

Perturbation Methods

① Correlated Sampling

- motivation is doing parametric studies
- goal is to estimate how a response/QoI changes when model parameters change using a single calculation

② Differential Operator Sampling

- motivation are sensitivity studies
- formulate estimators to compute derivatives of response/QoIs w.r.t. model parameters

Correlated Sampling

⇒ apply to a discrete-time Markov Chain,
but more general random processes can
be used as well.

Define: $R = \text{response} / Q \cdot I$

α = input model parameter

ω = index for a random walk/realization

$R = \sum_{\omega} r(\omega) f(\omega)$, $r(\omega)$ = scoring/response from
for r.w. ω

$f(\omega)$ = prob. of r.w. ω
occurring

R' = perturbed response b/c of some
change α , call it $\Delta\alpha$

⇒ $\Delta\alpha$ leads to the following changes to the
simulation process

① Direct Effect: changes $r(\omega)$ by Δr
independent of change to
the random walks

② Indirect Effect: changes $f(\omega)$ by Δf ,
change in the r.w.
probability

Perturbed Response: $R' = \sum_{\omega'} r'(\omega') f'(\omega')$ \Rightarrow perturbations
 are NOT derivatives
 (in)
 r.w.s for perturbed case

\Rightarrow expand $f(\omega)$ as the product of probabilities,
 of taking individual steps

$$f(\omega) = \prod_{k=1}^{n(\omega)} p_k(\omega), \quad n(\omega) \approx \# \text{ steps in r.w. } \omega$$

$p_k(\omega) \approx \text{prob. of the } k\text{th step in r.w. } \omega$

\Rightarrow Insert into expression for R'

$$R' = \sum_{\omega'} r'(\omega') \prod_{k=1}^{n'(\omega')} p'_k(\omega')$$

\Rightarrow Our desire is to use the r.w.'s ω in the base/unperturbed case vs. the perturbed r.w.'s ω'

$$R' \approx \sum_{\omega} r'(\omega) \prod_{k=1}^{n(\omega)} p'_k(\omega)$$

↑ approximate b/c changing a model parameter could "open up" new parts of the sample space not in the base case

$$R' \approx \sum_{\omega} r'(\omega) \prod_{k=1}^{n(\omega)} \underbrace{\left(\frac{p_k'(\omega)}{p_k(\omega)} \right)}_{a_k(\omega)} p_k(\omega)$$

$a_k(\omega)$ = adjustment factor
for k-th step

$$= \sum_{\omega} r'(\omega) \prod_{k=1}^{n(\omega)} a_k(\omega) p_k(\omega)$$

$$= \sum_{\omega} r'(\omega) \underbrace{\left(\prod_{k=1}^{n(\omega)} a_k(\omega) \right)}_{a(\omega)} \underbrace{\left(\prod_{k=1}^{n(\omega)} p_k(\omega) \right)}_{f(\omega)}$$

$$R' \approx \sum_{\omega} r'(\omega) a(\omega) f(\omega)$$

handled by the frequency of n.w.
 ω occurring

scoring/response fun for
the perturbed response

\Rightarrow assume an additive scoring fun:

$$r(\omega) = \sum_k r_k(\omega), \quad r_k(\omega) = \text{response/scoring contribution for } k\text{-th step}$$

$$r'(\omega) = \sum_k r'_k(\omega) = \sum_k (r_k(\omega) + \underbrace{\Delta r_k(\omega)}_{\text{change b/c of } \Delta x})$$

\Rightarrow change in response

$$\Delta R = R' - R$$

$$\approx \sum_{\omega} r'(\omega) a(\omega) f(\omega) - \sum_{\omega} r(\omega) f(\omega)$$

$$= \sum_{\omega} \left(\frac{r'(\omega) a(\omega) r(\omega)}{r(\omega)} - r(\omega) \right) f(\omega)$$

$$= \sum_{\omega} \left(\frac{r'(\omega)}{r(\omega)} a(\omega) - 1 \right) r(\omega) f(\omega)$$

\rightarrow put in terms of Δr

$$\Delta R \approx \sum_{\omega} \left[\left(1 + \frac{\Delta r(\omega)}{r(\omega)} \right) a(\omega) - 1 \right] r(\omega) f(\omega)$$

direct effect

indirect effect

Scoring fun for ΔR

Modification of DTMC Algorithm

At the start of each random walk/sample we set $a_m = 1$, $\Delta r_m = 0$ for each perturbation $m=1, \dots, M$

a_m = multiplicative accumulator for the adjustment factor for pert. m

Δr_m = additive accumulator for the change in scoring fun for pert. m

\Rightarrow Sample each step in random walks as below

- now for each step $k=1, \dots, n$

$$a_m * = \frac{p'_{m,k}}{p_k} = \frac{\text{perturbed transition prob.}}{\text{unperturbed / base " "}}$$

*current state
transition
matrix for
kth step*

(the one we are
simulating)

$$\Delta r_m + = \Delta r_{m,k} = \text{change in response / score contribution for kth step}$$

\Rightarrow at the end of the random walk

make the sum for per m:

$$\Delta R_m + \varepsilon = \left[\left(1 + \frac{\Delta r_m}{n} \right) a_m - 1 \right] r$$

Not each
Step!

\Rightarrow repeat for numerous random walks/samples
and divide ΔR_m by the # samples
to get the estimate

Ex: geometric distribution

$$f(n) = \lambda^{n-1} (1-\lambda), n=1, 2, 3, \dots$$

$$P = \begin{bmatrix} \lambda & 0 \\ 1-\lambda & 1 \end{bmatrix} \xrightarrow{\text{GO}} \begin{bmatrix} 1-\lambda & 0 \\ 0 & 1 \end{bmatrix},$$

\Rightarrow let R = expected # steps to reach state 2

$$R = \sum_{n=1}^{\infty} n c_n f(n) = \sum_{n=1}^{\infty} n \lambda^{n-1} (1-\lambda) = \frac{1}{1-\lambda}$$

\Rightarrow for perturbed r.w. w/ $\lambda \rightarrow \lambda'$

$$R' = \frac{1}{1-\lambda'}$$

\Rightarrow will corrected sampling produce this value of R' ?

$$\begin{aligned}
 R' &= ? \sum_{n=1}^{\infty} \underbrace{r(n)}_{=r'(n)=n} a(n) f(n) \\
 &= (1) \left[\frac{1-\lambda'}{1-x} \right] (1-\lambda) \\
 &\quad + (2) \left[\left(\frac{\lambda'}{x} \right) \left(\frac{1-\lambda'}{1-x} \right) \right] x (1-\lambda) \\
 &\quad + (3) \left[\left(\frac{\lambda'}{x} \right)^2 \left(\frac{1-\lambda'}{1-x} \right) \right] x^2 (1-\lambda) \\
 &= \sum_{n=1}^{\infty} n(\lambda')^{n-1} (1-\lambda') = \frac{1}{1-\lambda'} \checkmark
 \end{aligned}$$

\Rightarrow In simulation, if we step 1 \rightarrow 1
 we multiply a_m by $\frac{\lambda'}{\lambda}$,
 if we step 1 \rightarrow 2, we multiply
 a_m by $\frac{1-\lambda'}{1-\lambda}$

Remarks

- ⇒ works well when the cost of accuracy the perturbed estimates is fast compared to the computational cost of the simulation
(ex. particle transport) compare to separate realizations
- ⇒ The estimator for adjustment factor is multiplicative and can be very large for some random walks → high variance, when $\Delta\alpha$ is large (keep the changes to model parameters modest)