Vishnu Prem

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EDUCATION

University of Pennsylvania, School of Engineering & Applied Science

Philadelphia, PA

Candidate for Master of Science in Engineering in Robotics – GPA: 3.33/4

May 2021

Courses: Design of Mechatronic Systems, Introduction to Robotics, Applied Machine Learning , Machine Perception, Deep Learning for Data Science, Learning in Robotics

Manipal Academy of Higher Education, School of Engineering & IT

Dubai, UAE

Bachelor of Technology in Mechatronics Engineering— *GPA*: 9.46/10; Minor: Robotics and Automation

Oct 2018

Research Abroad: University of Salford, UK in Spring 2018

EXPERIENCE

Autonomous Systems and Advanced Robotics Research Centre- University of Salford

Manchester, UK

Undergraduate Student Researcher

Feb 2018 – May 2018

- Developed algorithm for mobile robot localization based on visual landmarks using 3D depth camera
- Deployed object detection model for identifying landmarks and retrained on new classes using transfer learning
- Implemented obstacle avoidance using sensor fusion of multiple sonar sensors

Mimic Production

Berlin, Germany

Robotics and Animatronics Intern

Mar 2019 – May 2019

- Developed software pipeline in Python for animatronic control of robot face with RaspberryPi
- Designed and fabricated mechanism for realistic humanoid robot face

Pico International

Dubai, UAE

Mechatronics Intern

Oct 2018 - Jan 2019

Developed embedded software for mechatronic exhibits at events and exhibitions

TECHNICAL SKILLS

• Software: C, C++, Python, ROS, Git

• Libraries: OpenCV, Numpy, PyTorch, OpenAlGym

RELEVANT PROJECTS

[portfolio: vishnuprem.github.io for more]

CNN for Violence Detection from videos (2019)

- Extracted optical flow data to train CNN to detect violent actions from videos using PyTorch and OpenCV Chess Playing Robot (2017)
 - · Developed computer vision algorithm using Python and OpenCV for tracking chess pieces and identifying move
 - CAD design and 3D printing of robot arm and gripper to pick and place chess pieces

Motion Tracker (2017)

Surveillance camera that detects and turns towards detected motion using OpenCV and Python

RL for Bipedal walking (2017)

- Built and optimized a NN controller with genetic algorithm for a two-legged agent using Python and OpenAI Gym **Tic-Tac-Toe Program** (2013)
 - C++ program that plays Tic-Tac-Toe against a human

ACTIVITIES & OTHER ACHIEVMENTS

Volunteer Head of Mechatronics Department for annual tech festival Technovanza'17 at MAHE Dubai • 1st Place in 'Institute of Physics' Young Lecturer Competition '18 at Manchester Metropolitan University, UK • Best Actor Award at Interhouse Drama Competition '14 SEPS, Abu Dhabi • Best Speaker at Interhouse Debate Competition'14 SEPS, Abu Dhabi