

CANoe.DiVa

Diagnostic Integration and Validation Assistant



Agenda

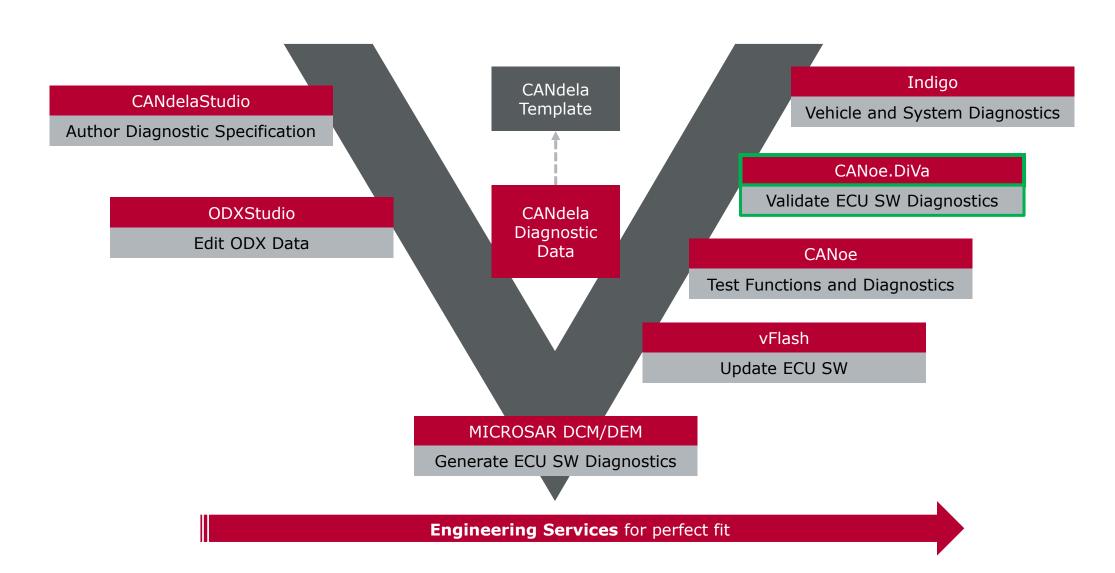
Overview

Features

Summary



CANoe.DiVa in Diagnostics Development Process





The Mission

automated

test run

test generation

CANoe.DiVa

documented

broad and detailed

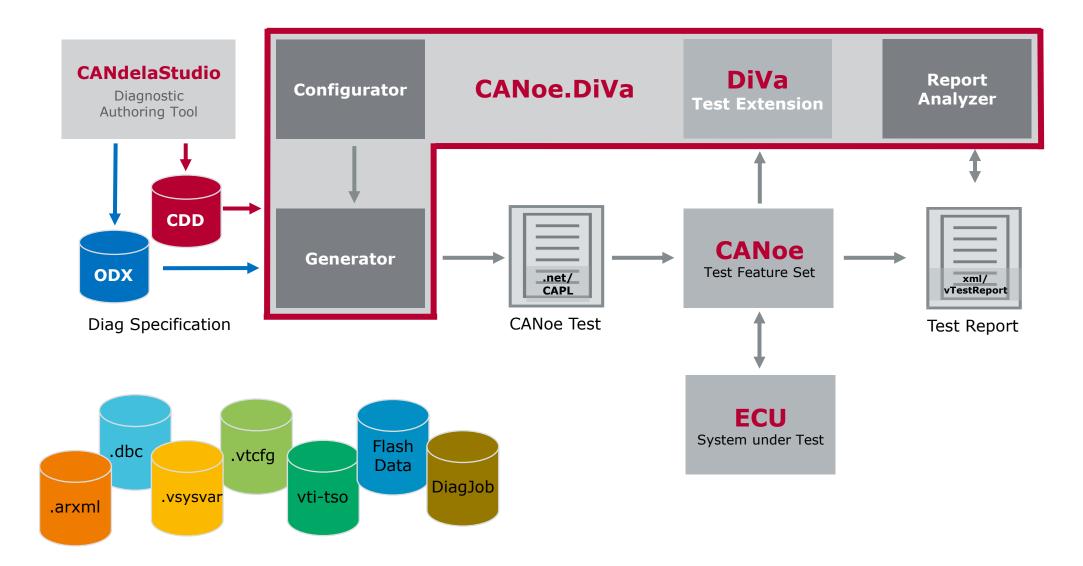
reproducible

data driven

diagnostic tests

VECTOR >

CANoe.DiVa





Supported Protocols

- ▶ ISO 14229 Unified Diagnostic Services (UDS)
- ► ISO 14230 Keyword Protocol 2000 (KWP)
- ► ISO 27145 World-wide harmonized OBD (WWH-OBD)
- ▶ ISO 15031/J1979 On Board Diagnostics: OBD II, OBDonUDS and ZEVonUDs
 - > Including Production Vehicle Evaluation (PVE)
 - > Including automation for J1699-3/-5

 Various manufacturer specific test extensions e.g. for DTAG, FCA, GM, HMC, Mercedes, TMC,...



Comprehensive Diagnostic Testing Solution

Diagnostic Application

Fault memory, parameter contents, environment conditions,...

SW Update

Valid SW update & error conditions (power loss, under-voltage,...)
Test ability to recover from errors

Diagnostic Sequences

Testing of diagnostic scripts e.g. for Production, After-Sales or OTA use cases

Diagnostic Protocol

Timing, Format, Data type definitions, Sessions, Authentication/Security,... on all diagnostic busses:

CAN, LIN, FlexRay, DoIP, K-Line,...

Process Integration

Development

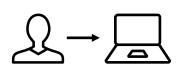
 Control and automate test execution to support CI/CT use cases via CANoe Server Edition or Command Line

Quality

- Requirement Traceability for the major TDM/RQM systems (via the Connection Utilities)
- Open interfaces to integrate with others/proprietary solutions (xml or .net API)

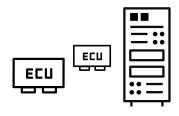


CANoe.DiVa Product Editions



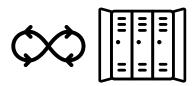
Desktop

Workplace tool for diagnostic test engineers
Test of HW and SW based HPCs and ECUs (real-time and above)



Test Bench

Shared tool usage on a test bench for diagnostic test engineers Remote and anonymous access Test of HW and SW based HPCs and ECUs in real-time



Server

Script-based headless test generation and execution to support DevOps, CI/CT applications (GitLab, Jenkins etc.) Test of HW and SW based HPCs and ECUs (real-time and above)



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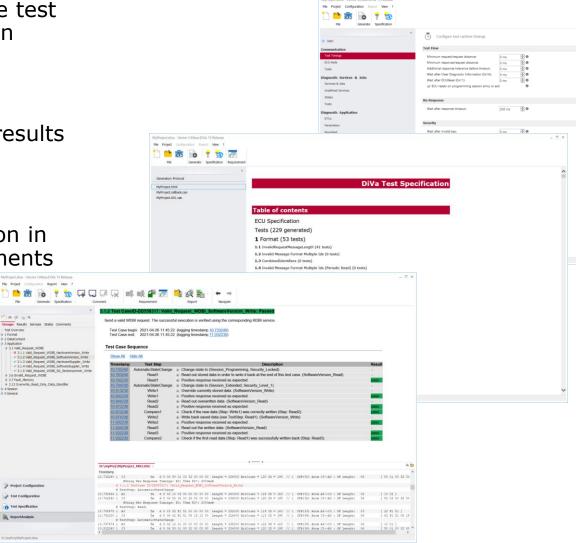
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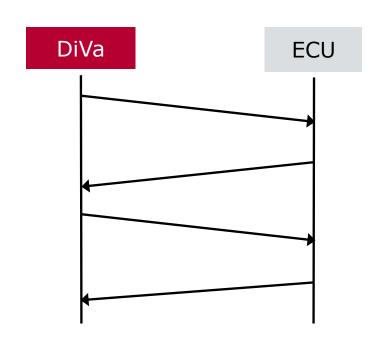
- Automated generation of a CANoe test based on a diagnostic specification
- User interface to configure tests
- Generation of a test specification
- Clear and detailed report of test results
- Support of test report analysis
- Requirement traceability
- Automatable control for integration in build- or regression test environments (e.g. Jenkins)
- Extensible test functionality





Protocol Testing

- Diagnostic Message Flow
 - Physical, functional addressing and timing
- Diagnostic Protocol Format
 - Valid, Combined and Invalid Requests
 - Response (single, none, multiple)
- Data Type Checks
- Sessions and Security Levels
 - Service execution in the different sessions and security levels
 - Session and security state transitions





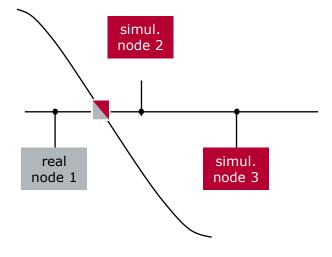
Application Testing: Diagnostic Parameter

- Passive parameter validation against
 - Diagnostic values (e.g. read/write)
 - Configured data ranges
 - Expectation values
 - CCP/XCP values
 - CANoe System Variables
- ► Active control of I/Os to validate diagnostic parameter content
 - CAN messages using CANoe rest bus simulation
 - ► HW I/Os via VT System channels
 - Any I/O using CANoe system variables



Application Testing: Fault Memory

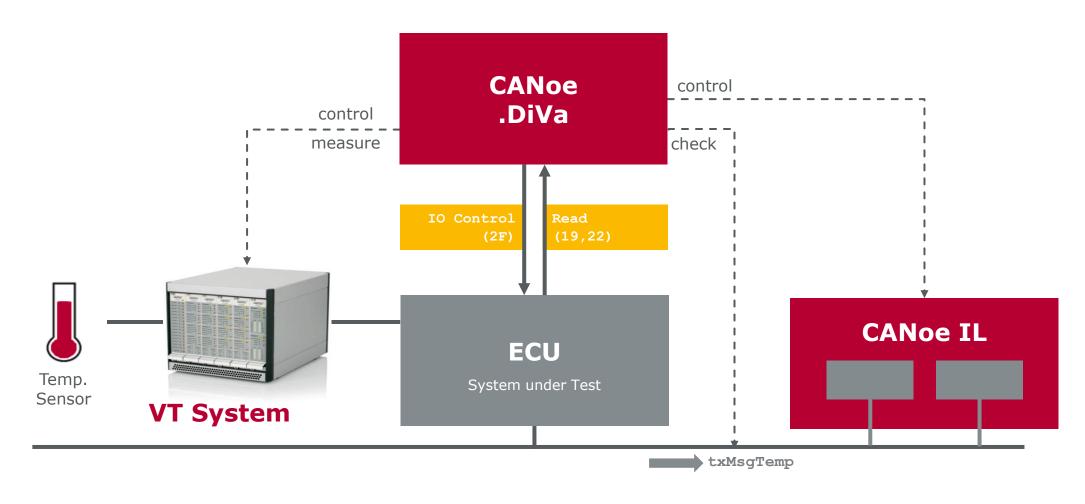
- Provoke network signal failures
 - Communication timeouts
 - Data consistency failures
- Provoke hardware failures using the VT System:
 - Short-circuits (Ground, UBatt, Pins)
 - I/O failures (interruption, resistance, voltage)
 - Individual error settings
- Any other failures using user scripts





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Application Testing



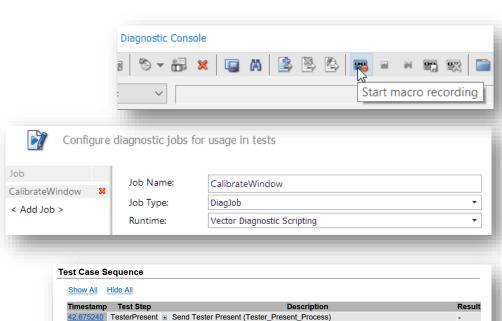


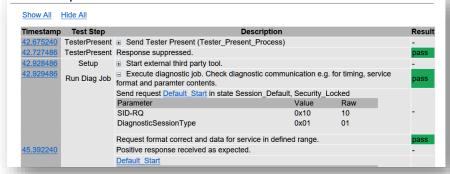
Diagnostic Job Testing using Vector Diagnostic Scripting

- ▶ **Motivation** *Test ECU-individual diagnostic sequences*
 - > Prove that a required diagnostic sequence/feature is correctly supported
- ► Fast & easy setup
 - Use the CANoe macro recorder to record ECU-specific diagnostic sequences (e.g. "Calibration of roof window")
 - > Configure the recorded VDS macro in DiVa and run it in a Test
 - > Flexible: Use Vector Diagnostic Scripting (VDS) to implement test sequences in C#/.net

Benefits

- CANoe.DiVa standard checks (format, data, timing etc.) are automatically applied
- Automated and reproducible diagnostic sequence/feature test
- Use of CANoe's testing, reporting and post-processing features
- Allows pure virtual SW based testing of diagnostic jobs in combination with vVirtualTarget ECU
- Can be used to emulate not yet available diagnostic tester systems: e.g. On-Board Tester







Software Download Test







Test Setup

- SW download tool to bring the SW download sequence and flash data
- Supported tools: Vector vFlash & D-PDU API based tools

Test Coverage

- Valid Flashing under different conditions
 - > Validation of timing and format
- Test of various fault conditions: validate that the ECU can recover
 - > Over- and under voltage tests
 - > Cancel data transfer: stop transmission or power loss
 - > Cancel after or during erase memory (clamp reset) or skip erase memory routine
 - > Write inconsistent data (signature/checksum fails)
- Endurance test of the ECU's update capability
 - > Flash x times in a row
- Additional SW Download tests available for various OEMs



CI/CT: CANoe.DiVa Server Edition

- ► Test early and continuously!
- Automated test generation and execution on a server
 - > CANoe SE .DiVa: testing real/HW and virtual/SW components in a CI
 - > CANoe4SW SE .DiVa: testing virtual/SW components in a CI
- ► Easy and fast test setup via .yaml files
 - > "from the scratch" just using a diagnostic file (CDD, PDX)
 - > via a DiVa configuration template or

#for test results check cli or \$PSScriptRoot/working-dir/TestReports

> using an existing project

```
$\text{canoe4sw_se_install_dir = "C:\Program Files\Vector CANoe Server Edition 18\Exec64"}
$\text{diva_se_install_dir = "C:\Program Files\Vector CANoe Server Edition .DiVa 18\Bin"}

$\text{ErrorActionPreference = "Stop"}
$\text{Set-StrictMode -Version 3}

#create environment

$\text{$\text{$\text{canoe4sw_se_install_dir/environment-make.exe} "$\text{$\text{PSScriptRoot/venvironment.yaml" -o "$\text{$\text{PSScriptRoot" -A Win32}}}

#create DiVa Test...

# ... from the scratch

$\text{$\text{$\text{diva_se_install_dir/diva-make.exe} "$\text{$\text{PSScriptRoot/abs.diva.yaml" -o "$\text{$\text{PSScriptRoot/DiVa"}}}}

#create & compile the CANoe.DiVa test for the test environment

$\text{$\text{$\text{$\text{$\text{Canoe4sw} \set \text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\text{$\t
```

& \$canoe4sw se install dir/canoe4sw-se.exe "\$PSScriptRoot/Default.venvironment" -d "\$PSScriptRoot/working-dir" --test-unit "\$PSScriptRoot/abs.vtestunit" --show-progress "test-case" -t 60





```
version: 1
diag-description:
file-path: SUT\ABS.cdd
sut:
ecu: ABS
variant: CommonDiagnostics
```

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#run tests



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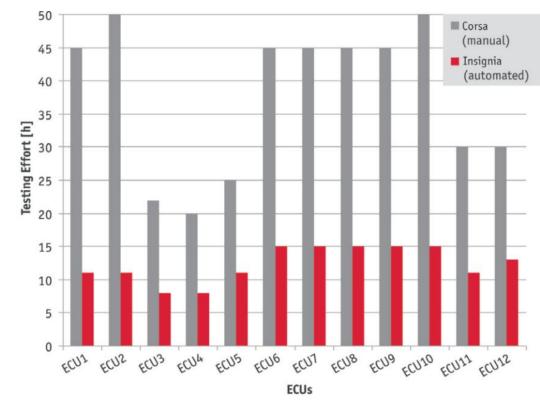
Summary



Benefits

- Significant savings of time and effort
- Further quality improvement of the ECU Software
- All development stages supported

- Excellent test coverage
- Efficient, generation-based approach
- Automated tests without user interaction
- User-defined tests allow tailoring



- Widely used by OEMs and suppliers already with a proven record of success
- Continuously enhanced features through implementation of customers' requirements



For more information about diagnostics and flashing at Vector please visit:



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