

Vishnu Prem

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EDUCATION

University of Pennsylvania, School of Engineering & Applied Science Philadelphia, PA
Candidate for Master of Science in Engineering in Robotics – GPA: 3.33/4 May 2021
Courses: Design of Mechatronic Systems, Introduction to Robotics, Applied Machine Learning, Machine Perception, Deep Learning for Data Science, Learning in Robotics

Manipal Academy of Higher Education, School of Engineering & IT Dubai, UAE
Bachelor of Technology in Mechatronics Engineering— GPA: 9.46/10; Minor: Robotics and Automation Oct 2018
Research Abroad: University of Salford, UK in Spring 2018

EXPERIENCE

Autonomous Systems and Advanced Robotics Research Centre- University of Salford Manchester, UK
Undergraduate Student Researcher-Guide: Dr. Theo Theodoridis Feb 2018 – May 2018

- Development of navigation and localization software stack using ARIA API for Pioneer 3-DX robot platform
- Incorporated 3D depth camera and deep learning object detection model for landmark location
- Implemented complementary sensor fusion model for 8 sonar sensors for obstacle avoidance
- Retrained object detection model on new classes using transfer learning

Mimic Productions Berlin, Germany
Robotics and Animatronics Intern Mar 2019 – May 2019

- Developed software pipeline on embedded Linux platform in Python for electromechanical control

Pico International Dubai, UAE
Mechatronics Intern Oct 2018 – Jan 2019

- Developed embedded software in Python and C++ for mechatronic projects at events and exhibitions

TECHNICAL SKILLS

- Software: C, C++, Python, ROS, Git
 - Libraries: OpenCV, Numpy, PyTorch, OpenAI Gym
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RELEVANT PROJECTS

[portfolio: vishnuprem.github.io for more]

Semi-autonomous Battlebot

- Programmed embedded platform for robot localization using IR beacon and incorporated PD control for autonomous navigation

Deep Learning for Violence Detection (2019)

- Developed video preprocessing pipeline and extracted optical flow data to train convolutional neural network to detect actions deemed to be violent from videos using PyTorch and OpenCV

Chess Playing Robot (2017)

- Developed computer vision algorithm in Python using OpenCV for tracking chess pieces and move identification
- Programmed embedded platform for electromechanical control of robot arm

Motion Tracker (2017)

- Surveillance camera developed on embedded platform for tracking human motion using OpenCV and Python
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ACTIVITIES & OTHER ACHIEVEMENTS

Volunteer Head of Mechatronics Department for annual tech festival Technovanza'17 at MAHE Dubai • 1st Place in 'Institute of Physics' Young Lecturer Competition '18 at Manchester Metropolitan University, UK • Best Actor Award at Interhouse Drama Competition '14 SEPS, Abu Dhabi • Best Speaker at Interhouse Debate Competition'14 SEPS, Abu Dhabi