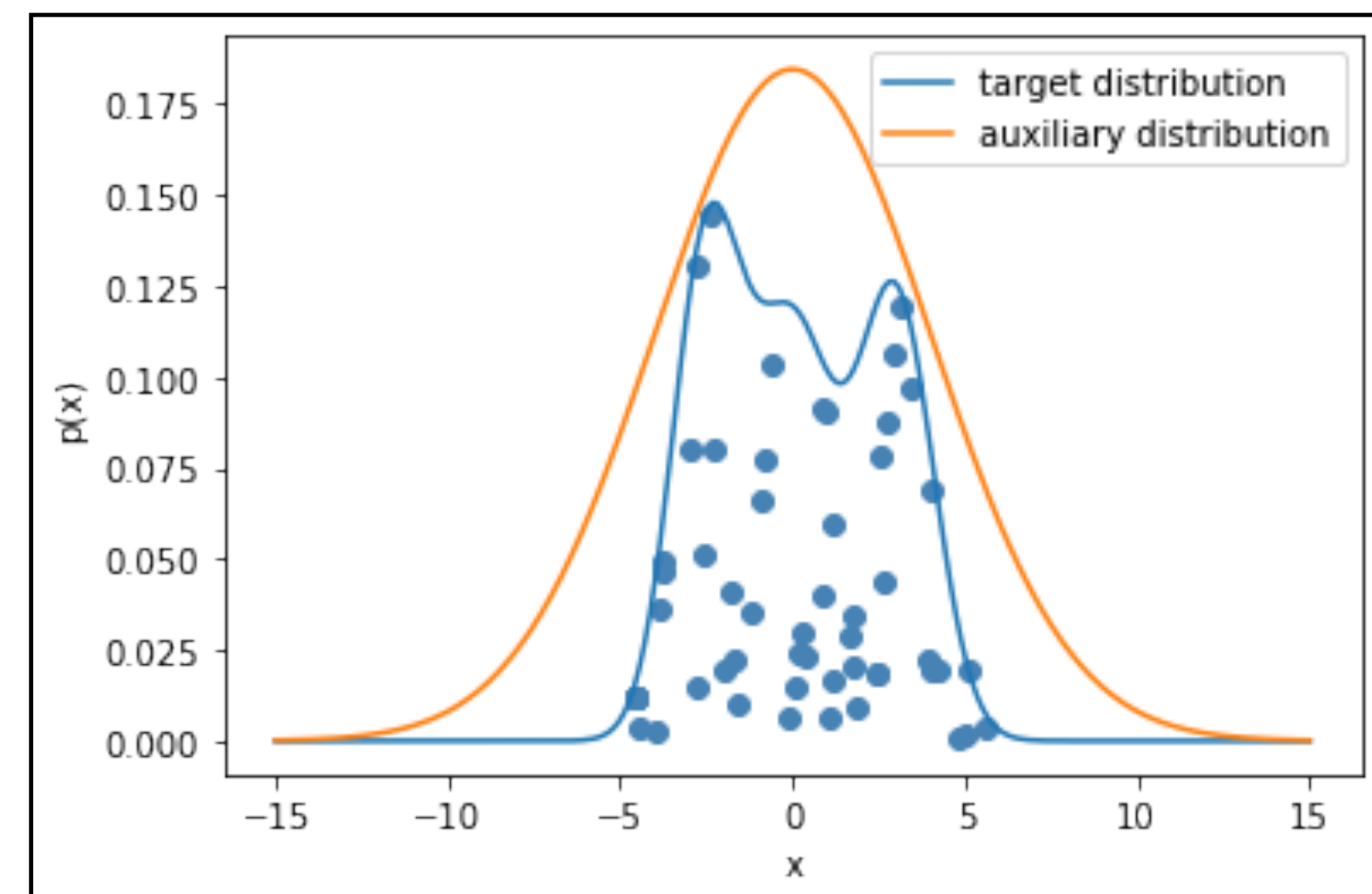
1. generate sample  $x_i \sim Q$  (**auxiliary distribution**)
2. generate sample  $u \sim \mathcal{U}(0, \text{const} \cdot Q(x_i))$
3. if  $u \leq P(x_i)$  then **accept**  $x_i$  else **reject**.



works for most distribution



if the « **gaps** » between  $P$  and  $Q$  are too large,  
we reject most of the sample



$X_1$

$X_2$

...

$X_n$

# 1. Monte Carlo estimation

## Usual simulations : the power of uniform distribution

**Starting point** : we know how to simulate a pseudo-random uniform  $U \sim \mathcal{U}(0,1)$

**For « usual » distributions** : both **discrete** and **continuous r.v.** can be sampled thanks to the uniform distribution

| **In practice (with python)** we can easily sample them (via **scipy** and **numpy** for example)

**Otherwise** : if there isn't an analytical way to sample it then

| **Rejection sampling** algorithm.

| Assumption : we can compute **distribution's pdf**  $P$  and sample from an **auxiliary distribution**  $Q$  s.t.  $P \leq \text{const} \times Q$

### Algorithm

1. generate sample  $x_i \sim Q$  (**auxiliary distribution**)
2. generate sample  $u \sim \mathcal{U}(0, \text{const} \cdot Q(x_i))$
3. if  $u \leq P(x_i)$  then **accept**  $x_i$  else **reject**.

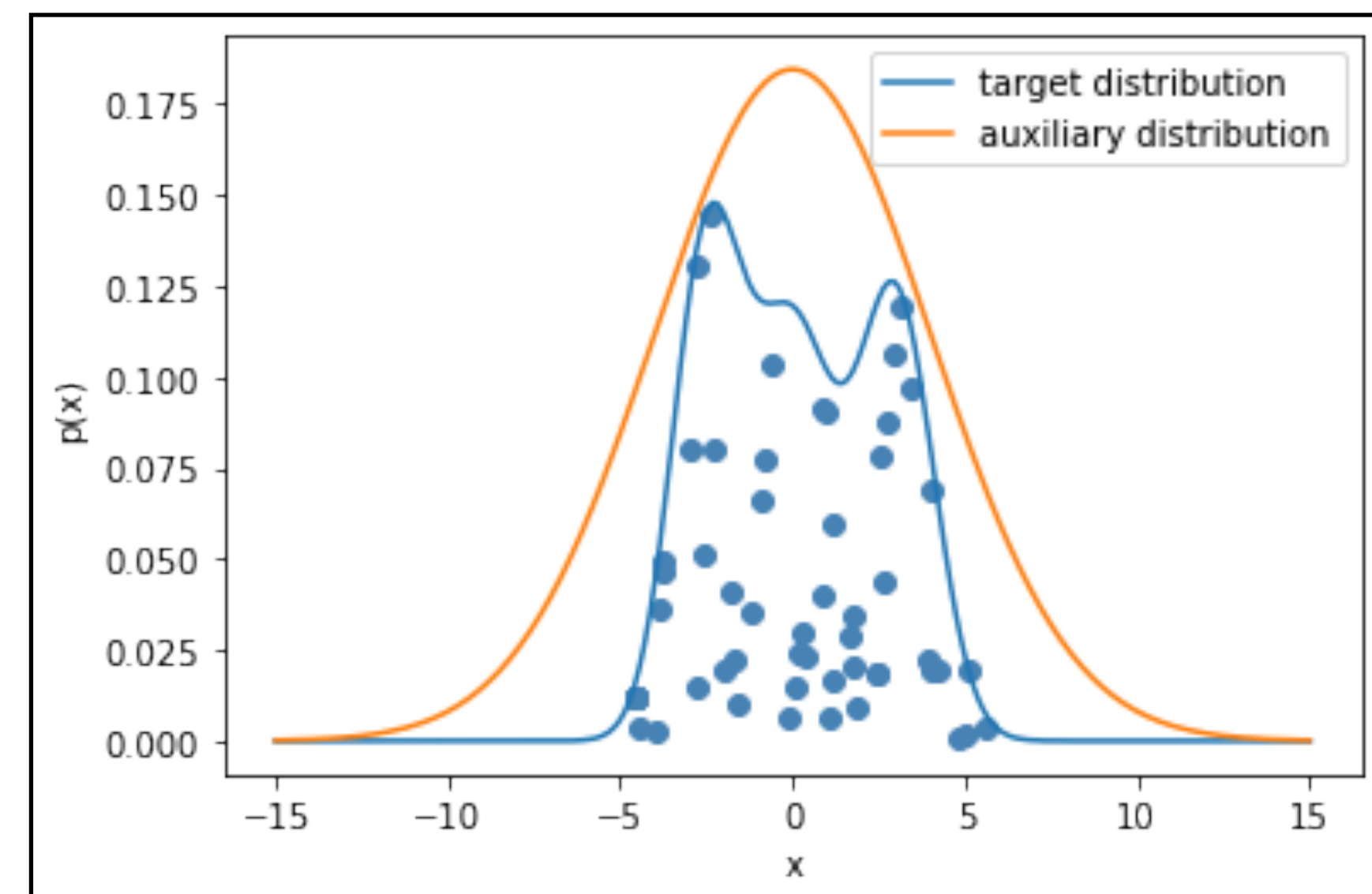


works for most distribution



if the « **gaps** » between  $P$  and  $Q$  are too large,  
we reject most of the sample

use MCMC



$X_1$

$X_2$

...

$X_n$

## **2 Markov Chain Monte Carlo : Definition**

## 2. Markov Chain Monte Carlo

### Definition : Monte Carlo sampling

**Monte Carlo sampling** : generates **independent** samples from the probability distribution in order to estimate an expected value


$$X_1$$

$$X_2$$

...

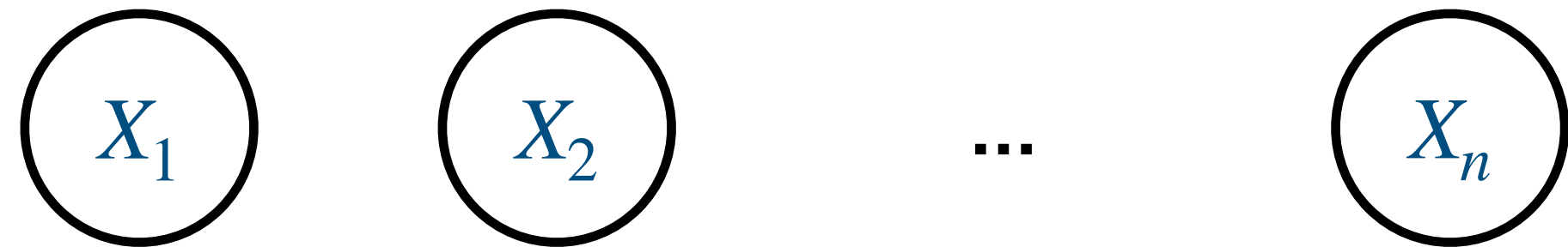
$$X_n$$

where  $X_1, \dots, X_n \sim P$  i.i.d

## 2. Markov Chain Monte Carlo

### Definition : Markov Chain

**Monte Carlo sampling** : generates **independent** samples from the probability distribution in order to estimate an expected value



where  $X_1, \dots, X_n \sim P$  i.i.d

**Markov Chain** : generates a sequence of r.v. where the *next* variable is probabilistically dependent upon the *current* variable.

$P$  is called **stationary** if  $P(x') = \sum_{x \in \text{supp}(X)} T(x, x') \cdot P(x)$

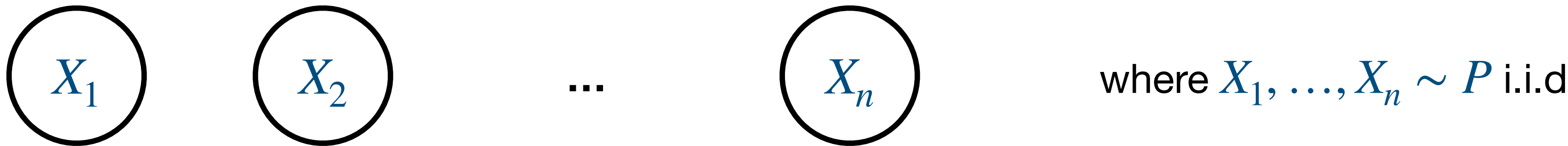
$T(x, x')$  the transition probability of being in the state  $x'$  given the current state  $x$



# 2. Markov Chain Monte Carlo

## Definition : Markov Chain Monte Carlo

**Monte Carlo sampling** : generates **independent** samples from the probability distribution in order to estimate an expected value

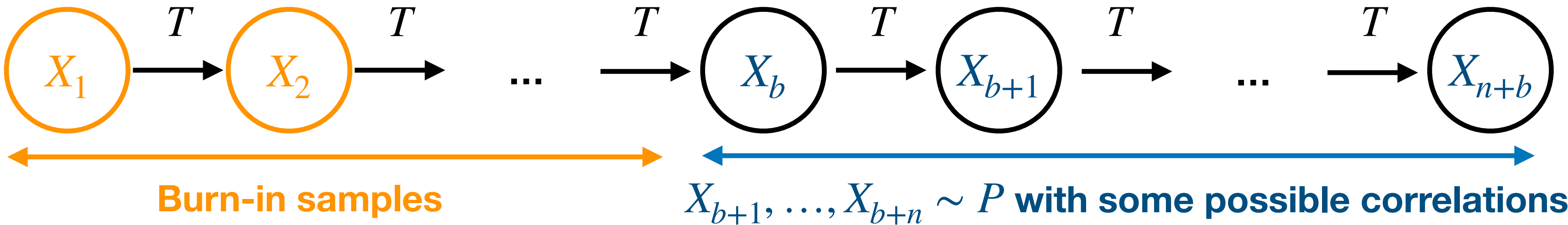


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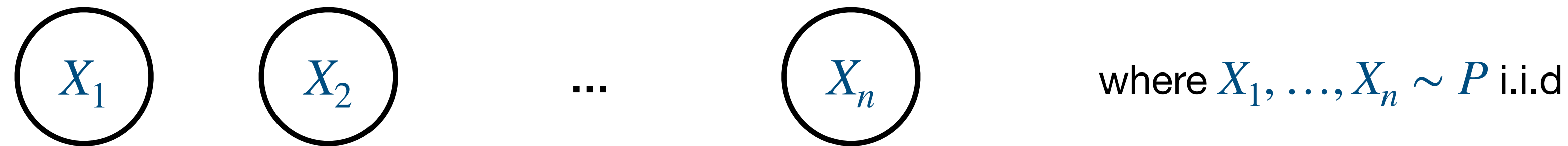
**Markov Chain Monte Carlo sampling** : a sequence of *Monte Carlo Samples* where the *next* sample is dependent upon the *current* sample



## 2. Markov Chain Monte Carlo

### Definition : Markov Chain Monte Carlo

**Monte Carlo sampling** : generates **independent** samples from the probability distribution in order to estimate an expected value

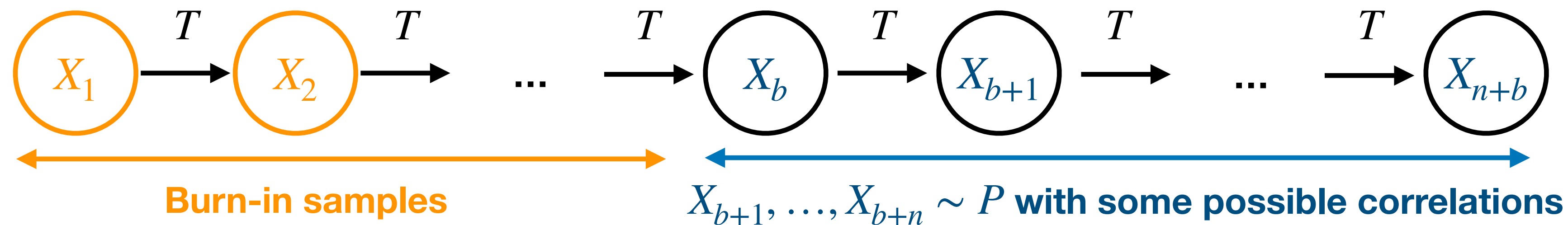


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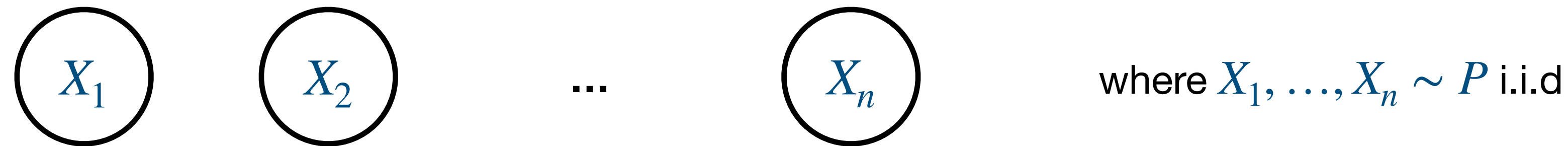
**Objective** : Build a Markov Chain that converges to the target distribution  $P$  no matter the starting point



## 2. Markov Chain Monte Carlo

### Definition : Markov Chain Monte Carlo

**Monte Carlo sampling** : generates **independent** samples from the probability distribution in order to estimate an expected value

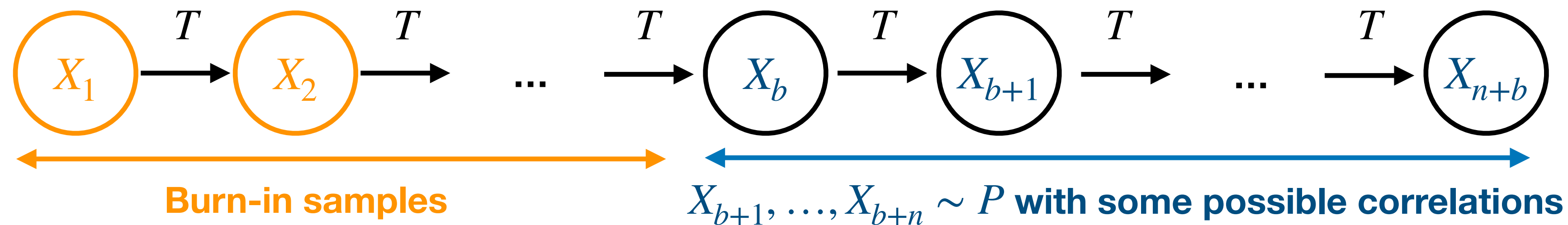


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$T(x, x')$  the transition probability of being in the state  $x'$  given the current state  $x$

**Markov Chain Monte Carlo sampling** : a sequence of *Monte Carlo Samples* where the *next* sample is dependent upon the *current* sample



**Objective** : Build a Markov Chain that converges to the target distribution  $P$  no matter the starting point

**Theorem** : if  $T(x, x') > 0$  for all  $x, x'$  then there exists an *unique* **stationary** and **convergent** distribution

## **3 Markov Chain Monte Carlo : Algorithms**

# 3. Markov Chain Monte Carlo

## Algorithm : Gibbs sampling

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

**Remark** : we denote  $x^{(i)} := (x_1^{(i)}, \dots, x_d^{(i)})$  ;  $x_{-j} = (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_d)$  ;  $x_{m:n} = (x_m, x_{m+1}, \dots, x_n)$

### Gibbs Sampling Algorithm

- **Hypothesis** : The conditional  $P(x_j | x_{-j})$  can be sampled
- **Initialisation** :  $x^{(0)} = (0, \dots, 0)$  or random values
- **Repeat** :

# 3. Markov Chain Monte Carlo

## Algorithm : Gibbs sampling

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- **Hypothesis** : The conditional  $P(x_j | x_{-j})$  can be sampled
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- **Repeat** :

sample  $x^{(i)} = (x_1^{(i)}, \dots, x_d^{(i)})$  based on  $x^{(i-1)} = (x_1^{(i-1)}, \dots, x_d^{(i-1)})$

$$x_1^{(i)} \sim P(x_1 | x_2^{(i-1)}, x_3^{(i-1)}, \dots, x_d^{(i-1)})$$

# 3. Markov Chain Monte Carlo

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$$x_1^{(i)} \sim P(x_1 | x_2^{(i-1)}, x_3^{(i-1)}, \dots, x_d^{(i-1)})$$

$$x_2^{(i)} \sim P(x_2 | x_1^{(i)}, x_3^{(i-1)}, \dots, x_d^{(i-1)})$$

# 3. Markov Chain Monte Carlo

## Algorithm : Gibbs sampling

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...

$$x_d^{(i)} \sim P(x_d | x_2^{(i)}, x_3^{(i)}, \dots, x_d^{(i-1)})$$

# 3. Markov Chain Monte Carlo

## Algorithm : Gibbs sampling

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

**Remark** : we denote  $x^{(i)} := (x_1^{(i)}, \dots, x_d^{(i)})$  ;  $x_{-j} = (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_d)$  ;  $x_{m:n} = (x_m, x_{m+1}, \dots, x_n)$

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for each position,  $x_k^{(i)} \sim P(x_k | x_{1:k-1}^{(i)}, x_{k+1:d}^{(i-1)})$

# 3. Markov Chain Monte Carlo

## Algorithm : Gibbs sampling

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

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for each position,  $x_k^{(i)} \sim P(x_k | x_{1:k-1}^{(i)}, x_{k+1:d}^{(i-1)})$

sometimes it can converge slowly to the desired distribution

sometimes Gibbs samples can be too correlated



# 3. Markov Chain Monte Carlo

## Algorithm : Gibbs sampling

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

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for each position,  $x_k^{(i)} \sim P(x_k | x_{1:k-1}^{(i)}, x_{k+1:d}^{(i-1)})$

sometimes it can converge slowly to the desired distribution

Use a variant Gibbs sampling : **Metropolis-Hastings**  
sometimes Gibbs samples can be too correlated

# 3. Markov Chain Monte Carlo

## Algorithm : Metropolis-Hastings

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

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### Metropolis-Hastings Algorithm

- **Hypothesis** : Let  $P = \hat{P}/\text{const}$  where  $\hat{P}$  can be calculated and let  $Q$  be an **auxiliary distribution** we can sample from
- **Initialisation** :  $x^{(0)} = (0, \dots, 0)$  or random values
- **Repeat** :

# 3. Markov Chain Monte Carlo

## Algorithm : Metropolis-Hastings

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

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- **Repeat** :

sample a **candidate**  $x^{(i)} \sim Q(x^{(i)} | x^{(i-1)})$  = (example of auxiliary distribution)  $\mathcal{N}(x^{(i-1)}, \sigma^2 I)$

# 3. Markov Chain Monte Carlo

## Algorithm : Metropolis-Hastings

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**Remark** : we denote  $x^{(i)} := (x_1^{(i)}, \dots, x_d^{(i)})$  ;  $x_{-j} = (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_d)$  ;  $x_{m:n} = (x_m, x_{m+1}, \dots, x_n)$

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sample a **candidate**  $x^{(i)} \sim Q(x^{(i)} | x^{(i-1)})$  = (example of auxiliary distribution)  $\mathcal{N}(x^{(i-1)}, \sigma^2 I)$

with **acceptance probability** :  $\min \left( 1, \frac{Q(x^{(i-1)} | x^{(i)}) \times \hat{P}(x^{(i)})}{Q(x^{(i)} | x^{(i-1)}) \times \hat{P}(x^{(i-1)})} \right)$  accept  $x^{(i)}$  as an sample from  $P$

# 3. Markov Chain Monte Carlo

## Algorithm : Metropolis-Hastings

**Reminder** : we want to sample  $x^{(1)}, \dots, x^{(n)} \sim P(x_1, x_2, \dots, x_d)$

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# 3. Markov Chain Monte Carlo

## Algorithm : Metropolis-Hastings

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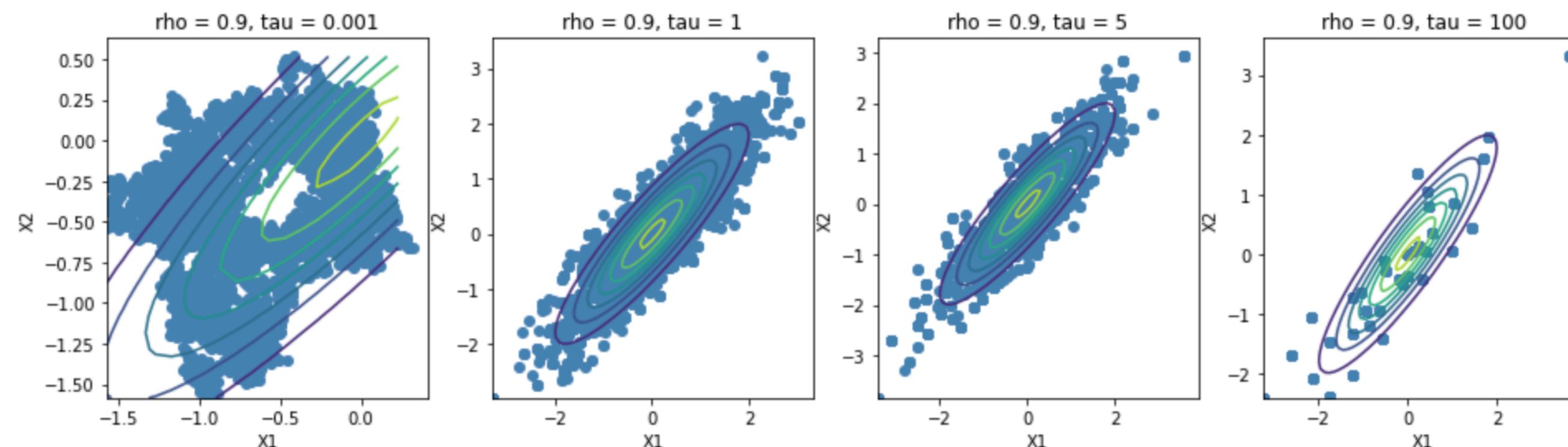
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$\tau = \sigma^2$  and  $\rho$  the correlation between two gaussians  $X_1$  and  $X_2$

3.b.

**MCMC vs VI**



# 3.b. MCMC vs VI

## pros and cons

### MCMC

#### Pros :

- Useful when the posterior is intractable
- Asymptotically exact
- Suited to small / medium dataset

#### Cons :

- Usually slower than alternatives (VI)
- Can generate dependant samples from the distribution

### VI (see lecture 3)

#### Pros :

- Useful when the posterior is intractable
- Suited to large dataset

#### Cons :

- Can never generate exact result



## **4 Applications and examples : notebook**

# Application and examples

website : <https://curiousml.github.io/>

## EPITA - École pour l'informatique et les techniques avancées (2020 - ...)

---

- Master of Science in Artificial Intelligence Systems : **Bayesian Machine Learning** by [François HU](#)
  - Training session / prerequisite : [\[Statistics with python\]](#), [\[Data\]](#)
  - Lecture 1 : [\[Bayesian statistics\]](#)
  - Practical work 1 : [\[Conjugate distributions\]](#) [\[Correction\]](#)
  - Lecture 2 : [\[Latent Variable Models and EM-algorithm\]](#)
  - Practical work 2 : [\[Probabilistic K-means and probabilistic PCA\]](#) [\[corr1, HTML\]](#) [\[corr1, ipynb\]](#)
  - Lecture 3 : [\[Variational Inference and intro to NLP\]](#)
  - Practical work 3 : [\[Topic Modeling with LDA\]](#) [\[No correction\]](#)
  - Lecture 4 : [\[Markov Chain Monte Carlo\]](#)
  - Practical work 4 : [\[MCMC samples\]](#)
  - Lecture 5 : (soon available)

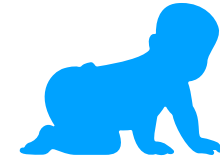


**TODO**



**Road map**

## Bayesian statistics (03/05/21)



1

### Bayesian perspective :

$$P(\theta|X) = \frac{P(X, \theta)}{P(X)} = \frac{\overset{\text{Likelihood}}{P(X|\theta)} \cdot \overset{\text{Prior distribution}}{P(\theta)}}{\underset{\text{Evidence}}{P(X)}}$$

Posterior distribution

$\theta$  parameters

$X$  observations

**Example :**  
Naive Bayes classifier,  
Linear regression, ....

**MAP :**  $\arg \max_{\theta} P(X|\theta) \cdot P(\theta)$

Conjugate distribution

Pros :

- exact posterior

Cons :

- conjugate prior maybe inadequate

## Latent variable models (17/05/21)



2

### Hidden variable models :

$$P(X|\theta) = \sum_{t \in T_{\text{indexes}}} P(X, T = t | \theta)$$

$$P(X, T | \theta) = P(X | T, \theta) P(T | \theta)$$

**Example :**  
GMM, K-means, PCA/PPCA

Pros :

- fewer parameters / simpler models
- hidden variable sometimes meaningful
- clustering / dimensionality reduction

Cons :

- harder to work with
- requires math
- only local maximum or saddle point
- EM : the posterior of T could be intractable

## Variational Inference (07/06/21)

3

### Deterministic approximation of posterior :

$$p(Z|X) = \frac{P(X|Z) \cdot P(Z)}{P(X)}$$

Mean Field Approximation !

### Example :

Topic modelling, LDA trained by VI

Pros :

- Useful when the posterior is intractable
- Suited to large dataset

Cons :

- can never generate exact result

## Markov Chain Monte Carlo (14/06/21)

4

### Sampling techniques for estimate expected values :

$$\mathbb{E}_{p(x)} [h(x)] \approx \frac{1}{M} \sum_{s=1}^M f(x_s)$$

$f(x_s) \sim p(x)$  Gibbs sampling / Metropolis-Hastings !

### Example :

Topic modelling, LDA trained by MCMC

Pros :

- train / inference almost every probabilistic model
- asymptotically exact
- suited to small / medium dataset

Cons :

- Usually slower than alternatives (VI)
- can generate dependant samples from the distribution

## Extensions (28/06/21)

5