

ASSEMBLY PROGRAMMING

LAB 08 REPORT

TASK ASSIGNED:

- Run the original and modified code files of 01FIRST.ASM, 03MOVE.ASM, 04INCJMP.ACM to get familiar with microprocessor simulator.
- Modify 02LIGHT.ASM as per the given table and reimplement an efficient code using a similar loop in 06PROC.ASM.
- Verify the functionality of modified 02LIGHT.ASM via running the simulation.
- Modify 99SEVSEG.ASM to display last two digits of the index number. (2003 '32' X)
- Create a program to calculate and display hexadecimal value of factorial 5.

ALL ASSEMBLY FILES:

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1. ; ===== WORK OUT 2 PLUS 2 =====
   CLO                ; Close unwanted windows.
   MOV AL,2           ; Copy a 2 into the AL register.
   MOV BL,2           ; Copy a 2 into the BL register.
   ADD AL,BL          ; Add AL to BL. Answer goes into AL.
   END                ; Program ends
; ===== Program Ends =====

2. ; ===== WORK OUT 2 MINUS 2 =====
   CLO                ; Close unwanted windows.
   MOV AL,2           ; Copy a 2 into the AL register.
   MOV BL,2           ; Copy a 2 into the BL register.
   SUB AL,BL          ; Subtract BL from AL. Answer goes into AL.
   END                ; Program ends
; ===== Program Ends =====

3. ; ===== WORK OUT MULTIPLY 2 BY 2 =====
   CLO                ; Close unwanted windows.
   MOV AL,2           ; Copy a 2 into the AL register.
   MOV BL,2           ; Copy a 2 into the BL register.
   MUL AL,BL          ; Multiply AL by BL. Answer goes into AL.
   END                ; Program ends
; ===== Program Ends =====

4. ; ===== WORK OUT DIVIDE 2 BY 2 =====
   CLO                ; Close unwanted windows.
   MOV AL,2           ; Copy a 2 into the AL register.
   MOV BL,2           ; Copy a 2 into the BL register.
   DIV AL,BL          ; Divide AL to BL. Answer goes into AL.
   END                ; Program ends
; ===== Program Ends =====

5. ; ===== Decrementing =====
   MOV BL,40          ; Initial value stored in BL
   Rep:               ; Jump back to this label
       DEC BL         ; Subtract ONE to BL
       JMP Rep        ; Jump back to Rep
   END                ; Program Ends

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; ===== Program Ends =====

6. ; ===== Counting in 3s =====
MOV BL,40 ; Initial value stored in BL
Rep:      ; Jump back to this label
    ADD    BL,3    ; Count In 3s
    JMP    Rep     ; Jump back to Rep
    END      ; Program Ends

; ===== Program Ends =====

7. ; ===== Counting in powers of 2 =====
MOV BL,1 ; Initial value stored in BL
Rep:      ; Jump back to this label
    MUL    BL,2    ; Count in powers of 2
    JMP    Rep     ; Jump back to Rep
    END      ; Program Ends

; ===== Program Ends =====

8. ; ===== Counting in fibonacci sums =====
MOV BL,0 ; Initial value stored in BL
MOV AL,1 ; Initial value stored in BL
MOV [50],AL ; Copy a AL value into the [50] location
MOV [60],BL ; Copy a BL value into the [60] location

REP:
    MOV    AL,[50] ;Interchange the values between registers and memory locations
    MOV    BL,[60] ;
    MOV    [60],AL ;
    ADD    AL,BL ; Keep adding to each 2 sums to develop fibonacci sequence

    MOV    [50],AL ;
    JMP    REP ;

    END      ; Program Ends
; ===== Program Ends =====

9. ; ===== CONTROL THE TRAFFIC LIGHTS (without loop) =====

CLO;      Close unwanted windows.

Start:
MOV AL,84; Copy 10000100 into the AL register.
OUT 01;    Red on left side and Green on right side.
NOP;      Do nothing for 10 cycles
NOP;
NOP;
NOP;
NOP;
NOP;
NOP;
NOP;
NOP;
NOP;
NOP;
NOP;

MOV AL,48; Copy 01001000 into the AL register.
OUT 01;    Yellow on both sides.
NOP;      Do nothing for a cycle.

MOV AL,30; Copy 00110000 into the AL register.
OUT 01;    Green on left side and Red on right side.
NOP;      Do nothing for 5 cycles.
NOP;
NOP;
NOP;
NOP;
NOP;

JMP Start ; Jump back to the start.
END        ; Program ends.

; ===== Program Ends =====

10. ; ===== CONTROL THE TRAFFIC LIGHTS-Using a loop =====

CLO;      Close unwanted windows.

Start:
MOV AL,84; Copy 10000100 into the AL register.
MOV BL,A;  10 cycles

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    OUT 01;      Red on left side and Green on right side.
    CALL 30;     Call time delay procedure at 30

    MOV AL,48;   Copy 01001000 into the AL register.
    MOV BL,1;    1 cycle
    OUT 01;      Yellow on both sides.
    CALL 30;     Call time delay procedure at 30

    MOV AL,30;   Copy 00110000 into the AL register.
    MOV BL,5;    5 cycles
    OUT 01;      Green on left side and Red on right side.
    CALL 30;     Call time delay procedure

    JMP Start    ; Jump back to the start.

;---TIME DELAY PROCEDURE STORED AT ADDRESS [30]-----
    ORG 30;      Generate machine code from address[30]

    PUSH BL;     Save BL on the stack
    PUSHF;       Save CPU flags on the stack
REP:
    DEC BL;      Subtract 1 from BL value
    JNZ REP;     If BL !=0 ,Jump back to REP

    POPF;        Restore the CPU flags from the stack to their original value
    POP BL;      Restore BL from the stack to original

    RET;         Return from the procedure.
;-----
    END;
; ===== Program Ends =====

11. ; ===== Seven Segment Displays Port 02 =====
;Index number : 2003'32'X
Start:
    MOV AL,9E ; 1001 1110
    OUT 02 ; Send the data in AL to Port 02

    MOV AL,B7 ; 1011 0111
    OUT 02 ; Send the data in AL to Port 02

    JMP Start

    END
; ===== Program Ends =====

12. ;=====Display Hex value of factorial 5=====
MOV AL,1; Copy 1 to AL register
MOV BL,5; Copy 5 to BL register

REP:
    MUL AL,BL; Multiply the values at AL and BL, the answer goes to AL
    DEC BL; Decrement BL register by 1
    JNZ REP; If BL != 0 then repeat

;Answer is 120 in decimal and 78 when converted to Hexadecimal
MOV AL,8A; 1000 1010
OUT 02; Send the value in Al to port2

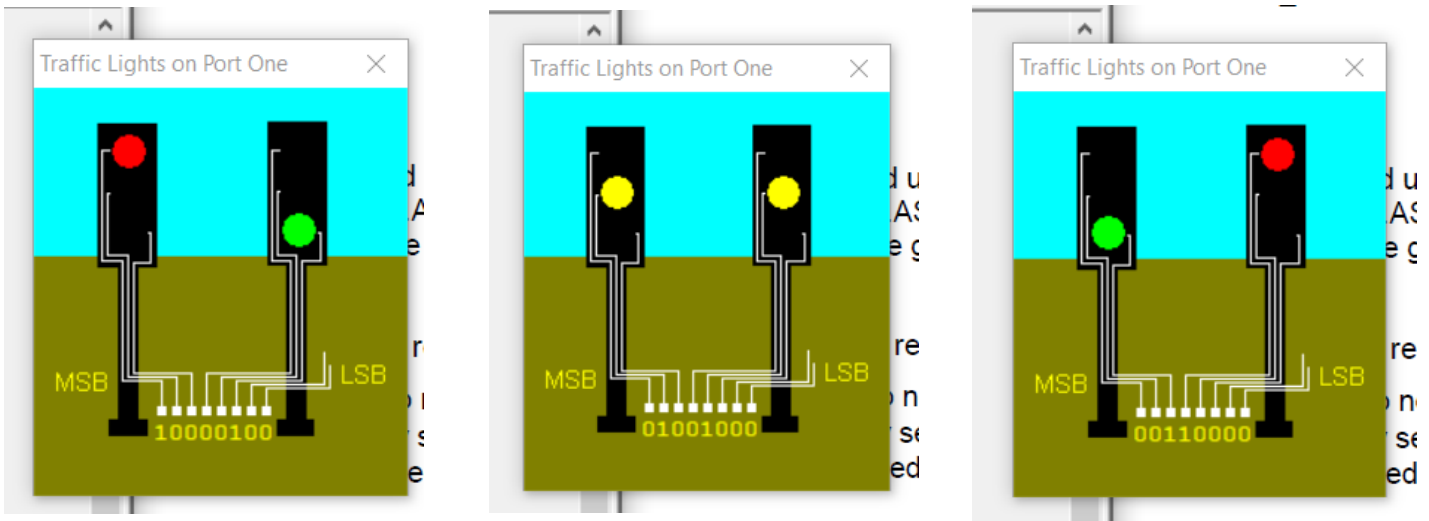
MOV AL,FF; 1111 1111
OUT 02; Send the value in Al to port2

END;
; ===== Program Ends =====

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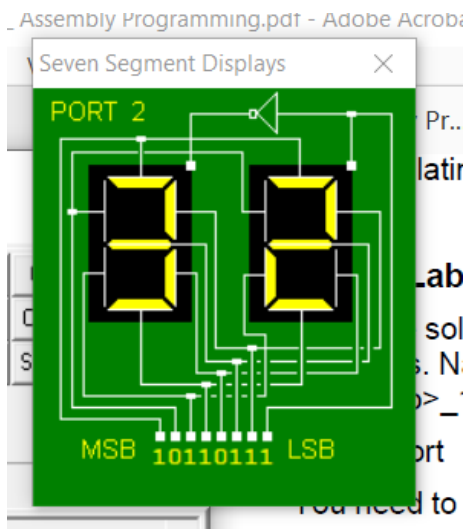
SCREENSHOTS OF SIMULATION:

01.Simulation of traffic lights. (FROM 200332X_8.ASM)



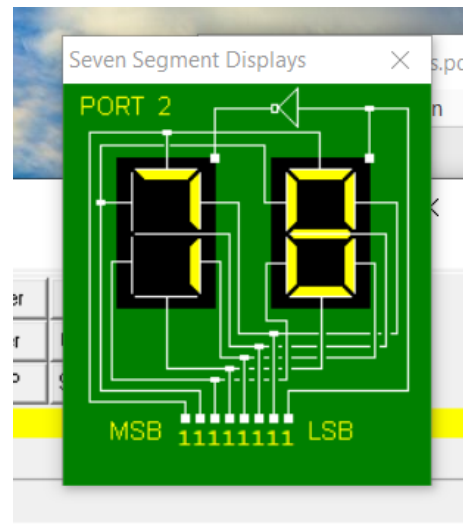
02.Simulation of last 2 digits of index number on the Seven segment.

(FROM 200332X_10.ASM)



03.Simulation of displaying the hexadecimal value of factorial 5 on the Seven segment.

(FROM 200332X_11.ASM)



CONCLUSIONS:

- Assembly language can be used to design and develop simple programs to achieve certain objectives and their functionality can be verified via running a simulation.
- By interfacing input and output devices to the microprocessor, the already developed logics can be put in practice in a useful way.