

Perturbation Methods

① Correlated Sampling

- motivation is doing parametric studies
- goal is to estimate how a response/ QoI changes when model parameters change using a single calculation

② Differential Operator Sampling

- motivation are sensitivity studies
- formulate estimators to compute derivative of response/ QoI w.r.t. model parameters

Correlated Sampling

⇒ apply to a discrete-time Markov Chain,
but more general random processing can
be used as well

Define: $R = \text{response} / Q \cdot I$

$\alpha = \text{input model parameter}$

$\omega = \text{index for a random walk/realization}$

$$R = \sum_{\omega} r(\omega) f(\omega), \quad r(\omega) = \text{scoring/response fun for r.w. } \omega$$

$f(\omega) = \text{prob. of r.w. } \omega \text{ occurring}$

R' = perturbed response b/c of some
change α , call it $\Delta\alpha$

⇒ $\Delta\alpha$ leads to the following changes to the
simulation process

① Direct Effect: changes $r(\omega)$ by Δr
independent of changes to
the random walks

② Indirect Effect: changes $f(\omega)$ by Δf ,
change in the r.w.
probability

Perturbed Response: $R' = \sum_{\omega'} r'(\omega') f'(\omega') \Rightarrow$ perturbation and NOT derivative
 ω' r.w.'s for perturbed case

\Rightarrow expand $f(\omega)$ as the product of probabilities of taking individual steps

$$f(\omega) = \prod_{k=1}^{n(\omega)} p_k(\omega), \quad \begin{array}{l} n(\omega) = \# \text{ steps in r.w. } \omega \\ p_k(\omega) = \text{prob. of the } k\text{th step in r.w. } \omega \end{array}$$

\Rightarrow Insert into expression for R'

$$R' = \sum_{\omega'} r'(\omega') \prod_{k=1}^{n'(\omega')} p'_k(\omega')$$

\Rightarrow Our desire is to use the r.w.'s ω in the base/unperturbed case vs. the perturbed r.w.'s ω'

$$R' \approx \sum_{\omega} r'(\omega) \prod_{k=1}^{n(\omega)} p'_k(\omega)$$

\uparrow approximate b/c changing a model parameter could "open up" new parts of the sample space not in the base case

$$R' \approx \sum_{\omega} r'(\omega) \prod_{k=1}^{n(\omega)} \underbrace{\left(\frac{p_k'(\omega)}{p_k(\omega)} \right)}_{a_k(\omega)} p_k(\omega)$$

$a_k(\omega)$ = adjustment factor
for k th step

$$= \sum_{\omega} r'(\omega) \prod_{k=1}^{n(\omega)} a_k(\omega) p_k(\omega)$$

$$= \sum_{\omega} r'(\omega) \underbrace{\left(\prod_{k=1}^{n(\omega)} a_k(\omega) \right)}_{a(\omega)} \underbrace{\left(\prod_{k=1}^{n(\omega)} p_k(\omega) \right)}_{f(\omega)}$$

$$R' \approx \sum_{\omega} \underbrace{r'(\omega) a(\omega)}_{\text{scoring/response fun for the perturbed response}} \underbrace{f(\omega)}_{\text{handled by the frequency of n.w. occurring}}$$

handled by the
frequency of n.w.
occurring

scoring/response fun for
the perturbed response

⇒ assume an additive scoring fun:

$$r(w) = \sum_k r_k(w), \quad r_k(w) = \text{response/scoring contribution for } k\text{th step}$$

$$r'(w) = \sum_k r'_k(w) = \sum_k (r_k(w) + \underbrace{\Delta r_k(w)}_{\text{change b/c of } \Delta x})$$

⇒ change in response

$$\Delta R = R' - R$$

$$\approx \sum_w r'(w) a(w) f(w) - \sum_w r(w) f(w)$$

$$= \sum_w \left(\frac{r'(w)}{r(w)} a(w) r(w) - r(w) \right) f(w)$$

$$= \sum_w \left(\underbrace{\frac{r'(w)}{r(w)}}_{\text{put in terms of } \Delta r} a(w) - 1 \right) r(w) f(w)$$

$$\Delta R \approx \sum_w \left[\underbrace{\left(1 + \frac{\Delta r(w)}{r(w)} \right)}_{\text{direct effect}} a(w) - 1 \right] r(w) f(w)$$

direct effect
indirect effect

Scoring fun for ΔR

Modification of DTMC Algorithm

⇒ at the start of each random walk/sample we set $a_m = 1$, $\Delta r_m = 0$ for each perturbation $m = 1, \dots, M$

a_m = multiplicative accumulator for the adjustment factor for pert. m

Δr_m = additive accumulator for the change in scoring fun for pert. m

⇒ sample each step in random walks as before

- now for each step $k = 1, \dots, n$

$$a_m \leftarrow \underbrace{p_{m,k}}_{\substack{\text{element of} \\ \text{Transition} \\ \text{matrix for} \\ \text{kth step}}} = \frac{\text{perturbed transition prob.}}{\text{unperturbed / base " "}} \quad \text{(the one we are simulating)}$$

$$\Delta r_m \leftarrow \Delta r_m + \Delta r_{m,k} \quad \text{change in response / score contribution for kth step}$$

⇒ at the end of the random walk
make the score for port m :

$$\Delta R_m + \varepsilon \left[\left(1 + \frac{\Delta R_m}{r} \right) a_m - 1 \right] r$$

Not each
step!

⇒ repeat for numerous random walks/samples
and divide ΔR_m by the # samples,
to get the estimate

ex: geometric distribution

$$f(n) = \lambda^{n-1} (1-\lambda), \quad n=1, 2, 3, \dots$$

$$P = \begin{bmatrix} \lambda & 0 \\ 1-\lambda & 1 \end{bmatrix} \quad \begin{array}{c} \text{State 1} \xrightarrow{\lambda} \text{State 1} \\ \text{State 1} \xrightarrow{1-\lambda} \text{State 2} \end{array}$$

\Rightarrow let R = expected # steps to reach state 2

$$R = \sum_{n=1}^{\infty} n f(n) = \sum_{n=1}^{\infty} n \lambda^{n-1} (1-\lambda) = \frac{1}{1-\lambda}$$

\Rightarrow for perturbed r.v. w/ $\lambda \rightarrow \lambda'$

$$R' = \frac{1}{1-\lambda'}$$

\Rightarrow will corrected sampling produce the value of R' ?

$$R' \stackrel{?}{=} \sum_{n=1}^{\infty} \overbrace{r(n)}^{=r'(n)=n} a(n) f(n)$$

$$= (1) \left[\frac{1-\lambda'}{1-\lambda} \right] \cancel{(1-\lambda)}$$

$$+ (2) \left[\left(\frac{\lambda'}{\lambda} \right) \left(\frac{1-\lambda'}{1-\lambda} \right) \right] \cancel{\lambda(1-\lambda)}$$

$$+ (3) \left[\left(\frac{\lambda'}{\lambda} \right)^2 \left(\frac{1-\lambda'}{1-\lambda} \right) \right] \cancel{\lambda^2(1-\lambda)}$$

$$= \sum_{n=1}^{\infty} n(\lambda')^{n-1} (1-\lambda') = \frac{1}{1-\lambda'} \quad \checkmark$$

\Rightarrow In simulation, if we step $1 \rightarrow 1$
we multiply a_n by $\frac{\lambda'}{\lambda}$,

if we step $1 \rightarrow 2$, we multiply
 a_n by $\frac{1-\lambda'}{1-\lambda}$

Remarks

- ⇒ works well when the cost of accruing the perturbed estimators is fast compared to the computational cost of the simulation (ex. particle transport) compared to separate realizations
- ⇒ the estimator for adjustment factor is multiplicative and can be very large for some random walks → high variance, when $\Delta\alpha$ is large (keep the changes to model parameters modest)