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21AIE315 AI in Speech Processing

Sheet 1

MATRIX, the foundation for MATLAB

```
C = [-1, 0, 0; 1,1,0; 1,-1,0; 0,0,2]
C = 4 \times 3
-1  0  0
```

$$D = 4 \times 3$$
-1 0 0
1 1 0
1 -1 0
0 0
2

The semicolon here is going to distinguish the row and colomns in the matrix.

$$B = [3,5,6]$$

$$B = 1 \times 3$$
 $3 \quad 5 \quad 6$

another matrix can be instuted under another matrix.

The matrix can be extended/modified by defining new elements.

$$S(2) = 2$$

$$S = 1 \times 5$$
 $7 \quad 2 \quad 3 \quad 5 \quad 6$

$$S = 1 \times 6$$
7 2 3 5 6 9

```
S(9) = 13
 S = 1 \times 9
              3 5 6 9 0 0 13
 I = [1,2,4];
 S(I) = 42
 S = 1 \times 9
         42 3 42 6 9 0 0 13
    42
 S(I+1) = 45
 S = 1 \times 9
    42
         45 45
                  42 45 9 0 0 13
Colon Operator
The colon operator is a very powerful operator for creating new matrices.
 % Create a row vector from 1 to 10
 vec = 1:10
 vec = 1 \times 10
     1 2 3
                   4 5 6 7 8 9 10
 % Create a column vector from 1 to 10
 vec_column = (1:10)'
 vec\_column = 10 \times 1
     1
     2
     3
     4
     5
     6
     7
     8
     9
     10
 % Create a 3x3 matrix
 A = [1, 2, 3; 4, 5, 6; 7, 8, 9]
 A = 3 \times 3
     1
          2 3
     4
          5
               6
     7
          8
               9
 % Select the second row of matrix A
```

 $row_2 = A(2, :)$

 $C = 2 \times 3$

2

5

3

```
% Access the second element using linear indexing
 second_element = C(2)
 second_element = 4
Matrix Operator
 % Define two matrices
 A = [1, 2, 3; 4, 5, 6; 7, 8, 9];
 B = [9, 8, 7; 6, 5, 4; 3, 2, 1];
 % Matrix addition
 C = A + B
 C = 3 \times 3
    10 10 10
    10 10 10
    10 10
             10
 % Matrix subtraction
 D = A - B
 D = 3 \times 3
    -8 -6 -4
    -2 0 2
     4 6 8
 % Matrix multiplication
 E = A * B
 E = 3 \times 3
    30 24 18
    84 69 54
   138 114 90
 % Element-wise multiplication
 F = A \cdot * B
 F = 3 \times 3
    9 16 21
    24 25 24
 % Transpose of A
 A_transpose = A'
 A_{transpose} = 3 \times 3
     1 4 7
     2 5 8
     3 6 9
 % Inverse of A
 A_{inverse} = inv(A)
```

```
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 1.541976
A_inverse = 3 \times 3
10^{16} \times
  -0.4504 0.9007 -0.4504
   0.9007 -1.8014 0.9007
  -0.4504
          0.9007 -0.4504
% Matrix exponentiation
A_squared = A^2
A_squared = 3 \times 3
   30
        36
             42
   66
        81
             96
  102 126 150
zeros(6)
ans = 6 \times 6
    0
         0
                             0
              0
                  0
                        0
                   0 0 0
    0
              0
         0
    0
         0
              0 0 0 0
    0
         0
              0
                  0 0 0
    0
         0
              0
                  0 0 0
    0
zeros(3,2)
ans = 3 \times 2
    0
         0
    0
         0
    0
ones(6)
ans = 6 \times 6
    1
         1
              1
                   1
                        1
    1
         1
              1
                   1
                          1
    1
         1
              1
                   1
                        1
                          1
    1
              1 1
                        1 1
        1
                  1
                       1
    1
        1
              1
                            1
              1 1
                        1
    1
       1
                             1
ones(3,2)
ans = 3 \times 2
    1
         1
    1
         1
    1
         1
C = [1, 2, 3; 4,5,6; 7,8,9]
```

 $C = 3 \times 3$

```
5
                  6
                  9
 % prints the diagonal of D
 diag(C)
  ans = 3 \times 1
      1
      5
      9
Labsheet -1
lab exercises
1
 help sqrt
   sqrt Square root.
      sqrt(X) is the square root of the elements of X. Complex
      results are produced if X is not positive.
     See also sqrtm, realsqrt, hypot.
     Documentation for sqrt
     Other uses of sqrt
 x = sqrt(4)
  x = 2
 y = sqrt(9)
 y = 3
 % we get square roots for the variables given
  who
  Your variables are:
                 A_inverse
                                 A_squared
                                                A_transpose
                                                                                               D
  whos
   Name
                        Size
                                        Bytes Class
                                                        Attributes
                                          72 double
                        3x3
   A_inverse
                                          72 double
                        3x3
                                          72 double
   A_squared
                        3x3
   A_transpose
                        3x3
                                          72 double
```

72 double

72 double

2

1

3

3x3

3x3

C

```
D
                                        72 double
                     3x3
Ε
                     3x3
                                        72 double
F
                                        72 double
                     3x3
Ι
                                        24 double
                     1x3
S
                     1x9
                                        72 double
                                        24 double
ans
                     3x1
col_2
                                        24 double
                     3x1
                                       168 double
range
                     1x21
reshaped_B
                     2x6
                                        96 double
                                        80 double
reverse_range
                     1x10
row_2
                     1x3
                                        24 double
                                        8 double
{\sf second\_element}
                     1x1
submatrix
                     2x2
                                        32 double
VAC
                     1×10
                                        80 double
```

 $z = \sin(0)$

z = 0

z1 = sin(pi/2)

z1 = 1

whos

Name	Size	Bytes	Class	Attributes
Α	3x3	72	double	
A_inverse	3x3	72	double	
				
A_squared	3x3	72	double	
A_transpose	3x3	72	double	
В	3x3	72	double	
C	3x3	72	double	
D	3x3	72	double	
E	3x3	72	double	
F	3x3	72	double	
I	1x3	24	double	
S	1x9	72	double	
ans	3x1	24	double	
col_2	3x1	24	double	
range	1x21	168	double	
reshaped_B	2x6	96	double	
reverse_range	1x10	80	double	
row_2	1x3	24	double	
second_element	1x1	8	double	
submatrix	2x2	32	double	
vec	1x10	80	double	
vec_column	10x1	80	double	
X	1x1	8	double	

clc who

Your variables are:

A A_inverse A_squared A_transpose B C D

```
clear
who
size(x)
Unrecognized function or variable 'x'.
a = [1 \ 2 \ 3]
a = 1 \times 3
  1 2 3
b = [3 \ 4 \ 5]
b = 1 \times 3
  3 4 5
a.*b
ans = 1 \times 3
3 8 15
C = [a b]
C = 1 \times 6
  1 2 3 3 4 5
zeros(4)
ans = 4 \times 4
  0 0 0 0
    0 0 0 0
   0 0 0
                  0
   0 0
zeros(1, 3)
ans = 1 \times 3
 0 0 0
ones(1, 2)
ans = 1 \times 2
  1 1
P = [zeros(1,3) \ 1 \ 1 \ ones(1,2)]
P = 1 \times 7
  0 0 0 1 1 1 1
Y = 1 : 0.5 : 5
Y = 1 \times 9
```

1.0000 1.5000 2.0000 2.5000 3.0000 3.5000 4.0000 4.5000 5.0000

•

```
M = [1 \ 2 \ 3]
 4 5 6
 7 8 9]
 M = 3 \times 3
     1
         2 3
     4
           5
               6
     7
           8
                9
 fprintf('%f\n', M)
 1.000000
 4.000000
 7.000000
 2.000000
 5.000000
 8.000000
 3.000000
 6.000000
 9.000000
 X = M(1,:)
 X = 1 \times 3
    1 2 3
2
a.
 A = [3, 12, 6, 8; 5, 3, 9, 11; 1, 2, 14, 7; 10, 5, 3, 6]
 A = 4 \times 4
     3
        12 6
                    8
          3 9
     5
                    11
     1
           2 14
                    7
     10
           5
               3
                     6
 A = [3, 12, 6, 8]
    5, 3, 9, 11
     1, 2, 14, 7
     10, 5, 3, 6]
 A = 4 \times 4
     3
          12
             6
                    8
     5
               9
         3
                    11
     1
           2
               14
                    7
     10
         5
             3
                     6
 E = [3, 12, 6, 8; 5, 3, 9, 11]
 F = [1, 2, 14, 7; 10, 5, 3, 6]
 G = [E; F]
 E = 2 \times 4
```

3 12 6

3

5

8

11

9

```
F = 2 \times 4
     1
         2 14 7
     10
         5
               3
 G = 4 \times 4
     3
          12 6
                    8
     5
           3
                9
                    11
     1
           2
               14
                     7
     10
           5
                3
b.
 A_transpose = A';
 disp('Transpose of A:');
 Transpose of A:
 disp(A_transpose);
     3
           5
               1
                    10
     12
                2
                     5
           3
     6
           9
               14
                     3
     8
          11
                7
 A_{inverse} = inv(A);
 disp('Inverse of A:');
 Inverse of A:
 disp(A_inverse);
            -0.0607
    -0.0490
                      0.0296
                               0.1421
    0.0979
           -0.0831
                    0.0091
                               0.0113
    -0.0140 -0.0920 0.1286
                             0.0373
    0.0070
            0.2165 -0.1211
                             -0.0982
C.
 size(A)
d.
 % Extract the second row into vector X
 X = A(2, :);
 % Extract the third column into vector Y
 Y = A(:, 3);
 % Display the vectors
 disp('Vector X (second row of A):');
 Vector X (second row of A):
 disp(X);
           3
                    11
```

```
disp('Vector Y (third column of A):');
 Vector Y (third column of A):
 disp(Y);
      6
      9
     14
      3
e.
 % Multiply X and Y (performing the dot product)
 result = X * Y;
 % Display the result
 disp('Result of multiplying X and Y:');
 Result of multiplying X and Y:
 disp(result);
    216
f.
 % Multiply X and Y element-wise
 result_elementwise = X .* Y;
 % Display the result
 disp('Result of element-wise multiplication of X and Y:');
 Result of element-wise multiplication of X and Y:
 disp(result_elementwise);
     30
          18 54
                    66
     45
          27 81
                    99
     70
          42 126 154
     15 9 27 33
g.
 % Define the new row vector
 new_row = [1, 5, 9, 0];
 % Replace the last row of A with the new row vector
 A(end, :) = new_row;
 % Display the updated matrix A
 disp('Updated matrix A with the last row replaced:');
```

Updated matrix A with the last row replaced:

```
disp(A);
     3
         12 6
     5
         3 9 11
     1 2 14 7
          5 9
h.
 % Print the elements in one row
 disp('Matrix A printed in one row:');
 Matrix A printed in one row:
 disp(A(:)');
     3
          5
               1
                   1 12 3 2 5 6 9 14 9 8 11
                                                                         7
                                                                              0
 % Print the elements in one column
 disp('Matrix A printed in one column:');
 Matrix A printed in one column:
 disp(A(:));
     3
     5
     1
     1
     12
     3
     2
     5
     6
     9
     14
     9
     8
     11
     7
i.
 % Calculate the total number of elements in A
 total_elements = numel(A);
 % Print the elements of A in reverse order
 disp('Matrix A printed in reverse order:');
 Matrix A printed in reverse order:
```

```
for i = total_elements:-1:1
   fprintf('%d ', A(i));
```

```
end
```

```
0 7 11 8 9 14 9 6 5 2 3 12 1 1 5 3
 fprintf('\n');
j.
 % Extract the diagonal elements of A into vector D
 D = diag(A);
 % Display the vector D containing diagonal elements
 disp('Vector D containing diagonal elements of matrix A:');
 Vector D containing diagonal elements of matrix A:
 disp(D);
      3
      3
     14
      0
k.
 % Extract the diagonal elements of A into vector D
 D = diag(A);
 % Create a diagonal matrix V with the extracted diagonal elements
 V = diag(D);
 % Display the diagonal matrix V
 disp('Diagonal matrix V with the extracted diagonal elements:');
 Diagonal matrix V with the extracted diagonal elements:
 disp(V);
      3
           0
              0
                     0
           3 0
           0
               14
           0
                0
I.
 % Get the size of the matrix V
 [size_rows, size_columns] = size(V);
 % Create an identity matrix of the same size as V
 identity_matrix = eye(size_rows, size_columns);
 % Display the identity matrix
 disp('Identity matrix of the same size as V:');
```

Identity matrix of the same size as V:

```
disp(identity_matrix);
          0
              0
          1
m.
 % Get the size of the matrix V
 [size_rows, size_columns] = size(V);
 % Create an identity matrix of the same size as V
 identity_matrix = eye(size_rows, size_columns);
 % Concatenate V and the identity matrix along columns
 new_matrix = [V, identity_matrix];
 % Create a new matrix double the size by concatenating new_matrix with itself along rows
 new_matrix_double_size = [new_matrix; new_matrix];
 % Display the new matrix double the size
 disp('New matrix double the size:');
 New matrix double the size:
 disp(new_matrix_double_size);
     3
          0
                       1
                              0
                                      0
          3
              0
     0 0 14 0 0 0 1
                  0 0 0 0
     0
         0 0
     3 0 0 0 1 0 0
        3 0 0 0 1 0
     0
     0 0 14 0 0 0 1 0
     0 0 0 0 0 0 1
3.
 % Create a vector with the specified elements
 vector = 0:0.01:1;
 % Find the length of the vector
 vector_length = length(vector);
 % Display the vector and its length
 disp('Vector:');
 Vector:
 disp(vector);
            0.0100
                    0.0200
                           0.0300
                                   0.0400
                                           0.0500
                                                   0.0600
                                                                          0.09
                                                          0.0700
                                                                  0.0800
```

```
disp(['Length of the vector: ', num2str(vector_length)]);
 Length of the vector: 101
4.
 % Define the vectors x and y
 x = [1, 6, 9, 2];
 y = [2, 0, 3, 8];
 % Element-wise sum of x and y
 sum_xy = x + y;
 % Element-wise product of x and y
 product_xy = x .* y;
 % Display the element-wise sum and product
 disp('Element-wise sum of x and y:');
 Element-wise sum of x and y:
 disp(sum_xy);
      3 6 12
                    10
 disp('Element-wise product of x and y:');
 Element-wise product of x and y:
 disp(product_xy);
           0 27
                     16
5.
 % Define some variables
 x = 1;
 y = [2, 3];
 z = 'hello';
 % Display variable names using who
 disp('Variables in workspace (using who):');
 Variables in workspace (using who):
 who
 Your variables are:
                                                                 C
 Α
                      A_inverse
                                            A_transpose
                                                                                       D
 % Display detailed information using whos
```

```
disp('Variables in workspace (using whos):');
```

Variables in workspace (using whos):

whos			

Name	Size	Bytes	Class	Attributes	
Α	4x4	128	double		
A_inverse	4x4	128	double		
A_transpose	4x4	128	double		
С	1x6	48	double		
D	4x1	32	double		
Е	2x4	64	double		
F	2x4	64	double		
G	4x4	128	double		
M	3x3	72	double		
Р	1x7	56	double		
V	4x4	128	double		
Χ	1x4	32	double		
Υ	4x1	32	double		

6.

```
% Define the matrix U
U = [4, 5, 6, 7];

% Calculate the sum of all elements
sum_U = sum(U);

% Calculate the mean of all elements
mean_U = mean(U);

% Calculate the median of all elements
median_U = median(U);

% Display the results
disp(['Sum of all elements of U: ', num2str(sum_U)]);
```

```
Sum of all elements of U: 22
```

```
disp(['Mean of all elements of U: ', num2str(mean_U)]);
```

```
Mean of all elements of U: 5.5
```

```
disp(['Median of all elements of U: ', num2str(median_U)]);
```

```
Median of all elements of U: 5.5
```