

Q5 We can add an extra invertible matrix  $S$  into  $X^2$  to give  $\Rightarrow$

$$X^2 = (d - Am)^T S^T S^{-1} N^{-1} S^{-1} S (d - Am)$$

$$= (Sd - SAM)^T (S N S^T)^{-1} (Sd - SAM)$$

Now we define the new rotated variables as:-

$$\tilde{d} = Sd \quad \tilde{A} = SA \quad \tilde{N} = S N S^T$$

Then the new  $X^2$  becomes  $\Rightarrow$

$$X^2 = (\tilde{d} - \tilde{A}m)^T \tilde{N}^{-1} (\tilde{d} - \tilde{A}m)$$

This can be true only if  $\Rightarrow$

$$\tilde{N}_{ij} = \langle \tilde{n}_i, \tilde{n}_j \rangle \quad - (1)$$

(Since in the original definition of  $X^2$ ,  $N = \langle n_i, n_j \rangle$ )

Let's prove (1)  $\Rightarrow$

$$RHS = \langle \tilde{n}_i, \tilde{n}_j \rangle$$

$$\tilde{n} = S n \quad \tilde{n} = S n$$

$$\text{Thus, } \tilde{n}_i = \sum_k S_{ik} n_k$$

So,  $\langle n_i n_j \rangle =$

$$\left\langle \left( \sum_k S_{ik} n_k \right) \left( \sum_l S_{jl} n_l \right) \right\rangle$$

Since the original noises are independent of each other  $\Rightarrow n_i n_j = \delta_{ij} \sigma_i^2$

Thus  $\langle n_i n_j \rangle =$

$$\left\langle \sum_k S_{ik} S_{jk} n_k^2 \right\rangle$$

$$= \sum_k S_{ik} S_{jk} \sigma_k^2 \quad \text{--- (I)}$$

$$\text{LHS} = \tilde{N}_{ij} = \sum_k (S N)_{ik} S_{kj}^T$$

$$= \sum_k S_{ik} \sigma_k^2 S_{jk}$$

$$= \sum_k S_{ik} S_{jk} \sigma_k^2 \quad \text{--- (II)}$$

$$\text{(I)} = \text{(II)} \Rightarrow \tilde{N}_{ij} = \langle n_i n_j \rangle$$