

# HAARIS RAHMAN

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## EDUCATION

<b>University of California, San Diego</b> Master of Science in Electrical and Computer Engineering   GPA: 3.67 / 4 Relevant Coursework: Statistical Learning, Probabilistic Reasoning and Learning, Linear Control Theory	La Jolla, California Expected June 2023
<b>Ramaiah Institute of Technology</b> Bachelor of Engineering in Electronics and Instrumentation   GPA: 9.86 / 10 Relevant Coursework: Robotics, (Advanced) Control Systems, Artificial Neural Networks and Fuzzy Logic, OOPS with C++ and Data Structures	Bangalore, India August 2017 - July 2021

## SKILLS

Languages: Python, C, C++, Matlab  
Tools: Pandas, Numpy, Pytorch, Keras(Familiar), Computer Vision, Microsoft Office, Google Suite  
Soft Skills: Leadership, Cooperative, Willing to Learn, Adaptable, Time Management

## RESEARCH EXPERIENCE

<b>Professor Pengtao Xie's Lab</b> [Python, Pytorch] <i>Summer Research Intern</i>	UC San Diego, California June 2021 - Present
<ul style="list-style-type: none"><li>• Research on optimizing evolutionary and differentiable neural architecture search (NAS) algorithms</li><li>• Apply neural architecture search to skin cancer classification in Python with a model accuracy of 82%</li><li>• Leverage human-learning skills for NAS to increase model accuracy to 84%</li></ul>	
<b>iMov MotionTech Pvt. Ltd.</b> [Python, Keras, Pandas, ESP32, Embedded C] <i>Gait Analyst Research Intern</i>	Bangalore, India Oct 2019 - June 2021
<ul style="list-style-type: none"><li>• Collected acceleration, gyroscopic and Euler data of several individuals wirelessly</li><li>• Modelled the gait cycle of individuals and predicted the 'heel strike' using deep learning algorithms in Python with a model accuracy of 100%</li><li>• Programmed a deep learning model on a microcontroller from scratch for real time prediction of heel strike in 'C'</li></ul>	

## PROJECTS

<b>Autonomous Maze Solving Robot</b> [Arduino, Embedded C]	June 2018 - Dec 2018
<ul style="list-style-type: none"><li>• Constructed a robot to find the shortest path within a maze and avoid obstacles</li><li>• Developed a PID algorithm for corrections in deviation from the path while following a line</li></ul>	
<b>GyroBot   Engineering Design Course</b> [Arduino, Embedded C]	Feb 2018 - April 2018
<ul style="list-style-type: none"><li>• Designed a self-balancing robot based on Arduino microcontroller</li><li>• Implemented a PID algorithm to vary the speed of the motors using linear and angular acceleration values</li></ul>	
<b>BatMan</b> [Arduino, Embedded C]	Sep 2017 - Oct 2017
<ul style="list-style-type: none"><li>• Made an Arduino based spectacle, glove and listening system to aid the visually impaired in detecting the presence and height of steps using triangulation method</li><li>• Indicated the color and degree of hotness of objects by varying the frequencies of acoustic signals</li></ul>	

## PUBLICATIONS

• <b>Haaris Rahman</b> , Ashwiji Kumbala, Megharjun V N, Viswanath Talasila Accepted at Sixth International Conference on ICT for Sustainable Development, India, 2021	June 2021
• Sekhar, SR Mani, Snehil Tewari, <b>Haaris Rahman</b> , G. M. Siddesh. "Data Collection in Fog Data Analytics." In <i>Fog Data Analytics for IoT Applications</i> , pp. 79-104. Springer, Singapore, 2020.	Oct 2020

## CERTIFICATIONS

<b>Modern Robotics: Mechanics, Planning and Control Specialization</b> , Northwestern University, Coursera	July 2020
<b>Deep Learning Specialization</b> , Deeplearning.ai, Coursera	Jan 2020
<b>Machine Learning</b> , Stanford University, Coursera	Aug 2019
<b>Introduction to Data Science in Python</b> , University of Michigan, Coursera	July 2019