Lab Manual For

NEURAL NETWORKS LAB (CM703PC)

IV B. TECH I SEMESTER (R20 - AUTONOMOUS)



DEPARTMENT OF CSE (ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING)





An Autonomous Institution

Ghatkesar, Hyderabad - 501 301, Telangana.

Approved by AICTE & Affiliated to JNTUH

NBA Accredited B.Tech Courses, Accorded NACC A-Grade with 3.20 CGPA



ACE



Engineering College

An Autonomous Institution

Ghatkesar, Hyderabad - 501 301, Telangana.

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DEPARTMENT OF CSE

(ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING)

Lab Manual

Neural Networks Lab (CM703PC)

IV B. TECH I SEMESTER

Institute Vision:

To be a leading Technical Institute to prepare high quality Engineers to cater the needs of the stakeholders in the field of Engineering and Technology with global competence fundamental comprehensive analytical skills, critical reasoning, research aptitude, entrepreneur skills, ethical values and social concern.

Institute Mission:

Imparting Quality Technical Education to young Engineers by providing the state-of-the-art laboratories, quality instructions by qualified and experienced faculty and research facilities to meet the requirements of stakeholders in real time usage and in training them to excel in competitive examinations for higher education and employment to interface globally emerging techno-informative challenges in the growth corridor of techno-excellence.

Department Vision:

To be an epicenter of excellence in education by offering thrust courses, research and services for the students and make them to succeed in professional **competitive examinations** globally with an attitude of entrepreneurial skills, ethical values and social concern.

Department Mission:

Imparting quality Technical Education to young Computer Engineer by providing them

M1: Impart quality technical Education with State of-the-art laboratories, Analytical and Technical Skills with International standards by qualified and experienced faculty

M2: Prepare for competitive examinations for higher studies / Employment

M3: Develop professional attitude, Research aptitude, Critical Reasoning and technical consultancy by providing training in cutting edge technologies.

M4: Endorse and Nurture knowledge, Life-long learning, Entrepreneurial practices, ethical values and social concern

Program Educational Objectives (PEOs):

- **PEO 1:** To prepare the students for successful careers in Computer Science and Engineering and fulfill the need by providing training to excel in competitive examinations for higher education and employment.
- **PEO 2:** To provide students a broad-based curriculum with a firm foundation in Computer Science and Engineering, Applied Mathematics & Sciences. To impart high quality technical skills for designing, modeling, analyzing and critical problem solving with global competence.
- **PEO 3:** To inculcate professional, social, ethical, effective communication skills and entrepreneurial practice among their holistic growth.
- **PEO 4:** To provide Computer Science and Engineering students with an academic environment and members associated with student related to professional bodies for multi-disciplinary approach and for lifelong learning.
- **PEO 5:** To develop research aptitude among the students in order to carry out research in cutting edge technologies, solve real world problems and provide technical consultancy services.

Program Outcomes:

Program Outcomes	Statement
PO1	An ability to apply knowledge of mathematics, science, and engineering and knowledge of Fundamental Principles.
PO2	An ability to Identify, formulate and solve engineering problems.
PO3	An ability to design a system, component, or process to meet desired needs in Computer Science and Engineering within realistic constraints such as economic, environmental, social, political, ethical, health and safety, manufacturability and sustainability, Design and Modeling.
PO4	An ability to design and conduct experiments, as well as to analyze and interpret data, Experimentation & Interpret/Engineering Analysis.
PO5	An ability to use the techniques, skills and modern Computer Science and Engineering tools necessary for system design with embedded engineering

	practice.	
PO6	Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.	
PO7	The broad education necessary to understand the impact of engineering solutions in a global, economic, environmental, and societal context.	
PO8	An understanding of professional and ethical responsibility.	
PO9	An ability to function on multidisciplinary teams.	
PO10	An ability to communicate effectively.	
PO11	Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.	
PO12	A recognition of the need for, and an ability to engage in life-long learning.	

Program Specific Outcomes:

Program Specific Outcomes	Statement
PSO1	To prepare the students ready for industry usage by providing required training in cutting edge technologies.
PSO2	An Ability to use the core concepts of computing and optimization techniques to develop more efficient and effective computing mechanisms.
PSO3	Prepare the graduates to demonstrate a sense of societal and ethical responsibility In their professional endeavors and will remain informed and involved as full participants in the profession and our society.







ACE Engineering College An AUTONOMOUS Institution

Ghatkesar, Medchal (Dist), Hyderabad, Telangana State – 501 301 (NBA Accredited B.Tech Courses Accredited NAAC with A Grade 3.20 CGPA)

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DEPARTMENT OF CSE (ARTIFICIAL INTELLIGENCE & MACHINE LEARNING)

NEURAL NETWORKS LAB

B.Tech .IV Year I Sem. CM703PC

LTPC 0021

LIST OF EXPERIMENTS:

- 1. Implementation of Perceptron Model in Python
- 2. Implementation of Sigmoid Model in Python
- 3. Implement 2 layer Feed Forward Network(FFN) for non separable 2 class problem in Python and compare the performance with the sigmoid Model
- 4. Introduction to Frameworks- Pytorch
- 5. Implement Fully Connected Neural Network(FCNN) for MNIST dataset in Pytorch
- 6. Analyze vanishing gradient problem by using various activation functions
- 7. Analyze the performance of FCNN using various Optimization methods
- 8. Apply dropout regularization technique to enhance the performance of FCNN
- 9. Implement Convolution Neural Network(CNN) on CIFAR10 data set
- 10. Implement Recurrent Neural network for text classification

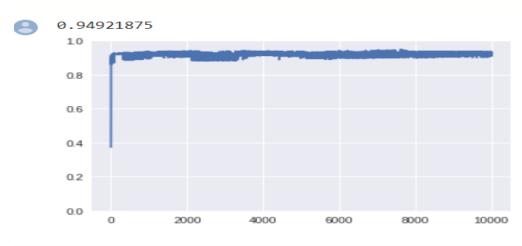
1. Program to implementation Perceptron Model in Python

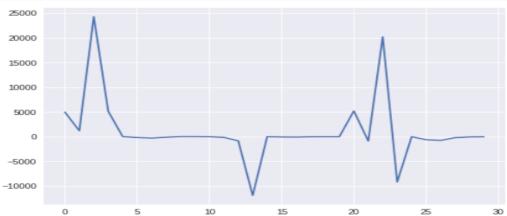
```
import sklearn.datasets
import numpy as np
import pandas as pd
from sklearn.model_selection import train_test_split
#Perceptron Model
class Perceptron:
 def init (self):
  self.w = None
  self.b = None
 def model(self, x):
  return 1 if (np.dot(self.w, x) \ge self.b) else o
 def predict(self, X):
  Y = []
  for x in X:
   result = self.model(x)
   Y.append(result)
  return np.array(Y)
 def fit(self, X, Y, epochs = 1, lr = 1):
  self.w = np.ones(X.shape[1])
  self.b = o
  accuracy = {}
  max_accuracy = 0
  wt matrix = []
  for i in range(epochs):
   for x, y in zip(X, Y):
    y_pred = self.model(x)
    if y == 1 and y_pred == 0:
     self.w = self.w + lr * x
     self.b = self.b - lr * 1
    elif y == 0 and y_pred == 1:
     self.w = self.w - lr * x
     self.b = self.b + lr * 1
   wt matrix.append(self.w)
   accuracy[i] = accuracy_score(self.predict(X), Y)
   if (accuracy[i] > max_accuracy):
    max_accuracy = accuracy[i]
    chkptw = self.w
    chkptb = self.b
  self.w = chkptw
  self.b = chkptb
  print(max accuracy)
  plt.plot(accuracy.values())
  plt.ylim([0, 1])
  plt.show()
  return np.array(wt matrix)
# Loading the dataset and splitting the dataset
breast cancer = sklearn.datasets.load breast cancer()
```

```
X = breast cancer.data
Y = breast_cancer.target
data = pd.DataFrame(breast cancer.data, columns=breast cancer.feature names)
data['class'] = breast_cancer.target
X = data.drop('class', axis=1)
Y = data['class']
X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size=0.1, stratify = Y,
                 random state=1)
X train = X train.values
X_{\text{test}} = X_{\text{test.values}}
# Model Training & Prediction
perceptron = Perceptron()
wt matrix = perceptron.fit(X train, Y train, 10000, 0.5)
Y_pred_test = perceptron.predict(X_test)
print(accuracy_score(Y_pred_test, Y_test))
plt.plot(wt_matrix[-1,:])
plt.show()
```

Output:

0.9298245614035088





2. Program to implementation Sigmoid Model in Python

```
import numpy as np
import matplotlib.pyplot as plt
from mpl toolkits import mplot3d
import matplotlib.colors
import pandas as pd
from sklearn.preprocessing import StandardScaler, MinMaxScaler
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy score, mean squared error
from tqdm import tqdm notebook
class SigmoidNeuron:
 def init (self):
  self.w = None
  self.b = None
 def perceptron(self, x):
 return np.dot(x, self.w.T) + self.b
 def sigmoid(self, x):
 return 1.0/(1.0 + np.exp(-x))
 def grad w(self, x, y):
 y pred = self.sigmoid(self.perceptron(x))
 return (y pred - y) * y pred * (1 - y pred) * x
 def grad b(self, x, y):
 y_pred = self.sigmoid(self.perceptron(x))
 return (y pred - y) * y pred * (1 - y pred)
 def fit(self, X, Y, epochs=1, learning rate=1, initialise=True, display loss=False):
  # initialise w, b
 if initialise:
   self.w = np.random.randn(1, X.shape[1])
   self.b = o
 if display_loss:
   loss = \{\}
  for i in tqdm notebook(range(epochs), total=epochs, unit="epoch"):
   dw = 0
   db = 0
   for x, y in zip(X, Y):
    dw += self.grad_w(x, y)
    db += self.grad b(x, y)
   self.w -= learning rate * dw
   self.b -= learning_rate * db
   if display loss:
    Y_pred = self.sigmoid(self.perceptron(X))
    loss[i] = mean squared error(Y pred, Y)
 if display_loss:
```

```
plt.plot(loss.values())
plt.xlabel('Epochs')
plt.ylabel('Mean Squared Error')
plt.show()

def predict(self, X):
Y_pred = []
for x in X:
y_pred = self.sigmoid(self.perceptron(x))
Y_pred.append(y_pred)
return np.array(Y_pred)

#Fit for toy data
X = np.asarray([[2.5, 2.5], [4, -1], [1, -4], [-3, 1.25], [-2, -4], [1, 5]])
Y = [1, 1, 1, 0, 0, 0]
sn = SigmoidNeuron()
sn.fit(X, Y, 1, 0.25, True)
```

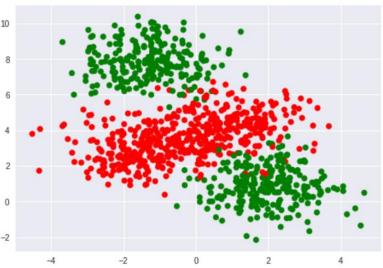
3. Implement 2 layer Feed Forward Network(FFN) for non separable 2 class problem in Python and compare the performance with the sigmoid Model

```
import numpy as np
import matplotlib.pyplot as plt
import matplotlib.colors
import pandas as pd
from sklearn.model selection import train test split
from sklearn.metrics import accuracy_score, mean_squared_error
from tgdm import tgdm notebook
from sklearn.preprocessing import OneHotEncoder
from sklearn.datasets import make blobs
class SigmoidNeuron:
 def __init__(self):
  self.w = None
  self.b = None
 def perceptron(self, x):
  return np.dot(x, self.w.T) + self.b
 def sigmoid(self, x):
  return 1.0/(1.0 + np.exp(-x))
 def grad_w_mse(self, x, y):
  y_pred = self.sigmoid(self.perceptron(x))
  return (y pred - y) * y pred * (1 - y pred) * x
 def grad_b_mse(self, x, y):
  v pred = self.sigmoid(self.perceptron(x))
  return (y_pred - y) * y_pred * (1 - y_pred)
 def grad w ce(self, x, y):
  y_pred = self.sigmoid(self.perceptron(x))
  if y == 0:
   return y_pred * x
  elif y == 1:
   return -1 * (1 - y pred) * x
   raise ValueError("y should be o or 1")
 def grad_b_ce(self, x, y):
  y pred = self.sigmoid(self.perceptron(x))
  if y == 0:
   return v pred
  elif y == 1:
   return -1 * (1 - y_pred)
   raise ValueError("y should be o or 1")
```

```
def fit(self, X, Y, epochs=1, learning rate=1, initialise=True, loss fn="mse", display loss=False):
  # initialise w, b
  if initialise:
   self.w = np.random.randn(1, X.shape[1])
   self.b = 0
  if display loss:
   loss = \{\}
  for i in tqdm notebook(range(epochs), total=epochs, unit="epoch"):
   db = 0
   for x, y in zip(X, Y):
    if loss fn == "mse":
     dw += self.grad_w_mse(x, y)
     db += self.grad\_b mse(x, y)
    elif loss fn == "ce":
     dw += self.grad_w_ce(x, y)
     db += self.grad_b_ce(x, y)
   m = X.shape[1]
   self.w -= learning_rate * dw/m
   self.b -= learning rate * db/m
   if display loss:
    Y pred = self.sigmoid(self.perceptron(X))
    if loss fn == "mse":
     loss[i] = mean squared error(Y, Y pred)
    elif loss fn == "ce":
     loss[i] = log_loss(Y, Y_pred)
  if display loss:
   plt.plot(loss.values())
   plt.xlabel('Epochs')
   if loss_fn == "mse":
    plt.ylabel('Mean Squared Error')
   elif loss fn == "ce":
    plt.ylabel('Log Loss')
   plt.show()
 def predict(self, X):
  Y_pred = []
  for x in X:
   y pred = self.sigmoid(self.perceptron(x))
   Y_pred.append(y_pred)
  return np.array(Y_pred)
my cmap = matplotlib.colors.LinearSegmentedColormap.from list("", ["red", "yellow", "green"])
```

```
#Generate data
```

```
data, labels = make_blobs(n_samples=1000, centers=4, n_features=2, random_state=0)
print(data.shape, labels.shape)
labels_orig = labels
labels = np.mod(labels_orig, 2)
plt.scatter(data[:,0], data[:,1], c=labels, cmap=my_cmap)
plt.show()
X_train, X_val, Y_train, Y_val = train_test_split(data, labels, stratify=labels, random_state=0)
print(X_train.shape, X_val.shape)
```



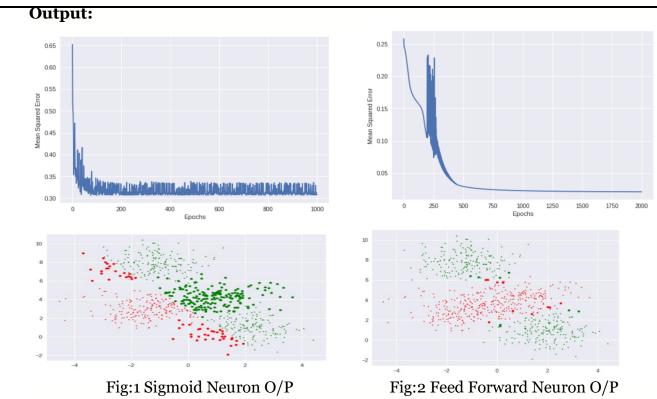
#SN classification

self.w3 = np.random.randn()
self.w4 = np.random.randn()
self.w5 = np.random.randn()
self.w6 = np.random.randn()

```
sn = SigmoidNeuron()
sn.fit(X train, Y train, epochs=1000, learning rate=0.5, display loss=True)
Y pred train = sn.predict(X train)
Y pred binarised train = (Y pred train >= 0.5).astype("int").ravel()
Y \text{ pred } val = sn.predict(X val)
Y_pred_binarised_val = (Y_pred_val >= 0.5).astype("int").ravel()
accuracy_train = accuracy_score(Y_pred_binarised_train, Y_train)
accuracy val = accuracy score(Y pred binarised val, Y val)
print("Training accuracy", round(accuracy_train, 2))
print("Validation accuracy", round(accuracy_val, 2))
plt.scatter(X train[:,0], X train[:,1], c=Y pred binarised train, cmap=my cmap,
s=15*(np.abs(Y pred binarised train-Y train)+.2))
plt.show()
#Our First FF Network
class FirstFFNetwork:
 def __init (self):
  self.w1 = np.random.randn()
  self.w2 = np.random.randn()
```

```
self.b1 = 0
 self.b2 = 0
 self.b3 = 0
def sigmoid(self, x):
 return 1.0/(1.0 + np.exp(-x))
def forward pass(self, x):
 self.x1. self.x2 = x
 self.a1 = self.w1*self.x1 + self.w2*self.x2 + self.b1
 self.h1 = self.sigmoid(self.a1)
 self.a2 = self.w3*self.x1 + self.w4*self.x2 + self.b2
 self.h2 = self.sigmoid(self.a2)
 self.a_3 = self.w_5 * self.h_1 + self.w_6 * self.h_2 + self.h_3
 self.h3 = self.sigmoid(self.a3)
 return self.h3
def grad(self, x, y):
 self.forward_pass(x)
 self.dw_5 = (self.h_3-y) * self.h_3*(1-self.h_3) * self.h_1
 self.dw6 = (self.h3-y) * self.h3*(1-self.h3) * self.h2
 self.db3 = (self.h3-y) * self.h3*(1-self.h3)
 self.dw1 = (self.h3-y) * self.h3*(1-self.h3) * self.w5 * self.h1*(1-self.h1) * self.x1
 self.dw2 = (self.h3-y) * self.h3*(1-self.h3) * self.w5 * self.h1*(1-self.h1) * self.x2
 self.db1 = (self.h3-y) * self.h3*(1-self.h3) * self.w5 * self.h1*(1-self.h1)
 self.dw_3 = (self.h_3-v) * self.h_3*(1-self.h_3) * self.w_6 * self.h_2*(1-self.h_2) * self.x_1
 self.dw4 = (self.h3-y) * self.h3*(1-self.h3) * self.w6 * self.h2*(1-self.h2) * self.x2
 self.db2 = (self.h3-y) * self.h3*(1-self.h3) * self.w6 * self.h2*(1-self.h2)
def fit(self, X, Y, epochs=1, learning rate=1, initialise=True, display loss=False):
 # initialise w. b
 if initialise:
  self.w1 = np.random.randn()
  self.w2 = np.random.randn()
  self.w3 = np.random.randn()
  self.w4 = np.random.randn()
  self.w5 = np.random.randn()
  self.w6 = np.random.randn()
  self.b1 = 0
  self.b2 = 0
  self.b3 = 0
 if display_loss:
  loss = \{\}
 for i in tqdm notebook(range(epochs), total=epochs, unit="epoch"):
  dw1, dw2, dw3, dw4, dw5, dw6, db1, db2, db3 = [0]*9
```

```
for x, y in zip(X, Y):
    self.grad(x, y)
    dw1 += self.dw1
    dw2 += self.dw2
    dw3 += self.dw3
    dw4 += self.dw4
    dw_5 += self.dw_5
    dw6 += self.dw6
    db1 += self.db1
    db2 += self.db2
    db3 += self.db3
   m = X.shape[1]
   self.w1 -= learning rate * dw1 / m
   self.w2 -= learning rate * dw2 / m
   self.w3 -= learning_rate * dw3 / m
   self.w4 -= learning rate * dw4 / m
   self.w5 -= learning rate * dw5 / m
   self.w6 -= learning_rate * dw6 / m
   self.b1 -= learning rate * db1 / m
   self.b2 -= learning_rate * db2 / m
   self.b3 -= learning rate * db3 / m
   if display loss:
    Y pred = self.predict(X)
    loss[i] = mean squared error(Y pred, Y)
  if display loss:
   plt.plot(loss.values())
   plt.xlabel('Epochs')
   plt.ylabel('Mean Squared Error')
   plt.show()
 def predict(self, X):
  Y pred = []
  for x in X:
   y_pred = self.forward_pass(x)
   Y pred.append(y pred)
  return np.array(Y pred)
ffn = FirstFFNetwork()
ffn.fit(X_train, Y_train, epochs=2000, learning_rate=.01, display_loss=True)
Y pred train = ffn.predict(X train)
Y_pred_binarised_train = (Y_pred_train >= 0.5).astype("int").ravel()
Y pred val = ffn.predict(X val)
Y_pred_binarised_val = (Y_pred_val >= 0.5).astype("int").ravel()
accuracy train = accuracy score(Y pred binarised train, Y train)
accuracy_val = accuracy_score(Y_pred_binarised_val, Y_val)
plt.scatter(X train[:,0], X train[:,1], c=Y pred binarised train, cmap=my cmap,
s=15*(np.abs(Y pred binarised train-Y train)+.2))
plt.show()
```



```
4. Introduction to Frameworks- Pytorch
      import torch
      import numpy as np
      import matplotlib.pyplot as plt
#Initialise tensors
      x = torch.ones(3, 2)
      print(x)
      x = torch.zeros(3, 2)
      print(x)
      x = torch.rand(3, 2)
      print(x)
      Output
      tensor([[1., 1.],
           [1., 1.],
           [1., 1.]
      tensor([[o., o.],
           [0., 0.],
           [0., 0.]
      tensor([[0.3102, 0.8892],
           [0.1277, 0.3445],
           [0.0322, 0.5172]
      x = torch.empty(3, 2)
      print(x)
      y = torch.zeros_like(x)
      print(y)
      Output:
      tensor([[4.4765e-35, 0.0000e+00],
           [1.2773e-01, 3.4447e-01],
           [8.9683e-44, 0.0000e+00]])
      tensor([[o., o.],
           [0., 0.],
           [0., 0.]
      x = torch.linspace(0, 1, steps=5)
      print(x)
      tensor([0.0000, 0.2500, 0.5000, 0.7500, 1.0000])
      x = torch.tensor([[1, 2],
               [3, 4],
               [5, 6]])
      print(x)
      Output:
      tensor([[1, 2],
           [3, 4],
           [5, 6]]
```

Slicing tensors

```
print(x.size())
       print(x[:, 1])
       print(x[o, :])
       Output:
       torch.Size([3, 2])
       tensor([2, 4, 6])
       tensor([1, 2])
       y = x[1, 1]
       print(y)
       print(y.item())
       Output:
       tensor(4)
       4
       ## Reshaping tensors
       print(x)
       y = x.view(2, 3)
       print(y)
       Output:
       tensor([[1, 2],
           [3, 4],
           [5, 6]])
       tensor([[1, 2, 3],
           [4, 5, 6]]
      y = x.view(6,-1)
       print(y)
       Output:
       tensor([[1],
           [2],
           [3],
           [4],
           [5],
           [6]])
#Simple Tensor Operations
       x = torch.ones([3, 2])
       y = torch.ones([3, 2])
       z = x + y
       print(z)
       z = x - y
       print(z)
       z = x * y
       print(z)
       Output:
       tensor([[2., 2.],
           [2., 2.],
           [2., 2.]]
       tensor([[o., o.],
           [0., 0.],
```

```
[0., 0.]
       tensor([[1., 1.],
           [1., 1.],
           [1., 1.]]
      z = y.add(x)
       print(z)
       print(y)
       Output:
       tensor([[2., 2.],
           [2., 2.],
           [2., 2.]]
      tensor([[1., 1.],
           [1., 1.],
           [1., 1.]]
      z = y.add_(x)
       print(z)
       print(y)
       Output:
      tensor([[2., 2.],
           [2., 2.],
           [2., 2.]]
      tensor([[2., 2.],
           [2., 2.],
           [2., 2.]]
#CUDA support
      print(torch.cuda.device_count())
      print(torch.cuda.device(o))
      print(torch.cuda.get_device_name(o))
       Output:
       <torch.cuda.device object at 0x7f785e6ec2b0>
       Tesla T4
      cudao = torch.device('cuda:o')
      a = torch.ones(3, 2, device=cudao)
       b = torch.ones(3, 2, device=cudao)
       c = a + b
       print(c)
      print(a)
      Output:
      tensor([[2., 2.],
           [2., 2.],
           [2., 2.]], device='cuda:0')
    tensor([[1., 1.],
```

```
1., 1.
     [1., 1.]], device='cuda:0')
      %%time
      for i in range(10):
       a = np.random.randn(10000,10000)
       b = np.random.randn(10000,10000)
       np.add(b, a)
      Output:
      CPU times: user 54.7 s, sys: 4.26 s, total: 59 s
      Wall time: 58.9 s
      %%time
      for i in range(10):
       a_cpu = torch.randn([10000, 10000])
       b cpu = torch.randn([10000, 10000])
       b cpu.add (a cpu)
      Output:
      CPU times: user 1.88 ms, sys: 2.87 ms, total: 4.75 ms
      Wall time: 29.6 ms
      %%time
      for i in range(10):
       a = torch.randn([10000, 10000], device=cudao)
       b = torch.randn([10000, 10000], device=cudao)
       b.add (a)
      Output:
      CPU times: user 1.88 ms, sys: 2.87 ms, total: 4.75 ms
      Wall time: 29.6 ms
      %%time
      for i in range(10):
       a = np.random.randn(10000,10000)
       b = np.random.randn(10000,10000)
       np.matmul(b, a)
%%time
for i in range(10):
 a = torch.randn([10000, 10000], device=cudao)
 b = torch.randn([10000, 10000], device=cudao)
 torch.matmul(a, b)
      Output:
CPU times: user 24.1 ms, sys: 18.9 ms, total: 42.9 ms
Wall time: 154 ms
```

```
#Autodiff
      x = torch.ones([3, 2], requires_grad=True)
      print(x)
      Output:
      tensor([[1., 1.],
           [1., 1.],
           [1., 1.]], requires_grad=True)
      y = x + 5
      print(y)
      Output:
      tensor([[6., 6.],
           [6., 6.],
           [6., 6.]], grad_fn=<AddBackwardo>)
      z = y^*y + 1
      print(z)
      Output:
      tensor([[37., 37.],
           [37., 37.],
           [37., 37.]], grad_fn=<AddBackwardo>)
      t = torch.sum(z)
      print(t)
      Output:
      tensor(222., grad_fn=<SumBackwardo>)
      t.backward()
      print(x.grad)
      Output:
      tensor([[12., 12.],
          [12., 12.],
           [12., 12.]])
```

```
t = \sum_{i} z_i, z_i = y_i^2 + 1, y_i = x_i + 5
  rac{\partial t}{\partial x_i} = rac{\partial z_i}{\partial x_i} = rac{\partial z_i}{\partial y_i} rac{\partial y_i}{\partial x_i} = 2y_i 	imes 1
  At x = 1, y = 6, \frac{\partial t}{\partial x} = 12
x = torch.ones([3, 2], requires_grad=True)
y = x + 5
r = 1/(1 + torch.exp(-y))
print(r)
s = torch.sum(r)
s.backward()
print(x.grad)
Output:
tensor([[0.9975, 0.9975],
     [0.9975, 0.9975],
     [0.9975, 0.9975]], grad fn=<MulBackwardo>)
tensor([[0.0025, 0.0025],
    [0.0025, 0.0025],
     [0.0025, 0.0025]])
x = torch.ones([3, 2], requires grad=True)
y = x + 5
r = 1/(1 + torch.exp(-y))
a = torch.ones([3, 2])
r.backward(a)
print(x.grad)
Output:
tensor([[0.0025, 0.0025],
    [0.0025, 0.0025],
    [0.0025, 0.0025]])
%%time
learning rate = 0.001
N = 10000000
epochs = 200
w = torch.rand([N], requires grad=True)
b = torch.ones([1], requires grad=True)
# print(torch.mean(w).item(), b.item())
for i in range(epochs):
 x = torch.randn([N])
 y = torch.dot(3*torch.ones([N]), x) - 2
 y_hat = torch.dot(w, x) + b
```

```
loss = torch.sum((y hat - y)**2)
loss.backward()
with torch.no grad():
 w -= learning_rate * w.grad
 b -= learning rate * b.grad
  w.grad.zero_()
 b.grad.zero_()
# print(torch.mean(w).item(), b.item())
Output:
CPU times: user 36.7 s, sys: 443 ms, total: 37.2 s
Wall time: 37.2 s
%%time
learning_rate = 0.001
N = 10000000
epochs = 200
w = torch.rand([N], requires_grad=True, device=cudao)
b = torch.ones([1], requires grad=True, device=cudao)
# print(torch.mean(w).item(), b.item())
for i in range(epochs):
x = torch.randn([N], device=cudao)
y = torch.dot(3*torch.ones([N], device=cudao), x) - 2
y hat = torch.dot(w, x) + b
loss = torch.sum((y_hat - y)^{**}2)
loss.backward()
 with torch.no grad():
 w -= learning_rate * w.grad
 b -= learning_rate * b.grad
 w.grad.zero ()
 b.grad.zero_()
 #print(torch.mean(w).item(), b.item())
Output:
CPU times: user 467 ms, sys: 305 ms, total: 772 ms
Wall time: 784 ms
```

```
5. Implementation of FCNN in Pytorch on MNIST data
import torch
import torch.nn as nn
import torchvision
import torchvision.transforms as transforms
import matplotlib.pyplot as plt
device = torch.device('cuda' if torch.cuda.is available() else 'cpu')
input size = 784 # 28x28
hidden size = 500
num classes = 10
num_epochs = 2
batch size = 100
learning rate = 0.001
# Import MNIST dataset
train dataset = torchvision.datasets.MNIST(root='./data',
                      train=True,
                      transform=transforms.ToTensor(),
                      download=True)
test_dataset = torchvision.datasets.MNIST(root='./data',
                      train=False.
                      transform=transforms.ToTensor())
# Data loader
train loader = torch.utils.data.DataLoader(dataset=train dataset,
                      batch size=batch size,
                      shuffle=True)
test loader = torch.utils.data.DataLoader(dataset=test dataset,
                      batch size=batch size,
                      shuffle=False)
# Fully connected neural network with one hidden layer
class NeuralNet(nn.Module):
  def init (self, input size, hidden size, num classes):
    super(NeuralNet, self). init ()
    self.input size = input size
    self.l1 = nn.Linear(input size, hidden size)
    self.relu = nn.ReLU()
    self.l2 = nn.Linear(hidden size, num_classes)
  def forward(self, x):
    out = self.l1(x)
    out = self.relu(out)
    out = self.l2(out)
    # no activation and no softmax at the end
    return out
model = NeuralNet(input_size, hidden_size, num_classes).to(device)
# Loss and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr=learning rate)
# Train the model
n total steps = len(train loader)
```

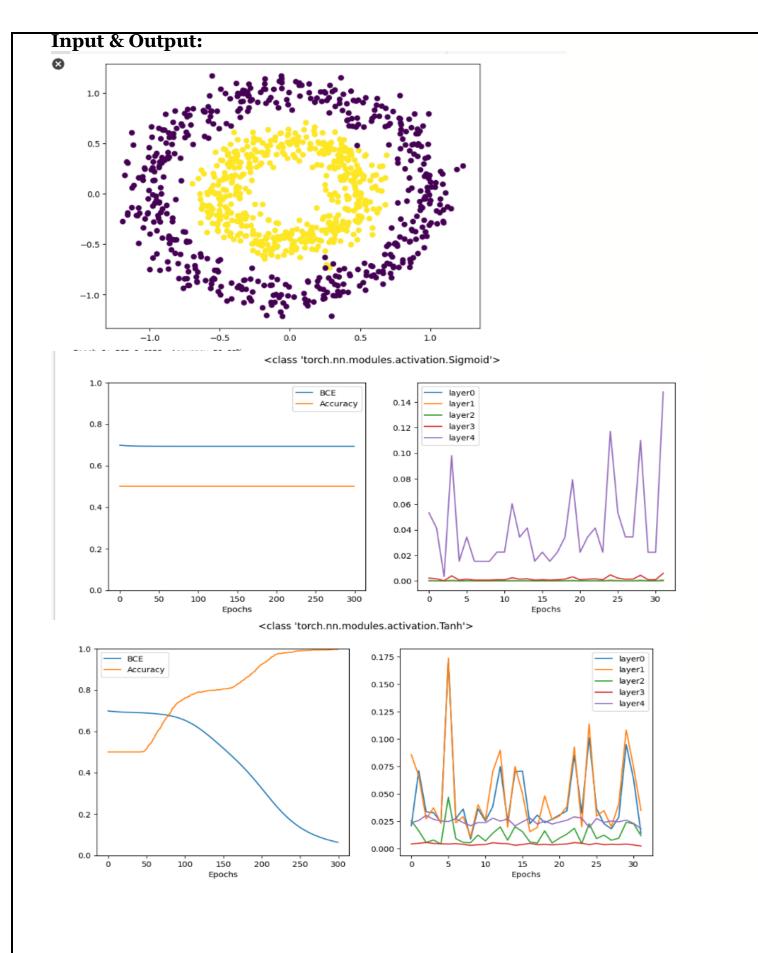
```
for epoch in range(num epochs):
  for i, (images, labels) in enumerate(train loader):
    # origin shape: [100, 1, 28, 28]
    # resized: [100, 784]
    images = images.reshape(-1, 28*28).to(device)
    labels = labels.to(device)
    # Forward pass
    outputs = model(images)
    loss = criterion(outputs, labels)
    # Backward and optimize
    optimizer.zero grad()
    loss.backward()
    optimizer.step()
    if (i+1) \% 100 == 0:
      print (f'Epoch [\{epoch+1\}/\{num epochs\}\}], Step [\{i+1\}/\{n total steps\}\}], Loss:
{loss.item():.4f}')
 # Test the model
# In test phase, we don't need to compute gradients (for memory efficiency)
with torch.no grad():
  n correct = 0
  n_samples = 0
  for images, labels in test_loader:
    images = images.reshape(-1, 28*28).to(device)
    labels = labels.to(device)
    outputs = model(images)
    # max returns (value ,index)
    , predicted = torch.max(outputs.data, 1)
    n samples += labels.size(o)
    n correct += (predicted == labels).sum().item()
  acc = 100.0 * n correct / n samples
  print(f'Accuracy of the network on the 10000 test images: {acc} %')
    0
   10
                           10
   20
                           20
                                            20
                                                            10
                                                                   20
    0
   10
                           10
                                                  10
                           20
   20
                    20
                                            20
                                                                   20
                                                     Ó
```

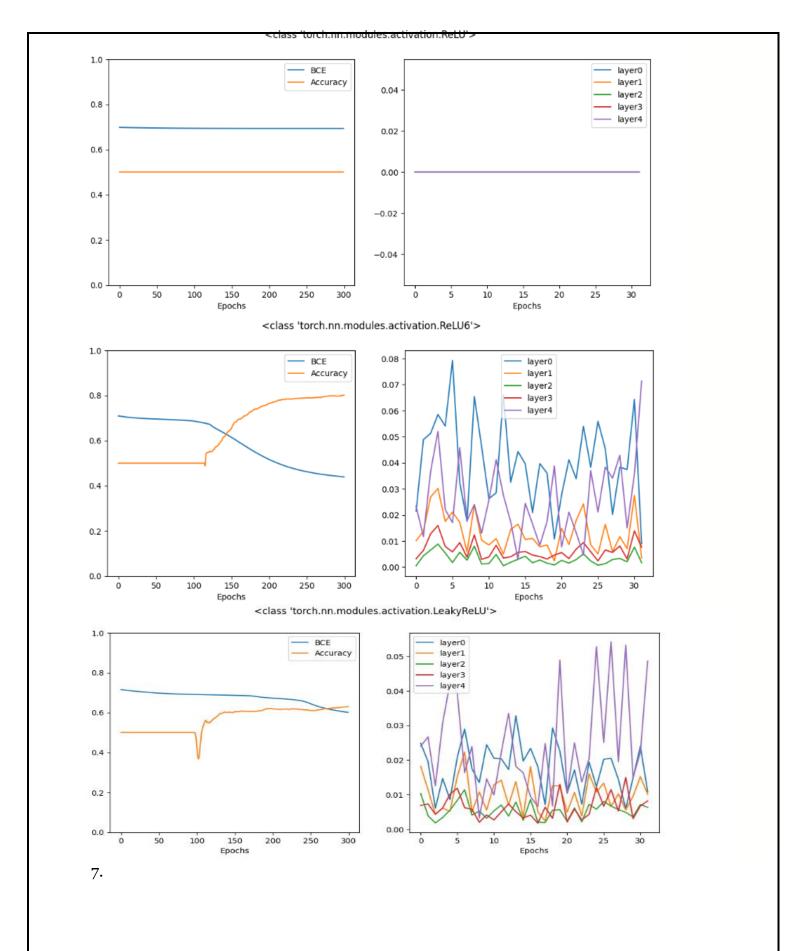
Output:

Accuracy of the network on the 10000 test images: 97.22 %

```
6. Analyze vanishing gradient problem by using various activation functions
from sklearn.datasets import make circles
import matplotlib.pyplot as plt
import torch
import torch.nn as nn
import torch.optim as optim
# Make data: Two circles on x-y plane as a classification problem
X, y = make_circles(n_samples=1000, factor=0.5, noise=0.1)
X = torch.tensor(X, dtype=torch.float32)
y = torch.tensor(y.reshape(-1, 1), dtype=torch.float32)
plt.figure(figsize=(8,6))
plt.scatter(X[:,0], X[:,1], c=y)
plt.show()
# Binary classification model
class Model(nn.Module):
  def __init__(self, activation=nn.ReLU):
    super(). init ()
    self.layero = nn.Linear(2,5)
    self.acto = activation()
    self.layer1 = nn.Linear(5.5)
    self.act1 = activation()
    self.layer2 = nn.Linear(5.5)
    self.act2 = activation()
    self.layer3 = nn.Linear(5.5)
    self.act3 = activation()
    self.layer4 = nn.Linear(5,1)
    self.act4 = nn.Sigmoid()
  def forward(self, x):
    x = self.acto(self.layero(x))
    x = self.act1(self.layer1(x))
    x = self.act2(self.layer2(x))
    x = self.act3(self.layer3(x))
    x = self.act4(self.layer4(x))
    return x
# train the model and produce history
def train_loop(model, X, y, n_epochs=300, batch_size=32):
  loss fn = nn.BCELoss()
  optimizer = optim.Adam(model.parameters(), lr=0.0001)
  batch_start = torch.arange(o, len(X), batch_size)
  bce hist = []
  acc hist = []
  grad_hist = [[],[],[],[],[]]
  for epoch in range(n_epochs):
    # train model with optimizer
    model.train()
```

```
layer grad = [ ], ], ], ], [ ]
    for start in batch_start:
      X batch = X[start:start+batch size]
      y batch = y[start:start+batch size]
      v pred = model(X batch)
      loss = loss fn(y pred, y batch)
      optimizer.zero grad()
      loss.backward()
      optimizer.step()
      # collect mean absolute value of gradients
      layers = [model.layer0, model.layer1, model.layer2, model.layer3, model.layer4]
      for n, layer in enumerate(layers):
        mean grad = float(layer.weight.grad.abs().mean())
        layer grad[n].append(mean grad)
    # evaluate BCE and accuracy at end of each epoch
    model.eval()
    with torch.no grad():
      y \text{ pred} = \text{model}(X)
      bce = float(loss_fn(y_pred, y))
      acc = float((y pred.round() == y).float().mean())
    bce_hist.append(bce)
    acc hist.append(acc)
    for n, grads in enumerate(layer grad):
      grad hist[n].append(sum(grads)/len(grads))
    # print metrics every 10 epochs
    if epoch \% 10 == 9:
      print("Epoch %d: BCE=%.4f, Accuracy=%.2f%%" % (epoch, bce, acc*100))
  return bce hist, acc hist, layer grad
# pick different activation functions and compare the result visually
for activation in [nn.Sigmoid, nn.Tanh, nn.ReLU, nn.ReLU6, nn.LeakyReLU]:
  model = Model(activation=activation)
  bce hist, acc hist, grad hist = train loop(model, X, y)
  fig, ax = plt.subplots(1, 2, figsize=(12, 5))
  ax[o].plot(bce hist, label="BCE")
  ax[o].plot(acc_hist, label="Accuracv")
  ax[o].set xlabel("Epochs")
  ax[o].set ylim(o, 1)
  for n, grads in enumerate(grad hist):
    ax[1].plot(grads, label="layer"+str(n))
  ax[1].set xlabel("Epochs")
  fig.suptitle(str(activation))
  ax[o].legend()
  ax[1].legend()
  plt.show()
```

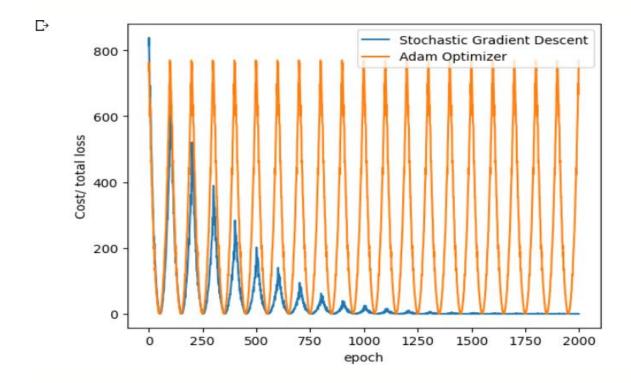




7. Analyze the performance of FCNN using various Optimization methods import matplotlib.pyplot as plt import numpy as np import torch from torch.utils.data import Dataset, DataLoader # Creating our dataset class class Build_Data(Dataset): # Constructor def init (self): self.x = torch.arange(-5, 5, 0.1).view(-1, 1) self.func = -5 * self.x + 1self.y = self.func + 0.4 * torch.randn(self.x.size()) self.len = self.x.shape[o] # Getting the data def __getitem__(self, index): return self.x[index], self.y[index] # Getting length of the data def len (self): return self.len # Create dataset object data_set = Build_Data() model = torch.nn.Linear(1, 1) criterion = torch.nn.MSELoss() # Creating Dataloader object trainloader = DataLoader(dataset = data_set, batch_size=1) # define optimizer optimizer = torch.optim.Adam(model.parameters(), lr=0.01) loss SGD = []n iter = 20for i in range(n_iter): for x, y in trainloader: # making a prediction in forward pass y hat = model(x)# calculating the loss between original and predicted data points loss = criterion(y hat, y) # store loss into list loss_SGD.append(loss.item()) # zeroing gradients after each iteration optimizer.zero grad() # backward pass for computing the gradients of the loss w.r.t to learnable parameters loss.backward() # updating the parameters after each iteration optimizer.step()

```
model = torch.nn.Linear(1, 1)
loss Adam = []
for i in range(n iter):
  for x, y in trainloader:
    # making a prediction in forward pass
    y hat = model(x)
    # calculating the loss between original and predicted data points
    loss = criterion(y hat, y)
    # store loss into list
    loss Adam.append(loss.item())
    # zeroing gradients after each iteration
    optimizer.zero_grad()
    # backward pass for computing the gradients of the loss w.r.t to learnable parameters
    loss.backward()
    # updating the parameters after each iteration
    optimizer.step()
plt.plot(loss_SGD,label = "Stochastic Gradient Descent")
plt.plot(loss_Adam,label = "Adam Optimizer")
plt.xlabel('epoch')
plt.ylabel('Cost/ total loss')
plt.legend()
plt.show()
```

Output:



8. Apply various regularization techniques to enhance the performance of FCNN

```
Using Dropouton the Hidden layers
import numpy as np
import pandas as pd
import torch
import torch.nn as nn
import torch.optim as optim
from sklearn.preprocessing import LabelEncoder
from sklearn.model selection import StratifiedKFold
# Read data
data = pd.read_csv("sonar.csv", header=None)
X = data.iloc[:, 0:60]
y = data.iloc[:, 60]
# Label encode the target from string to integer
encoder = LabelEncoder()
encoder.fit(y)
y = encoder.transform(y)
# Convert to 2D PyTorch tensors
X = torch.tensor(X.values, dtvpe=torch.float32)
y = torch.tensor(y, dtype=torch.float32).reshape(-1, 1)
# Define PyTorch model, with dropout at hidden layers
class SonarModel(nn.Module):
  def __init__(self):
    super(). init ()
    self.layer1 = nn.Linear(60, 60)
    self.act1 = nn.ReLU()
    self.dropout1 = nn.Dropout(0.2)
    self.layer2 = nn.Linear(60, 30)
    self.act2 = nn.ReLU()
    self.dropout2 = nn.Dropout(0.2)
    self.output = nn.Linear(30, 1)
    self.sigmoid = nn.Sigmoid()
  def forward(self, x):
    x = self.act1(self.layer1(x))
    x = self.dropout1(x)
    x = self.act_2(self.laver_2(x))
    x = self.dropout2(x)
    x = self.sigmoid(self.output(x))
    return x
# Helper function to train the model and return the validation result
def model train(model, X train, y train, X val, y val,
        n epochs=300, batch size=16):
 loss fn = nn.BCELoss()
  optimizer = optim.SGD(model.parameters(), lr=0.01, momentum=0.8)
```

```
batch start = torch.arange(o, len(X train), batch size)
  model.train()
  for epoch in range(n_epochs):
    for start in batch start:
      X batch = X train[start:start+batch size]
      y_batch = y_train[start:start+batch_size]
      y pred = model(X batch)
      loss = loss fn(y pred, y batch)
      optimizer.zero_grad()
      loss.backward()
      optimizer.step()
  # evaluate accuracy after training
  model.eval()
  y \text{ pred} = \text{model}(X_val})
  acc = (y pred.round() == y val).float().mean()
  acc = float(acc)
  return acc
# run 10-fold cross validation
kfold = StratifiedKFold(n_splits=10, shuffle=True)
accuracies = []
for train, test in kfold.split(X, y):
  # create model, train, and get accuracy
  model = SonarModel()
  acc = model_train(model, X[train], y[train], X[test], y[test])
  print("Accuracy: %.2f" % acc)
  accuracies.append(acc)
# evaluate the model
mean = np.mean(accuracies)
std = np.std(accuracies)
print("Baseline: %.2f%% (+/- %.2f%%)" % (mean*100, std*100))
import numpy as np
import pandas as pd
import torch
import torch.nn as nn
import torch.optim as optim
from sklearn.preprocessing import LabelEncoder
from sklearn.model selection import StratifiedKFold
# Read data
data = pd.read_csv("sonar.csv", header=None)
X = data.iloc[:, 0:60]
y = data.iloc[:, 60]
# Label encode the target from string to integer
encoder = LabelEncoder()
encoder.fit(y)
y = encoder.transform(y)
```

```
# Convert to 2D PyTorch tensors
X = torch.tensor(X.values, dtype=torch.float32)
y = torch.tensor(y, dtype=torch.float32).reshape(-1, 1)
# Define PyTorch model
class SonarModel(nn.Module):
  def __init__(self):
    super().__init__()
    self.layer1 = nn.Linear(60, 60)
    self.act1 = nn.ReLU()
    self.laver2 = nn.Linear(60, 30)
    self.act2 = nn.ReLU()
    self.output = nn.Linear(30, 1)
    self.sigmoid = nn.Sigmoid()
  def forward(self, x):
    x = self.act1(self.layer1(x))
    x = self.act2(self.layer2(x))
    x = self.sigmoid(self.output(x))
    return x
# Helper function to train the model and return the validation result
def model_train(model, X_train, y_train, X_val, y_val,
        n epochs=300, batch size=16):
  loss fn = nn.BCELoss()
  optimizer = optim.SGD(model.parameters(), lr=0.01, momentum=0.8)
  batch start = torch.arange(o, len(X train), batch size)
  model.train()
  for epoch in range(n epochs):
    for start in batch start:
      X batch = X train[start:start+batch size]
      y batch = y train[start:start+batch size]
      y pred = model(X batch)
      loss = loss_fn(y_pred, y_batch)
      optimizer.zero grad()
      loss.backward()
      optimizer.step()
  # evaluate accuracy after training
  model.eval()
  y \text{ pred} = \text{model}(X \text{ val})
  acc = (y_pred.round() == y_val).float().mean()
  acc = float(acc)
  return acc
# run 10-fold cross validation
kfold = StratifiedKFold(n_splits=10, shuffle=True)
accuracies = \square
for train, test in kfold.split(X, y):
  # create model, train, and get accuracy
  model = SonarModel()
```

```
acc = model_train(model, X[train], y[train], X[test], y[test])
print("Accuracy: %.2f" % acc)
accuracies.append(acc)

# evaluate the model
mean = np.mean(accuracies)
std = np.std(accuracies)
print("Baseline: %.2f%% (+/- %.2f%%)" % (mean*100, std*100))
```

Output: Using Dropout

Accuracy: 0.71
Accuracy: 1.00
Accuracy: 0.71
Accuracy: 0.90
Accuracy: 0.86
Accuracy: 0.81
Accuracy: 0.90
Accuracy: 0.86
Accuracy: 0.80
Accuracy: 0.80
Accuracy: 0.90

Baseline: 84.62% (+/- 8.48%)

Output: Without Dropout

Accuracy: 0.90
Accuracy: 0.81
Accuracy: 0.76
Accuracy: 0.81
Accuracy: 0.81
Accuracy: 0.90
Accuracy: 0.95
Accuracy: 0.90
Accuracy: 0.90
Accuracy: 0.65
Accuracy: 0.80

Baseline: 83.07% (+/- 8.42%)

9. Implement Convolution Neural Network(CNN) on CIFAR10 data set

Dataset Link:

```
http://archive.ics.uci.edu/ml/datasets/Connectionist+Bench+(Sonar,+Mines+vs.+Rocks)
import torch
import torch.optim as optim
import matplotlib.pyplot as plt
import torch.nn as nn
import numpy as np
import torchvision
import torchvision.transforms as transforms
#download CIFAR data set
trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                     download=True,
                     transform=transforms.ToTensor())
classes = ('plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship',
'truck')
trainloader = torch.utils.data.DataLoader(trainset, batch_size=4, shuffle=True)
dataiter = iter(trainloader)
images, labels = next(dataiter)
print(images.shape)
print(images[1].shape)
print(labels[1].item())
# Visualize the data
def imshow(img):
  npimg = img.numpy()
  plt.imshow(np.transpose(npimg, (1, 2, 0)))
  plt.show()
imshow(torchvision.utils.make_grid(images))
print(' '.join(classes[labels[j]] for j in range(4)))
#Single Convolutional Layer
class LeNet(nn.Module):
  def init (self):
    super(LeNet, self).__init__()
    self.cnn model = nn.Sequential(
      nn.Conv2d(3, 6, 5),
                              # (N, 3, 32, 32) -> (N, 6, 28, 28)
      nn.Tanh(),
      nn.AvgPool2d(2, stride=2), # (N, 6, 28, 28) -> (N, 6, 14, 14)
      nn.Conv2d(6, 16, 5),
                             # (N, 6, 14, 14) -> (N, 16, 10, 10)
      nn.Tanh().
      nn.AvgPool2d(2, stride=2) # (N,16, 10, 10) -> (N, 16, 5, 5)
    self.fc_model = nn.Sequential(
      nn.Linear(400,120), # (N, 400) -> (N, 120)
      nn.Tanh(),
```

```
# (N, 120) -> (N, 84)
      nn.Linear(120,84),
      nn.Tanh(),
      nn.Linear(84,10)
                               \# (N, 84) \rightarrow (N, 10)
    )
 def forward(self, x):
    x = self.cnn model(x)
    x = x.view(x.size(o), -1)
    x = self.fc model(x)
    return x
batch size = 128
trainset = torchvision.datasets.CIFAR10(root='./data', train=True, download=True,
transform=transforms.ToTensor())
trainloader = torch.utils.data.DataLoader(trainset, batch size=batch size, shuffle=True)
testset = torchvision.datasets.CIFAR10(root='./data', train=False, download=True,
transform=transforms.ToTensor())
testloader = torch.utils.data.DataLoader(testset, batch size=batch size, shuffle=False)
def evaluation(dataloader):
  total, correct = o, o
  for data in dataloader:
    inputs, labels = data
    outputs = net(inputs)
    _, pred = torch.max(outputs.data, 1)
    total += labels.size(o)
    correct += (pred == labels).sum().item()
  return 100 * correct / total
net = LeNet()
loss fn = nn.CrossEntropyLoss()
opt = optim.Adam(net.parameters())
%%time
loss arr = []
loss epoch arr = []
max epochs = 16
for epoch in range(max epochs):
  for i, data in enumerate(trainloader, o):
    inputs, labels = data
    opt.zero grad()
    outputs = net(inputs)
loss = loss_fn(outputs, labels)
loss.backward()
    opt.step()
    loss arr.append(loss.item())
  loss epoch arr.append(loss.item())
  print('Epoch: %d/%d, Test acc: %0.2f, Train acc: %0.2f' % (epoch, max epochs,
```

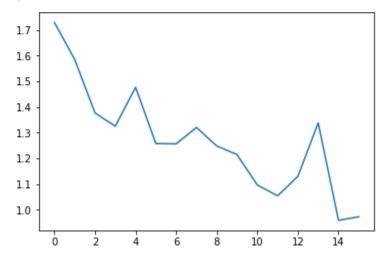
evaluation(testloader), evaluation(trainloader)))

plt.plot(loss_epoch_arr)
plt.show()

Output:



Epoch: 0/16, Test acc: 38.39, Train acc: 38.13 Epoch: 1/16, Test acc: 43.67, Train acc: 43.74 Epoch: 2/16, Test acc: 46.30, Train acc: 46.62 Epoch: 3/16, Test acc: 49.37, Train acc: 50.37 Epoch: 4/16, Test acc: 50.15, Train acc: 51.86 Epoch: 5/16, Test acc: 52.14, Train acc: 54.40 Epoch: 6/16, Test acc: 52.72, Train acc: 56.28 Epoch: 7/16, Test acc: 53.53, Train acc: 57.73 Epoch: 8/16, Test acc: 54.44, Train acc: 58.82 Epoch: 9/16, Test acc: 54.61, Train acc: 59.97 Epoch: 10/16, Test acc: 55.91, Train acc: 61.58 Epoch: 11/16, Test acc: 55.41, Train acc: 61.88 Epoch: 12/16, Test acc: 55.28, Train acc: 63.09 Epoch: 13/16, Test acc: 56.54, Train acc: 64.56 Epoch: 14/16, Test acc: 56.37, Train acc: 64.63 Epoch: 15/16, Test acc: 56.54, Train acc: 66.50



CPU times: user 7min 39s, sys: 9.16 s, total: 7min 48s Wall time: 7min 49s

10. Implement RNN for Text Classification

return torch.tensor([languages.index(lang)], dtype=torch.long)

```
https://www.kaggle.com/datasets/rp1985/name2lang
Data Set:
from io import open
import os, string, random, time, math
import matplotlib.pyplot as plt
import seaborn as sns
import numpy as np
from sklearn.model selection import train test split
import torch
import torch.nn as nn
import torch.optim as optim
from IPython.display import clear_output
languages = []
data = \prod
X = []
y = \prod
#Dataset Loading
with open('/content/name2lang.txt', 'r') as f:
  for line in f:
    line = line.split(',')
    name = line[o].strip()
    lang = line[1].strip()
    if not lang in languages:
      languages.append(lang)
    X.append(name)
    v.append(lang)
    data.append((name, lang))
    n languages = len(languages)
#Train-test split
X train, X test, y train, y test = train test split(X, y, test size=0.2, random state=0, stratify=y)
#Encoding names and language
all letters = string.ascii letters + " ..; "
n letters = len(all letters)
def name_rep(name):
  rep = torch.zeros(len(name), 1, n_letters)
  for index, letter in enumerate(name):
    pos = all letters.find(letter)
    rep[index][o][pos] = 1
  return rep
def lang rep(lang):
```

```
def dataloader(npoints, X, y):
  to ret = []
  for i in range(npoints):
    index_ = np.random.randint(len(X_))
    name, lang = X_[index_], y_[index_]
    to ret.append((name, lang, name rep(name), lang rep(lang)))
  return to_ret
def eval(net, n_points, k, X_, y_):
  data_ = dataloader(n_points, X_, y_)
correct = 0
  for name, language, name ohe, lang rep in data:
    output = infer(net, name)
val, indices = output.topk(k)
    if lang rep in indices:
      correct += 1
  accuracy = correct/n points
def train(net, opt, criterion, n points):
  opt.zero grad()
  total loss = 0
  data_ = dataloader(n_points, X_train, y_train)
  for name, language, name ohe, lang rep in data:
    hidden = net.init hidden()
    for i in range(name ohe.size()[0]):
      output, hidden = net(name ohe[i], hidden)
    loss = criterion(output, lang rep)
    loss.backward(retain graph=True)
    total loss += loss
  opt.step()
 return total loss/n points
def infer(net, name):
  net.eval()
  name_ohe = name_rep(name)
  hidden = net.init hidden()
  for i in range(name ohe.size()[0]):
    output, hidden = net(name ohe[i], hidden)
  return output
```

```
#Basic network and testing inference
class RNN net(nn.Module):
  def init (self, input size, hidden size, output size):
    super(RNN_net, self).__init__()
    self.hidden size = hidden size
    self.i2h = nn.Linear(input size + hidden size, hidden size)
    self.i20 = nn.Linear(input_size + hidden_size, output_size)
    self.softmax = nn.LogSoftmax(dim=1)
  def forward(self, input , hidden):
    combined = torch.cat((input_, hidden), 1)
    hidden = self.i2h(combined)
    output = self.i2o(combined)
    output = self.softmax(output)
    return output, hidden
  definit hidden(self):
    return torch.zeros(1, self.hidden size)
def train setup(net, lr = 0.01, n batches = 100, batch_size = 10, momentum = 0.9, display_freq=5):
  criterion = nn.NLLLoss()
  opt = optim.SGD(net.parameters(), lr=lr, momentum=momentum)
  loss arr = np.zeros(n batches + 1)
  for i in range(n batches):
    loss arr[i+1] = (loss arr[i]*i + train(net, opt, criterion, batch size))/(i+1)
    if i%display freq == display freq-1:
      clear output(wait=True)
      print('Iteration', i, 'Top-1:', eval(net, len(X_test), 1, X_test, y_test), 'Top-2:',
eval(net, len(X_test), 2, X_test, y_test), 'Loss', loss_arr[i])
      plt.figure()
      plt.plot(loss arr[1:i], '-*')
      plt.xlabel('Iteration')
      plt.ylabel('Loss')
      plt.show()
      print(' \setminus n \setminus n')
n hidden = 128
net = RNN net(n letters, n hidden, n languages)
train setup(net, lr=0.0005, n batches=100, batch size = 256)
```

Output:

☐→ Iteration 99 Top-1: 0.6428927680798004 Top-2: 0.7713216957605985 Loss 1.4926992654800415

