

Vishnu Rudrasamudram

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EDUCATION

Worcester Polytechnic Institute

MS in Robotics Engineering, Jan 2018 - Dec 2019 (Expected)

Rajiv Gandhi University of Knowledge Technologies, RK Valley

Bachelor of Technology, May 2015

GPA: 8.9/10

Concentration: Electronics and Communication Engineering,

Coursework: Programming and Data Structures, Design of Algorithms, Intro. to Mechanics, Control Systems, Digital Electronics, Digital Signal Processing, Digital Image Processing, Computer Vision, Data Mining, Pattern Recognition and Machine Intelligence

EXPERIENCE

Project Research Assistant

Dept. of Systems and Control Engineering

Feb 2017 – Dec 2017

IITB, Mumbai, India

Supervisor: Prof. Arpita Sinha

- Developing algorithms for path planning and patrolling for autonomous car-like vehicle in an urban campus environment
- The algorithms were implemented in python using Robot Operating System in Ubuntu 14.04 Environment.

Project Engineer

Wipro Technologies

Aug 2015 – Jan 2017

Hyderabad, India

- Got trained on C++/Unix Systems, Perl and Shell scripting
- Worked on various projects using C, C++ and Javascript
- Simultaneously worked as a Linux System administrator.

Research Intern

Robotics & Intelligent Systems Lab

June 2014 – Aug 2014

IIT Kharagpur, India

Supervisor: Prof. CS Kumar

- Worked on development of Android applications for LEGO MINDSTORMS NXT robots using App inventor2
- Implemented algorithms pertaining to Control systems through Android application for Self-balancing robot

Robotics & Embedded Sys. Trainee

i3indya Technologies

May 2013 – June 2013

Hyderabad, India

- Interfaced various input and output devices with the microcontroller - AVR Atmega16, and programmed using Embedded C. About 30 applications were programmed.

SKILLS

Programming Languages: Python, C, C++, Javascript, Java, Perl, Shell

Software: ROS, OpenCV, MATLAB, Numpy, Matplotlib, L^AT_EX.

Hardware: Microcontrollers (Arduino/Atmega, MSP 430), Spartan 3E

Operating Systems: Windows, Linux/Unix

Others: Basic Web designing, Photoshop, Processing

PRESENTATION

N. Naga Srinivasarao, **R. Vishnu Vadhan**, M. Vinay Kumar, Design of Electronic Logic Circuit for Auto Irrigation Unit at 29th National Convention of Electronics and Telecommunication Engineers, 29-30 October 2014 at The Institute of Engineers, Hyderabad, India.

UG FINAL PROJECT

Indoor Aerial Imaging Using MAV

Supervisor: Ramakanth Yadav, Lecturer, ECE Dept., RGUKT RKV

Dec 2014 – Apr 2015

Programmed a drone using Robot Operating System (ROS) to travel in an indoor environment and capture images, and stitched all images to get high detail mosaic view of that area. It is implemented on Parrot AR Drone. Operating system used was Ubuntu with ROS (python) and OpenCV (python).

PROJECTS

Face Tracking Using Quadrotor Drone

Team size: 2

Robotics, Computer Vision

Programmed the drone to track the human face using its front camera and change its yaw according to the face movements. It is made on Robot Operating System (ROS) using Autonomy package and implemented on Parrot AR Drone.

Aerial Robot to Aid Agricultural Industry

Team size: 5

Embedded Systems, Design, Robotics

Guide: Naga Srinivasa Rao, Lecturer, Mechanical Engg., RGUKT RKV

Executed Design and implementation of Quadcopter embedding different sensors and modules.

Android Device controlled Two Wheel Self-balancing Robot

Team size: 2

Robotics, Control Systems

An android application is developed to balance a two wheel LEGO robot. The android device is the part of the system which is used both as sensor to sense the tilts and processor to process the signals and give control commands.

Auto Irrigation Unit Using Embedded Systems

Team size: 3

Embedded Systems

Guide: Naga Srinivasa Rao, Lecturer, Mechanical Engg., RGUKT RKV

The project aimed at achieving very effective automation at low cost in the field of agriculture. Dummy roots (tentiometers) are placed in various points in the field, which sense and interact with microcontroller for processing and automating irrigation.

Optimal Route Finder

Algorithms

This program displays optimal routes for a set of source and destination cities. The optimality of the route (distance or cost) is decided by the user. This is programmed in C++ using STL, and Depth First Search algorithm is used to find all possible routes.

ACTIVITIES

Organized LabView Workshop at Abhiyanth15, a Technical Fest at RGUKT RKV

Event Coordinator for Zonal Rounds of RoboTryst-2015.

Robotics Club, RGUKT RKV Founder

Participated in a two-day workshop on Quadcopter Designing as part of zonal round competition at IIIT-H conducted by Robosapiens Technologies Pvt. Ltd. in association with Tryst 2014 IIT Delhi.

Participated in Reformation A Challenge to lead India, organised by Techfest, IIT Bombay.

Attended a National Seminar on Emerging Trends in Electronics and Telecommunication Engineering at 29th National Convention of Electronics and Telecommunication Engineers, The Institute of Engineers (India).

Attended a two-day workshop on Li2 Augmented Reality (image processing based robots using microcontrollers) conducted during ENGINEER 2012, at NIT-K Surathkal.

Volunteered as a Web Casting Engineer

- Bye-Elections at Kurnool - 2012
- General elections at Ananthapur - 2014.