

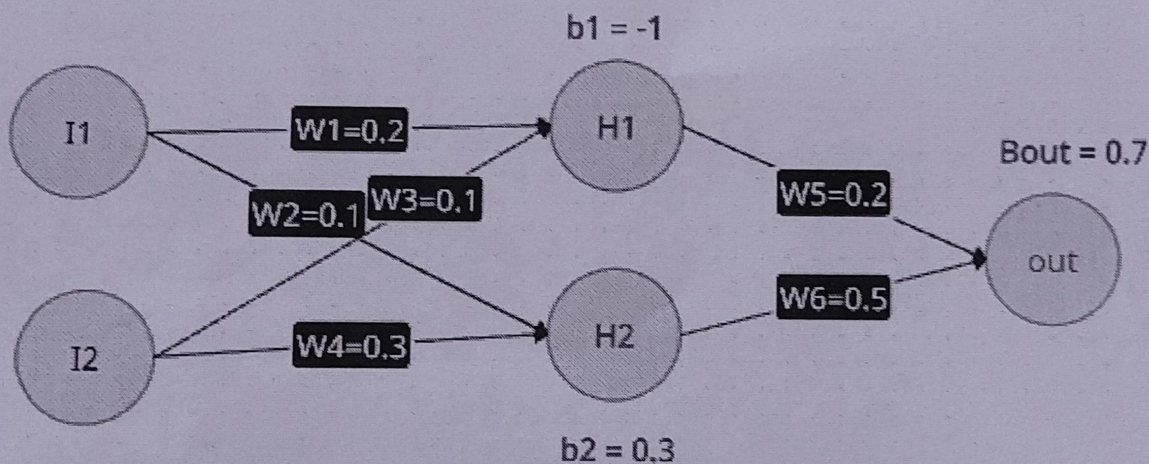
Date: 11.11.2025

Time: 9.30 pm to 12.30 pm

Max.Marks: 40

Answer all questions

1. a. Show mathematically that a single-layer perceptron cannot solve the XOR logic problem, regardless of how its weights and bias are chosen. (2)
- b. Calculate the output Y of a three-input neuron with bias. The input feature vector is (x_1, x_2, x_3) : $(0.8, 0.6, 0.2)$, the weight values are $[w_1, w_2, w_3]$: $[0.2, 0.1, -0.3]$, and the Bias is 0.25. Use the binary sigmoid, Tanh, and ReLU activation functions. (3)
- c. Update the parameters in the given MLP using back propagation with a learning rate of 0.5 and an activation function as sigmoid. The initial weights and biases are shown in the diagram below. The input = $[0.6, 0.9]$, and the target output = 1. (3)



- d. Which regularization method leads to weight sparsity? Explain why. (1)
2. a. Assume an input volume of dimension $64 \times 64 \times 3$. What are the dimensions of the resulting volume after convolving a 5×5 kernel with zero padding, a stride of 1 and 2 filters? (3)
- b. What is the role of Backpropagation Through Time (BPTT) in training RNNs, and how does it work? (3)
- c. Explain the importance of choosing the right step size in the neural network. (2)
3. a. How does ICA handle non-Gaussian signals compared to PCA, and why is this important for signal separation? (2)
- b. Explain the concept of a Variational Autoencoder and describe its working mechanism with its loss function. (3)
- c. Explain the difference between Vanilla Autoencoders and Undercomplete Autoencoders (2)
4. a. Describe the structure and working mechanism of a Boltzmann Machine. (3)
- b. Explain the concept of Zero-Shot Learning (ZSL) and discuss how it utilizes Transfer Learning. (3)
- c. Explain why pre-trained CNNs like VGG or ResNet are widely used in transfer learning applications. (2)

a. Consider a Convolutional Neural Network (CNN) composed of the layers listed below. (3)

For each layer, determine:

1. The output activation volume dimensions in the format (H, W, C), where H = height, W = width, and C = number of channels.
2. The number of learnable parameters in that layer.

Unless otherwise specified, assume padding = 1 and stride = 1 for all convolutional layers.

Notation:

- CONV x -N denotes a convolutional layer with N filters with height and width equal to x .
- POOL- n denotes an $n \times n$ max-pooling layer with a stride of n and 0 padding.
- FLATTEN flattens its inputs, identical to `torch.nn.flatten` / `tf.layers.flatten`.
- FC-N denotes a fully-connected layer with N neurons

| Layer Activation | Output Volume (H, W, C) | Number of parameters |
|------------------|-------------------------|----------------------|
| Input | 32 x 32 x 3 | 0 |
| CONV3-8 | | |
| Leaky ReLU | | |
| POOL-2 | | |
| BATCHNORM | | |
| CONV3-16 | | |
| Leaky ReLU | | |
| POOL-2 | | |
| FLATTEN | | |
| FC-10 | | |

Fill in the output volume dimensions and the number of parameters for each layer in the table above.

b. You are given a content image of a cityscape X_C , and a style image of a famous painting X_S . Explain how Neural Style Transfer can generate a new image X_Y that preserves the structure of the city while adopting the artistic patterns of the painting. (3)

c. Describe how Multi-Head Attention improves the performance of a Transformer compared to single-head attention. (2)