Vishnu Prem

email vprem@seas.upenn.edu • website vishnuprem.github.io • linkedin.com/in/vishnuprem6/ • phone +1 (267)-916-6313

EDUCATION

University of Pennsylvania, School of Engineering & Applied Science

Philadelphia, PA

Candidate for Master of Science in Engineering in Robotics – GPA: 3.3/4

May 2021

Courses: Design of Mechatronic Systems, Introduction to Robotics, Applied Machine Learning

Manipal Academy of Higher Education, School of Engineering & IT

Dubai, UAE

Bachelor of Technology in Mechatronics Engineering—GPA: 9.46/10; Minor: Robotics and Automation

Oct 2018

Research Abroad: University of Salford, UK in Spring 2018

EXPERIENCE

Penn Engineering Online Learning

Philadelphia, PA

Teaching Assistant

Oct 2019 - current

Supporting online learners by answering queries on forums for 6 Robotics Specialization courses on Coursera

Mimic Production
Robotics and Animatronics Intern

Berlin, Germany Mar 2019 – May 2019

• Developed software pipeline in Python for animatronic control of robot face with RaspberryPi

• Designed and prototyped mechanism for realistic humanoid robot face

Autonomous Systems and Advanced Robotics Research Centre- University of Salford

Manchester, UK

Undergraduate Student Researcher

Feb 2018 - May 2018

• Created algorithms for mobile robot localization using computer vision with depth camera

• Implemented obstacle avoidance using sensor fusion of multiple sonar sensors

• Deployed deep learning-based object detection model and retrained on new classes using transfer learning

Pico International

Dubai, UAE

Intern- Digital Media & IT department

Jul 2019 – Aug 2019

• Implemented and tested software for mechatronic exhibits at events and exhibitions

TECHNICAL SKILLS

• Software: C, C++, Python, ROS

• Libraries: OpenCV, Numpy, PyTorch, OpenAlGym

RELEVANT PROJECTS

[portfolio: vishnuprem.github.io for more]

CNN for Violence Detection from videos (2019)

- Extracted optical flow data to train CNN for detecting violent actions from videos using PyTorch and OpenCV FMT* Planner (2019)
 - Fast marching tree planner implementation in C++ with simulation in RViz using ROS

Chess Playing Robot (2017)

- Developed computer vision algorithm using Python and OpenCV for detecting move made by human
- CAD design and 3D printing of robot arm and gripper to pick and place chess pieces

Motion Tracker (2017)

• Surveillance camera that detects and turns towards detected motion using OpenCV and Python

RL for Bipedal walking (2017)

• Built and optimized a NN controller with genetic algorithm for a two-legged agent using Python and OpenAl Gym **Tic-Tac-Toe Program** (2013)

C++ program that plays Tic-Tac-Toe against a human

ACTIVITIES & OTHER ACHIEVMENTS

Volunteer Head of Mechatronics Department for annual tech festival Technovanza'17 at MAHE Dubai • 1st Place in 'Institute of Physics' Young Lecturer Competition '18 at Manchester Metropolitan University, UK • Best Actor Award at Interhouse Drama Competition'14 SEPS, Abu Dhabi • Best Speaker at Interhouse Debate Competition'14 SEPS, Abu Dhabi