```
## Load libraries
import pandas as pd
import numpy as np
import sys
import matplotlib.pyplot as plt
import matplotlib.cm as cm
from keras.datasets import mnist
plt.style.use('dark_background')
%matplotlib inline

np.set_printoptions(precision=2)
import tensorflow as tf

tf.__version__
```

Load MNIST Data

```
## Load MNIST data
(X_train, y_train), (X_test, y_test) = mnist.load_data()
X train = X train.transpose(1, 2, 0)
X_test = X_test.transpose(1, 2, 0)
X_train = X_train.reshape(X_train.shape[0]*X_train.shape[1], X_train.shape[2])
X_test = X_test.reshape(X_test.shape[0]*X_test.shape[1], X_test.shape[2])
num_labels = len(np.unique(y_train))
num_features = X_train.shape[0]
num_samples = X_train.shape[1]
# One-hot encode class labels
Y_train = tf.keras.utils.to_categorical(y_train).T
Y_test = tf.keras.utils.to_categorical(y_test).T
# Normalize the samples (images)
xmax = np.amax(X_train)
xmin = np.amin(X_train)
X_train = (X_train - xmin) / (xmax - xmin) # all train features turn into a number between
X_{\text{test}} = (X_{\text{test}} - xmin)/(xmax - xmin)
print('MNIST set')
print('----')
print('Number of training samples = %d'%(num samples))
print('Number of features = %d'%(num features))
print('Number of output labels = %d'%(num_labels))
```

A generic layer class with forward and backward methods

```
class Layer:
    def __init__(self):
        self.input = None
        self.output = None

    def forward(self, input):
        pass

def backward(self, output_gradient, learning_rate):
    pass
```

The softmax classifier steps for a batch of comprising \$b\$ samples represented as the \$785\times b\$-matrix (784 pixel values plus the bias feature absorbed as its last row) \$\$\mathbb{X} = \left[\frac{x}^{(0)}, \frac{x}^{(1)}, \frac{x}^{(0)}, \frac{x}{(0)}, \frac{x}^{(0)}, \frac{

- 2. Calculate \$10\times b\$-softmax predicted probabilities matrix: $$\ \phi_{a}^{(0)}&\dots_{mathbf{a}^{(b-1)}\end{bmatrix} \&= \dots_{text}\left(\mathbf{z}^{(0)}\right)\dots_{text}\left(\mathbf{z}^{(0)}\right)\dots_{text}\left(\mathbf{z}^{(b-1)}\right)\end{bmatrix}\dots_{text}\left(\mathbf{z}^{(b-1)}\right)\end{bmatrix}\dots_{text}\left(\mathbf{z}^{(b-1)}\right)\end{align*}$
- 3. Predicted probability matrix get a new name: \$\hat{\mathbf{Y}} = \mathbf{A}.\$
- 4. The crossentropy (CCE) loss for the \$i\$th sample is \$\$L_i = \sum_{k=0}^9-y^{(i)}\setminus \{y^{(i)}_k\} = {\mathbf{Y}^{(i)}}^{(i)}}^{\infty}T_{\log\left(\mathbb{Y}^{(i)}_k\} \right) = {\mathbf{Y}^{(i)}}^{(i)}}^{\infty}T_{\log\left(\mathbb{Y}^{(i)}_k\} \right) = {\mathbf{Y}^{(i)}}^{\infty}T_{\log\left(\mathbb{Y}^{(i)}_k\} \right)
- 5. The computational graph for the samples in the batch are presented below:

 $\label{thm:local-constraint} $$\ \an {1.5in} \left(1.5in} \an {1.5in} \end{thm:local-constraint} $$ \operatorname{2}^{(0)} \an {1.5in} \an {1$

 $\color{yellow}\downarrow}\\hat{W}\end{align*} $\quad\cdots\quad$\begin{align*} L_{b-1}\\color{yellow}\downarrow}\ \hat{\mathcal{y}}^{(b-1)} &= \mathbb{a}^{(b-1)}\ \color{yellow}\downarrow}\\hathbf{z}^{(b-1)}\ \color{yellow}\downarrow}\\hathbf{W}\end{align*} $$

6. Calculate the gradient of the average batch loss w.r.t. weights as:

 $\$ \begin{align*}\Rightarrow \nabla_\mathbf{W}(L) &= \frac{1}

 $\label{thm:left(L_0)+cdots+nabla_mathbf(W)} left(L_{b-1}) + \label{thm:left(L_0)+cdots+nabla_mathbf(W)} left(L_{b-1}) + \label{thm:left(L_0)+cdots+nabla_mathbf(W)+cdots+nabla_mathbf(W)} left(L_{b-1}) + \label{thm:left(L_0)+cdots+nabla_mathbf(W)+cdots+nabla_mat$

1\right)\right]\\&= \frac{1}

 $b\leq \int \left(\frac{y}{(0)}\right) dy$

 $\times \times \times$

 $$$ (L_0)\right]_{\text{\mathbf(W)}\left(x^{(b-1)}\right)}_{\text{\mathbf(z)}^{(b-1)}}\left(x^{(b-1)}\right)} \left(x^{(b-1)}\right)^{(b-1)}\left(x^{(b-1)}\right)^{(b-1)}} $$$

1) $\left(\frac{hat{\mathbf{y}}^{(b-1)}(L_{b-1})\right)}_{\xi}_{\xi}^{(b-1)}(L_{b-1})\right)}$

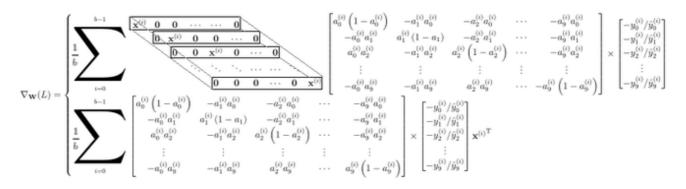
 1\left(\\ \ \|x\|^{1}\right)\ \ \|x\|^{1}\left(\\ \|x\|^{1}\right)\ \ \|x\|^{1}\left(\ \|x\|^{1}\right)\ \ \|x\|^{1}\left(\ \|x\|^{1}\right)\ \ \|x\|^{2}^{(0)}\left(\ \|x\|^{2}\right)\ \ \|x\|^{2}\left(\ \|x\|^{2}\right)\$

 $$$ (L_0)\right]_{\text{\mathbf(W)}\left(x^{(b-1)}\right)} \times {(b-1)}\right) \times {(b-1)}$

 $1) $$ 1) \times \mathbb{L}(b-1) \cdot \mathbb{L}($

1right).\end{align*}\$\$

7. The full gradient can be written as



CCE loss and its gradient for the batch samples:

 $y^{(0)} \log \left(\frac{y}^{(0)}_k \right) + \cosh(hat{y}^{(0)}_k \right) + \cosh(hat{y}^{(b-1)} \log \left(\frac{y}^{(b-1)} \right)$

1)}_ $k\right)\$

 $y_0^{(0)}\wedge hat\{y\}_0^{(0)}\& \cdot y_0^{(0)}\wedge hat\{y\}_0^{(0)}\wedge hat\{y\}_1^{(0)}\& \cdot y_1^{(0)}\wedge hat\{y\}_1^{(0)}\& \cdot y_1^{(0)}\otimes hat\{y\}_2^{(0)}\& \cdot y_2^{(0)}\otimes hat\{y\}_2^{(0)}\otimes hat\{y\}_2^{(0$

```
## Define the loss function and its gradient
def cce(Y, Yhat):
    return(np.mean(np.?(?*?, axis = ?)))

def cce_gradient(Y, Yhat):
    return(?/?)

# TensorFlow in-built function for categorical crossentropy loss
#cce = tf.keras.losses.CategoricalCrossentropy()
```

Softmax activation layer class:

 $\begin{align*}\begin{bmatrix}\mathbf{a}^{(0)}&\ldots&\mathbf{a}^{(b-1)}\end{bmatrix} &= \\ \end{bmatrix}$

 $\begin{bmatrix}\text{softmax}\left(\mathbf{z}^{(0)}\right)&\dots&\text{softmax}\left(\mathbf{z}^{(b-1)}\right)\end{bmatrix}\\\label{A} &= \text{softmax}\end{bmatrix}\\\label{A} &= \text{softmax}\end{bmatrix}$

 $\begin{bmatrix}\text{softmax}\left(\mathbb{z}^{(0)}\right)&\dots&\text{softmax}\left(\mathbb{z}^{(b-1)}\right)\end{bmatrix}\\A &= \text{softmax}(\mathbb{Z}).\end{align*}$

 $\label{lem:backward: $$\begin{array} color= Backward: $$\Big(a); \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{align*} \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{bmatrix} \end{align*} \end{bmatrix} \end{align*} \end{bmatrix} \end{bmat$

- $0)\}\\(L_0)\&\cdots\&\nabla_{\mathbb{Z}^{(b-1)}}\left(\frac{a}{a}\right)^{(b-1)}\\$
- 1) $\left(\frac{h-1}{(b-1)}\right)$

$$=\begin{bmatrix} \begin{bmatrix} a_0^{(0)} \left(1-a_0^{(0)}\right) & -a_0^{(0)} a_0^{(0)} & -a_2^{(0)} a_0^{(0)} & \cdots & -a_3^{(0)} a_0^{(0)} \\ -a_0^{(0)} a_1^{(0)} & a_1^{(0)} \left(1-a_1\right) & -a_2^{(0)} a_1^{(0)} & \cdots & -a_3^{(0)} a_0^{(0)} \\ -a_0^{(0)} a_1^{(0)} & a_1^{(0)} \left(1-a_1\right) & -a_2^{(0)} a_1^{(0)} & \cdots & -a_3^{(0)} a_0^{(0)} \\ -a_0^{(0)} a_1^{(0)} & a_1^{(0)} \left(1-a_1\right) & -a_2^{(0)} a_1^{(0)} & \cdots & -a_3^{(0)} a_0^{(0)} \\ -a_0^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} & a_2^{(0)} \left(1-a_2^{(0)}\right) & \cdots & -a_3^{(0)} a_2^{(0)} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ -a_0^{(0)} a_0^{(0)} & -a_1^{(0)} a_0^{(0)} & -a_1^{(0)} a_0^{(0)} & a_2^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_0^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_1^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_1^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & \cdots & -a_9^{(0)} a_1^{(0)} \\ -a_0^{(0)} a_1^{(0)} a_1^{(0)} & -a_1^{(0)} a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)} a_2^{(0)} & -a_1^{(0)} a_2^{(0)$$

```
## Softmax activation layer class
class Softmax(Layer):
    def forward(self, input):
        self.output = tf.nn.softmax(?, axis = ?).numpy()

def backward(self, output_gradient, learning_rate = None):
    ## Following is the inefficient way of calculating the backward gradient
    softmax_gradient = np.empty((self.input.shape[0], output_gradient.shape[1]), dtype = np.
    for b in range(softmax_gradient.shape[1]):
        softmax_gradient[:, ?] = np.dot((np.identity(self.output.shape[0])-self.?[:, ?].reshareturn(softmax_gradient)
        ## Following is the efficient of calculating the backward gradient
    #T = (np.transpose(np.identity(self.output.shape[0]) - np.atleast_2d(self.output).T[:,
        #return(np.einsum('ijk, ik -> jk', T, output_gradient))
```

Dense layer class:

 $\label{thm:prop:cond} Forward: $$\$$\$\S\$\ \egin{align*} \egin{bmatrix} \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{((b-1)}\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(0)}\&\cdot \mathbb{z}^{(0)}\otimes\cdot \mathbb{z}^{(b-1)}\cdot \mathbb{z}^{((b-1)}\cdot \mathbb{z}^{((b-1)}\cdot \mathbb{z}^{(0)}\otimes\cdot \mathbb{z}^{(0)}\otimes\cdot$

```
## Dense layer class
class Dense(Layer):
    def __init__(self, input_size, output_size):
        self.weights = 0.01*np.random.randn(?, ?+1) # bias trick
        self.weights[:, ?] = 0.01 # set all bias values to the same nonzero constant
    def forward(self, input):
        self.input = np.vstack([?, np.ones((1, input.shape[?]))]) # bias trick
        self.output= np.dot(?, ?)
    def backward(self, output_gradient, learning_rate):
        ## Following is the inefficient way of calculating the backward gradient
        dense_gradient = np.zeros((self.output.shape[?], self.input.shape[?]), dtype = np.f
        for b in range(output_gradient.shape[1]):
          dense_gradient += np.dot(output_gradient[?, b].reshape(-1, 1), self.input[:, ?].r
        dense_gradient = (1/output_gradient.shape[1])*dense_gradient
        ## Following is the efficient way of calculating the backward gradient
        #dense_gradient = (1/output_gradient.shape[1])*np.dot(np.atleast_2d(output_gradient
        self.weights = self.weights + learning_rate * (-dense_gradient)
```

Function to generate sample indices for batch processing according to batch size

```
## Function to generate sample indices for batch processing according to batch size
def generate_batch_indices(num_samples, batch_size):
    # Reorder sample indices
    reordered_sample_indices = np.random.choice(num_samples, num_samples, replace = False)
    # Generate batch indices for batch processing
    batch_indices = np.split(reordered_sample_indices, np.arange(batch_size, len(reordered_sample_indices))
```

Example generation of batch indices

```
## Example generation of batch indices
num_samples = 64
batch_size = 16
batch_indices = generate_batch_indices(num_samples, batch_size)
print(batch_indices)
```

Train the 0-layer neural network using batch training with batch size = 16

```
## Train the 0-layer neural network using batch training with batch size = 16
learning_rate = ? # learning rate
batch_size = ? # batch size
nepochs = ? # number of epochs
loss_epoch = np.empty(nepochs, dtype = np.float32) # create empty array to store losses ov€
# Neural network architecture
dlayer = Dense(?, ?) # define dense layer
softmax = Softmax() # define softmax activation layer
# Steps: run over each sample in the batch, calculate loss, gradient of loss,
# and update weights.
epoch = 0
while epoch < nepochs:
  batch_indices = generate_batch_indices(num_samples, batch_size)
  for b in range(len(batch indices)):
    dlayer.forward(?) # forward prop
    softmax.forward(?) # Softmax activate
    loss += cce(?, ?) # calculate loss
    # Backward prop starts here
## Plot training loss as a function of epoch:
plt.plot(loss epoch)
plt.xlabel('Epoch')
plt.ylabel('Loss value')
plt.show()
## Accuracy on test set
dlayer.forward(X_test)
softmax.forward(dlayer.output)
ypred = np.argmax(softmax.output.T, axis = 1)
print(ypred)
ytrue = np.argmax(Y test.T, axis = 1)
print(ytrue)
np.mean(ytrue == ypred)
```