CSE 2320 Notes 11: Rooted Trees

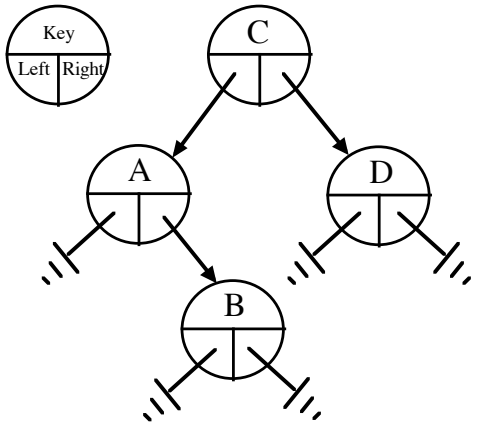
(Last updated 10/21/18 10:41 AM)

CLRS 10.4, 12.1-12.3, 14.1, 13.2

11.A. TREES

Representing Trees (main memory, disk devices in CSE 3330)

Binary tree



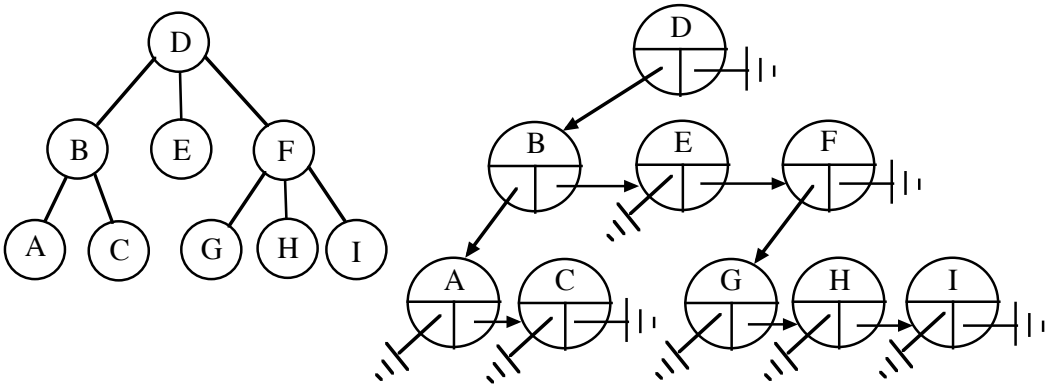
Mandatory

- Left
- Right

Optional

- Parent
- Key
- Data
- Subtree Size

Rooted tree with linked siblings



Mandatory

- First Child
- Right Sibling

Optional

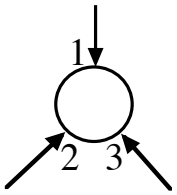
- Last Child
- Left Sibling
- Parent
- Key
- Data
- Subtree Size

11.B. Binary Tree Traversals (review)

1st Visit – Preorder

2nd Visit – Inorder

3rd Visit – Postorder

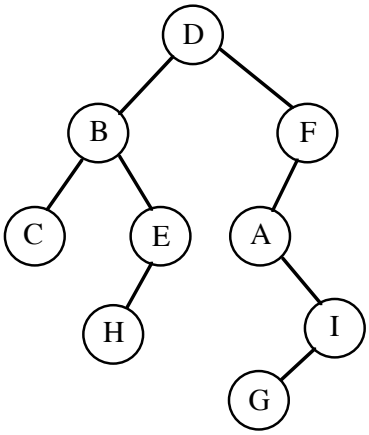



```
recTraversal(Node h)
{
  if (h!=null)
  {

    recTraversal(h.l);

    recTraversal(h.r);

  }
}
```



Preorder

D B C E H F A I G

Inorder

C B H E D A G I F

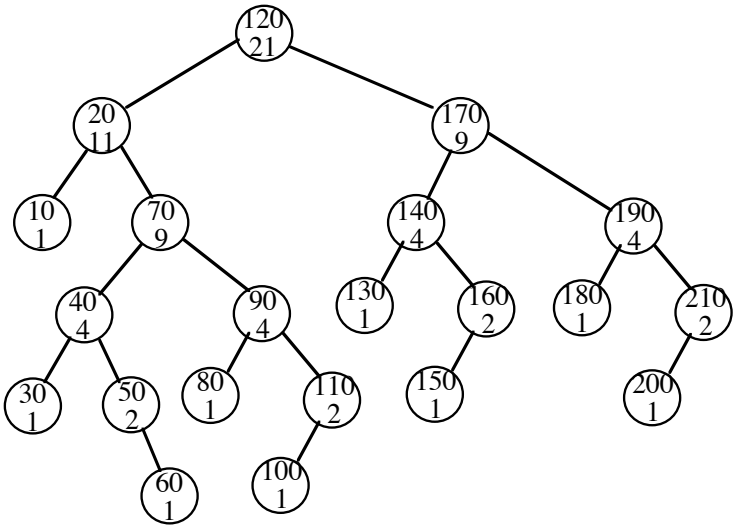
Postorder

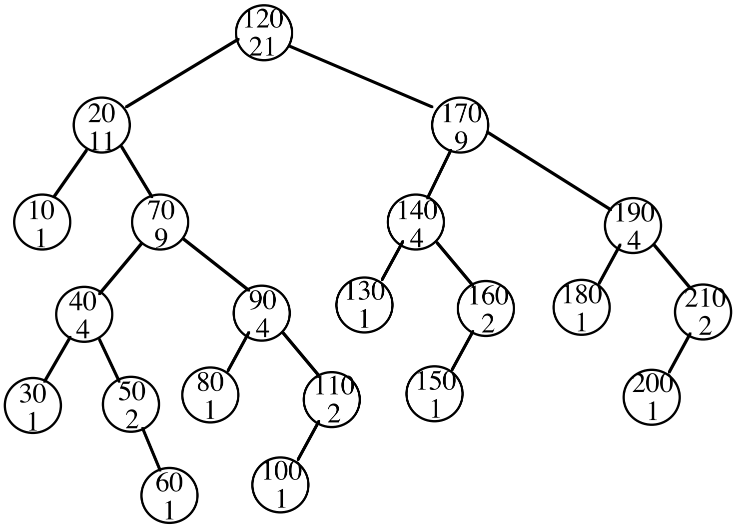
C H E B G I A F D

11.C. BINARY SEARCH TREES

Basic property – Go left for smaller keys. Go right for larger keys. (Use of sentinel)

Which traversal lists the keys in ascending order?




120
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170
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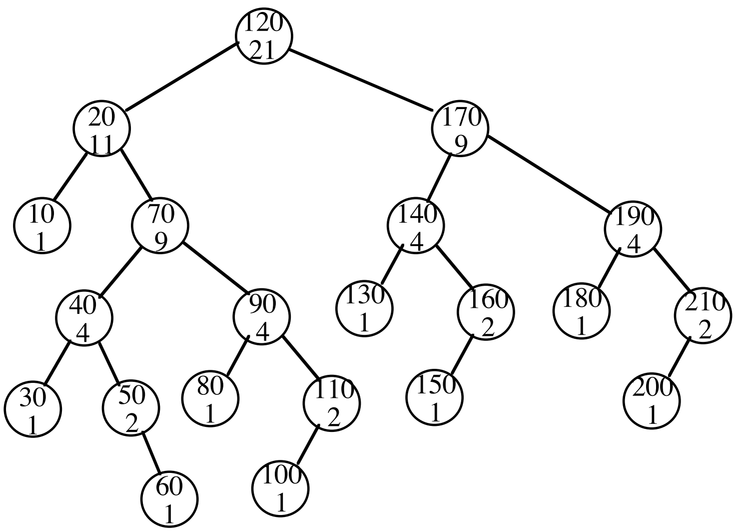
190
4
40
4
90
4
130
1
160
2
180
1
210
2
30
1
50
2
80
1
110
2
150
1
200
1
60
1
100
1


120
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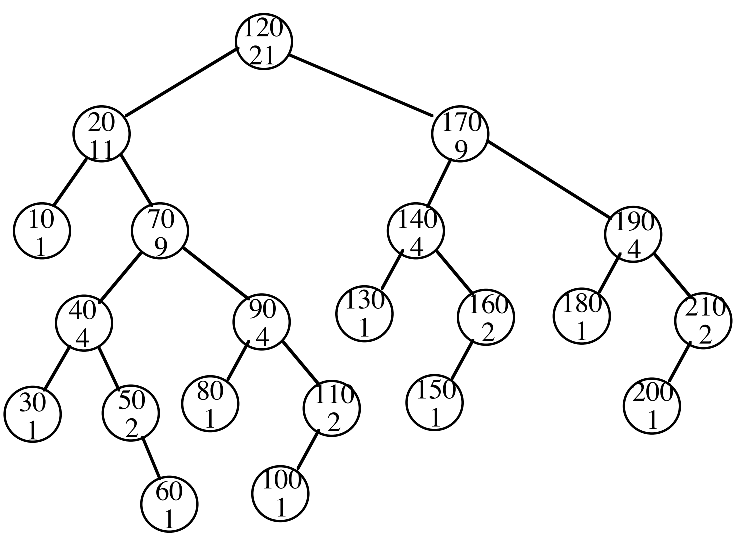
4
40
4
90
4
130
1
160
2
180
1
210
2
30
1
50
2
80
1
110
2
150
1
200
1
60
1
100
1


120
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130
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160
2
180
1
210
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30
1
50
2
80
1
110
2
150
1
200
1
60
1
100
1

Operations: (see `http://ranger.uta.edu/~weems/NOTES2320/REDBLACKC/RB.c`)

1. Search (`searchR`)
2. Minimum / maximum in tree
3. Successor/predecessor of a node
4. Insert (unbalanced in `http://ranger.uta.edu/~weems/NOTES2320/REDBLACKC/RB.loadAndGo.c`)
5. Deletion of key and associated data is contained in:
    a. Leaf
    b. Node with one child
    c. Node with two children
        1. Find node's successor (convention)
        2. Move key and data (but not pointer values) from successor node to node of deletion.
        3. Successor has either
            a. Zero children – leaf is removed (5.a)
            b. One child (right) – point around successor node to remove (5.b)

    May also use *tombstones* and periodically recycle garbage.

Implementing operations 6. and 7. efficiently requires maintaining subtree sizes "incrementally".

Rank of a key X that appears in tree = number of nodes with keys ≤ X.

Number of nodes on search path to X with keys ≤ key in given node

+

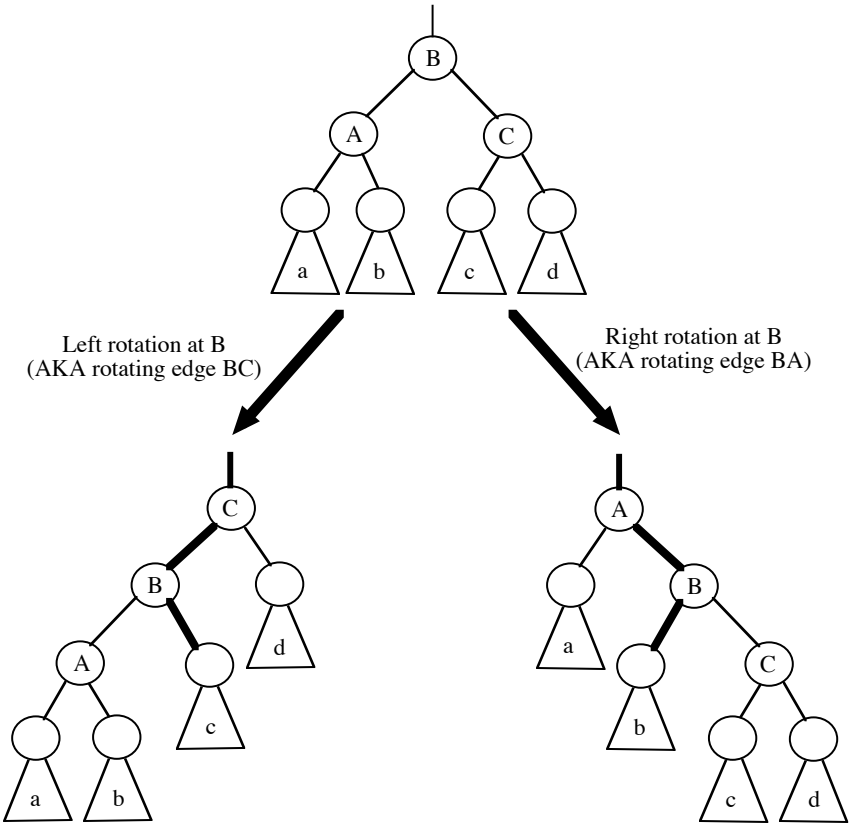
Sizes of their left subtrees

6. Rank of a key (`invSelectR`).
7. Finds key with a given rank (`selectR`) - This is the same as flattening tree into an ordered array and then subscripting (or using inorder traversal).

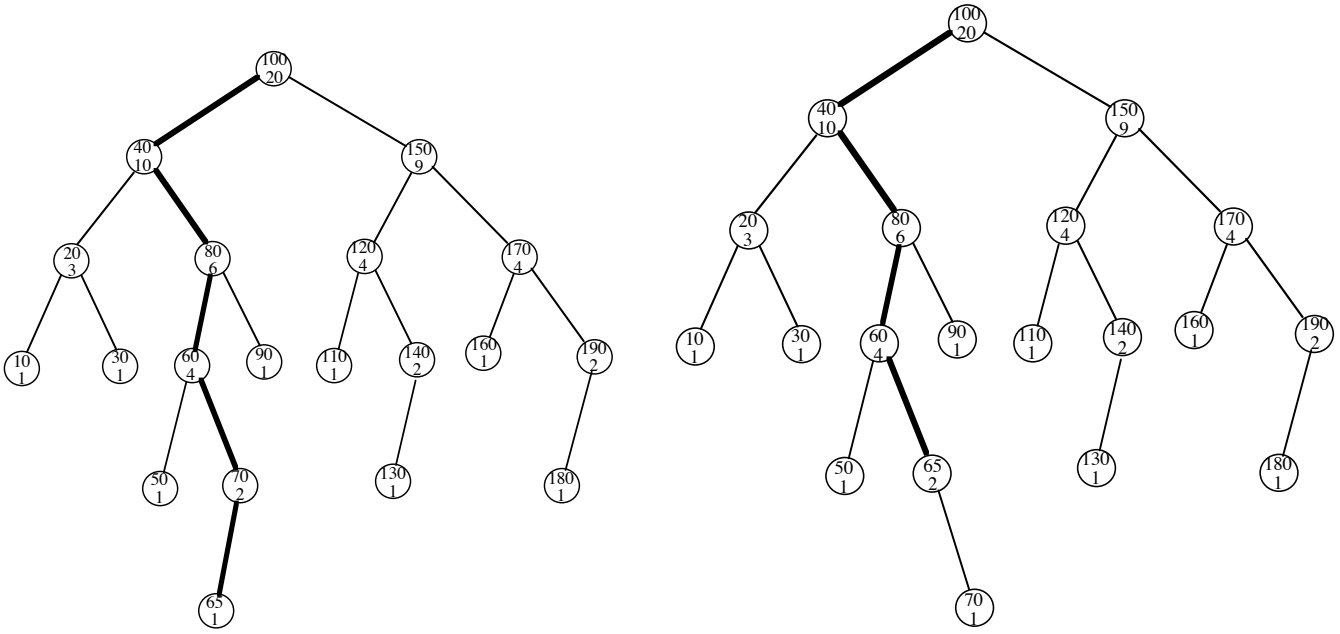
Time for operations?

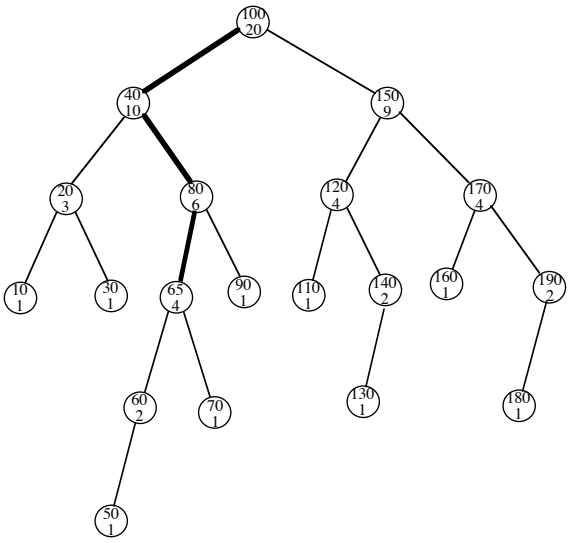
11.D. ROTATIONS

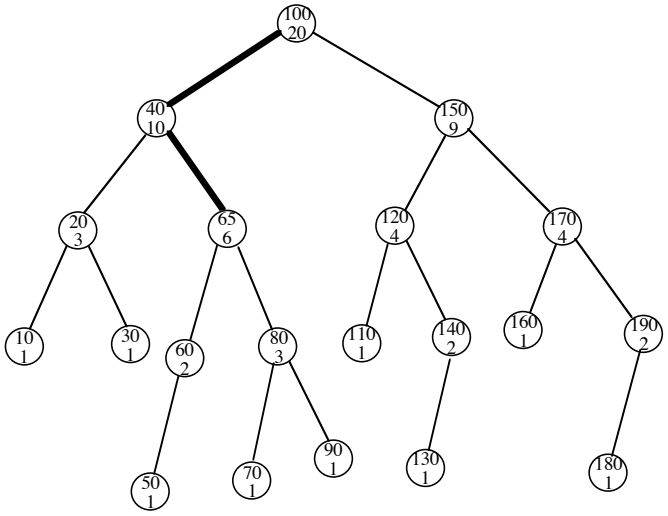
Technique for rebalancing in balanced binary search tree schemes. Takes $\Theta(1)$ time.

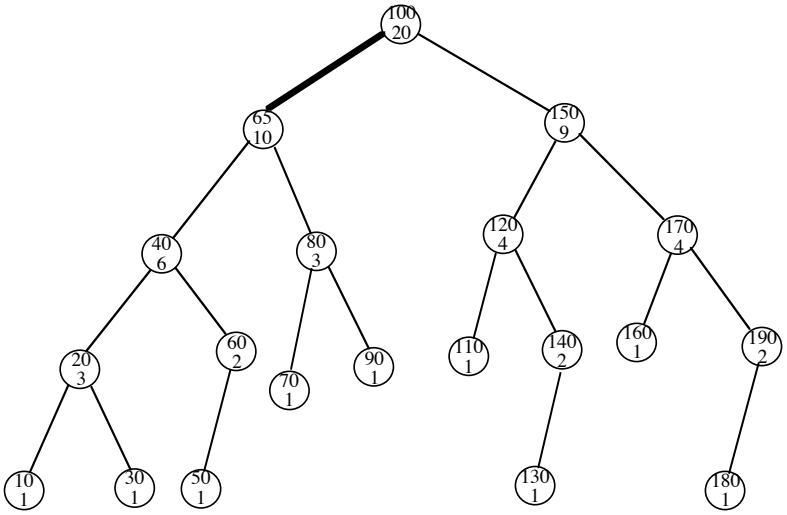


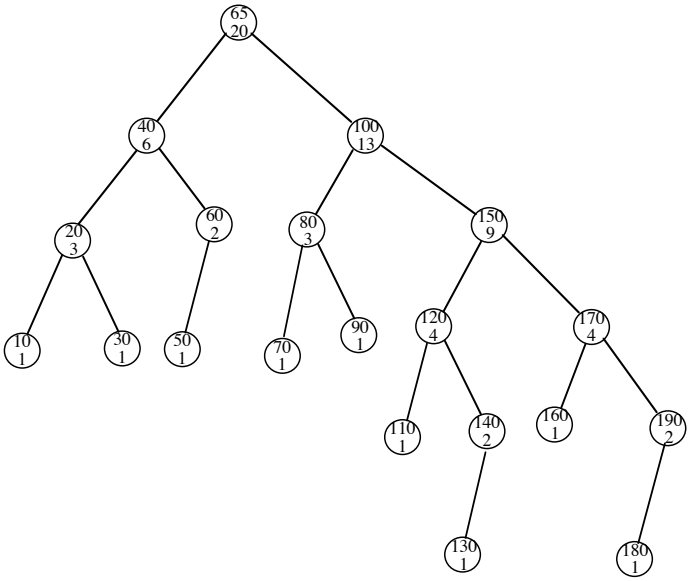
11.E. INSERTION AT ROOT: rotates all edges on the insertion path:











http://ranger.uta.edu/~weems/NOTES2320/bst.step.html